



Politecnico di Torino

OverkillaTO

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- 1 Contest
- 2 Mathematics
- 3 Data structures
- 4 Numerical
- 5 Number theory
- 6 Combinatorial
- 7 Graph
- 8 Geometry
- 9 Strings
- 10 Various

Contest (1)

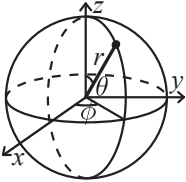
template.cpp	20 lines
<pre>// #pragma GCC optimize("O2") #include <bits/stdc++.h> using namespace std; #define rep(i, a, b) for(int i = a; i < (b); ++i) #define all(x) begin(x), end(x) #define sz(x) (int)(x).size() #define MSB(x) (63 - __builtin_clzll(1ll(x))) #define bit(x, b) ((x >> b) & 1) typedef long long ll; typedef pair<int, int> pii; typedef vector<int> vi; template<typename T> using vec = vector<T> int32_t main() { ios::sync_with_stdio(0);cin.tie(0); cout.tie(0); cin.exceptions(cin.failbit); } //bs..Find_first() ..Find_next(i) .set() .reset() .count()</pre>	
.bashrc	3 lines
<pre>alias c='g++ -Wall -Wconversion -Wfatal-errors -g -std=c++14 \ -fsanitize=undefined,address' xmodmap -e 'clear lock' -e 'keycode 66=less greater' #caps =◇</pre>	
gen.cpp	6 lines
<pre>ll rand(ll l, ll r) { return l + rand() % (r - l + 1); } int32_t main(int argc, char* argv[]){ srand(atoi(argv[1])); ll n = rand(2, 20); //input size cout << "TEST" << '\n'; }</pre>	

tester.sh	11 lines
<pre>g++ sol.cpp -std=c++17 -o main g++ naive.cpp -std=c++17 -o naive g++ gen.cpp -std=c++17 -o gen for((i = 1; ; ++i)); do echo test case: \$i ./gen \$i > input ./naive < input > output1 ./main < input > output2 diff -w output1 output2 break echo passed! done</pre>	
.vimrc	20 lines
<pre>set autoindent set cindent set smartindent set nu set ts=4 set sw=4 set tabstop=4 set hlsearch inoremap ((<left> inoremap { {<left> inoremap [[<left> inoremap ' ''<left> inoremap " ""<left> syntax on "" colorscheme habamax colorscheme darkblue "" colorscheme zaibatsu</pre>	
hash.sh	3 lines
<pre># Hashes a file, ignoring all whitespace and comments. Use for # verifying that code was correctly typed. cpp -dD -P -fpreprocessed tr -d '[:space:]' md5sum cut -c-6</pre>	
flags.txt	4 lines
<pre>// useful g++ flags // Wshadow for variable shadowing warning, _GLIBCXX_ASSERTIONS // for OOB/bad iterator errors -Wall -Wextra -Wshadow -D_GLIBCXX_DEBUG -D_GLIBCXX_ASSERTIONS - fdiagnostics-color=always</pre>	
troubleshoot.txt	52 lines
<pre>Pre-submit: Write a few simple test cases if sample is not enough. Are time limits close? If so, generate max cases. Is the memory usage fine? Could anything overflow? Make sure to submit the right file. Wrong answer: Print your solution! Print debug output, as well. Are you clearing all data structures between test cases? Can your algorithm handle the whole range of input? Read the full problem statement again. Do you handle all corner cases correctly? Have you understood the problem correctly? Any uninitialized variables? Any overflows?</pre>	

Confusing N and M, i and j, etc.? Are you sure your algorithm works? What special cases have you not thought of? Are you sure the STL functions you use work as you think? Add some assertions, maybe resubmit. Create some testcases to run your algorithm on. Go through the algorithm for a simple case. Go through this list again. Explain your algorithm to a teammate. Ask the teammate to look at your code. Go for a small walk, e.g. to the toilet. Is your output format correct? (including whitespace) Rewrite your solution from the start or let a teammate do it.
Runtime error: Have you tested all corner cases locally? Any uninitialized variables? Are you reading or writing outside the range of any vector? Any assertions that might fail? Any possible division by 0? (mod 0 for example) Any possible infinite recursion? Invalidated pointers or iterators? Are you using too much memory? Debug with resubmits (e.g. remapped signals, see Various).
Time limit exceeded: Do you have any possible infinite loops? What is the complexity of your algorithm? Are you copying a lot of unnecessary data? (References) How big is the input and output? (consider scanf) Avoid vector, map. (use arrays/unordered_map) What do your teammates think about your algorithm?
Memory limit exceeded: What is the max amount of memory your algorithm should need? Are you clearing all data structures between test cases?
Mathematics (2)
2.1 Geometry
2.1.1 Triangles
Side lengths: a, b, c
Semiperimeter: $p = \frac{a + b + c}{2}$
Area: $A = \sqrt{p(p - a)(p - b)(p - c)}$
Circumradius: $R = \frac{abc}{4A}$
Inradius: $r = \frac{A}{p}$
Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$
Length of bisector (divides angles in two): $s_a = \sqrt{bc \left[1 - \left(\frac{a}{b + c} \right)^2 \right]}$
Law of sines: $\frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$
Law of cosines: $a^2 = b^2 + c^2 - 2bc \cos \alpha$

Law of tangents: $\frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$

2.1.2 Spherical coordinates



$$\begin{aligned} x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \arccos(z/\sqrt{x^2 + y^2 + z^2}) \\ z &= r \cos \theta & \phi &= \operatorname{atan2}(y, x) \end{aligned}$$

2.2 Sums

$$c^a + c^{a+1} + \cdots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$\begin{aligned} 1 + 2 + 3 + \cdots + n &= \frac{n(n+1)}{2} \\ 1^2 + 2^2 + 3^2 + \cdots + n^2 &= \frac{n(2n+1)(n+1)}{6} \\ 1^3 + 2^3 + 3^3 + \cdots + n^3 &= \frac{n^2(n+1)^2}{4} \\ 1^4 + 2^4 + 3^4 + \cdots + n^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30} \end{aligned}$$

First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each which yields success with probability p is $Fs(p)$, $0 \leq p \leq 1$.

$$p(k) = p(1 - p)^{k-1}, k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$$

Poisson distribution

The number of events occuring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $Po(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, 2, \dots$$

$$\mu = \lambda, \sigma^2 = \lambda$$

2.2.1 Continuous distributions

Data structures (3)

OrderStatisticTree.h

Description: A set (not multiset!) with support for finding the n 'th element, and finding the index of an element. To get a map, change null-type. **Time:** $\mathcal{O}(\log N)$

```
#include <bits/extc++.h>
using namespace __gnu_pbds;

template<class T>
using Tree = tree<T, null_type, less<T>, rb_tree_tag,
tree_order_statistics_node_update>;

// #include <ext/pb_ds/assoc.container.hpp>
// #include <ext/pb_ds/tree_policy.hpp> //commented for ump
#define ordered_setll tree<ll, null_type, less<ll>, rb_tree_tag,
tree_order_statistics_node_update>
template<typename T> using ordered_set = tree<T, null_type,
less<T>, rb_tree_tag, tree_order_statistics_node_update>;
unordered_map<ll, tree<pair<ll, ll>, null_type, less<pair<ll,
ll>>, rb_tree_tag, tree_order_statistics_node_update>> ump;

void example() {
    Tree<int> t, t2; t.insert(8);
    auto it = t.insert(10).first;
    assert(it == t.lower_bound(9));
    assert(t.order_of_key(10) == 1);
    assert(t.order_of_key(11) == 2);
    assert(*t.find_by_order(0) == 8);
    t.join(t2); // assuming T< T2 or T> T2, merge t2 into t
}
```

HashMap.h

Description: Hash map with mostly the same API as unordered_map, but ~3x faster. Uses 1.5x memory. Initial capacity must be a power of 2 (if provided).

```
#include <bits/extc++.h>
// To use most bits rather than just the lowest ones:
struct chash { // large odd number for C
    const uint64_t C = 11(4e18 * acos(0)) | 71;
    ll operator()(ll x) const { return __builtin_bswap64(x*C); }
};
__gnu_pbds::gp_hash_table<ll,int,chash> h({}, {}, {}, {}, {1<<16});
```

SegmentTree.h

Description: Zero-indexed max-tree. Bounds are inclusive to the left and exclusive to the right. Can be changed by modifying T, f and unit. **Time:** $\mathcal{O}(\log N)$

```
struct Tree {
    typedef int T;
    static constexpr T unit = INT_MIN;
    T f(T a, T b) { return max(a, b); } // (any associative fn)
    vector<T> s; int n;
    Tree(int n = 0, T def = unit) : s(2*n, def), n(n) {}
    void update(int pos, T val) {
        for (s[pos += n] = val; pos /= 2; )
            s[pos] = f(s[pos * 2], s[pos * 2 + 1]);
    }
    T query(int b, int e) { // query [b, e)
        T ra = unit, rb = unit;
        for (b += n, e += n; b < e; b /= 2, e /= 2) {
            if (b % 2) ra = f(ra, s[b++]);
            if (e % 2) rb = f(s[--e], rb);
        }
    }
};
```

```
}
return f(ra, rb);
}
```

LazySegmentTree.h

Description: Segment tree with ability to add or set values of large intervals, and compute max of intervals. Can be changed to other things. Use with a bump allocator for better performance, and SmallPtr or implicit indices to save memory. **Usage:** Node* tr = new Node(v, 0, sz(v)); **Time:** $\mathcal{O}(\log N)$.

```
../various/BumpAllocator.h
const int inf = 1e9;
struct Node {
    Node *l = 0, *r = 0;
    int lo, hi, mset = inf, madd = 0, val = -inf;
    Node(int lo, int hi) : lo(lo), hi(hi) {} // Large interval of -inf
    Node(vi& v, int lo, int hi) : lo(lo), hi(hi) {
        if (lo + 1 < hi) {
            int mid = lo + (hi - lo)/2;
            l = new Node(v, lo, mid); r = new Node(v, mid, hi);
            val = max(l->val, r->val);
        }
        else val = v[lo];
    }
    int query(int L, int R) {
        if (R <= lo || hi <= L) return -inf;
        if (L <= lo && hi <= R) return val;
        push();
        return max(l->query(L, R), r->query(L, R));
    }
    void set(int L, int R, int x) {
        if (R <= lo || hi <= L) return;
        if (L <= lo && hi <= R) mset = val = x, madd = 0;
        else {
            push(), l->set(L, R, x), r->set(L, R, x);
            val = max(l->val, r->val);
        }
    }
    void add(int L, int R, int x) {
        if (R <= lo || hi <= L) return;
        if (L <= lo && hi <= R) {
            if (mset != inf) mset += x;
            else madd += x;
            val += x;
        }
        else {
            push(), l->add(L, R, x), r->add(L, R, x);
            val = max(l->val, r->val);
        }
    }
    void push() {
        if (!l) {
            int mid = lo + (hi - lo)/2;
            l = new Node(lo, mid); r = new Node(mid, hi);
        }
        if (mset != inf)
            l->set(lo,hi,mset), r->set(lo,hi,mset), mset = inf;
        else if (madd)
            l->add(lo,hi,madd), r->add(lo,hi,madd), madd = 0;
    }
};
```

2FenInsteadOfSegment.h

Description: Does advanced queries with two fenwicks **Time:** $\mathcal{O}(\log N)$.

```
ll Fen[2][MXN];
```

```
void Add(int id, int p, int x){
    for(; p < MXN; p += p & -p) Fen[id][p] += x;
}
ll Ask(int id, int p){
    ll niw = 0;
    for(; p; p -= p & -p) niw += Fen[id][p];
    return niw;
}
void UpdFen(int l, int r, int x){
    Add(0, l, x);
    Add(0, r + 1, -x);
    Add(1, l, x * (1 - 1));
    Add(1, r + 1, -x * r);
}
ll Get(int r){
    return Ask(0, r) * r - Ask(1, r);
}
ll GetFen(int l, int r){
    return Get(r) - Get(l - 1);
}
```

Matrix.h

Description: Basic operations on square matrices.

Usage: Matrix M = Matrix(2, 1)

MAX.M[1][0]

d41d8c, 65 lines

```
const ll MXZ = 100 + 10;
struct Matrix{
    int n, m; ll M[MXZ][MXZ];
    Matrix(int _n, int _m, ll num = 0){
        n = _n, m = _m;
        if(num == -1)
            for(int i = 0; i < n; i++)
                for(int j = 0; j < m; j++) M[i][j] = (i == j);
        else
            for(int i = 0; i < n; i++)
                for(int j = 0; j < m; j++) M[i][j] = num;
    }
    void Print(bool f = 0){
        cerr << "====N.N====\n";
        if(f) cerr << "Size : " << n << ' ' << m << '\n';
        for(int i = 0; i < n; i++, cerr << '\n'){
            for(int j = 0; j < m; j++) cerr << M[i][j] << ' ';
        }
        cerr << "====N.N====\n";
    }
    Matrix operator + (const Matrix &T){
        Matrix R = Matrix(n, m);
        for(int i = 0; i < n; i++)
            for(int j = 0; j < m; j++)
                R.M[i][j] = (M[i][j] + T.M[i][j]) % Mod;
        return R;
    }
    Matrix operator * (const Matrix &T){
        Matrix R = Matrix(n, T.m);
        if(m != T.n){
            cerr << "Cannot * Matrices !" << '\n'; return R;
        }
        for(int i = 0; i < n; i++){
            for(int j = 0; j < T.m; j++){
                for(int k = 0; k < m; k++){
                    ll now = (Ok(M[i][k]) * Ok(T.M[k][j])) % Mod;
                    R.M[i][j] = (R.M[i][j] + now) % Mod;
                }
            }
        }
        return R;
    }
}
```

Matrix LineContainer FenwickTree XorHashingFenwick

```
Matrix operator ^ (const ll t){
    Matrix R = Matrix(n, m, -1);
    if(n != m){
        cerr << "Cannot ^ Matrice with n != m !" << '\n'; return R;
    }
    if(t == 0) return R;
    Matrix T = Matrix(n, m);
    for(int i = 0; i < n; i++)
        for(int j = 0; j < m; j++)
            T.M[i][j] = M[i][j];
    ll p = t;
    while(p){
        if(p & 1LL) R = R * T;
        T = (T * T), p /= 2;
    }
    return R;
}
};
ll Fib(ll t){
    if(t == 1) return 1; Matrix M(2, 1), C(2, 2, 1);
    M.M[0][0] = M.M[1][0] = 1; C.M[1][1] = 0;
    C = (C ^ (t - 2)); M = (C * M); return M.M[0][0];
}
```

LineContainer.h

Description: Container where you can add lines of the form $kx+m$, and query maximum values at points x . Useful for dynamic programming (“convex hull trick”).

Time: $\mathcal{O}(\log N)$

d41d8c, 30 lines

```
struct Line {
    mutable ll k, m, p;
    bool operator<(const Line& o) const { return k < o.k; }
    bool operator<(ll x) const { return p < x; }
};

struct LineContainer : multiset<Line, less<>> {
    // (for doubles, use inf = 1./0, div(a,b) = a/b)
    static const ll inf = LLONG_MAX;
    ll div(ll a, ll b) { // floored division
        return a / b - ((a ^ b) < 0 && a % b); }
    bool isect(iterator x, iterator y) {
        if (y == end()) return x->p = inf, 0;
        if (x->k == y->k) x->p = x->m > y->m ? inf : -inf;
        else x->p = div(y->m - x->m, x->k - y->k);
        return x->p >= y->p;
    }
    void add(ll k, ll m) {
        auto z = insert({k, m, 0}), y = z++, x = y;
        while (isect(y, z)) z = erase(z);
        if (x != begin() && isect(--x, y)) isect(x, y = erase(y));
        while ((y = x) != begin() && (--x)->p >= y->p)
            isect(x, erase(y));
    }
    ll query(ll x) {
        assert(!empty());
        auto l = *lower_bound(x);
        return l.k * x + l.m;
    }
};
```

FenwickTree.h

Description: Computes partial sums

Time: $\mathcal{O}(\log N)$.

d41d8c, 22 lines

```
ll Fen[MXN]; //Be careful with Mod
void Upd(ll p, ll x){
    for(; p < MXN; p += p & -p) Fen[p] += x;
```

```
} // Call fill(Fen, Fen + n + 5, 0) in main
void Upd(ll l, ll r, ll x){
    Upd(l, x), Upd(r + 1, -x);
}
ll Get(ll p){
    ll s = 0; for(; p; p -= p & -p) s += Fen[p]; return s;
}
ll Get(ll l, ll r){
    return (r < 1 ? 0 : Get(r) - Get(l - 1));
}
ll Find(ll k){
    ll ans = 0;
    for(int i = LOG; ~i; i--){
        if(ans + (1LL << i) < MXN && Fen[ans + (1LL << i)] >= k)
            ans += (1LL << i), k -= Fen[ans];
    }
    return ans + 1;
}
```

XorHashingFenwick.h

Description: Random number generators and fenwick on it with xor

d41d8c, 61 lines

```
const ll MXN = 3e5 + 10;
const ll MXK = 32; //16
//Random number generation (64 bits is safe):
// mt19937.64 rng(chrono::steady_clock::now().time_since_epoch
//    (.count()));
// mt19937 Rnd(chrono::high_resolution_clock::now().
//    time_since_epoch().count());
// mt19937 rng(time(0)); // mt19937 mrnd(19260817);
// srand(time(0)); srand(time(NULL));
// ll uld(ll a, ll b) { return uniform_int_distribution<ll>(a,
//    b)(Rnd); }
```

typedef unsigned long long u64;
const valarray<u64> zero(0ull, MXK);

```
static uint64_t hsh(uint64_t x){
    // http://xorshift.di.unimi.it/splitmix64.c
    x += 0x9e3779b97f4a7c15;
    x = (x ^ (x >> 30)) * 0xbf58476d1ce4e5b9;
    x = (x ^ (x >> 27)) * 0x94d049b133111eb;
    return x ^ (x >> 31);
}
valarray<u64> to_arr(u64 x){
    static const uint64_t FIXED_RANDOM = chrono::steady_clock::
        now().time_since_epoch().count();
    x += FIXED_RANDOM;
    valarray<u64> ans(0ull, MXK);
    for(ll i = 0; i < MXK; i++)
        ans[i] = hsh(x + i * i * i + i) % (1ull << 32);
    return ans;
}
```

```
valarray<u64> Fen[MXN];
inline void initFen(){ //boundry can be n itself
    for(int i = 0; i < MXN; i++) Fen[i] = zero;
}
void Upd(ll p, valarray<u64> x){
    for(; p < MXN; p += p & -p) Fen[p] += x;
}
valarray<u64> Get(ll p){
    valarray<u64> s(0ull, MXK); for(; p; p -= p & -p) s += Fen[
        p]; return s;
}
ll n;
```

```
valarray<u64> A[MXN];

struct ValarrayComparator {
    bool operator()(const valarray<u64>& a, const valarray<u64>
        >& b) const {
        assert(a.size() == MXK && b.size() == MXK);
        for(size_t i = 0; i < MXK; ++ i){
            if(a[i] != b[i]) return a[i] < b[i];
        }
        return false;
    }
}; //Check mod k for understanding if it appeared kt times
map<valarray<u64>, ll, ValarrayComparator> mp;

int32_t main(){
    initFen();
    cin >> n;
    for(int i = 1; i <= n; i++){
        ll x; cin >> x;
        A[i] = to_arr(x); //auto y = ..
    }
}
```

FenwickTree2d.h

Description: Computes sums a[i,j] for all i<I, j<J, and increases single elements a[i,j]. Requires that the elements to be updated are known in advance (call fakeUpdate() before init()).
Time: $\mathcal{O}(\log^2 N)$. (Use persistent segment trees for $\mathcal{O}(\log N)$.)

"FenwickTree.h" d41d8c, 22 lines

```
struct FT2 {
    vector<vi> ys; vector<FT> ft;
    FT2(int limx) : ys(limx) {}
    void fakeUpdate(int x, int y) {
        for (; x < sz(ys); x |= x + 1) ys[x].push_back(y);
    }
    void init() {
        for (vi& v : ys) sort(all(v)), ft.emplace_back(sz(v));
    }
    int ind(int x, int y) {
        return (int)(lower_bound(all(ys[x]), y) - ys[x].begin()); }
    void update(int x, int y, ll dif) {
        for (; x < sz(ys); x |= x + 1)
            ft[x].update(ind(x, y), dif);
    }
    ll query(int x, int y) {
        ll sum = 0;
        for (; x; x &= x - 1)
            sum += ft[x-1].query(ind(x-1, y));
        return sum;
    }
};
```

RMQ.h

Description: Range Minimum Queries on an array (constant time).

d41d8c, 19 lines

```
int rmq[LOG][MXN], lg[MXN];
inline void BuildRmq(){
    for(int i = 1; i <= n; i++) rmq[0][i] = A[i];
    for(int j = 1; j < LOG; j++){
        for(int i = 1; i <= n; i++){
            if(i < (1LL << j)) continue;
            rmq[j][i] = max(rmq[j - 1][i], rmq[j - 1][i - (1LL
                << (j - 1))]);
        }
    }
}
inline int Max(int l, int r){
    if(l == r) return rmq[0][l];
    if(r < l) swap(l, r);
```

```
        return max(rmq[lg[r - 1 + 1]][r], rmq[lg[r - 1 + 1]][l + (1
            LL << lg[r - 1 + 1]) - 1]);
    }
    inline void InitLog(){
        for(int i = 0; (1LL << i) < MXN; i++) lg[(1LL << i)] = i;
        for(int i = 1; i < MXN; i++) lg[i] = max(lg[i - 1],
            lg[i]);
    } //Call InitLog() & BuildRmq();
```

MoQueries.h

Description: Answer interval or tree path queries by finding an approximate TSP through the queries, and moving from one query to the next by adding/removing points at the ends. If values are on tree edges, change step to add/remove the edge (a, c) and remove the initial add call (but keep in).
Time: $\mathcal{O}(N\sqrt{Q})$

d41d8c, 23 lines

```
bool CMP(int x, int y){
    if(Ql[x] / SQR == Ql[y] / SQR) return (Qr[x] < Qr[y]);
    return (Ql[x] / SQR < Ql[y] / SQR);
}
bool CmP(int x, int y){
    if(Ql[x] / SQR == Ql[y] / SQR) return ((Ql[x] / SQR) % 2) ^
        (Qr[x] < Qr[y]);
    return (Ql[x] / SQR < Ql[y] / SQR);
}
void Add(ll x){ x = A[x]; /* ... */ }
void Ers(ll x){ x = A[x]; /* ... */ }
int main(){
    for(int i = 1; i <= q; i++) cin >> Ql[i] >> Qr[i], vec.
        push_back(i);
    sort(vec.begin(), vec.end(), CmP);
    ll Ml = 1, Mr = 0;
    for(auto id : vec){
        int l = Ql[id], r = Qr[id];
        while(Mr < r) Mr ++, Add(Mr);
        while(l < Ml) Ml --, Add(Ml);
        while(Mr > r) Ers(Mr), Mr --;
        while(Ml < l) Ers(Ml), Ml ++;
    }
    return 0;
}
```

Numerical (4)

4.1 Polynomials and recurrences

PolyArithmetic.h

Description: Inputs must be in [0, mod).
Time: $\mathcal{O}(N \log N)$ for more complex operations (high constant), $\mathcal{O}(N)$ for simple operations

d41d8c, 66 lines

```
using poly = vector<Z>;

void fix(poly &a) {
    while (a.size() and a.back().x == 0) a.pop_back();
}

poly trunc(poly a, int k) {
    poly f = a;
    f.resize(k);
    return f;
}

poly add(poly a, poly b) {
    int n = max(a.size(), b.size());
    poly res(n);
    for (int i = 0; i < (int)a.size(); i++) res[i] += a[i];
    for (int i = 0; i < (int)b.size(); i++) res[i] += b[i];
```

```
    return res;
}

poly sub(poly a, poly b) {
    int n = max(a.size(), b.size());
    poly res(n);
    for (int i = 0; i < (int)a.size(); i++) res[i] += a[i];
    for (int i = 0; i < (int)b.size(); i++) res[i] -= b[i];
    return res;
}

poly mult(poly a, poly b) {
    fix(a), fix(b);
    return conv(a, b);
}

poly deriv(poly a) {
    if (a.empty()) return a;
    poly res(a.size() - 1);
    for (int i = 0; i < a.size() - 1; ++i) res[i] = a[i + 1] *
        (i+1);
    return res;
}

poly integr(poly a) {
    poly res(a.size() + 1);
    for (int i = 0; i < a.size(); ++i) res[i + 1] = a[i] / (i +
        1);
    return res;
}

poly inv(poly a, int m) {
    poly x{Z(1)/a[0]};
    int k = 1;
    while (k < m) k *= 2, x = trunc(mult(x, (sub(poly{2}, mult(
        trunc(a, k), x)))), k);
    return trunc(x, m);
}

poly log(poly a, int m) {
    poly res = mult(deriv(a), inv(a, m));
    res = trunc(integr(res), m);
    return res;
}

poly exp(poly a, int m) {
    poly x{1};
    int k = 1;
    while (k < m) k *= 2, x = trunc(mult(x, add(sub(poly{1},
        log(x, k)), trunc(a, k))), k);
    return trunc(x, m);
}
// for pow shift until first non zero coeff, then reshift back,
p^x = exp(x * log p)

PolyRoots.h
Description: Finds the real roots to a polynomial.
Usage: polyRoots({{2,-3,1}},-1e9,1e9) // solve x^2-3x+2 = 0
Time:  $\mathcal{O}(n^2 \log(1/\epsilon))$ 
"Polynomial.h" d41d8c, 23 lines
vector<double> polyRoots(Poly p, double xmin, double xmax) {
    if (sz(p.a) == 2) { return {-p.a[0]/p.a[1]}; }
    vector<double> ret;
    Poly der = p;
    der.diff();
    auto dr = polyRoots(der, xmin, xmax);
    dr.push_back(xmin-1);
    dr.push_back(xmax+1);
    sort(all(dr));
```

```
rep(i,0,sz(dr)-1) {
    double l = dr[i], h = dr[i+1];
    bool sign = p(l) > 0;
    if (sign ^ (p(h) > 0)) {
        rep(it,0,60) { // while (h - l > 1e-8)
            double m = (l + h) / 2, f = p(m);
            if ((f <= 0) ^ sign) l = m;
            else h = m;
        }
        ret.push_back((l + h) / 2);
    }
}
return ret;
}
```

PolyInterpolate.h

Description: Given n points $(x[i], y[i])$, computes an n -1-degree polynomial p that passes through them: $p(x) = a[0] * x^0 + \dots + a[n-1] * x^{n-1}$. For numerical precision, pick $x[k] = c * \cos(k/(n-1) * \pi), k = 0 \dots n-1$.
Time: $\mathcal{O}(n^2)$

```
typedef vector<double> vd;
vd interpolate(vd x, vd y, int n) {
    vd res(n), temp(n);
    rep(k,0,n-1) rep(i,k+1,n)
        y[i] = (y[i] - y[k]) / (x[i] - x[k]);
    double last = 0; temp[0] = 1;
    rep(k,0,n) rep(i,0,n) {
        res[i] += y[k] * temp[i];
        swap(last, temp[i]);
        temp[i] -= last * x[k];
    }
    return res;
}
```

BerlekampMassey.h

Description: Recovers any n -order linear recurrence relation from the first $2n$ terms of the recurrence. Useful for guessing linear recurrences after brute-forcing the first terms. Should work on any field, but numerical stability for floats is not guaranteed. Output will have size $\leq n$.
Usage: berlekampMassey({0, 1, 1, 3, 5, 11}) // {1, 2}
Time: $\mathcal{O}(N^2)$

```
vector<ll> berlekampMassey(vector<ll> s) {
    int n = sz(s), L = 0, m = 0;
    vector<ll> C(n), B(n), T;
    C[0] = B[0] = 1;

    ll b = 1;
    rep(i,0,n) { ++m;
        ll d = s[i] % mod;
        rep(j,1,L+1) d = (d + C[j] * s[i - j]) % mod;
        if (!d) continue;
        T = C; ll coef = d * modpow(b, mod-2) % mod;
        rep(j,m,n) C[j] = (C[j] - coef * B[j - m]) % mod;
        if (2 * L > i) continue;
        L = i + 1 - L; B = T; b = d; m = 0;
    }

    C.resize(L + 1); C.erase(C.begin());
    for (ll& x : C) x = (mod - x) % mod;
    return C;
}
```

LinearRecurrence.h

Description: Generates the k 'th term of an n -order linear recurrence $S[i] = \sum_j S[i - j - 1]tr[j]$, given $S[0 \dots \geq n - 1]$ and $tr[0 \dots n - 1]$. Faster than matrix multiplication. Useful together with Berlekamp-Massey.

```
Usage: linearRec({0, 1}, {1, 1}, k) // k'th Fibonacci number
Time:  $\mathcal{O}(n^2 \log k)$ 
d41d8c, 26 lines

typedef vector<ll> Poly;
ll linearRec(Poly S, Poly tr, ll k) {
    int n = sz(tr);

    auto combine = [&](Poly a, Poly b) {
        Poly res(n * 2 + 1);
        rep(i,0,n+1) rep(j,0,n+1)
            res[i + j] = (res[i + j] + a[i] * b[j]) % mod;
        for (int i = 2 * n; i > n; --i) rep(j,0,n)
            res[i - 1 - j] = (res[i - 1 - j] + res[i] * tr[j]) % mod;
        res.resize(n + 1);
        return res;
    };

    Poly pol(n + 1), e(pol);
    pol[0] = e[1] = 1;

    for (++k; k; k /= 2) {
        if (k % 2) pol = combine(pol, e);
        e = combine(e, e);
    }

    ll res = 0;
    rep(i,0,n) res = (res + pol[i + 1] * S[i]) % mod;
    return res;
}
```

4.2 Optimization

GoldenSectionSearch.h

Description: Finds the argument minimizing the function f in the interval $[a, b]$ assuming f is unimodal on the interval, i.e. has only one local minimum and no local maximum. The maximum error in the result is eps . Works equally well for maximization with a small change in the code. See Ternary-Search.h in the Various chapter for a discrete version.
Usage: double func(double x) { return 4+x+.3*x*x; }
double xmin = gss(-1000,1000,func);
Time: $\mathcal{O}(\log((b-a)/\epsilon))$

```
double gss(double a, double b, double (*f)(double)) {
    double r = (sqrt(5)-1)/2, eps = 1e-7;
    double x1 = b - r*(b-a), x2 = a + r*(b-a);
    double f1 = f(x1), f2 = f(x2);
    while (b-a > eps)
        if (f1 < f2) { //change to > to find maximum
            b = x2; x2 = x1; f2 = f1;
            x1 = b - r*(b-a); f1 = f(x1);
        } else {
            a = x1; x1 = x2; f1 = f2;
            x2 = a + r*(b-a); f2 = f(x2);
        }
    return a;
}
```

HillClimbing.h

Description: Poor man's optimization for unimodal functions.
Time: $\mathcal{O}(n^2)$
d41d8c, 14 lines

```
typedef array<double, 2> P;

template<class F> pair<double, P> hillClimb(P start, F f) {
    pair<double, P> cur(f(start), start);
    for (double jmp = 1e9; jmp > 1e-20; jmp /= 2) {
        rep(j,0,100) rep(dx,-1,2) rep(dy,-1,2) {
            P p = cur.second;
            p[0] += dx*jmp;
            p[1] += dy*jmp;
            cur = min(cur, make_pair(f(p), p));
        }
    }
}
```

```
}
}
return cur;
}

Integrate.h
Description: Simple integration of a function over an interval using Simpson's rule. The error should be proportional to  $h^4$ , although in practice you will want to verify that the result is stable to desired precision when epsilon changes.
d41d8c, 7 lines

template<class F>
double quad(double a, double b, F f, const int n = 1000) {
    double h = (b - a) / 2 / n, v = f(a) + f(b);
    rep(i,1,n*2)
        v += f(a + i*h) * (i&1 ? 4 : 2);
    return v * h / 3;
}

IntegrateAdaptive.h
Description: Fast integration using an adaptive Simpson's rule.
Usage: double sphereVolume = quad(-1, 1, [](double x) {
return quad(-1, 1, [&](double y) {
return quad(-1, 1, [&](double z) {
return x*x + y*y + z*z < 1; });});});
d41d8c, 15 lines

typedef double d;
#define S(a,b) (f(a) + 4*f((a+b) / 2) + f(b)) * (b-a) / 6

template <class F>
d rec(F& f, d a, d b, d eps, d S) {
    d c = (a + b) / 2;
    d S1 = S(a, c), S2 = S(c, b), T = S1 + S2;
    if (abs(T - S) <= 15 * eps || b - a < 1e-10)
        return T + (T - S) / 15;
    return rec(f, a, c, eps / 2, S1) + rec(f, c, b, eps / 2, S2);
}

template<class F>
d quad(d a, d b, F f, d eps = 1e-8) {
    return rec(f, a, b, eps, S(a, b));
}

Simplex.h
Description: Solves a general linear maximization problem: maximize  $c^T x$  subject to  $Ax \leq b, x \geq 0$ . Returns -inf if there is no solution, inf if there are arbitrarily good solutions, or the maximum value of  $c^T x$  otherwise. The input vector is set to an optimal  $x$  (or in the unbounded case, an arbitrary solution fulfilling the constraints). Numerical stability is not guaranteed. For better performance, define variables such that  $x = 0$  is viable.
Usage: vvd A = {{1,-1}, {-1,1}, {-1,-2}};
vd b = {1,1,-4}, c = {-1,-1}, x;
T val = LPSolver(A, b, c).solve(x);
Time:  $\mathcal{O}(NM * \text{\#pivots})$ , where a pivot may be e.g. an edge relaxation.  $\mathcal{O}(2^n)$  in the general case.
d41d8c, 68 lines

typedef double T; // long double, Rational, double + modP>...
typedef vector<T> vd;
typedef vector<vd> vvd;

const T eps = 1e-8, inf = 1/.0;
#define MP make_pair
#define ltj(X) if(s == -1 || MP(X[j],N[j]) < MP(X[s],N[s])) s=j

struct LPSolver {
    int m, n;
    vi N, B;
    vvd D;

    LPSolver(const vvd& A, const vd& b, const vd& c) :
```

```
m(sz(b)), n(sz(c)), N(n+1), B(m), D(m+2, vd(n+2)) {
    rep(i,0,m) rep(j,0,n) D[i][j] = A[i][j];
    rep(i,0,m) { B[i] = n+i; D[i][n] = -1; D[i][n+1] = b[i]; }
    rep(j,0,n) { N[j] = j; D[m][j] = -c[j]; }
    N[n] = -1; D[m+1][n] = 1;
}

void pivot(int r, int s) {
    T *a = D[r].data(), inv = 1 / a[s];
    rep(i,0,m+2) if (i != r && abs(D[i][s]) > eps) {
        T *b = D[i].data(), inv2 = b[s] * inv;
        rep(j,0,n+2) b[j] -= a[j] * inv2;
        b[s] = a[s] * inv2;
    }
    rep(j,0,n+2) if (j != s) D[r][j] *= inv;
    rep(i,0,m+2) if (i != r) D[i][s] *= -inv;
    D[r][s] = inv;
    swap(B[r], N[s]);
}

bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
        int s = -1;
        rep(j,0,n+1) if (N[j] != -phase) ltj(D[x]);
        if (D[x][s] >= -eps) return true;
        int r = -1;
        rep(i,0,m) {
            if (D[i][s] <= eps) continue;
            if (r == -1 || MP(D[i][n+1] / D[i][s], B[i])
                < MP(D[r][n+1] / D[r][s], B[r])) r = i;
        }
        if (r == -1) return false;
        pivot(r, s);
    }
}

T solve(vd &x) {
    int r = 0;
    rep(i,1,m) if (D[i][n+1] < D[r][n+1]) r = i;
    if (D[r][n+1] < -eps) {
        pivot(r, n);
        if (!simplex(2) || D[m+1][n+1] < -eps) return -inf;
        rep(i,0,m) if (B[i] == -1) {
            int s = 0;
            rep(j,1,n+1) ltj(D[i]);
            pivot(i, s);
        }
    }
    bool ok = simplex(1); x = vd(n);
    rep(i,0,m) if (B[i] < n) x[B[i]] = D[i][n+1];
    return ok ? D[m][n+1] : inf;
}
};
```

Determinant.h
Description: Calculates determinant of a matrix. Destroys the matrix.
Time: $\mathcal{O}(N^3)$

double det(vector<vector<**double**>>& a) {
 int n = sz(a); **double** res = 1;
 rep(i,0,n) {
 int b = i;
 rep(j,i+1,n) **if** (fabs(a[j][i]) > fabs(a[b][i])) b = j;
 if (i != b) swap(a[i], a[b]), res *= -1;
 res *= a[i][i];
 if (res == 0) **return** 0;
 rep(j,i+1,n) {

```
        double v = a[j][i] / a[i][i];  
        if (v != 0) rep(k,i+1,n) a[j][k] -= v * a[i][k];  
    }  
    return res;  
}
```

IntDeterminant.h
Description: Calculates determinant using modular arithmetics. Modulos can also be removed to get a pure-integer version.
Time: $\mathcal{O}(N^3)$

const ll mod = 12345;
ll det(vector<vector<ll>>& a) {
 int n = sz(a); ll ans = 1;
 rep(i,0,n) {
 rep(j,i+1,n) {
 while (a[j][i] != 0) { *// gcd step*
 ll t = a[i][i] / a[j][i];
 if (t) rep(k,i,n)
 a[i][k] = (a[i][k] - a[j][k] * t) % mod;
 swap(a[i], a[j]);
 ans *= -1;
 }
 }
 ans = ans * a[i][i] % mod;
 if (!ans) **return** 0;
 }
 return (ans + mod) % mod;
}

SolveLinear.h
Description: Solves $A * x = b$. If there are multiple solutions, an arbitrary one is returned. Returns rank, or -1 if no solutions. Data in A and b is lost.
Time: $\mathcal{O}(n^2m)$

typedef vector<**double**> vd;
const double eps = 1e-12;

int solveLinear(vector<vd>& A, vd& b, vd& x) {
 int n = sz(A), m = sz(x), rank = 0, br, bc;
 if (n) assert(sz(A[0]) == m);
 vi col(m); iota(all(col), 0);

rep(i,0,n) {
 double v, bv = 0;
 rep(r,i,n) rep(c,i,m)
 if ((v = fabs(A[r][c])) > bv)
 br = r, bc = c, bv = v;
 if (bv <= eps) {
 rep(j,i,n) **if** (fabs(b[j]) > eps) **return** -1;
 break;
 }
 swap(A[i], A[br]);
 swap(b[i], b[br]);
 swap(col[i], col[bc]);
 rep(j,0,n) swap(A[j][i], A[j][bc]);
 bv = 1/A[i][i];
 rep(j,i+1,n) {
 double fac = A[j][i] * bv;
 b[j] -= fac * b[i];
 rep(k,i+1,m) A[j][k] -= fac*A[i][k];
 }
 rank++;
 }

x.assign(m, 0);
 for (**int** i = rank; i--;) {
 b[i] /= A[i][i];

```
        x[col[i]] = b[i];  
        rep(j,0,i) b[j] -= A[j][i] * b[i];  
    }  
    return rank; // (multiple solutions if rank < m)  
}
```

SolveLinear2.h
Description: To get all uniquely determined values of x back from SolveLinear, make the following changes:

"SolveLinear.h" d41d8c, 7 lines

rep(j,0,n) **if** (j != i) *// instead of rep(j,i+1,n)*
// ... then at the end:
x.assign(m, undefined);
rep(i,0,rank) {
 rep(j,rank,m) **if** (fabs(A[i][j]) > eps) **goto** fail;
 x[col[i]] = b[i] / A[i][i];
fail;; }

SolveLinearBinary.h
Description: Solves $Ax = b$ over \mathbb{F}_2 . If there are multiple solutions, one is returned arbitrarily. Returns rank, or -1 if no solutions. Destroys A and b .
Time: $\mathcal{O}(n^2m)$

typedef bitset<1000> bs;

int solveLinear(vector<bs>& A, vi& b, bs& x, **int** m) {
 int n = sz(A), rank = 0, br;
 assert(m <= sz(x));
 vi col(m); iota(all(col), 0);
 rep(i,0,n) {
 for (br=i; br<n; ++br) **if** (A[br].any()) **break**;
 if (br == n) {
 rep(j,i,n) **if** (b[j]) **return** -1;
 break;
 }
 int bc = (**int**)A[br]._Find_next(i-1);
 swap(A[i], A[br]);
 swap(b[i], b[br]);
 swap(col[i], col[bc]);
 rep(j,0,n) **if** (A[j][i] != A[j][bc]) {
 A[j].flip(i); A[j].flip(bc);
 }
 rep(j,i+1,n) **if** (A[j][i]) {
 b[j] ^= b[i];
 A[j] ^= A[i];
 }
 rank++;
 }

x = bs();
 for (**int** i = rank; i--;) {
 if (!b[i]) **continue**;
 x[col[i]] = 1;
 rep(j,0,i) b[j] ^= A[j][i];
 }
 return rank; *// (multiple solutions if rank < m)*
}

MatrixInverse.h
Description: Invert matrix A . Returns rank; result is stored in A unless singular (rank < n). Can easily be extended to prime moduli; for prime powers, repeatedly set $A^{-1} = A^{-1}(2I - AA^{-1}) \pmod{p^k}$ where A^{-1} starts as the inverse of $A \pmod p$, and k is doubled in each step.
Time: $\mathcal{O}(n^3)$

int matInv(vector<vector<**double**>>& A) {
 int n = sz(A); vi col(n);
 vector<vector<**double**>> tmp(n, vector<**double**>(n));
 rep(i,0,n) tmp[i][i] = 1, col[i] = i;

```
rep(i,0,n) {
    int r = i, c = i;
    rep(j,i,n) rep(k,i,n)
        if (fabs(A[j][k]) > fabs(A[r][c]))
            r = j, c = k;
    if (fabs(A[r][c]) < 1e-12) return i;
    A[i].swap(A[r]); tmp[i].swap(tmp[r]);
    rep(j,0,n)
        swap(A[j][i], A[j][c]), swap(tmp[j][i], tmp[j][c]);
    swap(col[i], col[c]);
    double v = A[i][i];
    rep(j,i+1,n) {
        double f = A[j][i] / v;
        A[j][i] = 0;
        rep(k,i+1,n) A[j][k] -= f*A[i][k];
        rep(k,0,n) tmp[j][k] -= f*tmp[i][k];
    }
    rep(j,i+1,n) A[i][j] /= v;
    rep(j,0,n) tmp[i][j] /= v;
    A[i][i] = 1;
}

for (int i = n-1; i > 0; --i) rep(j,0,i) {
    double v = A[j][i];
    rep(k,0,n) tmp[j][k] -= v*tmp[i][k];
}

rep(i,0,n) rep(j,0,n) A[col[i]][col[j]] = tmp[i][j];
return n;
}
```

Tridiagonal.h
Description: $x = \text{tridiagonal}(d, p, q, b)$ solves the equation system

$$\begin{pmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_{n-1} \end{pmatrix} = \begin{pmatrix} d_0 & p_0 & 0 & 0 & \cdots & 0 \\ q_0 & d_1 & p_1 & 0 & \cdots & 0 \\ 0 & q_1 & d_2 & p_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & q_{n-3} & d_{n-2} & p_{n-2} \\ 0 & 0 & \cdots & 0 & q_{n-2} & d_{n-1} \end{pmatrix} \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_{n-1} \end{pmatrix}.$$

This is useful for solving problems on the type

$$a_i = b_i a_{i-1} + c_i a_{i+1} + d_i, 1 \leq i \leq n,$$

where a_0, a_{n+1}, b_i, c_i and d_i are known. a can then be obtained from

$$\{a_i\} = \text{tridiagonal}(\{1, -1, -1, \dots, -1, 1\}, \{0, c_1, c_2, \dots, c_n\}, \{b_1, b_2, \dots, b_n, 0\}, \{a_0, d_1, d_2, \dots, d_n, a_{n+1}\}).$$

Fails if the solution is not unique.
If $|d_i| > |p_i| + |q_{i-1}|$ for all i , or $|d_i| > |p_{i-1}| + |q_i|$, or the matrix is positive definite, the algorithm is numerically stable and neither `tr` nor the check for `diag[i] == 0` is needed.
Time: $\mathcal{O}(N)$

```
#define d41d8c, 26 lines
typedef double T;
vector<T> tridiagonal(vector<T> diag, const vector<T>& super,
    const vector<T>& sub, vector<T> b) {
    int n = sz(b); vi tr(n);
    rep(i,0,n-1) {
        if (abs(diag[i]) < 1e-9 * abs(super[i])) { // diag[i] == 0
            b[i+1] -= b[i] * diag[i+1] / super[i];
            if (i+2 < n) b[i+2] -= b[i] * sub[i+1] / super[i];
            diag[i+1] = sub[i]; tr[i+1] = 1;
        } else {
            diag[i+1] -= super[i]*sub[i]/diag[i];
            b[i+1] -= b[i]*sub[i]/diag[i];
        }
    }
}
```

```
for (int i = n; i--;) {
    if (tr[i]) {
        swap(b[i], b[i-1]);
        diag[i-1] = diag[i];
        b[i] /= super[i-1];
    } else {
        b[i] /= diag[i];
        if (i) b[i-1] -= b[i]*super[i-1];
    }
}
return b;
}
```

4.4 Fourier transforms

FastFourierTransform.h
Description: `fft(a)` computes $\hat{f}(k) = \sum_x a[x] \exp(2\pi i \cdot kx/N)$ for all k . N must be a power of 2. Useful for convolution: `conv(a, b) = c`, where $c[x] = \sum a[i]b[x-i]$. For convolution of complex numbers or more than two vectors: FFT, multiply pointwise, divide by n , reverse(start+1, end), FFT back. Rounding is safe if $(\sum a_i^2 + \sum b_i^2) \log_2 N < 9 \cdot 10^{14}$ (in practice 10^{16} ; higher for random inputs). Otherwise, use NTT/FFTMod.
Time: $\mathcal{O}(N \log N)$ with $N = |A| + |B|$ ($\sim 1s$ for $N = 2^{22}$)

```
#define d41d8c, 35 lines
typedef complex<double> C;
typedef vector<double> vd;
void fft(vector<C>& a) {
    int n = sz(a), L = 31 - __builtin_clz(n);
    static vector<complex<long double>> R(2, 1);
    static vector<C> rt(2, 1); // (^ 10% faster if double)
    for (static int k = 2; k < n; k *= 2) {
        R.resize(n); rt.resize(n);
        auto x = polar(1.0L, acos(-1.0L) / k);
        rep(i,k,2*k) rt[i] = R[i] = i&1 ? R[i/2] * x : R[i/2];
    }
    vi rev(n);
    rep(i,0,n) rev[i] = (rev[i / 2] | (i & 1) << L) / 2;
    rep(i,0,n) if (i < rev[i]) swap(a[i], a[rev[i]]);
    for (int k = 1; k < n; k *= 2)
        for (int i = 0; i < n; i += 2 * k) rep(j,0,k) {
            C z = rt[j+k] * a[i+j+k]; // (25% faster if hand-rolled)
            a[i + j + k] = a[i + j] - z;
            a[i + j] += z;
        }
}
vd conv(const vd& a, const vd& b) {
    if (a.empty() || b.empty()) return {};
    vd res(sz(a) + sz(b) - 1);
    int L = 32 - __builtin_clz(sz(res)), n = 1 << L;
    vector<C> in(n), out(n);
    copy(all(a), begin(in));
    rep(i,0,sz(b)) in[i].imag(b[i]);
    fft(in);
    for (C& x : in) x *= x;
    rep(i,0,n) out[i] = in[-i & (n - 1)] - conj(in[i]);
    fft(out);
    rep(i,0,sz(res)) res[i] = imag(out[i]) / (4 * n);
    return res;
}
```

FastFourierTransformMod.h
Description: Higher precision FFT, can be used for convolutions modulo arbitrary integers as long as $N \log_2 N \cdot \text{mod} < 8.6 \cdot 10^{14}$ (in practice 10^{16} or higher). Inputs must be in $[0, \text{mod})$.
Time: $\mathcal{O}(N \log N)$, where $N = |A| + |B|$ (twice as slow as NTT or FFT)
"FastFourierTransform.h" d41d8c, 22 lines

```
typedef vector<ll> vl;
template<int M> vl convMod(const vl &a, const vl &b) {
    if (a.empty() || b.empty()) return {};
```

```
vl res(sz(a) + sz(b) - 1);
int B=32-__builtin_clz(sz(res)), n=1<<B, cut=int(sqrt(M));
vector<C> L(n), R(n), outs(n), outl(n);
rep(i,0,sz(a)) L[i] = C((int)a[i] / cut, (int)a[i] % cut);
rep(i,0,sz(b)) R[i] = C((int)b[i] / cut, (int)b[i] % cut);
fft(L), fft(R);
rep(i,0,n) {
    int j = -i & (n - 1);
    outl[j] = (L[i] + conj(L[j])) * R[i] / (2.0 * n);
    outs[j] = (L[i] - conj(L[j])) * R[i] / (2.0 * n) / 1i;
}
fft(outl), fft(outs);
rep(i,0,sz(res)) {
    ll av = ll(real(outl[i])+.5), cv = ll(imag(outs[i])+.5);
    ll bv = ll(imag(outl[i])+.5) + ll(real(outs[i])+.5);
    res[i] = ((av % M * cut + bv) % M * cut + cv) % M;
}
return res;
}
```

NumberTheoreticTransform.h
Description: `ntt(a)` computes $\hat{f}(k) = \sum_x a[x]g^{xk}$ for all k , where $g = \text{root}^{(\text{mod}-1)/N}$. N must be a power of 2. Useful for convolution modulo specific nice primes of the form $2^a b + 1$, where the convolution result has size at most 2^a . For arbitrary modulo, see FFTMod. `conv(a, b) = c`, where $c[x] = \sum a[i]b[x-i]$. For manual convolution: NTT the inputs, multiply pointwise, divide by n , reverse(start+1, end), NTT back. Inputs must be in $[0, \text{mod})$.
Time: $\mathcal{O}(N \log N)$
"../number-theory/ModPow.h" d41d8c, 33 lines

```
const ll mod = (119 << 23) + 1, root = 62; // = 998244353
// For p < 2^30 there is also e.g. 5 << 25, 7 << 26, 479 << 21
// and 483 << 21 (same root). The last two are > 10^9.
typedef vector<ll> vl;
void ntt(vl &a) {
    int n = sz(a), L = 31 - __builtin_clz(n);
    static vl rt(2, 1);
    for (static int k = 2, s = 2; k < n; k *= 2, s++) {
        rt.resize(n);
        ll z[] = {1, modpow(root, mod >> s)};
        rep(i,k,2*k) rt[i] = rt[i / 2] * z[i & 1] % mod;
    }
    vi rev(n);
    rep(i,0,n) rev[i] = (rev[i / 2] | (i & 1) << L) / 2;
    rep(i,0,n) if (i < rev[i]) swap(a[i], a[rev[i]]);
    for (int k = 1; k < n; k *= 2)
        for (int i = 0; i < n; i += 2 * k) rep(j,0,k) {
            ll z = rt[j + k] * a[i + j + k] % mod, &ai = a[i + j];
            a[i + j + k] = ai - z + (z > ai ? mod : 0);
            ai += (ai + z >= mod ? z - mod : z);
        }
}
vl conv(const vl &a, const vl &b) {
    if (a.empty() || b.empty()) return {};
    int s = sz(a) + sz(b) - 1, B = 32 - __builtin_clz(s), n = 1 << B;
    int inv = modpow(n, mod - 2);
    vl L(a), R(b), out(n);
    L.resize(n), R.resize(n);
    ntt(L), ntt(R);
    rep(i,0,n) out[-i & (n - 1)] = (ll)L[i] * R[i] % mod * inv % mod;
    ntt(out);
    return {out.begin(), out.begin() + s};
}
```


FastSubsetTransform.h

Description: Transform to a basis with fast convolutions of the form $c[z] = \sum_{z=x\oplus y} a[x] \cdot b[y]$, where \oplus is one of AND, OR, XOR. The size of a must be a power of two.

Time: $\mathcal{O}(N \log N)$

```
void FST(vi& a, bool inv) {
    for (int n = sz(a), step = 1; step < n; step *= 2) {
        for (int i = 0; i < n; i += 2 * step) rep(j,i,i+step) {
            int &u = a[j], &v = a[j + step]; tie(u, v) =
                inv ? pii(v - u, u) : pii(v, u + v); // AND
            inv ? pii(v, u - v) : pii(u + v, u); // OR
            pii(u + v, u - v); // XOR
        }
    }
    if (inv) for (int& x : a) x /= sz(a); // XOR only
}

vi conv(vi a, vi b) {
    FST(a, 0); FST(b, 0);
    rep(i,0,sz(a)) a[i] *= b[i];
    FST(a, 1); return a;
}
```

Number theory (5)

5.1 Modular arithmetic

ModularArithmetic.h

Description: Operators for modular arithmetic. You need to set mod to some number first and then you can use the structure.

```
const ll mod = 998244353;
struct mint {
    ll x;
    mint() : x(0) {}
    mint(ll xx) : x(xx) {}
    mint operator+(mint b) { return mint((x + b.x) % mod); }
    mint operator-(mint b) { return mint((x - b.x + mod) % mod); }
    }
    mint operator*(mint b) { return mint((x * b.x) % mod); }
    mint operator/(mint b) { return *this * invert(b); }
    // mint operator+=(mint b) { return *this = *this + b; } //
    // can be ignored if not necessary
    // mint operator-=(mint b) { return *this = *this - b; }
    // mint operator*=(mint b) { return *this = *this * b; }
    // mint operator/=(mint b) { return *this = *this / b; }
    mint invert(mint a) { // euclid for non prime mod
        return a ^ (mod - 2);
    }
    mint operator^(ll e) {
        if (!e) return mint(1);
        mint r = *this ^ (e / 2); r = r * r;
        return e&1 ? *this * r : r;
    }
};
```

ModInverseAndExtendedGCD.h

Description: inverse of x mod Mod iff $\gcd(Mod, x) = 1$

```
ll gcd(ll x, ll y){
    return (!y ? x : gcd(y, x % y));
}
// Extended euclidean algorithm - Bezout's identity
tuple<ll, ll, ll> extended_gcd(ll a, ll b){
    if(b == 0) return {a, 1, 0};
    auto [gcd, x1, y1] = extended_gcd(b, a % b);
    return {gcd, y1, x1 - (a / b) * y1};
}
```

```
ll inv(ll x, ll Mod){ // return 0 if doesn't exist
    auto [g, ix, _] = extended_gcd(x, Mod);
    if (g != 1) return 0;
    return (ix % Mod + Mod) % Mod;
}

void init(){ //inverse of x mod Mod
    ll p = 2, m = Mod; phi = m;
    while(p * p <= m){
        if(m % p == 0){
            while(m % p == 0) m /= p;
            phi -= phi / p;
        }
        p ++;
    }
    if(m > 1) phi -= phi / m;
    ll x = 10, inv_x = power(x, phi - 1);
}
```

ModLog.h

Description: Returns the smallest $x > 0$ s.t. $a^x = b \pmod m$, or -1 if no such x exists. modLog(a,1,m) can be used to calculate the order of a .

Time: $\mathcal{O}(\sqrt{m})$

```
ll modLog(ll a, ll b, ll m) {
    ll n = (ll) sqrt(m) + 1, e = 1, f = 1, j = 1;
    unordered_map<ll, ll> A;
    while (j <= n && (e = f = e * a % m) != b % m)
        A[e * b % m] = j++;
    if (e == b % m) return j;
    if (__gcd(m, e) == __gcd(m, b))
        rep(i,2,n+2) if (A.count(e = e * f % m))
            return n * i - A[e];
    return -1;
}
```

ModSum.h

Description: Sums of mod'ed arithmetic progressions.

modsum(to, c, k, m) = $\sum_{i=0}^{to-1} (ki + c) \% m$. divsum is similar but for floored division.

Time: $\log(m)$, with a large constant.

```
#define ull unsigned long long
ull sumsq(ull to) { return to / 2 * ((to-1) | 1); }

ull divsum(ull to, ull c, ull k, ull m) {
    ull res = k / m * sumsq(to) + c / m * to;
    k %= m; c %= m;
    if (!k) return res;
    ull to2 = (to * k + c) / m;
    return res + (to - 1) * to2 - divsum(to2, m-1 - c, m, k);
}

ll modsum(ull to, ll c, ll k, ll m) {
    c = ((c % m) + m) % m;
    k = ((k % m) + m) % m;
    return to * c + k * sumsq(to) - m * divsum(to, c, k, m);
}
```

ModMulLL.h

Description: Calculate $a \cdot b \pmod c$ (or $a^b \pmod c$) for $0 \leq a, b \leq c \leq 7.2 \cdot 10^{18}$.

Time: $\mathcal{O}(1)$ for modmul, $\mathcal{O}(\log b)$ for modpow

```
#define ull unsigned long long
ull modmul(ull a, ull b, ull M) {
    ll ret = a * b - M * ull(1.L / M * a * b);
    return ret + M * (ret < 0) - M * (ret >= (ll)M);
}

ull modpow(ull b, ull e, ull mod) {
    ull ans = 1;
```

```
for (; e; b = modmul(b, b, mod), e /= 2)
    if (e & 1) ans = modmul(ans, b, mod);
return ans;
}
```

ModSqrt.h

Description: Tonelli-Shanks algorithm for modular square roots. Finds x s.t. $x^2 = a \pmod p$ ($-x$ gives the other solution).

Time: $\mathcal{O}(\log^2 p)$ worst case, $\mathcal{O}(\log p)$ for most p

```
"ModPow.h"
d41d8c, 24 lines

ll sqrt(ll a, ll p) {
    a %= p; if (a < 0) a += p;
    if (a == 0) return 0;
    assert(modpow(a, (p-1)/2, p) == 1); // else no solution
    if (p % 4 == 3) return modpow(a, (p+1)/4, p);
    // a^(n+3)/8 or 2^(n+3)/8 * 2^(n-1)/4 works if p % 8 == 5
    ll s = p - 1, n = 2;
    int r = 0, m;
    while (s % 2 == 0)
        ++r, s /= 2;
    while (modpow(n, (p - 1) / 2, p) != p - 1) ++n;
    ll x = modpow(a, (s + 1) / 2, p);
    ll b = modpow(a, s, p), g = modpow(n, s, p);
    for (; r = m) {
        ll t = b;
        for (m = 0; m < r && t != 1; ++m)
            t = t * t % p;
        if (m == 0) return x;
        ll gs = modpow(g, 1LL << (r - m - 1), p);
        g = gs * gs % p;
        x = x * gs % p;
        b = b * g % p;
    }
}
```

5.2 Primality

FastEratosthenes.h

Description: Prime sieve for generating all primes up to a certain limit.

```
ll pt; vector<ll> lpf, Prm, prm;
inline void Sieve(ll m){ //maximum value in inputs
    lpf.assign(m + 1, 0);
    for(int i = 2; i <= m; i ++){
        if(!lpf[i]) Prm.push_back(lpf[i] = i);
        for(int p : Prm){
            if(p > lpf[i] || p * i > m) break;
            lpf[p * i] = p;
        }
    }
    pt = Prm.size();
}

inline void factorize(ll num){
    prm.clear();
    for(int x = num, p = lpf[x]; x > 1; prm.push_back(p), p =
        lpf[x]){
        while(x % p == 0) x /= p;
    }
}

inline void GetPresentPrimes(){
    Prm.clear();
    for(int i = 1; i <= n; i ++){
        factorize(A[i]);
        for(auto X : prm) Prm.push_back(X);
    }
    sort(Prm.begin(), Prm.end());
    Prm.resize(pt = (unique(Prm.begin(), Prm.end()) - Prm.begin()
        ()));
}
```

```
inline int GetPrmId(ll x){
    return lower_bound(Prm.begin(), Prm.end(), x) - Prm.begin()
        + 1;
}
```

MillerRabin.h

Description: Deterministic Miller-Rabin primality test. Guaranteed to work for numbers up to $7 \cdot 10^{18}$; for larger numbers, use Python and extend A randomly.

Time: 7 times the complexity of $a^b \bmod c$.

"ModMulLL.h"	d41d8c, 12 lines
--------------	------------------

```
bool isPrime(ull n) {
    if (n < 2 || n % 6 % 4 != 1) return (n | 1) == 3;
    ull A[] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022},
        s = __builtin_ctzll(n-1), d = n >> s;
    for (ull a : A) { // ^ count trailing zeroes
        ull p = modpow(a%n, d, n), i = s;
        while (p != 1 && p != n-1 && a % n && i--)
            p = modmul(p, p, n);
        if (p != n-1 && i != s) return 0;
    }
    return 1;
}
```

Factor.h

Description: Pollard-rho randomized factorization algorithm. Returns prime factors of a number, in arbitrary order (e.g. 2299 -> {11, 19, 11}).

Time: $\mathcal{O}\left(n^{1/4}\right)$, less for numbers with small factors.

"ModMulLL.h", "MillerRabin.h"	d41d8c, 18 lines
-------------------------------	------------------

```
ull pollard(ull n) {
    auto f = [n](ull x) { return modmul(x, x, n) + 1; };
    ull x = 0, y = 0, t = 30, prd = 2, i = 1, q;
    while (t++ % 40 || __gcd(prd, n) == 1) {
        if (x == y) x = ++i, y = f(x);
        if ((q = modmul(prd, max(x,y) - min(x,y), n))) prd = q;
        x = f(x), y = f(f(y));
    }
    return __gcd(prd, n);
}

vector<ull> factor(ull n) {
    if (n == 1) return {};
    if (isPrime(n)) return {n};
    ull x = pollard(n);
    auto l = factor(x), r = factor(n / x);
    l.insert(l.end(), all(r));
    return l;
}
```

5.3 Divisibility

euclid.h

Description: Finds two integers x and y , such that $ax + by = \gcd(a, b)$. If you just need gcd, use the built in `__gcd` instead. If a and b are coprime, then x is the inverse of $a \pmod b$.

	d41d8c, 5 lines
--	-----------------

```
ll euclid(ll a, ll b, ll &x, ll &y) {
    if (!b) return x = 1, y = 0, a;
    ll d = euclid(b, a % b, y, x);
    return y -= a/b * x, d;
}
```

CRT.h

Description: Chinese Remainder Theorem.

`crt(a, m, b, n)` computes x such that $x \equiv a \pmod m, x \equiv b \pmod n$. If $|a| < m$ and $|b| < n$, x will obey $0 \leq x < \text{lcm}(m, n)$. Assumes $mn < 2^{62}$.

"euclid.h"	d41d8c, 7 lines
------------	-----------------

```
ll crt(ll a, ll m, ll b, ll n){
```

```
    if (n > m) swap(a, b), swap(m, n);
    ll x, y, g = euclid(m, n, x, y);
    assert((a - b) % g == 0); // else no solution
    x = (b - a) % n * x % n / g * m + a;
    return x < 0 ? x + m*n/g : x;
}
```

5.3.1 Bézout’s identity

For $a \neq, b \neq 0$, then $d = \gcd(a, b)$ is the smallest positive integer for which there are integer solutions to

$$ax + by = d$$

If (x, y) is one solution, then all solutions are given by

$$\left(x + \frac{kb}{\gcd(a,b)}, y - \frac{ka}{\gcd(a,b)}\right), \quad k \in \mathbb{Z}$$

phiFunction.h

Description: Euler’s ϕ function is defined as $\phi(n) := \#$ of positive integers $\leq n$ that are coprime with n . $\phi(1) = 1, p \text{ prime} \Rightarrow \phi(p^k) = (p-1)p^{k-1}$, $m, n \text{ coprime} \Rightarrow \phi(mn) = \phi(m)\phi(n)$. If $n = p_1^{k_1}p_2^{k_2}...p_r^{k_r}$ then $\phi(n) = (p_1-1)p_1^{k_1-1}...(p_r-1)p_r^{k_r-1}$. $\phi(n) = n \cdot \prod_{p|n} (1-1/p)$. $\sum_{d|n} \phi(d) = n, \sum_{1 \leq k \leq n, \gcd(k,n)=1} k = n\phi(n)/2, n > 1$

Euler’s thm: $a, n \text{ coprime} \Rightarrow a^{\phi(n)} \equiv 1 \pmod n$.

Fermat’s little thm: $p \text{ prime} \Rightarrow a^{p-1} \equiv 1 \pmod p \quad \forall a$.

	d41d8c, 8 lines
--	-----------------

```
const int LIM = 5000000;
int phi[LIM];

void calculatePhi() {
    rep(i, 0, LIM) phi[i] = i&1 ? i : i/2;
    for (int i = 3; i < LIM; i += 2) if(phi[i] == i)
        for (int j = i; j < LIM; j += i) phi[j] -= phi[j] / i;
}
```

5.4 Fractions

ContinuedFractions.h

Description: Given N and a real number $x \geq 0$, finds the closest rational approximation p/q with $p, q \leq N$. It will obey $|p/q - x| \leq 1/qN$.

For consecutive convergents, $p_{k+1}q_k - q_{k+1}p_k = (-1)^k$. (p_k/q_k) alternates between $> x$ and $< x$.) If x is rational, y eventually becomes ∞ ; if x is the root of a degree 2 polynomial the a ’s eventually become cyclic.

	d41d8c, 21 lines
--	------------------

```
typedef double d; // for N ~ 1e7; long double for N ~ 1e9
pair<ll, ll> approximate(d x, ll N) {
    ll LP = 0, LQ = 1, P = 1, Q = 0, inf = LLONG_MAX; d y = x;
    for (;;) {
        ll lim = min(P ? (N-LP) / P : inf, Q ? (N-LQ) / Q : inf),
            a = (ll)floor(y), b = min(a, lim),
            NP = b*P + LP, NQ = b*Q + LQ;
        if (a > b) {
            // If b > a/2, we have a semi-convergent that gives us a
            // better approximation; if b = a/2, we *may* have one.
            // Return {P, Q} here for a more canonical approximation.
            return (abs(x - (d)NP / (d)NQ) < abs(x - (d)P / (d)Q)) ?
                make_pair(NP, NQ) : make_pair(P, Q);
        }
        if (abs(y = 1/(y - (d)a)) > 3*N) {
            return {NP, NQ};
        }
        LP = P; P = NP;
        LQ = Q; Q = NQ;
    }
}
```

```
    }
}
```

FracBinarySearch.h

Description: Given f and N , finds the smallest fraction $p/q \in [0, 1]$ such that $f(p/q)$ is true, and $p, q \leq N$. You may want to throw an exception from f if it finds an exact solution, in which case N can be removed.

Usage: `fracBS([](Frac f) { return f.p>=3*f.q; }, 10);` // {1,3}

Time: $\mathcal{O}(\log(N))$

	d41d8c, 25 lines
--	------------------

```
struct Frac { ll p, q; };

template<class F>
Frac fracBS(F f, ll N) {
    bool dir = 1, A = 1, B = 1;
    Frac lo{0, 1}, hi{1, 1}; // Set hi to 1/0 to search (0, N]
    if (f(lo)) return lo;
    assert (f(hi));
    while (A || B) {
        ll adv = 0, step = 1; // move hi if dir, else lo
        for (int si = 0; step; (step *= 2) >= si) {
            adv += step;
            Frac mid{lo.p * adv + hi.p, lo.q * adv + hi.q};
            if (abs(mid.p) > N || mid.q > N || dir == !f(mid)) {
                adv -= step; si = 2;
            }
        }
        hi.p += lo.p * adv;
        hi.q += lo.q * adv;
        dir = !dir;
        swap(lo, hi);
        A = B; B = !adv;
    }
    return dir ? hi : lo;
}
```

5.5 Pythagorean Triples

The Pythagorean triples are uniquely generated by

$$a = k \cdot (m^2 - n^2), \quad b = k \cdot (2mn), \quad c = k \cdot (m^2 + n^2),$$

with $m > n > 0, k > 0, m \perp n$, and either m or n even.

5.6 Primes

$p = 962592769$ is such that $2^{21} \mid p-1$, which may be useful. For hashing use 970592641 (31-bit number), 31443539979727 (45-bit), 3006703054056749 (52-bit). There are 78498 primes less than 1 000 000.

Primitive roots exist modulo any prime power p^a , except for $p = 2, a > 2$, and there are $\phi(\phi(p^a))$ many. For $p = 2, a > 2$, the group $\mathbb{Z}_{2^a}^\times$ is instead isomorphic to $\mathbb{Z}_2 \times \mathbb{Z}_{2^{a-2}}$.

5.7 Estimates

$$\sum_{d|n} d = \mathcal{O}(n \log \log n).$$

The number of divisors of n is at most around 100 for $n < 5e4$, 500 for $n < 1e7$, 2000 for $n < 1e10$, 200 000 for $n < 1e19$.

5.8 Mobius Function

$$\mu(n) = \begin{cases} 0 & n \text{ is not square free} \\ 1 & n \text{ has even number of prime factors} \\ -1 & n \text{ has odd number of prime factors} \end{cases}$$

Mobius Inversion:

$$g(n) = \sum_{d|n} f(d) \Leftrightarrow f(n) = \sum_{d|n} \mu(d)g(n/d)$$

Other useful formulas/forms:

$$\sum_{d|n} \mu(d) = [n = 1] \text{ (very useful)}$$

$$g(n) = \sum_{n|d} f(d) \Leftrightarrow f(n) = \sum_{n|d} \mu(d/n)g(d)$$

$$g(n) = \sum_{1 \leq m \leq n} f(\lfloor \frac{n}{m} \rfloor) \Leftrightarrow f(n) = \sum_{1 \leq m \leq n} \mu(m)g(\lfloor \frac{n}{m} \rfloor)$$

Combinatorial (6)

6.1 Permutations

6.1.1 Factorial

<i>n</i>	1	2	3	4	5	6	7	8	9	10
<i>n</i> !	1	2	6	24	120	720	5040	40320	362880	3628800
<i>n</i>	11	12	13	14	15	16	17			
<i>n</i> !	4.0e7	4.8e8	6.2e9	8.7e10	1.3e12	2.1e13	3.6e14			
<i>n</i>	20	25	30	40	50	100	150	171		
<i>n</i> !	2e18	2e25	3e32	8e47	3e64	9e157	6e262	>DBL_MAX		

IntPerm.h
Description: Permutation -> integer conversion. (Not order preserving.)
Integer -> permutation can use a lookup table.
Time: $\mathcal{O}(n)$

```
d41d8c, 6 lines
int permToInt(vi& v) {
    int use = 0, i = 0, r = 0;
    for(int x:v) r = r * ++i + __builtin_popcount(use & ~(1<<x)),
        use |= 1 << x; // (note: minus, not ~!)
    return r;
}
```

6.1.2 Cycles

Let $g_S(n)$ be the number of n -permutations whose cycle lengths all belong to the set S . Then

$$\sum_{n=0}^\infty g_S(n) \frac{x^n}{n!} = \exp\left(\sum_{n \in S} \frac{x^n}{n}\right)$$

6.1.3 Derangements

Permutations of a set such that none of the elements appear in their original position.

$$D(n) = (n-1)(D(n-1)+D(n-2)) = nD(n-1)+(-1)^n = \left\lfloor \frac{n!}{e} \right\rfloor$$

6.1.4 Burnside’s lemma

Given a group G of symmetries and a set X , the number of elements of X *up to symmetry* equals

$$\frac{1}{|G|} \sum_{g \in G} |X^g|,$$

where X^g are the elements fixed by g ($g \cdot x = x$).

If $f(n)$ counts “configurations” (of some sort) of length n , we can ignore rotational symmetry using $G = \mathbb{Z}_n$ to get

$$g(n) = \frac{1}{n} \sum_{k=0}^{n-1} f(\gcd(n, k)) = \frac{1}{n} \sum_{k|n} f(k) \phi(n/k).$$

6.2 Partitions and subsets

6.2.1 Partition function

Number of ways of writing n as a sum of positive integers, disregarding the order of the summands.

$$p(0) = 1, \quad p(n) = \sum_{k \in \mathbb{Z} \setminus \{0\}} (-1)^{k+1} p(n - k(3k - 1)/2)$$

$$p(n) \sim 0.145/n \cdot \exp(2.56\sqrt{n})$$

<i>n</i>	0	1	2	3	4	5	6	7	8	9	20	50	100
<i>p</i> (<i>n</i>)	1	1	2	3	5	7	11	15	22	30	627	~2e5	~2e8

6.2.2 Lucas’ Theorem

Let n, m be non-negative integers and p a prime. Write $n = n_k p^k + \dots + n_1 p + n_0$ and $m = m_k p^k + \dots + m_1 p + m_0$. Then $\binom{n}{m} \equiv \prod_{i=0}^k \binom{n_i}{m_i} \pmod{p}$.

6.2.3 Binomials

nCr.h
Description: Computes $\binom{n}{k}$.

```
d41d8c, 26 lines
ll power(ll a, ll b){
    return (!b ? 1 : power(a * a % Mod, b / 2) * (b & 1LL ? a : 1) % Mod);
}
ll inv(ll x){ return power(x, Mod - 2); }
void mkay(ll &x){
    if(x < 0) x += Mod;
    if(x >= Mod) x -= Mod;
}
ll F[MXN], I[MXN];
ll nCr(ll n, ll r){
    if(r < 0 || r > n) return 0;
    return F[n] * I[r] % Mod * I[n - r] % Mod;
}
inline void Init(){
    F[0] = I[0] = 1;
    for(int i = 1; i < MXN; i++) F[i] = F[i - 1] * i % Mod;
    I[MXN - 1] = inv(F[MXN - 1]);
    for(int i = MXN - 2; i; -- i) I[i] = I[i + 1] * (i + 1) % Mod;
}
} // Call Init(); in main
ll nCr(ll n, ll r){ //Iterative version
    if(r < 0 || r > n) return 0;
    ll ans = 1;
    for(ll i = n; i > n - r; -- i) ans = ans * i % Mod;
    for(ll i = 2; i <= r; i++) ans = ans * inv(i) % Mod;
    return ans;
}
```

6.3 General purpose numbers

6.3.1 Bernoulli numbers

EGF of Bernoulli numbers is $B(t) = \frac{t}{e^t - 1}$ (FFT-able).
 $B[0, \dots] = [1, -\frac{1}{2}, \frac{1}{6}, 0, -\frac{1}{30}, 0, \frac{1}{42}, \dots]$

Sums of powers:

$$\sum_{i=1}^n n^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k \cdot (n+1)^{m+1-k}$$

Euler-Maclaurin formula for infinite sums:

$$\sum_{i=m}^\infty f(i) = \int_m^\infty f(x)dx - \sum_{k=1}^\infty \frac{B_k}{k!} f^{(k-1)}(m) \approx \int_m^\infty f(x)dx + \frac{f(m)}{2} - \frac{f'(m)}{12} + \frac{f'''(m)}{720} + O(f^{(5)}(m))$$

6.3.2 Stirling numbers of the first kind

Number of permutations on n items with k cycles.

$$c(n, k) = c(n - 1, k - 1) + (n - 1)c(n - 1, k), \quad c(0, 0) = 1$$
$$\sum_{k=0}^n c(n, k) x^k = x(x + 1) \dots (x + n - 1)$$

$$c(8, k) = 8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1$$
$$c(n, 2) = 0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, \dots$$

6.3.3 Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k j:s s.t. $\pi(j) > \pi(j + 1)$, $k + 1$ j:s s.t. $\pi(j) \geq j$, k j:s s.t. $\pi(j) > j$.

$$E(n, k) = (n - k)E(n - 1, k - 1) + (k + 1)E(n - 1, k)$$
$$E(n, 0) = E(n, n - 1) = 1$$
$$E(n, k) = \sum_{j=0}^k (-1)^j \binom{n + 1}{j} (k + 1 - j)^n$$

6.3.4 Stirling numbers of the second kind

Partitions of n distinct elements into exactly k groups.

$$S(n, k) = S(n - 1, k - 1) + kS(n - 1, k)$$
$$S(n, 1) = S(n, n) = 1$$
$$S(n, k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

6.3.5 Bell numbers

Total number of partitions of n distinct elements. $B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \dots$. For p prime,
 $B(p^m + n) \equiv mB(n) + B(n + 1) \pmod{p}$

6.3.6 Labeled unrooted trees

on n vertices: n^{n-2}
on k existing trees of size n_i : $n_1 n_2 \dots n_k n^{k-2}$
with degrees d_i : $(n - 2)! / ((d_1 - 1)! \dots (d_n - 1)!)$


```

MCMF(int N) : N(N), ed(N), seen(N), dist(N), pi(N), par(N)
{}

void addEdge(int from, int to, ll cap, EDGE_W cost) {
    if (from == to) return;
    ed[from].push_back(edge{ from,to,sz(ed[to]),cap,cost,0
    });
    ed[to].push_back(edge{ to,from,sz(ed[from])-1,0,-cost,0
    });
}

void path(int s) {
    fill(all(seen), 0);
    fill(all(dist), INF);
    dist[s] = 0; EDGE_W di;

    __gnu_pbds::priority_queue<pair<EDGE_W, int>> q;
    vector<decltype(q)::point_iterator> its(N);
    q.push({ 0, s });

    while (!q.empty()) {
        s = q.top().second; q.pop();
        seen[s] = 1; di = dist[s] + pi[s];
        for (edge& e : ed[s]) if (!seen[e.to]) {
            EDGE_W val = di - pi[e.to] + e.cost;
            if (e.cap - e.flow > 0 && val < dist[e.to]) {
                dist[e.to] = val;
                par[e.to] = &e;
                if (its[e.to] == q.end())
                    its[e.to] = q.push({ -dist[e.to], e.to
                });
            } else
                q.modify(its[e.to], { -dist[e.to], e.to
                });
        }
    }
    rep(i,0,N) pi[i] = min(pi[i] + dist[i], INF);
}

pair<ll, EDGE_W> maxflow(int s, int t) {
    ll totflow = 0;
    EDGE_W totcost = 0;
    while (path(s), seen[t]) {
        ll fl = INF;
        for (edge* x = par[t]; x; x = par[x->from])
            fl = min(fl, x->cap - x->flow);

        totflow += fl;
        for (edge* x = par[t]; x; x = par[x->from]) {
            x->flow += fl;
            ed[x->to][x->rev].flow -= fl;
        }
    }
    rep(i,0,N) for(edge& e : ed[i]) totcost += e.cost * e.
        flow;
    return {totflow, totcost/2};
}

// If some costs can be negative, call this before maxflow:
void setpi(int s) { // (otherwise, leave this out)
    fill(all(pi), INF); pi[s] = 0;
    int it = N, ch = 1; ll v;
    while (ch-- && it--)
        rep(i,0,N) if (pi[i] != INF)
            for (edge& e : ed[i]) if (e.cap)
                if ((v = pi[i] + e.cost) < pi[e.to])
                    pi[e.to] = v, ch = 1;
    assert(it >= 0); // negative cost cycle

```

```

}
};

```

EdmondsKarp.h

Description: Flow algorithm with guaranteed complexity $O(VE^2)$. To get edge flow values, compare capacities before and after, and take the positive values only.

d41d8c, 35 lines

```

template<class T> T edmondsKarp(vector<unordered_map<int, T>>&
    graph, int source, int sink) {
    assert(source != sink);
    T flow = 0;
    vi par(sz(graph)), q = par;

    for (;;) {
        fill(all(par), -1);
        par[source] = 0;
        int ptr = 1;
        q[0] = source;

        rep(i,0,ptr) {
            int x = q[i];
            for (auto e : graph[x]) {
                if (par[e.first] == -1 && e.second > 0) {
                    par[e.first] = x;
                    q[ptr++] = e.first;
                    if (e.first == sink) goto out;
                }
            }
        }
        return flow;
    out:
        T inc = numeric_limits<T>::max();
        for (int y = sink; y != source; y = par[y])
            inc = min(inc, graph[par[y]][y]);

        flow += inc;
        for (int y = sink; y != source; y = par[y]) {
            int p = par[y];
            if ((graph[p][y] -= inc) <= 0) graph[p].erase(y);
            graph[y][p] += inc;
        }
    }
}

```

MaxFlowNNG.h

Description: Maxflow

Time: $O(FE \log(V))$ where F is max flow. $O(VE)$ for setpi.

d41d8c, 73 lines

```

struct MaxFlow {
    struct Edge {
        int fr, to; ll cp, fl;
    };
    int n, src, snk; ll D;
    vector<Edge> E;
    vector<int> adj[maxn];
    int cnt[maxn]; ll dis[maxn];
    queue<int> qu;
    void init(int sz, int v1, int v2) {
        E.clear();
        n = sz; src = v1; snk = v2;
        for (int i = 0; i < n; i++) adj[i].clear();
    }
    void addEdge(int u, int v, ll cp) {
        adj[u].pb(len(E)); E.pb({u, v, cp, 0});
        adj[v].pb(len(E)); E.pb({v, u, 0, 0});
    }
    bool bfs() {
        int v = src;

```

```

        fill(dis, dis + n, oo); fill(cnt, cnt + n, 0);
        dis[v] = 0; qu.push(v);
        while (!qu.empty()) {
            int v = qu.front(); qu.pop();
            for (int j : adj[v]) {
                int u = E[j].to; ll cp = E[j].cp, fl = E[j].fl, rm = cp
                    - fl;
                if (rm < D) continue;
                if (dis[v] + 1 < dis[u]) {
                    dis[u] = dis[v] + 1;
                    qu.push(u);
                }
            }
        }
        return (dis[snk] < oo);
    }
    ll dfs(int v, ll f) {
        if (f < D) f = 0;
        if (v == snk || f == 0) return f;

        ll res = 0;
        for (; cnt[v] < len(adj[v]); cnt[v]++) {
            int j = adj[v][cnt[v]];
            int u = E[j].to; ll cp = E[j].cp, fl = E[j].fl, rm = cp -
                fl;
            if (dis[v] + 1 != dis[u]) continue;

            int x = dfs(u, min(f, rm));
            res += x; f -= x;
            E[j].fl += x; E[j ^ 1].fl -= x;
            if (f == 0) break;
        }
        return res;
    }
    ll dinic() {
        ll res = 0; D = 1;
        while (D > 0) {
            while (bfs()) res += dfs(src, INF);
            D /= 2;
        }
        return res;
    }
};
MaxFlow A;
int main(){
    A.init(c1 + c2 + 2, c1 + c2, c1 + c2 + 1);
    for (int i = 0; i < c1; i++) A.addEdge(A.src, i, 1);
    for (int i = c1; i < c1 + c2; i++) A.addEdge(i, A.snk, 1);
    for (int i = 0; i < n; i++) {
        int u = coll[i], v = c1 + col2[i];
        ind[i] = len(A.E); A.addEdge(u, v, 1);
    }
    cout << n - A.dinic() << endl;
    return 0;
}

```

MinCut.h

Description: After running max-flow, the left side of a min-cut from s to t is given by all vertices reachable from s , only traversing edges with positive residual capacity.

GlobalMinCut.h

Description: Find a global minimum cut in an undirected graph, as represented by an adjacency matrix.

Time: $O(V^3)$

d41d8c, 21 lines

```

pair<int, vi> globalMinCut(vector<vi> mat) {
    pair<int, vi> best = {INT_MAX, {}};

```

```
int n = sz(mat);
vector<vi> co(n);
rep(i,0,n) co[i] = {i};
rep(ph,1,n) {
    vi w = mat[0];
    size_t s = 0, t = 0;
    rep(it,0,n-ph) { // O(V^2) -> O(E log V) with prio. queue
        w[t] = INT_MIN;
        s = t, t = max_element(all(w)) - w.begin();
        rep(i,0,n) w[i] += mat[t][i];
    }
    best = min(best, {w[t] - mat[t][t], co[t]});
    co[s].insert(co[s].end(), all(co[t]));
    rep(i,0,n) mat[s][i] += mat[t][i];
    rep(i,0,n) mat[i][s] = mat[s][i];
    mat[0][t] = INT_MIN;
}
return best;
}
```

GomoryHu.h
Description: Given a list of edges representing an undirected flow graph, returns edges of the Gomory-Hu tree. The max flow between any pair of vertices is given by minimum edge weight along the Gomory-Hu tree path.
Time: $\mathcal{O}(V)$ Flow Computations

```
"PushRelabel.h" d41d8c, 13 lines

typedef array<ll, 3> Edge;
vector<Edge> gomoryHu(int N, vector<Edge> ed) {
    vector<Edge> tree;
    vi par(N);
    rep(i,1,N) {
        PushRelabel D(N); // Dinic also works
        for (Edge t : ed) D.addEdge(t[0], t[1], t[2], t[2]);
        tree.push_back({i, par[i], D.calc(i, par[i])});
        rep(j,i+1,N)
            if (par[j] == par[i] && D.leftOfMinCut(j)) par[j] = i;
    }
    return tree;
}
```

7.3 Matching

hopcroftKarp.h
Description: Fast bipartite matching algorithm. Graph g should be a list of neighbors of the left partition, and $btoa$ should be a vector full of -1's of the same size as the right partition. Returns the size of the matching. $btoa[i]$ will be the match for vertex i on the right side, or -1 if it's not matched.
Usage: $vi\ btoa(m, -1);$ hopcroftKarp($g, btoa$);
Time: $\mathcal{O}(\sqrt{VE})$

```
d41d8c, 42 lines

bool dfs(int a, int L, vector<vi>& g, vi& btoa, vi& A, vi& B) {
    if (A[a] != L) return 0;
    A[a] = -1;
    for (int b : g[a]) if (B[b] == L + 1) {
        B[b] = 0;
        if (btoa[b] == -1 || dfs(btoa[b], L + 1, g, btoa, A, B))
            return btoa[b] = a, 1;
    }
    return 0;
}
```

```
int hopcroftKarp(vector<vi>& g, vi& btoa) {
    int res = 0;
    vi A(g.size()), B(btoa.size()), cur, next;
    for (;;) {
        fill(all(A), 0);
        fill(all(B), 0);
        cur.clear();
        for (int a : btoa) if(a != -1) A[a] = -1;
```

```
rep(a,0,sz(g)) if(A[a] == 0) cur.push_back(a);
for (int lay = 1;; lay++) {
    bool islast = 0;
    next.clear();
    for (int a : cur) for (int b : g[a]) {
        if (btoa[b] == -1) {
            B[b] = lay;
            islast = 1;
        }
        else if (btoa[b] != a && !B[b]) {
            B[b] = lay;
            next.push_back(btoa[b]);
        }
    }
    if (islast) break;
    if (next.empty()) return res;
    for (int a : next) A[a] = lay;
    cur.swap(next);
}
rep(a,0,sz(g))
    res += dfs(a, 0, g, btoa, A, B);
}
```

DFSMatching.h
Description: Simple bipartite matching algorithm. Graph g should be a list of neighbors of the left partition, and $btoa$ should be a vector full of -1's of the same size as the right partition. Returns the size of the matching. $btoa[i]$ will be the match for vertex i on the right side, or -1 if it's not matched.
Usage: $vi\ btoa(m, -1);$ dfsMatching($g, btoa$);
Time: $\mathcal{O}(VE)$

```
d41d8c, 22 lines

bool find(int j, vector<vi>& g, vi& btoa, vi& vis) {
    if (btoa[j] == -1) return 1;
    vis[j] = 1; int di = btoa[j];
    for (int e : g[di])
        if (!vis[e] && find(e, g, btoa, vis)) {
            btoa[e] = di;
            return 1;
        }
    return 0;
}
int dfsMatching(vector<vi>& g, vi& btoa) {
    vi vis;
    rep(i,0,sz(g)) {
        vis.assign(sz(btoa), 0);
        for (int j : g[i])
            if (find(j, g, btoa, vis)) {
                btoa[j] = i;
                break;
            }
    }
    return sz(btoa) - (int)count(all(btoa), -1);
}
```

MinimumVertexCover.h
Description: Finds a minimum vertex cover in a bipartite graph. The size is the same as the size of a maximum matching, and the complement is a maximum independent set.

```
"DFSMatching.h" d41d8c, 20 lines

vi cover(vector<vi>& g, int n, int m) {
    vi match(m, -1);
    int res = dfsMatching(g, match);
    vector<bool> lfound(n, true), seen(m);
    for (int it : match) if (it != -1) lfound[it] = false;
    vi q, cover;
    rep(i,0,n) if (lfound[i]) q.push_back(i);
    while (!q.empty()) {
        int i = q.back(); q.pop_back();
```

```
lfound[i] = 1;
for (int e : g[i]) if (!seen[e] && match[e] != -1) {
    seen[e] = true;
    q.push_back(match[e]);
}
}
rep(i,0,n) if (!lfound[i]) cover.push_back(i);
rep(i,0,m) if (seen[i]) cover.push_back(n+i);
assert(sz(cover) == res);
return cover;
}
```

WeightedMatching.h
Description: Given a weighted bipartite graph, matches every node on the left with a node on the right such that no nodes are in two matchings and the sum of the edge weights is minimal. Takes $cost[N][M]$, where $cost[i][j]$ = cost for $L[i]$ to be matched with $R[j]$ and returns (min cost, match), where $L[i]$ is matched with $R[match[i]]$. Negate costs for max cost. Requires $N \leq M$.
Time: $\mathcal{O}(N^2M)$

```
d41d8c, 31 lines

pair<int, vi> hungarian(const vector<vi> &a) {
    if (a.empty()) return {0, {}};
    int n = sz(a) + 1, m = sz(a[0]) + 1;
    vi u(n), v(m), p(m), ans(n - 1);
    rep(i,1,n) {
        p[0] = i;
        int j0 = 0; // add "dummy" worker 0
        vi dist(m, INT_MAX), pre(m, -1);
        vector<bool> done(m + 1);
        do { // dijkstra
            done[j0] = true;
            int i0 = p[j0], j1, delta = INT_MAX;
            rep(j,1,m) if (!done[j]) {
                auto cur = a[i0 - 1][j - 1] - u[i0] - v[j];
                if (cur < dist[j]) dist[j] = cur, pre[j] = j0;
                if (dist[j] < delta) delta = dist[j], j1 = j;
            }
            rep(j,0,m) {
                if (done[j]) u[p[j]] += delta, v[j] -= delta;
                else dist[j] -= delta;
            }
            j0 = j1;
        } while (p[j0]);
        while (j0) { // update alternating path
            int j1 = pre[j0];
            p[j0] = p[j1], j0 = j1;
        }
    }
    rep(j,1,m) if (p[j]) ans[p[j] - 1] = j - 1;
    return {-v[0], ans}; // min cost
}
```

GeneralMatching.h
Description: Matching for general graphs. Fails with probability N/mod .
Time: $\mathcal{O}(N^3)$

```
"../numerical/MatrixInverse-mod.h" d41d8c, 40 lines

vector<pii> generalMatching(int N, vector<pii>& ed) {
    vector<vector<ll>> mat(N, vector<ll>(N)), A;
    for (pii pa : ed) {
        int a = pa.first, b = pa.second, r = rand() % mod;
        mat[a][b] = r, mat[b][a] = (mod - r) % mod;
    }

    int r = matInv(A = mat), M = 2*N - r, fi, fj;
    assert(r % 2 == 0);

    if (M != N) do {
        mat.resize(M, vector<ll>(M));
        rep(i,0,N) {
```

```
        mat[i].resize(M);
        rep(j,N,M) {
            int r = rand() % mod;
            mat[i][j] = r, mat[j][i] = (mod - r) % mod;
        }
    } while (matInv(A = mat) != M);

vi has(M, 1); vector<pii> ret;
rep(it,0,M/2) {
    rep(i,0,M) if (has[i])
        rep(j,i+1,M) if (A[i][j] && mat[i][j]) {
            fi = i; fj = j; goto done;
        } assert(0); done:
    if (fj < N) ret.emplace_back(fi, fj);
    has[fi] = has[fj] = 0;
    rep(sw,0,2) {
        ll a = modpow(A[fi][fj], mod-2);
        rep(i,0,M) if (has[i] && A[i][fj]) {
            ll b = A[i][fj] * a % mod;
            rep(j,0,M) A[i][j] = (A[i][j] - A[fi][j] * b) % mod;
        }
        swap(fi,fj);
    }
}
return ret;
}
```

7.4 DFS algorithms

SCC.h
Description: Finds strongly connected components in a directed graph. If vertices u, v belong to the same component, we can reach u from v and vice versa.
Usage: scc(graph, [&](vi& v) { ... }) visits all components in reverse topological order. comp[i] holds the component index of a node (a component only has edges to components with lower index). ncomps will contain the number of components.
Time: $\mathcal{O}(E + V)$

```
vi val, comp, z, cont;
int Time, ncomps;
template<class G, class F> int dfs(int j, G& g, F& f) {
    int low = val[j] = ++Time, x; z.push_back(j);
    for (auto e : g[j]) if (comp[e] < 0)
        low = min(low, val[e] ?: dfs(e,g,f));

    if (low == val[j]) {
        do {
            x = z.back(); z.pop_back();
            comp[x] = ncomps;
            cont.push_back(x);
        } while (x != j);
        f(cont); cont.clear();
        ncomps++;
    }
    return val[j] = low;
}
template<class G, class F> void scc(G& g, F f) {
    int n = sz(g);
    val.assign(n, 0); comp.assign(n, -1);
    Time = ncomps = 0;
    rep(i,0,n) if (comp[i] < 0) dfs(i, g, f);
}
```

BiconnectedComponents.h

Description: finds biconnected components (connected after vertex removal)
const int N = 5e5 + 1;

```
bitset<N> arti;
vector<int> g[N], st, comp[N];
int n, ptr, ncc, in[N], low[N], id[N];

void dfs(int u, int from = -1) {
    in[u] = low[u] = ++ptr;
    st.emplace_back(u);
    for (int v : g[u]) if (v ^ from) {
        if (!in[v]) {
            dfs(v, u);
            low[u] = min(low[u], low[v]);
            if (low[v] >= in[u]) {
                arti[u] = ~from or in[v] > in[u] + 1;
                comp[++ncc].emplace_back(u);
                while (comp[ncc].back() ^ v) {
                    comp[ncc].emplace_back(st.back());
                    st.pop_back();
                }
            }
        } else low[u] = min(low[u], in[v]);
    }
}

void bcc() {
    for (int i = 0; i < n; i++) {
        if (!in[i]) {
            dfs(i);
            if (g[i].empty()) comp[++ncc].push_back(i); //
                COMPS NUMBERED 1..ncc INCLUDED
            }
        }
    }
}

// BLOCK CUT TREE
// vector<int> tree[N];
// void buildTree() {
//     ptr = 0;
//     for (int i = 0; i < n; ++i) { // index nodes properly
//         here
//         if (arti[i]) id[i] = ++ptr;
//     }
//     for (int i = 1; i <= ncc; ++i) {
//         int x = ++ptr;
//         for (int u : comp[i]) {
//             if (arti[u]) tree[x].emplace_back(id[u]), tree[
//                 id[u]].emplace_back(x);
//             else id[u] = x;
//         }
//     }
// }
```

TwoEdgeConnectedComponents.h

Description: does dfs to find bridges, then removes them and does dfs to find 2CCs

```
struct LowLink{
    int n, pos = 0;
    vi ord, low, par, blg;
    vector<vi> G, C;

    LowLink(vector<vi>& adj) : n(sz(adj)), ord(n,-1), low(n),
        par(n,-1), blg(n,-1), G(adj) {}

    bool bridge(int u,int v){
        if(ord[u] > ord[v]) swap(u,v);
        return ord[u] < low[v];
    }
}
```

```
void dfs(int v){
    ord[v] = low[v] = pos++;
    int cnt = 0;
    for(int u : G[v]){
        if(u == par[v] && cnt == 0) cnt++;
        else if(~ord[u]) low[v] = min(low[v], ord[u]);
        else {
            par[u] = v;
            dfs(u);
            low[v] = min(low[v], low[u]);
        }
    }
}

void fill_comp(int v){
    C[blg[v]].emplace_back(v);
    for (int u : G[v]) {
        if (~blg[u] || bridge(u,v)) continue;
        blg[u] = blg[v];
        fill_comp(u);
    }
}

void add_comp(int v,int &k){
    if(~blg[v]) return;
    blg[v] = k++;
    C.emplace_back();
    fill_comp(v);
}

int build(){
    for(int i=0;i<n;i++) if(ord[i] < 0) dfs(i);

    int k = 0;
    for(int i=0;i<n;i++) add_comp(i, k);
    return k;
}

};
```

2sat.h

Description: Calculates a valid assignment to boolean variables a, b, c, \dots to a 2-SAT problem, so that an expression of the type $(a||b)\&\&(!a||c)\&\&(d||!b)\&\&\dots$ becomes true, or reports that it is unsatisfiable. Negated variables are represented by bit-inversions ($\sim x$).
Usage: TwoSat ts(number of boolean variables);
ts.either(0, ~3); // Var 0 is true or var 3 is false
ts.setValue(2); // Var 2 is true
ts.atMostOne({0,~1,2}); // ≤ 1 of vars 0, ~1 and 2 are true
ts.solve(); // Returns true iff it is solvable
ts.values[0..N-1] holds the assigned values to the vars
Time: $\mathcal{O}(N + E)$, where N is the number of boolean variables, and E is the number of clauses.

```
struct TwoSat {
    int N;
    vector<vi> gr;
    vi values; // 0 = false, 1 = true

    TwoSat(int n = 0) : N(n), gr(2*n) {}

    int addVar() { // (optional)
        gr.emplace_back();
        gr.emplace_back();
        return N++;
    }

    void either(int f, int j) {
        f = max(2*f, -1-2*f);
    }
}
```

```
j = max(2*j, -1-2*j);
gr[f].push_back(j^1);
gr[j].push_back(f^1);
}

void setValue(int x) { either(x, x); }

void atMostOne(const vi& li) { // (optional)
    if (sz(li) <= 1) return;
    int cur = ~li[0];
    rep(i,2,sz(li)) {
        int next = addVar();
        either(cur, ~li[i]);
        either(cur, next);
        either(~li[i], next);
        cur = ~next;
    }
    either(cur, ~li[1]);
}

vi val, comp, z; int time = 0;
int dfs(int i) {
    int low = val[i] = ++time, x; z.push_back(i);
    for(int e : gr[i]) if (!comp[e])
        low = min(low, val[e] ? dfs(e));
    if (low == val[i]) do {
        x = z.back(); z.pop_back();
        comp[x] = low;
        if (values[x]>1] == -1)
            values[x]>1] = x&1;
    } while (x != i);
    return val[i] = low;
}

bool solve() {
    values.assign(N, -1);
    val.assign(2*N, 0); comp = val;
    rep(i,0,2*N) if (!comp[i]) dfs(i);
    rep(i,0,N) if (comp[2*i] == comp[2*i+1]) return 0;
    return 1;
}

};
```

EulerWalk.h

Description: Eulerian undirected/directed path/cycle algorithm. Input should be a vector of (dest, global edge index), where for undirected graphs, forward/backward edges have the same index. Returns a list of nodes in the Eulerian path/cycle with src at both start and end, or empty list if no cycle/path exists. To get edge indices back, add .second to s and ret.
Time: $\mathcal{O}(V + E)$

```
vi eulerWalk(vector<vector<pii>&& gr, int nedges, int src=0) {
    int n = sz(gr);
    vi D(n), its(n), eu(nedges), ret, s = {src};
    D[src]++; // to allow Euler paths, not just cycles
    while (!s.empty()) {
        int x = s.back(), y, e, &it = its[x], end = sz(gr[x]);
        if (it == end){ ret.push_back(x); s.pop_back(); continue; }
        tie(y, e) = gr[x][it++];
        if (!eu[e]) {
            D[x]--, D[y]++;
            eu[e] = 1; s.push_back(y);
        }
    }
    for (int x : D) if (x < 0 || sz(ret) != nedges+1) return {};
    return {ret.rbegin(), ret.rend()};
}
```

7.5 Coloring

EdgeColoring.h

Description: Given a simple, undirected graph with max degree D , computes a $(D + 1)$ -coloring of the edges such that no neighboring edges share a color. (D -coloring is NP-hard, but can be done for bipartite graphs by repeated matchings of max-degree nodes.)
Time: $\mathcal{O}(NM)$

```
vi edgeColoring(int N, vector<pii> eds) {
    vi cc(N + 1), ret(sz(eds)), fan(N), free(N), loc;
    for (pii e : eds) ++cc[e.first], ++cc[e.second];
    int u, v, ncols = *max_element(all(cc)) + 1;
    vector<vi> adj(N, vi(ncols, -1));
    for (pii e : eds) {
        tie(u, v) = e;
        fan[0] = v;
        loc.assign(ncols, 0);
        int at = u, end = u, d, c = free[u], ind = 0, i = 0;
        while (d = free[v], !loc[d] && (v = adj[u][d]) != -1)
            loc[d] = ++ind, cc[ind] = d, fan[ind] = v;
        cc[loc[d]] = c;
        for (int cd = d; at != -1; cd ^= c ^ d, at = adj[at][cd])
            swap(adj[at][cd], adj[end = at][cd ^ c ^ d]);
        while (adj[fan[i]][d] != -1) {
            int left = fan[i], right = fan[++i], e = cc[i];
            adj[u][e] = left;
            adj[left][e] = u;
            adj[right][e] = -1;
            free[right] = e;
        }
        adj[u][d] = fan[i];
        adj[fan[i]][d] = u;
        for (int y : {fan[0], u, end})
            for (int& z = free[y] = 0; adj[y][z] != -1; z++);
    }
    rep(i,0,sz(eds))
        for (tie(u, v) = eds[i]; adj[u][ret[i]] != v;) ++ret[i];
    return ret;
}
```

7.6 Heuristics

MaximalCliques.h

Description: Runs a callback for all maximal cliques in a graph (given as a symmetric bitset matrix; self-edges not allowed). Callback is given a bitset representing the maximal clique.
Time: $\mathcal{O}\left(3^{n/3}\right)$, much faster for sparse graphs

```
typedef bitset<128> B;
template<class F>
void cliques(vector<B>& eds, F f, B P = ~B(), B X={}, B R={}) {
    if (!P.any()) { if (!X.any()) f(R); return; }
    auto q = (P | X)._Find_first();
    auto cands = P & ~eds[q];
    rep(i,0,sz(eds)) if (cands[i]) {
        R[i] = 1;
        cliques(eds, f, P & eds[i], X & eds[i], R);
        R[i] = P[i] = 0; X[i] = 1;
    }
}
```

MaximumClique.h

Description: Quickly finds a maximum clique of a graph (given as symmetric bitset matrix; self-edges not allowed). Can be used to find a maximum independent set by finding a clique of the complement graph.
Time: Runs in about 1s for n=155 and worst case random graphs (p=.90). Runs faster for sparse graphs.

```
typedef vector<bitset<200>> vb;
```

```
struct Maxclique {
    double limit=0.025, pk=0;
    struct Vertex { int i, d=0; };
    typedef vector<Vertex> vv;
    vb e;
    vv V;
    vector<vi> C;
    vi qmax, q, S, old;
    void init(vv& r) {
        for (auto& v : r) v.d = 0;
        for (auto& v : r) for (auto j : r) v.d += e[v.i][j.i];
        sort(all(r), [](auto a, auto b) { return a.d > b.d; });
        int mxD = r[0].d;
        rep(i,0,sz(r)) r[i].d = min(i, mxD) + 1;
    }
    void expand(vv& R, int lev = 1) {
        S[lev] += S[lev - 1] - old[lev];
        old[lev] = S[lev - 1];
        while (sz(R)) {
            if (sz(q) + R.back().d <= sz(qmax)) return;
            q.push_back(R.back().i);
            vv T;
            for(auto v:R) if (e[R.back().i][v.i]) T.push_back({v.i});
            if (sz(T)) {
                if (S[lev]++ / ++pk < limit) init(T);
                int j = 0, mxk = 1, mnk = max(sz(qmax) - sz(q) + 1, 1);
                C[1].clear(), C[2].clear();
                for (auto v : T) {
                    int k = 1;
                    auto f = [&](int i) { return e[v.i][i]; };
                    while (any_of(all(C[k]), f)) k++;
                    if (k > mxk) mxk = k, C[mxk + 1].clear();
                    if (k < mnk) T[j++].i = v.i;
                    C[k].push_back(v.i);
                }
                if (j > 0) T[j - 1].d = 0;
                rep(k,mnk,mxk + 1) for (int i : C[k])
                    T[j].i = i, T[j++].d = k;
                expand(T, lev + 1);
            } else if (sz(q) > sz(qmax)) qmax = q;
            q.pop_back(), R.pop_back();
        }
    }
    vi maxClique() { init(V), expand(V); return qmax; }
    Maxclique(vb conn) : e(conn), C(sz(e)+1), S(sz(C)), old(S) {
        rep(i,0,sz(e)) V.push_back({i});
    }
};
```

MaximumIndependentSet.h

Description: To obtain a maximum independent set of a graph, find a max clique of the complement. If the graph is bipartite, see MinimumVertex-Cover.

7.7 Trees

LCA.h

Description: Data structure for computing lowest common ancestors in a tree
Time: $\mathcal{O}(N \log N + Q)$

```
"../data-structures/RMQ.h"
11 Jad[LOG][MXN], dis[MXN];
void prep(11 u, 11 par){
    Jad[0][u] = par;
    for(int i = 1; i < LOG; i++){
        Jad[i][u] = Jad[i - 1][Jad[i - 1][u]];
    }
    for(auto v : adj[u]){
```



```
        if(v == par) continue;
        dis[v] = dis[u] + 1;
        prep(v, u);
    }
}

ll K_Jad(ll u, ll k){
    for(int i = 0; i < LOG; i++){
        if((k >> i) & 1LL) u = Jad[i][u];
    }
    return u;
}

ll LCA(ll u, ll v){
    if(dis[v] < dis[u]) swap(u, v);
    v = K_Jad(v, dis[v] - dis[u]);
    if(u == v) return u;
    for(int i = LOG - 1; ~i; i--){
        if(Jad[i][u] != Jad[i][v]) u = Jad[i][u], v = Jad[i][v];
    }
    return Jad[0][u];
}

inline ll Distance(ll u, ll v){
    return dis[u] + dis[v] - 2 * dis[LCA(u, v)];
}
```

CompressTree.h

Description: Given a rooted tree and a subset S of nodes, compute the minimal subtree that contains all the nodes by adding all (at most |S| - 1) pairwise LCA's and compressing edges. Returns a list of (par, orig_index) representing a tree rooted at 0. The root points to itself.

Time: $\mathcal{O}(|S| \log |S|)$

```
"LCA.h" d41d8c, 21 lines

typedef vector<pair<int, int>> vpi;
vpi compressTree(LCA& lca, const vi& subset) {
    static vi rev; rev.resize(sz(lca.time));
    vi li = subset, &T = lca.time;
    auto cmp = [&](int a, int b) { return T[a] < T[b]; };
    sort(all(li), cmp);
    int m = sz(li)-1;
    rep(i,0,m) {
        int a = li[i], b = li[i+1];
        li.push_back(lca.lca(a, b));
    }
    sort(all(li), cmp);
    li.erase(unique(all(li)), li.end());
    rep(i,0,sz(li)) rev[li[i]] = i;
    vpi ret = {pii(0, li[0])};
    rep(i,0,sz(li)-1) {
        int a = li[i], b = li[i+1];
        ret.emplace_back(rev[lca.lca(a, b)], b);
    }
    return ret;
}
```

HLD.h

Description: Decomposes a tree into vertex disjoint heavy paths and light edges such that the path from any leaf to the root contains at most log(n) light edges. Code does additive modifications and max queries, but can support commutative segtree modifications/queries on paths and subtrees. Takes as input the full adjacency list. VALS.EDGES being true means that values are stored in the edges, as opposed to the nodes. All values initialized to the segtree default. Root must be 0.

Time: $\mathcal{O}((\log N)^2)$

```
void prep(ll u, ll par){
    sub[u] ++, Par[u] = par;
    for(auto v : adj[u]){
        if(v == par) continue;
        prep(v, u);
        sub[u] += sub[v];
    }
}
```

CompressTree HLD LinkCutTree DirectedMST

```
        if(sub[v] > sub[hvs[u]]) hvs[u] = v;
    }
}

void dfs(ll u, ll par, ll head){
    Stm[u] = ++ timer;
    hd[u] = head;
    if(hvs[u]) dfs(hvs[u], u, head);
    for(auto v : adj[u]){
        if(v == par || v == hvs[u]) continue;
        dfs(v, u, v);
    }
    Ftm[u] = timer;
}

int main(){
    while(v){
        ll c = hd[v], r = Par[c];
        now = Lazy[r] * (n - sub[c]) % Mod * invn % Mod;
        ans = (ans + now) % Mod;
        v = r;
    }
}
```

LinkCutTree.h

Description: Represents a forest of unrooted trees. You can add and remove edges (as long as the result is still a forest), and check whether two nodes are in the same tree.

Time: All operations take amortized $\mathcal{O}(\log N)$.

```
d41d8c, 90 lines

struct Node { // Splay tree. Root's pp contains tree's parent.
    Node *p = 0, *pp = 0, *c[2];
    bool flip = 0;
    Node() { c[0] = c[1] = 0; fix(); }
    void fix() {
        if (c[0]) c[0]->p = this;
        if (c[1]) c[1]->p = this;
        // (+ update sum of subtree elements etc. if wanted)
    }
    void pushFlip() {
        if (!flip) return;
        flip = 0; swap(c[0], c[1]);
        if (c[0]) c[0]->flip ^= 1;
        if (c[1]) c[1]->flip ^= 1;
    }
    int up() { return p ? p->c[1] == this : -1; }
    void rot(int i, int b) {
        int h = i ^ b;
        Node *x = c[i], *y = b == 2 ? x : x->c[h], *z = b ? y : x;
        if ((y->p = p) p->c[up()] = y;
        c[i] = z->c[i ^ 1];
        if (b < 2) {
            x->c[h] = y->c[h ^ 1];
            y->c[h ^ 1] = x;
        }
        z->c[i ^ 1] = this;
        fix(); x->fix(); y->fix();
        if (p) p->fix();
        swap(pp, y->pp);
    }
    void splay() {
        for (pushFlip(); p; ) {
            if (p->p) p->p->pushFlip();
            p->pushFlip(); pushFlip();
            int c1 = up(), c2 = p->up();
            if (c2 == -1) p->rot(c1, 2);
            else p->p->rot(c2, c1 != c2);
        }
    }
    Node* first() {
```

```
        pushFlip();
        return c[0] ? c[0]->first() : (splay(), this);
    }
};

struct LinkCut {
    vector<Node> node;
    LinkCut(int N) : node(N) {}

    void link(int u, int v) { // add an edge (u, v)
        assert(!connected(u, v));
        makeRoot(&node[u]);
        node[u].pp = &node[v];
    }

    void cut(int u, int v) { // remove an edge (u, v)
        Node *x = &node[u], *top = &node[v];
        makeRoot(top); x->splay();
        assert(top == (x->pp ? x->c[0]));
        if (x->pp) x->pp = 0;
        else {
            x->c[0] = top->p = 0;
            x->fix();
        }
    }

    bool connected(int u, int v) { // are u, v in the same tree?
        Node* nu = access(&node[u])->first();
        return nu == access(&node[v])->first();
    }

    void makeRoot(Node* u) {
        access(u);
        u->splay();
        if(u->c[0]) {
            u->c[0]->p = 0;
            u->c[0]->flip ^= 1;
            u->c[0]->pp = u;
            u->c[0] = 0;
            u->fix();
        }
    }

    Node* access(Node* u) {
        u->splay();
        while (Node* pp = u->pp) {
            pp->splay(); u->pp = 0;
            if (pp->c[1]) {
                pp->c[1]->p = 0; pp->c[1]->pp = pp; }
            pp->c[1] = u; pp->fix(); u = pp;
        }
        return u;
    }
};
```

DirectedMST.h

Description: Finds a minimum spanning tree/arborescence of a directed graph, given a root node. If no MST exists, returns -1.

Time: $\mathcal{O}(E \log V)$

```
"../data-structures/UnionFindRollback.h" d41d8c, 60 lines

struct Edge { int a, b; ll w; };
struct Node {
    Edge key;
    Node *l, *r;
    ll delta;
    void prop() {
        key.w += delta;
        if (l) l->delta += delta;
        if (r) r->delta += delta;
        delta = 0;
    }
    Edge top() { prop(); return key; }
};
```

```
Node *merge(Node *a, Node *b) {
    if (!a || !b) return a ?: b;
    a->prop(), b->prop();
    if (a->key.w > b->key.w) swap(a, b);
    swap(a->l, (a->r = merge(b, a->r)));
    return a;
}

void pop(Node*& a) { a->prop(); a = merge(a->l, a->r); }
```

```
pair<ll, vi> dmst(int n, int r, vector<Edge>& g) {
    RollbackUF uf(n);
    vector<Node*> heap(n);
    for (Edge e : g) heap[e.b] = merge(heap[e.b], new Node{e});
    ll res = 0;
    vi seen(n, -1), path(n), par(n);
    seen[r] = r;
    vector<Edge> Q(n), in(n, {-1,-1}), comp;
    deque<tuple<int, int, vector<Edge>>> cycs;
    rep(s,0,n) {
        int u = s, qi = 0, w;
        while (seen[u] < 0) {
            if (!heap[u]) return {-1,{};};
            Edge e = heap[u]->top();
            heap[u]->delta -= e.w, pop(heap[u]);
            Q[qi] = e, path[qi++] = u, seen[u] = s;
            res += e.w, u = uf.find(e.a);
            if (seen[u] == s) {
                Node* cyc = 0;
                int end = qi, time = uf.time();
                do cyc = merge(cyc, heap[w = path[--qi]]);
                while (uf.join(u, w));
                u = uf.find(u), heap[u] = cyc, seen[u] = -1;
                cycs.push_front({u, time, {&Q[qi], &Q[end]}});
            }
        }
        rep(i,0,qi) in[uf.find(Q[i].b)] = Q[i];
    }

    for (auto& [u,t,comp] : cycs) { // restore sol (optional)
        uf.rollback(t);
        Edge inEdge = in[u];
        for (auto& e : comp) in[uf.find(e.b)] = e;
        in[uf.find(inEdge.b)] = inEdge;
    }
    rep(i,0,n) par[i] = in[i].a;
    return {res, par};
}
```

7.8 Math

7.8.1 Number of Spanning Trees

Create an $N \times N$ matrix mat , and for each edge $a \rightarrow b \in G$, do $mat[a][b]--$, $mat[b][b]++$ (and $mat[b][a]--$, $mat[a][a]++$ if G is undirected). Remove the i th row and column and take the determinant; this yields the number of directed spanning trees rooted at i (if G is undirected, remove any row/column).

7.8.2 Erdős–Gallai theorem

A simple graph with node degrees $d_1 \geq \dots \geq d_n$ exists iff $d_1 + \dots + d_n$ is even and for every $k = 1 \dots n$,

$$\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k).$$

Geometry (8)

8.1 Geometric primitives

Point.h

Description: Class to handle points in the plane. T can be e.g. double or long long. (Avoid int.)

```
template <class T> int sgn(T x) { return (x > 0) - (x < 0); }
template<class T>
struct Point {
    typedef Point P;
    T x, y;
    explicit Point(T x=0, T y=0) : x(x), y(y) {}
    bool operator<(P p) const { return tie(x,y) < tie(p.x,p.y); }
    bool operator==(P p) const { return tie(x,y)==tie(p.x,p.y); }
    P operator+(P p) const { return P(x+p.x, y+p.y); }
    P operator-(P p) const { return P(x-p.x, y-p.y); }
    P operator*(T d) const { return P(x*d, y*d); }
    P operator/(T d) const { return P(x/d, y/d); }
    T dot(P p) const { return x*p.x + y*p.y; }
    T cross(P p) const { return x*p.y - y*p.x; }
    T cross(P a, P b) const { return (a-*this).cross(b-*this); }
    T dist2() const { return x*x + y*y; }
    double dist() const { return sqrt((double)dist2()); }
    T distsq(P p) const {return (x-p.x)*(x-p.x)+(y-p.y)*(y-p.y);}
    double dist(P p) const { return sqrt(this->distsq(p)); }
    // angle to x-axis in interval [-pi, pi]
    double angle() const { return atan2(y, x); }
    P unit() const { return *this/dist(); } // makes dist()==1
    P perp() const { return P(-y, x); } // rotates +90 degrees
    P normal() const { return perp().unit(); }
    P _rot(P p, double a) const { // helper
        return P(p.x*cos(a)-p.y*sin(a),p.x*sin(a)+p.y*cos(a)); }
    // returns point rotated 'a' radians ccw around origin 'r'
    P rotate(double a, P r) { return r + _rot(*this-r,a); }
    friend ostream& operator<<(ostream& os, P p) {
        return os << "(" << p.x << ", " << p.y << ")"; }
};
```

lineDistance.h

Description:
Returns the signed distance between point p and the line containing points a and b . Positive value on left side and negative on right as seen from a towards b . $a==b$ gives nan. P is supposed to be $\text{Point}<T>$ or $\text{Point3D}<T>$ where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long. Using Point3D will always give a non-negative distance. For Point3D , call `.dist` on the result of the cross product.

```
template<class P>
double lineDist(const P& a, const P& b, const P& p) {
    return (double) (b-a).cross(p-a)/(b-a).dist();
}
```

"Point.h"

SegmentDistance.h

Description:
Returns the shortest distance between point p and the line segment from point s to e .

Usage: $\text{Point}<\text{double}> a, b(2,2), p(1,1);$
 $\text{bool onSegment} = \text{segDist}(a,b,p) < 1e-10;$

```
template<class P>
double segDist(P& s, P& e, P& p) {
    if (s==e) return (p-s).dist();
    auto d = (e-s).dist2(), t = min(d,max(.0, (p-s).dot(e-s)));
    return ((p-s)*d-(e-s)*t).dist()/d;
}
```

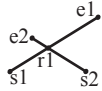
"Point.h"

SegmentIntersection.h

Description:
If a unique intersection point between the line segments going from s_1 to e_1 and from s_2 to e_2 exists then it is returned. If no intersection point exists an empty vector is returned. If infinitely many exist a vector with 2 elements is returned, containing the endpoints of the common line segment. The wrong position will be returned if P is $\text{Point}<\text{ll}>$ and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or long long.

Usage: $\text{vector}<P> \text{inter} = \text{segInter}(s_1,e_1,s_2,e_2);$
 $\text{if} (\text{sz}(\text{inter})==1)$
 $\text{cout} << \text{"segments intersect at " << inter[0] << endl};$

```
"Point.h", "OnSegment.h"
template<class P> vector<P> segInter(P a, P b, P c, P d) {
    auto oa = c.cross(d, a), ob = c.cross(d, b),
        oc = a.cross(b, c), od = a.cross(b, d);
    // Checks if intersection is single non-endpoint point.
    if (sgn(oa) * sgn(ob) < 0 && sgn(oc) * sgn(od) < 0)
        return {(a * ob - b * oa) / (ob - oa)};
    set<P> s;
    if (onSegment(c, d, a)) s.insert(a);
    if (onSegment(c, d, b)) s.insert(b);
    if (onSegment(a, b, c)) s.insert(c);
    if (onSegment(a, b, d)) s.insert(d);
    return {all(s)};
}
```

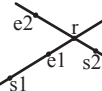


lineIntersection.h

Description:
If a unique intersection point of the lines going through s_1,e_1 and s_2,e_2 exists $\{1, \text{point}\}$ is returned. If no intersection point exists $\{0, (0,0)\}$ is returned and if infinitely many exists $\{-1, (0,0)\}$ is returned. The wrong position will be returned if P is $\text{Point}<\text{ll}>$ and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or ll.

Usage: $\text{auto res} = \text{lineInter}(s_1,e_1,s_2,e_2);$
 $\text{if} (\text{res.first} == 1)$
 $\text{cout} << \text{"intersection point at " << res.second << endl};$

```
"Point.h"
template<class P>
pair<int, P> lineInter(P s1, P e1, P s2, P e2) {
    auto d = (e1 - s1).cross(e2 - s2);
    if (d == 0) // if parallel
        return {(s1.cross(e1, s2) == 0), P(0, 0)};
    auto p = s2.cross(e1, e2), q = s2.cross(e2, s1);
    return {1, (s1 * p + e1 * q) / d};
}
```



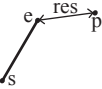
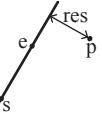
sideOf.h

Description: Returns where p is as seen from s towards e . $1/0/-1 \Leftrightarrow \text{left/on line/right}$. If the optional argument eps is given 0 is returned if p is within distance eps from the line. P is supposed to be $\text{Point}<T>$ where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long.

Usage: $\text{bool left} = \text{sideOf}(p_1,p_2,q)==1;$

```
"Point.h"
template<class P>
int sideOf(P s, P e, P p) { return sgn(s.cross(e, p)); }

template<class P>
int sideOf(const P& s, const P& e, const P& p, double eps) {
    auto a = (e-s).cross(p-s);
    double l = (e-s).dist()*eps;
    return (a > l) - (a < -l);
}
```



OnSegment.h

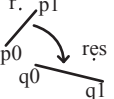
Description: Returns true iff p lies on the line segment from s to e. Use (segDist(s,e,p)<=epsilon) instead when using Point<double>.

"Point.h"41d8dc, 3 lines

```
template<class P> bool onSegment(P s, P e, P p) {
    return p.cross(s, e) == 0 && (s - p).dot(e - p) <= 0;
}
```

linearTransformation.h

Description:



Apply the linear transformation (translation, rotation and scaling) which takes line p0-p1 to line q0-q1 to point r.

"Point.h"41d8dc, 6 lines

```
typedef Point<double> P;
P linearTransformation(const P& p0, const P& p1,
    const P& q0, const P& q1, const P& r) {
    P dp = p1-p0, dq = q1-q0, num(dp.cross(dq), dp.dot(dq));
    return q0 + P((r-p0).cross(num), (r-p0).dot(num))/dp.dist2();
}
```

LineProjectionReflection.h

Description: Projects point p onto line ab. Set refl=true to get reflection of point p across line ab instead. Products of three coordinates are used in intermediate steps so watch out for overflow.

"Point.h"41d8dc, 16 lines

```
// projection of point p on line ax + by + c = 0
template<class P> P projOnLine(P p, dbl a, dbl b, dbl c) {
    double d = (a * p.x + b * p.y + c) / (a*a + b*b);
    return {p.x - a * d, p.y - b * d};
}
// projection of point p on line defined by points a and b
template<class P> P projOnLine(P p, P a, P b) {
    P ab = b - a;
    double t = (p - a).dot(b-a) / ab.dot(b-a);
    return a + ab * t;
}
// reflection of point p over line defined by points a and b
template<class P> P reflectOverLine(P p, P a, P b) {
    P proj = projOnLine(p, a, b);
    return proj * 2 - p;
}
}
```

Angle.h

Description: functions for angles in 2D geometry.

41d8dc, 14 lines

```
// smaller angle in B in radians [0, pi)
const double PI = acos(-1.0);
template<class P> double angle3pt(P a, P b, P c) {
    double dotp = (a-b).dot(c-b);
    double crsp = (a-b).cross(c-b);
    return fabs(atan2(crsp, dotp)); // [0, pi]
}
// comparator sorting angles ccw wrt to (0,0)
template <class P> bool half(const P &p) {
    return (p.y > 0 || (p.y == 0 && p.x > 0)); }
template <class P> bool cmp(const P &a, const P &b) {
    bool ha = half(a), hb = half(b);
    return (ha != hb) ? ha > hb : a.cross(b) > 0;
}
}
```

8.2 Circles

CircleIntersection.h

Description: Computes the pair of points at which two circles intersect. Returns false in case of no intersection.

"Point.h"41d8dc, 11 lines

```
typedef Point<double> P;
```

```
bool circleInter(P a,P b,double r1,double r2,pair<P, P>* out) {
    if (a == b) { assert(r1 != r2); return false; }
    P vec = b - a;
    double d2 = vec.dist2(), sum = r1+r2, dif = r1-r2,
        p = (d2 + r1*r1 - r2*r2)/(d2*2), h2 = r1*r1 - p*p*d2;
    if (sum*sum < d2 || dif*dif > d2) return false;
    P mid = a + vec*p, per = vec.perp() * sqrt(fmax(0, h2) / d2);
    *out = {mid + per, mid - per};
    return true;
}
}
```

CircleTangents.h

Description: Finds the external tangents of two circles, or internal if r2 is negated. Can return 0, 1, or 2 tangents – 0 if one circle contains the other (or overlaps it, in the internal case, or if the circles are the same); 1 if the circles are tangent to each other (in which case .first = .second and the tangent line is perpendicular to the line between the centers). .first and .second give the tangency points at circle 1 and 2 respectively. To find the tangents of a circle with a point set r2 to 0.

"Point.h"41d8dc, 13 lines

```
template<class P>
vector<pair<P, P>> tangents(P c1, double r1, P c2, double r2) {
    P d = c2 - c1;
    double dr = r1 - r2, d2 = d.dist2(), h2 = d2 - dr * dr;
    if (d2 == 0 || h2 < 0) return {};
    vector<pair<P, P>> out;
    for (double sign : {-1, 1}) {
        P v = (d * dr + d.perp() * sqrt(h2) * sign) / d2;
        out.push_back({c1 + v * r1, c2 + v * r2});
    }
    if (h2 == 0) out.pop_back();
    return out;
}
}
```

CirclePolygonIntersection.h

Description: Returns the area of the intersection of a circle with a ccw polygon.

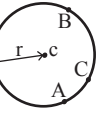
Time: $\mathcal{O}(n)$

"../../../../content/geometry/Point.h"41d8dc, 19 lines

```
typedef Point<double> P;
#define arg(p, q) atan2(p.cross(q), p.dot(q))
double circlePoly(P c, double r, vector<P> ps) {
    auto tri = [&](P p, P q) {
        auto r2 = r * r / 2;
        P d = q - p;
        auto a = d.dot(p)/d.dist2(), b = (p.dist2()-r*r)/d.dist2();
        auto det = a * a - b;
        if (det <= 0) return arg(p, q) * r2;
        auto s = max(0., -a-sqrt(det)), t = min(1., -a+sqrt(det));
        if (t < 0 || 1 <= s) return arg(p, q) * r2;
        P u = p + d * s, v = p + d * t;
        return arg(p,u) * r2 + u.cross(v)/2 + arg(v,q) * r2;
    };
    auto sum = 0.0;
    rep(i,0,sz(ps))
        sum += tri(ps[i] - c, ps[(i + 1) % sz(ps)] - c);
    return sum;
}
}
```

circumcircle.h

Description:



"Point.h"41d8dc, 9 lines

```
typedef Point<double> P;
```

```
double ccRadius(const P& A, const P& B, const P& C) {
    return (B-A).dist()*(C-B).dist()*(A-C).dist()/
        abs((B-A).cross(C-A))/2;
}
}
P ccCenter(const P& A, const P& B, const P& C) {
    P b = C-A, c = B-A;
    return A + (b*c.dist2()-c*b.dist2()).perp()/b.cross(c)/2;
}
}
```

MinimumEnclosingCircle.h

Description: Computes the minimum circle that encloses a set of points.

Time: expected $\mathcal{O}(n)$

"circumcircle.h"41d8dc, 17 lines

```
pair<P, double> mec(vector<P> ps) {
    shuffle(all(ps), mt19937(time(0)));
    P o = ps[0];
    double r = 0, EPS = 1 + 1e-8;
    rep(i,0,sz(ps)) if ((o - ps[i]).dist() > r * EPS) {
        o = ps[i], r = 0;
        rep(j,0,i) if ((o - ps[j]).dist() > r * EPS) {
            o = (ps[i] + ps[j]) / 2;
            r = (o - ps[i]).dist();
            rep(k,0,j) if ((o - ps[k]).dist() > r * EPS) {
                o = ccCenter(ps[i], ps[j], ps[k]);
                r = (o - ps[i]).dist();
            }
        }
    }
    return {o, r};
}
}
```

8.3 Polygons

InsidePolygon.h

Description: Returns true if p lies within the polygon. If strict is true, it returns false for points on the boundary. The algorithm uses products in intermediate steps so watch out for overflow.

Usage: vector<P> v = {P{4,4}, P{1,2}, P{2,1}};

bool in = inPolygon(v, P{3, 3}, false);

Time: $\mathcal{O}(n)$

"Point.h", "OnSegment.h", "SegmentDistance.h"41d8dc, 11 lines

```
template<class P>
bool inPolygon(vector<P> &p, P a, bool strict = true) {
    int cnt = 0, n = sz(p);
    rep(i,0,n) {
        P q = p[(i + 1) % n];
        if (onSegment(p[i], q, a)) return !strict;
        //or: if (segDist(p[i], q, a) <= eps) return !strict;
        cnt ^= ((a.y<p[i].y) - (a.y<q.y)) * a.cross(p[i], q) > 0;
    }
    return cnt;
}
}
```

PolygonArea.h

Description: Returns twice the signed area of a polygon. Clockwise enumeration gives negative area. Watch out for overflow if using int as T!

"Point.h"41d8dc, 6 lines

```
template<class T>
T polygonArea2(vector<Point<T>>& v) {
    T a = v.back().cross(v[0]);
    rep(i,0,sz(v)-1) a += v[i].cross(v[i+1]);
    return a;
}
}
```

PolygonCenter.h

Description: Returns the center of mass for a polygon.

Time: $\mathcal{O}(n)$

"Point.h"41d8dc, 9 lines

```
typedef Point<double> P;
P polygonCenter(const vector<P>& v) {
    P res(0, 0); double A = 0;
    for (int i = 0, j = sz(v) - 1; i < sz(v); j = i++) {
        res = res + (v[i] + v[j]) * v[j].cross(v[i]);
        A += v[j].cross(v[i]);
    }
    return res / A / 3;
}
```

PolygonCut.h

Description:

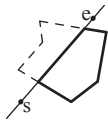
Returns a vector with the vertices of a polygon with everything to the left of the line going from s to e cut away.

Usage: vector<P> p = ...;

p = polygonCut(p, P(0,0), P(1,0));

"Point.h", "LineIntersection.h"

d41d8c, 13 lines



```
typedef Point<double> P;
vector<P> polygonCut(const vector<P>& poly, P s, P e) {
    vector<P> res;
    rep(i,0,sz(poly)) {
        P cur = poly[i], prev = i ? poly[i-1] : poly.back();
        bool side = s.cross(e, cur) < 0;
        if (side != (s.cross(e, prev) < 0))
            res.push_back(lineInter(s, e, cur, prev).second);
        if (side)
            res.push_back(cur);
    }
    return res;
}
```

Minkowski.h

Description:

Minkowski sum of two convex polygons. Make sure both polygons have at least 2 points !!!!!

Time: $\mathcal{O}(n + m)$

"Point.h"

d41d8c, 20 lines

```
template<class T> void reorder_polygon(vector<T> &P) {
    size_t pos = 0;
    for (size_t i = 1; i < P.size(); i++) {
        if (P[i].y < P[pos].y ||
            (P[i].y == P[pos].y && P[i].x < P[pos].x))
            pos = i;
    } rotate(P.begin(), P.begin() + pos, P.end());
}

template<class T> vector<T> Mink(vector<T> P, vector<T> Q) {
    reorder_polygon(P); reorder_polygon(Q);
    P.push_back(P[0]); P.push_back(P[1]);
    Q.push_back(Q[0]); Q.push_back(Q[1]);
    vector<T> result; size_t i = 0, j = 0;
    while (i < P.size() - 2 || j < Q.size() - 2) {
        result.push_back(P[i] + Q[j]);
        auto cross = (P[i + 1] - P[i]).cross(Q[j + 1] - Q[j]);
        if (cross >= 0 && i < P.size() - 2) ++i;
        if (cross <= 0 && j < Q.size() - 2) ++j;
    } return result;
}
```

ConvexHull.h

Description:

Returns a vector of the points of the convex hull in counter-clockwise order. Points on the edge of the hull between two other points are not considered part of the hull.

Time: $\mathcal{O}(n \log n)$

"Point.h"

d41d8c, 13 lines



```
sort(all(pts));
vector<P> h(sz(pts)+1);
int s = 0, t = 0;
for (int it = 2; it--; s = --t, reverse(all(pts)))
    for (P p : pts) {
        while (t >= s + 2 && h[t-2].cross(h[t-1], p) <= 0) t--;
        h[t++] = p;
    }
return {h.begin(), h.begin() + t - (t == 2 && h[0] == h[1])};
}
```

HullDiameter.h

Description:

Returns the two points with max distance on a convex hull (ccw, no duplicate/collinear points).

Time: $\mathcal{O}(n)$

"Point.h"

d41d8c, 12 lines

```
typedef Point<ll> P;
array<P, 2> hullDiameter(vector<P> S) {
    int n = sz(S), j = n < 2 ? 0 : 1;
    pair<ll, array<P, 2>> res({0, {S[0], S[0]}});
    rep(i,0,j)
        for (; j = (j + 1) % n; {
            res = max(res, {(S[i] - S[j]).dist2(), {S[i], S[j]}});
            if ((S[(j + 1) % n] - S[j]).cross(S[i + 1] - S[i]) >= 0)
                break;
        }
    return res.second;
}
```

PointInsideHull.h

Description:

Determine whether a point t lies inside a convex hull (CCW order, with no collinear points). Returns true if point lies within the hull. If strict is true, points on the boundary aren't included.

Time: $\mathcal{O}(\log N)$

"Point.h", "sideOf.h", "OnSegment.h"

d41d8c, 14 lines

```
typedef Point<ll> P;

bool inHull(const vector<P>& l, P p, bool strict = true) {
    int a = 1, b = sz(l) - 1, r = !strict;
    if (sz(l) < 3) return r && onSegment(l[0], l.back(), p);
    if (sideOf(l[0], l[a], l[b]) > 0) swap(a, b);
    if (sideOf(l[0], l[a], p) >= r || sideOf(l[0], l[b], p) <= -r)
        return false;
    while (abs(a - b) > 1) {
        int c = (a + b) / 2;
        (sideOf(l[0], l[c], p) > 0 ? b : a) = c;
    }
    return sgn(l[a].cross(l[b], p)) < r;
}
```

LineHullIntersection.h

Description:

Line-convex polygon intersection. The polygon must be ccw and have no collinear points. lineHull(line, poly) returns a pair describing the intersection of a line with the polygon: $\bullet(-1, -1)$ if no collision, $\bullet(i, -1)$ if touching the corner i , $\bullet(i, i)$ if along side $(i, i + 1)$, $\bullet(i, j)$ if crossing sides $(i, i + 1)$ and $(j, j + 1)$. In the last case, if a corner i is crossed, this is treated as happening on side $(i, i + 1)$. The points are returned in the same order as the line hits the polygon. extrVertex returns the point of a hull with the max projection onto a line.

Time: $\mathcal{O}(\log n)$

"Point.h"

d41d8c, 39 lines

```
#define cmp(i, j) sgn(dir.perp().cross(poly[(i)%n]-poly[(j)%n]))
#define extr(i) cmp(i + 1, i) >= 0 && cmp(i, i - 1 + n) < 0
template <class P> int extrVertex(vector<P>& poly, P dir) {
    int n = sz(poly), lo = 0, hi = n;
    if (extr(0)) return 0;
    while (lo + 1 < hi) {
```

kdTree.h

Description:

KD-tree (2d, can be extended to 3d)

"Point.h"

d41d8c, 63 lines

```
int m = (lo + hi) / 2;
if (extr(m)) return m;
int ls = cmp(lo + 1, lo), ms = cmp(m + 1, m);
(ls < ms || (ls == ms && ls == cmp(lo, m)) ? hi : lo) = m;
}
return lo;
}
```

```
#define cmpL(i) sgn(a.cross(poly[i], b))
template <class P>
array<int, 2> lineHull(P a, P b, vector<P>& poly) {
    int endA = extrVertex(poly, (a - b).perp());
    int endB = extrVertex(poly, (b - a).perp());
    if (cmpL(endA) < 0 || cmpL(endB) > 0)
        return {-1, -1};
    array<int, 2> res;
    rep(i,0,2) {
        int lo = endB, hi = endA, n = sz(poly);
        while ((lo + 1) % n != hi) {
            int m = ((lo + hi + (lo < hi ? 0 : n)) / 2) % n;
            (cmpL(m) == cmpL(endB) ? lo : hi) = m;
        }
        res[i] = (lo + !cmpL(hi)) % n;
        swap(endA, endB);
    }
    if (res[0] == res[1]) return {res[0], -1};
    if (!cmpL(res[0]) && !cmpL(res[1]))
        switch ((res[0] - res[1] + sz(poly) + 1) % sz(poly)) {
            case 0: return {res[0], res[0]};
            case 2: return {res[1], res[1]};
        }
    return res;
}
```

ClosestPair.h

Description:

Finds the closest pair of points.

Time: $\mathcal{O}(n \log n)$

"Point.h"

d41d8c, 17 lines

8.4 Misc. Point Set Problems

```
typedef Point<ll> P;
pair<P, P> closest(vector<P> v) {
    assert(sz(v) > 1);
    set<P> S;
    sort(all(v), [](P a, P b) { return a.y < b.y; });
    pair<ll, pair<P, P>> ret{LLONG_MAX, {P(), P()}};
    int j = 0;
    for (P p : v) {
        P d{1 + (ll)sqrt(ret.first), 0};
        while (v[j].y <= p.y - d.x) S.erase(v[j++]);
        auto lo = S.lower_bound(p - d), hi = S.upper_bound(p + d);
        for (; lo != hi; ++lo)
            ret = min(ret, {( *lo - p).dist2(), { *lo, p } });
        S.insert(p);
    }
    return ret.second;
}
```

kdTree.h

Description:

KD-tree (2d, can be extended to 3d)

"Point.h"

d41d8c, 63 lines

```
bool on_x(const P& a, const P& b) { return a.x < b.x; }
bool on_y(const P& a, const P& b) { return a.y < b.y; }

struct Node {
```

```
P pt; // if this is a leaf, the single point in it
T x0 = INF, x1 = -INF, y0 = INF, y1 = -INF; // bounds
Node *first = 0, *second = 0;

T distance(const P& p) { // min squared distance to a point
    T x = (p.x < x0 ? x0 : p.x > x1 ? x1 : p.x);
    T y = (p.y < y0 ? y0 : p.y > y1 ? y1 : p.y);
    return (P(x,y) - p).dist2();
}

Node(vector<P>&& vp) : pt(vp[0]) {
    for (P p : vp) {
        x0 = min(x0, p.x); x1 = max(x1, p.x);
        y0 = min(y0, p.y); y1 = max(y1, p.y);
    }
    if (vp.size() > 1) {
        // split on x if width >= height (not ideal...)
        sort(all(vp), x1 - x0 >= y1 - y0 ? on_x : on_y);
        // divide by taking half the array for each child (not
        // best performance with many duplicates in the middle)
        int half = sz(vp)/2;
        first = new Node({vp.begin(), vp.begin() + half});
        second = new Node({vp.begin() + half, vp.end()});
    }
};

struct KDTree {
    Node* root;
    KDTree(const vector<P>& vp) : root(new Node({all(vp)})) {}

    pair<T, P> search(Node *node, const P& p) {
        if (!node->first) {
            // uncomment if we should not find the point itself:
            // if (p == node->pt) return {INF, P()};
            return make_pair((p - node->pt).dist2(), node->pt);
        }

        Node *f = node->first, *s = node->second;
        T bfirst = f->distance(p), bsec = s->distance(p);
        if (bfirst > bsec) swap(bsec, bfirst), swap(f, s);

        // search closest side first, other side if needed
        auto best = search(f, p);
        if (bsec < best.first)
            best = min(best, search(s, p));
        return best;
    }

    // find nearest point to a point, and its squared distance
    // (requires an arbitrary operator< for Point)
    pair<T, P> nearest(const P& p) {
        return search(root, p);
    }
};
```

FastDelaunay.h
Description: Fast Delaunay triangulation. Each circumcircle contains none of the input points. There must be no duplicate points. If all points are on a line, no triangles will be returned. Should work for doubles as well, though there may be precision issues in 'circ'. Returns triangles in order {t[0][0], t[0][1], t[0][2], t[1][0], ... }, all counter-clockwise.
Time: $O(n \log n)$

"Point.h"	d41d8c, 88 lines
-----------	------------------

```
typedef Point<ll> P;
typedef struct Quad* Q;
typedef __int128_t ll1; // (can be ll if coords are < 2e4)
P arb(LLONG_MAX, LLONG_MAX); // not equal to any other point
```

```
struct Quad {
    Q rot, o; P p = arb; bool mark;
    P& F() { return r()->p; }
    Q& r() { return rot->rot; }
    Q prev() { return rot->o->rot; }
    Q next() { return r()->prev(); }
} *H;

bool circ(P p, P a, P b, P c) { // is p in the circumcircle?
    ll1 p2 = p.dist2(), A = a.dist2()-p2,
        B = b.dist2()-p2, C = c.dist2()-p2;
    return p.cross(a,b)*C + p.cross(b,c)*A + p.cross(c,a)*B > 0;
}

Q makeEdge(P orig, P dest) {
    Q r = H ? H : new Quad(new Quad{new Quad{new Quad{0}}});
    H = r->o; r->r()->r() = r;
    rep(i,0,4) r = r->rot, r->p = arb, r->o = i & 1 ? r : r->r();
    r->p = orig; r->F() = dest;
    return r;
}

void splice(Q a, Q b) {
    swap(a->o->rot->o, b->o->rot->o); swap(a->o, b->o);
}

Q connect(Q a, Q b) {
    Q q = makeEdge(a->F(), b->p);
    splice(q, a->next());
    splice(q->r(), b);
    return q;
}

pair<Q,Q> rec(const vector<P>& s) {
    if (sz(s) <= 3) {
        Q a = makeEdge(s[0], s[1]), b = makeEdge(s[1], s.back());
        if (sz(s) == 2) return { a, a->r() };
        splice(a->r(), b);
        auto side = s[0].cross(s[1], s[2]);
        Q c = side ? connect(b, a) : 0;
        return {side < 0 ? c->r() : a, side < 0 ? c : b->r() };
    }

#define H(e) e->F(), e->p
#define valid(e) (e->F().cross(H(base)) > 0)
    Q A, B, ra, rb;
    int half = sz(s) / 2;
    tie(ra, A) = rec({all(s) - half});
    tie(B, rb) = rec({sz(s) - half + all(s)});
    while ((B->p.cross(H(A)) < 0 && (A = A->next())) ||
        (A->p.cross(H(B)) > 0 && (B = B->r()->o)));
    Q base = connect(B->r(), A);
    if (A->p == ra->p) ra = base->r();
    if (B->p == rb->p) rb = base;

#define DEL(e, init, dir) Q e = init->dir; if (valid(e)) \
    while (circ(e->dir->F(), H(base), e->F())) { \
        Q t = e->dir; \
        splice(e, e->prev()); \
        splice(e->r(), e->r()->prev()); \
        e->o = H; H = e; e = t; \
    }
    for (;;) {
        DEL(LC, base->r(), o); DEL(RC, base, prev());
        if (!valid(LC) && !valid(RC)) break;
        if (!valid(LC) || (valid(RC) && circ(H(RC), H(LC))))
            base = connect(RC, base->r());
        else
            base = connect(base->r(), LC->r());
    }
    return { ra, rb };
}
```

```
vector<P> triangulate(vector<P> pts) {
    sort(all(pts)); assert(unique(all(pts)) == pts.end());
    if (sz(pts) < 2) return {};
    Q e = rec(pts).first;
    vector<Q> q = {e};
    int qi = 0;
    while (e->o->F().cross(e->F(), e->p) < 0) e = e->o;
#define ADD { Q c = e; do { c->mark = 1; pts.push_back(c->p); \
    q.push_back(c->r()); c = c->next(); } while (c != e); }
    ADD; pts.clear();
    while (qi < sz(q)) if (!(e = q[qi++])->mark) ADD;
    return pts;
}
```

8.5 3D
PolyhedronVolume.h
Description: Magic formula for the volume of a polyhedron. Faces should point outwards.

	d41d8c, 6 lines
--	-----------------

```
template<class V, class L>
double signedPolyVolume(const V& p, const L& trilst) {
    double v = 0;
    for (auto i : trilst) v += p[i.a].cross(p[i.b]).dot(p[i.c]);
    return v / 6;
}
```

Point3D.h
Description: Class to handle points in 3D space. T can be e.g. double or long long.

	d41d8c, 32 lines
--	------------------

```
template<class T> struct Point3D {
    typedef Point3D P;
    typedef const P& R;
    T x, y, z;
    explicit Point3D(T x=0, T y=0, T z=0) : x(x), y(y), z(z) {}
    bool operator<(R p) const {
        return tie(x, y, z) < tie(p.x, p.y, p.z); }
    bool operator==(R p) const {
        return tie(x, y, z) == tie(p.x, p.y, p.z); }
    P operator+(R p) const { return P(x+p.x, y+p.y, z+p.z); }
    P operator-(R p) const { return P(x-p.x, y-p.y, z-p.z); }
    P operator*(T d) const { return P(x*d, y*d, z*d); }
    P operator/(T d) const { return P(x/d, y/d, z/d); }
    T dot(R p) const { return x*p.x + y*p.y + z*p.z; }
    P cross(R p) const {
        return P(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x);
    }
    T dist2() const { return x*x + y*y + z*z; }
    double dist() const { return sqrt((double)dist2()); }
    //Azimuthal angle (longitude) to x-axis in interval [-pi, pi]
    double phi() const { return atan2(y, x); }
    //Zenith angle (latitude) to the z-axis in interval [0, pi]
    double theta() const { return atan2(sqrt(x*x+y*y), z); }
    P unit() const { return *this/(T)dist(); } //makes dist()==1
    //returns unit vector normal to *this and p
    P normal(P p) const { return cross(p).unit(); }
    //returns point rotated 'angle' radians ccw around axis
    P rotate(double angle, P axis) const {
        double s = sin(angle), c = cos(angle); P u = axis.unit();
        return u*dot(u)*(1-c) + (*this)*c - cross(u)*s;
    }
};
```

3dHull.h
Description: Computes all faces of the 3-dimension hull of a point set. *No four points must be coplanar*, or else random results will be returned. All faces will point outwards.

Time: $\mathcal{O}(n^2)$	
"Point3D.h"	d41d8c, 49 lines
<pre>typedef Point3D<double> P3;</pre>	
<pre>struct PR { void ins(int x) { (a == -1 ? a : b) = x; } void rem(int x) { (a == x ? a : b) = -1; } int cnt() { return (a != -1) + (b != -1); } int a, b; }; struct F { P3 q; int a, b, c; };</pre>	
<pre>vector<F> hull3d(const vector<P3>& A) { assert(sz(A) >= 4); vector<vector<PR>> E(sz(A), vector<PR>(sz(A), {-1, -1})); #define E(x,y) E[f.x][f.y] vector<F> FS; auto mf = [&](int i, int j, int k, int l) { P3 q = (A[j] - A[i]).cross((A[k] - A[i])); if (q.dot(A[l]) > q.dot(A[i])) q = q * -1; F f{q, i, j, k}; E(a,b).ins(k); E(a,c).ins(j); E(b,c).ins(i); FS.push_back(f); }; rep(i,0,4) rep(j,i+1,4) rep(k,j+1,4) mf(i, j, k, 6 - i - j - k); rep(i,4,sz(A)) { rep(j,0,sz(FS)) { F f = FS[j]; if(f.q.dot(A[i]) > f.q.dot(A[f.a])) { E(a,b).rem(f.c); E(a,c).rem(f.b); E(b,c).rem(f.a); swap(FS[j--], FS.back()); FS.pop_back(); } } int nw = sz(FS); rep(j,0,nw) { F f = FS[j]; #define C(a, b, c) if (E(a,b).cnt() != 2) mf(f.a, f.b, i, f.c); C(a, b, c); C(a, c, b); C(b, c, a); } for (F& it : FS) if ((A[it.b] - A[it.a]).cross(A[it.c] - A[it.a]).dot(it.q) <= 0) swap(it.c, it.b); return FS; }; };</pre>	

sphericalDistance.h

Description: Returns the shortest distance on the sphere with radius r between the points with azimuthal angles (longitude) f_1 (ϕ_1) and f_2 (ϕ_2) from x axis and zenith angles (latitude) t_1 (θ_1) and t_2 (θ_2) from z axis (0 = north pole). All angles measured in radians. The algorithm starts by converting the spherical coordinates to cartesian coordinates so if that is what you have you can use only the two last rows. $dx \cdot radius$ is then the difference between the two points in the x direction and $d \cdot radius$ is the total distance between the points.	d41d8c, 8 lines
<pre>double sphericalDistance(double f1, double t1, double f2, double t2, double radius) { double dx = sin(t2)*cos(f2) - sin(t1)*cos(f1); double dy = sin(t2)*sin(f2) - sin(t1)*sin(f1); double dz = cos(t2) - cos(t1); double d = sqrt(dx*dx + dy*dy + dz*dz); return radius*2*asin(d/2); };</pre>	

}	
---	--

Strings (9)

KMP.h

Description: $pi[x]$ computes the length of the longest prefix of s that ends at x , other than $s[0...x]$ itself (abacaba -> 0010123). Can be used to find all occurrences of a string.	
Time: $\mathcal{O}(n)$	d41d8c, 16 lines

<pre>vi pi(const string& s) { vi p(sz(s)); rep(i,1,sz(s)) { int g = p[i-1]; while (g && s[i] != s[g]) g = p[g-1]; p[i] = g + (s[i] == s[g]); } return p; } vi match(const string& s, const string& pat) { vi p = pi(pat + '\0' + s), res; rep(i,sz(p)-sz(s),sz(p)) if (p[i] == sz(pat)) res.push_back(i - 2 * sz(pat)); return res; }</pre>	
--	--

Zfunc.h

Description: $z[x]$ computes the length of the longest common prefix of $s[i:]$ and s , except $z[0] = 0$. (abacaba -> 0010301)	
Time: $\mathcal{O}(n)$	d41d8c, 12 lines

<pre>vi Z(const string& S) { vi z(sz(S)); int l = -1, r = -1; rep(i,1,sz(S)) { z[i] = i >= r ? 0 : min(r - i, z[i - l]); while (i + z[i] < sz(S) && S[i + z[i]] == S[z[i]]) z[i]++; if (i + z[i] > r) l = i, r = i + z[i]; } return z; }</pre>	
---	--

Manacher.h

Description: For each position in a string, computes $p[0][i] =$ half length of longest even palindrome around pos i , $p[1][i] =$ longest odd (half rounded down).	
Time: $\mathcal{O}(N)$	d41d8c, 13 lines

<pre>array<vi, 2> manacher(const string& s) { int n = sz(s); array<vi,2> p = {vi(n+1), vi(n)}; rep(z,0,2) for (int i=0,l=0,r=0; i < n; i++) { int t = r-i+!z; if (i<r) p[z][i] = min(t, p[z][l+t]); int L = i-p[z][i], R = i+p[z][i]-!z; while (L>=1 && R+1<n && s[L-1] == s[R+1]) p[z][i]++, L--, R++; if (R>r) l=L, r=R; } return p; }</pre>	
---	--

MinRotation.h

Description: Finds the lexicographically smallest rotation of a string.	
Usage: rotate(v.begin(), v.begin()+minRotation(v), v.end());	
Time: $\mathcal{O}(N)$	d41d8c, 8 lines

<pre>int minRotation(string s) { int a=0, N=sz(s); s += s; rep(b,0,N) rep(k,0,N) { if (a+k == b s[a+k] < s[b+k]) {b += max(0, k-1); break;} if (s[a+k] > s[b+k]) { a = b; break; } } return a; }</pre>	
---	--

SuffixArray.h

Description: Builds suffix array for a string. $sa[i]$ is the starting index of the suffix which is i 'th in the sorted suffix array. The returned vector is of size $n + 1$, and $sa[0] = n$. The lcp array contains longest common prefixes for neighbouring strings in the suffix array: $lcp[i] = lcp(sa[i], sa[i-1])$, $lcp[0] = 0$. The input string must not contain any zero bytes.	
Time: $\mathcal{O}(n \log n)$	d41d8c, 23 lines

<pre>struct SuffixArray { vi sa, lcp; SuffixArray(string& s, int lim=256) { // or basic_string<int> int n = sz(s) + 1, k = 0, a, b; vi x(all(s)+1), y(n), ws(max(n, lim)), rank(n); sa = lcp = y, iota(all(sa), 0); for (int j = 0, p = 0; p < n; j = max(1, j * 2), lim = p) { p = j, iota(all(y), n - j); rep(i,0,n) if (sa[i] >= j) y[p++] = sa[i] - j; fill(all(ws), 0); rep(i,0,n) ws[x[i]]++; rep(i,1,lim) ws[i] += ws[i - 1]; for (int i = n; i--;) sa[--ws[x[y[i]]]] = y[i]; swap(x, y), p = 1, x[sa[0]] = 0; rep(i,1,n) a = sa[i - 1], b = sa[i], x[b] = (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1 : p++; } rep(i,1,n) rank[sa[i]] = i; for (int i = 0, j; i < n - 1; lcp[rank[i++]] = k) for (k && k--, j = sa[rank[i] - 1]; s[i + k] == s[j + k]; k++); } };</pre>	
---	--

SuffixTree.h

Description: Ukkonen's algorithm for online suffix tree construction. Each node contains indices $[l, r)$ into the string, and a list of child nodes. Suffixes are given by traversals of this tree, joining $[l, r)$ substrings. The root is 0 (has $l = -1, r = 0$), non-existent children are -1. To get a complete tree, append a dummy symbol – otherwise it may contain an incomplete path (still useful for substring matching, though).	
Time: $\mathcal{O}(26N)$	d41d8c, 50 lines

<pre>struct SuffixTree { enum { N = 200010, ALPHA = 26 }; // N ~ 2*maxlen+10 int toi(char c) { return c - 'a'; } string a; // v = cur node, q = cur position int t[N][ALPHA], l[N], r[N], p[N], s[N], v=0, q=0, m=2; void ukkadd(int i, int c) { suff: if (r[v]<=q) { if (t[v][c]==-1) { t[v][c]=m; l[m]=i; p[m++]=v; v=s[v]; q=r[v]; goto suff; } v=t[v][c]; q=l[v]; } if (q==-1 c==toi(a[q])) q++; else { l[m+1]=i; p[m+1]=m; l[m]=l[v]; r[m]=q; p[m]=p[v]; t[m][c]=m+1; t[m][toi(a[q])]=v; } } };</pre>	
---	--

```
        l[v]=q; p[v]=m; t[p[m]][toi(a[l[m]])]=m;
        v=s[p[m]]; q=l[m];
        while (q<r[m]) { v=t[v][toi(a[q])]; q+=r[v]-l[v]; }
        if (q==r[m]) s[m]=v; else s[m]=m+2;
        q=r[v]-(q-r[m]); m+=2; goto suff;
    }
}

SuffixTree(string a) : a(a) {
    fill(r,r+N,sz(a));
    memset(s, 0, sizeof s);
    memset(t, -1, sizeof t);
    fill(t[1],t[1]+ALPHA,0);
    s[0] = 1; l[0] = l[1] = -1; r[0] = r[1] = p[0] = p[1] = 0;
    rep(i,0,sz(a)) ukkadd(i, toi(a[i]));
}

// example: find longest common substrng (uses ALPHA = 28)
pii best;
int lcs(int node, int i1, int i2, int olen) {
    if (l[node] <= i1 && i1 < r[node]) return 1;
    if (l[node] <= i2 && i2 < r[node]) return 2;
    int mask = 0, len = node ? olen + (r[node] - l[node]) : 0;
    rep(c,0,ALPHA) if (t[node][c] != -1)
        mask |= lcs(t[node][c], i1, i2, len);
    if (mask == 3)
        best = max(best, {len, r[node] - len});
    return mask;
}

static pii LCS(string s, string t) {
    SuffixTree st(s + (char)('z' + 1) + t + (char)('z' + 2));
    st.lcs(0, sz(s), sz(s) + 1 + sz(t), 0);
    return st.best;
}
};
```

Hashing.h

Description: Self-explanatory methods for string hashing. d41d8c, 24 lines

```
const ll MXH = 2; const ll BASE = 257;
const ll Mod[MXH] = {(ll)(1e9 + 7), (ll)(1e9 + 9)};
void mkay(int th, ll &x){
    if(x > Mod[th]){ x -= Mod[th]; }
}
ll pw[MXH][MXN], H[MXH][MXN];
void InitPow(){
    for(int th = 0; th < MXH; th++){
        pw[th][0] = 1;
        for(int i = 1; i < MXN; i++) pw[th][i] = pw[th][i - 1] *
            BASE % Mod[th];
    }
}
void InitHash(ll &n, string &s){
    assert(s[0] == '$' && s.size() == n + 1);
    for(int th = 0; th < MXH; th++){
        H[th][0] = 0;
        for(int i = 1; i <= n; i++){
            H[th][i] = (H[th][i - 1] * BASE + (s[i] - 'a' + 1)) % Mod[th];
        }
    }
}
inline ll Hash(int th, ll l, ll r){
    return (H[th][r] - H[th][l - 1] * pw[th][r - l + 1] % Mod[th] +
        Mod[th]) % Mod[th];
}
// Call InitPow(), InitHash(n, s); in main
```

PalHashing.h

Description: Checking if the string is palindrome d41d8c, 31 lines

```
ll n; string s; //! Length is important in RH!
ll pw[MXH][MXN], H[MXH][MXN], RH[MXH][MXN];
void InitPow(){ //RH: ith suffix Hash, i <=> n - i + 1
    for(int th = 0; th < MXH; th++){
        pw[th][0] = 1;
        for(int i = 1; i < MXN; i++) pw[th][i] = pw[th][i - 1] *
            BASE % Mod[th];
    }
}
void InitHash(){
    assert(s[0] == '$' && s.size() == n + 1);
    for(int th = 0; th < MXH; th++){
        H[th][0] = RH[th][0] = 0;
        for(int i = 1; i <= n; i++){
            H[th][i] = (H[th][i - 1] * BASE + (s[i] - 'a' + 1)) % Mod[th];
            RH[th][i] = (RH[th][i - 1] * BASE + (s[n - i + 1] - 'a' + 1)) % Mod[th];
        }
    }
}
inline ll Hash(int th, ll l, ll r){
    return (H[th][r] - H[th][l - 1] * pw[th][r - l + 1] % Mod[th] +
        Mod[th]) % Mod[th];
}
inline ll RHash(int th, ll l, ll r){
    // H(l, r) -> H[l] - H[r + 1] * pw[len]
    return (RH[th][n - l + 1] - RH[th][n - (r + 1) + 1] * pw[th][r - l + 1] % Mod[th] + Mod[th]) % Mod[th];
}
inline ll IsPal(ll l, ll r){
    for(int th = 0; th < MXH; th++){
        if(Hash(th, l, r) != RHash(th, l, r))
            return 0;
        return 1;
    }
}
```

AhoCorasick.h

Description: Aho-Corasick automaton, used for multiple pattern matching. Initialize with AhoCorasick ac(patterns); the automaton start node will be at index 0. find(word) returns for each position the index of the longest word that ends there, or -1 if none. findAll(—, word) finds all words (up to $N\sqrt{N}$ many if no duplicate patterns) that start at each position (shortest first). Duplicate patterns are allowed; empty patterns are not. To find the longest words that start at each position, reverse all input. For large alphabets, split each symbol into chunks, with sentinel bits for symbol boundaries. Time: construction takes $\mathcal{O}(26N)$, where N = sum of length of patterns. find(x) is $\mathcal{O}(N)$, where N = length of x. findAll is $\mathcal{O}(NM)$. d41d8c, 84 lines

```
const ll SGM = 26;
int n, q, ts = 1, timer;
int Q[MXN], Ver[MXN], seg[MXS], Lazy[MXS];
int nxt[MXN][SGM], lps[MXN];
char s[MXN];
void Add(int id){
    scanf("%s", s); int sz = strlen(s);
    int u = 1;
    for(int h = 0; h < sz; h++){
        if(!nxt[u][s[h] - 'a']) nxt[u][s[h] - 'a'] = ++ ts;
        u = nxt[u][s[h] - 'a'];
    }
    Ver[id] = u;
}
void Aho(){
    int L = 0, R = 0;
    for(int i = 0; i < SGM; i++){
```

```
        if(!nxt[l][i]) nxt[l][i] = 1;
        else{
            Q[R++] = nxt[l][i];
            lps[nxt[l][i]] = 1;
        }
    }
    while(L < R){
        int u = Q[L++];
        adj[lps[u]].push_back(u);
        for(int c = 0; c < SGM; c++){
            if(!nxt[u][c]) nxt[u][c] = nxt[lps[u]][c];
            else{
                lps[nxt[u][c]] = nxt[lps[u]][c];
                Q[R++] = nxt[u][c];
            }
        }
    }
}
void dfs(int u, int par){
    Stm[u] = ++ timer;
    for(auto v : adj[u]){
        if(v == par) continue;
        dfs(v, u);
    }
    Ftm[u] = timer;
}
void Shift(int id, int s, int e){
    if(!Lazy[id]) return;
    seg[id] += Lazy[id] * ln;
    if(ln > 1){
        Lazy[lc] += Lazy[id];
        Lazy[rc] += Lazy[id];
    }
    Lazy[id] = 0;
}
void Upd(int l, int r, int x, int id = 1, int s = 1, int e = ts){
    if(l == r) Shift(id, s, e);
    if(e < l || s > r) return;
    if(l <= s && e <= r){
        Lazy[id] += x; Shift(id, s, e);
        return;
    }
    Upd(l, r, x, lc, s, md), Upd(l, r, x, rc, dm, e);
    seg[id] = seg[lc] + seg[rc];
}
ll Get(int p, int id = 1, int s = 1, int e = ts){
    Shift(id, s, e);
    if(ln == 1) return seg[id];
    if(p <= md) return Get(p, lc, s, md);
    return Get(p, rc, dm, e);
}

int main(){
    scanf("%d%d", &q, &n); for(int i = 1; i <= n; i++) Add(i);
    Aho();
    dfs(1, 0); assert(timer == ts);
    for(int i = 1; i <= n; i++){
        Upd(Stm[Ver[i]], Ftm[Ver[i]], +1);
    }
    while(q--){
        ll Now = 0, ans = 1;
        scanf("%s", s); len = strlen(s);
        for(int i = 0; i < len; i++){
            ans = nxt[ans][s[i] - 'a'];
            Now += Get(Stm[ans]);
        }
        printf("%lld\n", Now);
    }
}
```


Various (10)

10.1 Intervals

IntervalContainer.h

Description: Add and remove intervals from a set of disjoint intervals. Will merge the added interval with any overlapping intervals in the set when adding. Intervals are [inclusive, exclusive).

Time: $\mathcal{O}(\log N)$

```
set<pii>::iterator addInterval(set<pii>& is, int L, int R) {
    if (L == R) return is.end();
    auto it = is.lower_bound({L, R}), before = it;
    while (it != is.end() && it->first <= R) {
        R = max(R, it->second);
        before = it = is.erase(it);
    }
    if (it != is.begin() && (--it)->second >= L) {
        L = min(L, it->first);
        R = max(R, it->second);
        is.erase(it);
    }
    return is.insert(before, {L,R});
}
```

```
void removeInterval(set<pii>& is, int L, int R) {
    if (L == R) return;
    auto it = addInterval(is, L, R);
    auto r2 = it->second;
    if (it->first == L) is.erase(it);
    else (int&)it->second = L;
    if (R != r2) is.emplace(R, r2);
}
```

IntervalCover.h

Description: Compute indices of smallest set of intervals covering another interval. Intervals should be [inclusive, exclusive). To support [inclusive, inclusive], change (A) to add | R.empty(). Returns empty set on failure (or if G is empty).

Time: $\mathcal{O}(N \log N)$

```
template<class T>
vi cover(pair<T, T> G, vector<pair<T, T>> I) {
    vi S(sz(I)), R;
    iota(all(S), 0);
    sort(all(S), [&](int a, int b) { return I[a] < I[b]; });
    T cur = G.first;
    int at = 0;
    while (cur < G.second) { // (A)
        pair<T, int> mx = make_pair(cur, -1);
        while (at < sz(I) && I[S[at]].first <= cur) {
            mx = max(mx, make_pair(I[S[at]].second, S[at]));
            at++;
        }
        if (mx.second == -1) return {};
        cur = mx.first;
        R.push_back(mx.second);
    }
    return R;
}
```

ConstantIntervals.h

Description: Split a monotone function on [from, to) into a minimal set of half-open intervals on which it has the same value. Runs a callback g for each such interval.

Usage: constantIntervals(0, sz(v), [&](int x){return v[x];}, [&](int lo, int hi, T val){...});

Time: $\mathcal{O}(k \log \frac{n}{k})$

```
template<class F, class G, class T>
void rec(int from, int to, F& f, G& g, int& i, T& p, T q) {
    if (p == q) return;
    if (from == to) {
        g(i, to, p);
        i = to; p = q;
    } else {
        int mid = (from + to) >> 1;
        rec(from, mid, f, g, i, p, f(mid));
        rec(mid+1, to, f, g, i, p, q);
    }
}

template<class F, class G>
void constantIntervals(int from, int to, F f, G g) {
    if (to <= from) return;
    int i = from; auto p = f(i), q = f(to-1);
    rec(from, to-1, f, g, i, p, q);
    g(i, to, q);
}
```

10.2 Misc. algorithms

TernarySearch.h

Description: Find the smallest i in $[a, b]$ that maximizes $f(i)$, assuming that $f(a) < \dots < f(i) \geq \dots \geq f(b)$. To reverse which of the sides allows non-strict inequalities, change the $<$ marked with (A) to $<=$, and reverse the loop at (B). To minimize f , change it to $>$, also at (B).

Usage: int ind = ternSearch(0,n-1,[&](int i){return a[i];});

Time: $\mathcal{O}(\log(b-a))$

```
template<class F>
int ternSearch(int a, int b, F f) {
    assert(a <= b);
    while (b - a >= 5) {
        int mid = (a + b) / 2;
        if (f(mid) < f(mid+1)) a = mid; // (A)
        else b = mid+1;
    }
    rep(i,a+1,b+1) if (f(a) < f(i)) a = i; // (B)
    return a;
}
```

LIS.h

Description: Compute indices for the longest increasing subsequence.

Time: $\mathcal{O}(N \log N)$

```
template<class I> vi lis(const vector<I>& S) {
    if (S.empty()) return {};
    vi prev(sz(S));
    typedef pair<I, int> p;
    vector<p> res;
    rep(i,0,sz(S)) {
        // change 0 => i for longest non-decreasing subsequence
        auto it = lower_bound(all(res), p{S[i], 0});
        if (it == res.end()) res.emplace_back(), it = res.end()-1;
        *it = {S[i], i};
        prev[i] = it == res.begin() ? 0 : (it-1)->second;
    }
    int L = sz(res), cur = res.back().second;
    vi ans(L);
    while (L--) ans[L] = cur, cur = prev[cur];
    return ans;
}
```

FastKnapsack.h

Description: Given N non-negative integer weights w and a non-negative target t , computes the maximum $S \leq t$ such that S is the sum of some subset of the weights.

Time: $\mathcal{O}(N \max(w_i))$

```
int knapsack(vi w, int t) {
    int a = 0, b = 0, x;
    while (b < sz(w) && a + w[b] <= t) a += w[b++];
    if (b == sz(w)) return a;
    int m = *max_element(all(w));
    vi u, v(2*m, -1);
    v[a+m-t] = b;
    rep(i,b,sz(w)) {
        u = v;
        rep(x,0,m) v[x+w[i]] = max(v[x+w[i]], u[x]);
        for (x = 2*m; --x > m;) rep(j, max(0,u[x]), v[x])
            v[x-w[j]] = max(v[x-w[j]], j);
    }
    for (a = t; v[a+m-t] < 0; a--);
    return a;
}
```

10.3 Dynamic programming

KnuthDP.h

Description: When doing DP on intervals: $a[i][j] = \min_{i < k < j} (a[i][k] + a[k][j]) + f(i, j)$, where the (minimal) optimal k increases with both i and j , one can solve intervals in increasing order of length, and search $k = p[i][j]$ for $a[i][j]$ only between $p[i][j-1]$ and $p[i+1][j]$. This is known as Knuth DP. Sufficient criteria for this are if $f(b, c) \leq f(a, d)$ and $f(a, c) + f(b, d) \leq f(a, d) + f(b, c)$ for all $a \leq b \leq c \leq d$. Consider also: LineContainer (ch. Data structures), monotone queues, ternary search.

Time: $\mathcal{O}(N^2)$

DivideAndConquerDP.h

Description: Given $a[i] = \min_{lo(i) \leq k < hi(i)} (f(i, k))$ where the (minimal) optimal k increases with i , computes $a[i]$ for $i = L..R-1$.

Time: $\mathcal{O}((N + (hi-lo)) \log N)$

```
struct DP { // Modify at will:
    int lo(int ind) { return 0; }
    int hi(int ind) { return ind; }
    ll f(int ind, int k) { return dp[ind][k]; }
    void store(int ind, int k, ll v) { res[ind] = pii(k, v); }

    void rec(int L, int R, int LO, int HI) {
        if (L >= R) return;
        int mid = (L + R) >> 1;
        pair<ll, int> best(LLONG_MAX, LO);
        rep(k, max(LO, lo(mid)), min(HI, hi(mid)))
            best = min(best, make_pair(f(mid, k), k));
        store(mid, best.second, best.first);
        rec(L, mid, LO, best.second+1);
        rec(mid+1, R, best.second, HI);
    }
    void solve(int L, int R) { rec(L, R, INT_MIN, INT_MAX); }
};
```

10.4 Debugging tricks

- signal(SIGSEGV, [](int) { _Exit(0); }); converts segfaults into Wrong Answers. Similarly one can catch SIGABRT (assertion failures) and SIGFPE (zero divisions). _GLIBCXX_DEBUG failures generate SIGABRT (or SIGSEGV on gcc 5.4.0 apparently).
- feenableexcept(29); kills the program on NaNs (1), 0-divs (4), infinities (8) and denormals (16).

10.5 Optimization tricks

`__builtin_ia32_ldmxcsr(40896);` disables denormals (which make floats 20x slower near their minimum value).

10.5.1 Bit hacks

- `x & -x` is the least bit in `x`.
- ```
for (int x = m; x;) { --x &= m; ... }
for(sub=mask; ;sub = (sub-1)&mask){
 //[Update] if(sub == 0) break; }
loops over all subset masks of m (except m itself).
```
- `c = x&-x, r = x+c; (((r^x) >> 2)/c) | r` is the next number after `x` with the same number of bits set.
- ```
rep(b,0,K) rep(i,0,(1 << K))
    if (i & 1 << b) D[i] += D[i^(1 << b)];
    for(j = 0; j < MXN;){for(mask = 0; mask < MXM)
if(bit(mask, j)) dp[mask^(1<<j)]+=dp[mask];} }
computes all sums of subsets.
```

10.5.2 Pragmas

- `#pragma GCC optimize ("Ofast")` will make GCC auto-vectorize loops and optimizes floating points better.
- `#pragma GCC target ("avx2")` can double performance of vectorized code, but causes crashes on old machines.
- `#pragma GCC optimize ("trapv")` kills the program on integer overflows (but is really slow).

FastMod.h

Description: Compute $a\%b$ about 5 times faster than usual, where b is constant but not known at compile time. Returns a value congruent to $a \pmod b$ in the range $[0, 2b)$.

```
typedef unsigned long long ull;
typedef __uint128_t L;
struct FastMod {
    ull b, m;
    FastMod(ull b) : b(b), m(ull((L(1) << 64) / b)) {}
    ull reduce(ull a) {
        ull q = (ull)((L(m) * a) >> 64);
        ull r = a - q * b;
        return r >= b ? r - b : r;
    }
};
FastMod f(2);
// f = FastMod(Mod); Inv[0] = Inv[1] = 1; //fast inverse calculation
// for(int i = 2; i < MXN; i ++){
//     Inv[i] = f.reduce(Mod - f.reduce(1ll * Mod / i * Inv[Mod % i]));
// }
```

FastInput.h

Description: Read an integer from stdin. Usage requires your program to pipe in input from file.
Usage: `./a.out < input.txt`
Time: About 5x as fast as `cin/scanf`.

```
inline char gc() { // like getchar()
    static char buf[1 << 16];
```

```
    static size_t bc, be;
    if (bc >= be) {
        buf[0] = 0, bc = 0;
        be = fread(buf, 1, sizeof(buf), stdin);
    }
    return buf[bc++]; // returns 0 on EOF
}
```

```
int readInt() {
    int a, c;
    while ((a = gc()) < 40);
    if (a == '-' ) return -readInt();
    while ((c = gc()) >= 48) a = a * 10 + c - 48;
    return a - 48;
}
```

BumpAllocator.h

Description: When you need to dynamically allocate many objects and don't care about freeing them. "new X" otherwise has an overhead of something like 0.05us + 16 bytes per allocation.

```
// Either globally or in a single class:
static char buf[450 << 20];
void* operator new(size_t s) {
    static size_t i = sizeof buf;
    assert(s < i);
    return (void*)&buf[i -= s];
}
void operator delete(void*) {}
```

SmallPtr.h

Description: A 32-bit pointer that points into BumpAllocator memory.

```
template<class T> struct ptr {
    unsigned ind;
    ptr(T* p = 0) : ind(p ? unsigned((char*)p - buf) : 0) {
        assert(ind < sizeof buf);
    }
    T& operator*() const { return *(T*)(buf + ind); }
    T* operator->() const { return &*this; }
    T& operator[](int a) const { return (&*this)[a]; }
    explicit operator bool() const { return ind; }
};
```

BumpAllocatorSTL.h

Description: BumpAllocator for STL containers.
Usage: `vector<vector<int, small<int>>> ed(N);`

```
char buf[450 << 20] alignas(16);
size_t buf_ind = sizeof buf;
```

```
template<class T> struct small {
    typedef T value_type;
    small() {}
    template<class U> small(const U&) {}
    T* allocate(size_t n) {
        buf_ind -= n * sizeof(T);
        buf_ind &= 0 - alignof(T);
        return (T*)(buf + buf_ind);
    }
    void deallocate(T*, size_t) {}
};
```

SIMD.h

Description: Cheat sheet of SSE/AVX intrinsics, for doing arithmetic on several numbers at once. Can provide a constant factor improvement of about 4, orthogonal to loop unrolling. Operations follow the pattern `"_mm(256)?_name_(si(128|256)|epi(8|16|32|64)|pd|ps)"`. Not all are described here; grep for `_mm` in `/usr/lib/gcc/*/4.9/include/` for more. If AVX is unsupported, try 128-bit operations, "emmintrin.h" and `#define _SSE_` and `_MMX_` before including it. For aligned memory use `_mm_malloc(size, 32)` or `int buf[N] alignas(32)`, but prefer `loadu/storeu`.

```
#pragma GCC target ("avx2") // or sse4.1
#include "immintrin.h"
```

```
typedef __m256i mi;
#define L(x) _mm256_loadu_si256((mi*)&(x))
```

```
// High-level/specific methods:
// load(u)?_si256, store(u)?_si256, setzero_si256, _mm_malloc
// blendv_(epi8|ps|pd) (z?y:x), movemask_epi8 (hibits of bytes)
// i32gather_epi32(addr, x, 4): map addr[] over 32-b parts of x
// sad_epu8: sum of absolute differences of u8, outputs 4xi64
// maddubs_epi16: dot product of unsigned i7's, outputs 16xi15
// madd_epi16: dot product of signed i16's, outputs 8xi32
// extractf128_si256(, i) (256->128), cvtsi128_si32 (128->lo32)
// permute2f128_si256(x,x,1) swaps 128-bit lanes
// shuffle_epi32(x, 3*64+2*16+1*4+0) == x for each lane
// shuffle_epi8(x, y) takes a vector instead of an mm
```

```
// Methods that work with most data types (append e.g. _epi32):
// set1, blend (i8?x:y), add, adds (sat.), mullo, sub, and/or,
// andnot, abs, min, max, sign(1,x), cmp(gt|eq), unpack(lo|hi)
```

```
int sumi32(mi m) { union {int v[8]; mi m; } u; u.m = m;
    int ret = 0; rep(i,0,8) ret += u.v[i]; return ret; }
mi zero() { return _mm256_setzero_si256(); }
mi one() { return _mm256_set1_epi32(-1); }
bool all_zero(mi m) { return _mm256_testz_si256(m, m); }
bool all_one(mi m) { return _mm256_testc_si256(m, one()); }
```

```
ll example_filteredDotProduct(int n, short* a, short* b) {
    int i = 0; ll r = 0;
    mi zero = _mm256_setzero_si256(), acc = zero;
    while (i + 16 <= n) {
        mi va = L(a[i]), vb = L(b[i]); i += 16;
        va = _mm256_and_si256(_mm256_cmpgt_epi16(vb, va), va);
        mi vp = _mm256_madd_epi16(va, vb);
        acc = _mm256_add_epi64(_mm256_unpacklo_epi32(vp, zero),
            _mm256_add_epi64(acc, _mm256_unpackhi_epi32(vp, zero)));
    }
    union {ll v[4]; mi m; } u; u.m = acc; rep(i,0,4) r += u.v[i];
    for (;i<n;++i) if (a[i] < b[i]) r += a[i]*b[i]; //<- equiv
    return r;
}
```

Techniques (A)

techniques.txt	159 lines
Recursion	
Divide and conquer	
Finding interesting points in N log N	
Algorithm analysis	
Master theorem	
Amortized time complexity	
Greedy algorithm	
Scheduling	
Max contiguous subvector sum	
Invariants	
Huffman encoding	
Graph theory	
Dynamic graphs (extra book-keeping)	
Breadth first search	
Depth first search	
* Normal trees / DFS trees	
Dijkstra's algorithm	
MST: Prim's algorithm	
Bellman-Ford	
Konig's theorem and vertex cover	
Min-cost max flow	
Lovasz toggle	
Matrix tree theorem	
Maximal matching, general graphs	
Hopcroft-Karp	
Hall's marriage theorem	
Graphical sequences	
Floyd-Warshall	
Euler cycles	
Flow networks	
* Augmenting paths	
* Edmonds-Karp	
Bipartite matching	
Min. path cover	
Topological sorting	
Strongly connected components	
2-SAT	
Cut vertices, cut-edges and biconnected components	
Edge coloring	
* Trees	
Vertex coloring	
* Bipartite graphs (=> trees)	
* 3^n (special case of set cover)	
Diameter and centroid	
K'th shortest path	
Shortest cycle	
Dynamic programming	
Knapsack	
Coin change	
Longest common subsequence	
Longest increasing subsequence	
Number of paths in a dag	
Shortest path in a dag	
Dynprog over intervals	
Dynprog over subsets	
Dynprog over probabilities	
Dynprog over trees	
3^n set cover	
Divide and conquer	
Knuth optimization	
Convex hull optimizations	
RMQ (sparse table a.k.a 2^k-jumps)	
Bitonic cycle	
Log partitioning (loop over most restricted)	
Combinatorics	

techniques

Computation of binomial coefficients
Pigeon-hole principle
Inclusion/exclusion
Catalan number
Pick's theorem
Number theory
Integer parts
Divisibility
Euclidean algorithm
Modular arithmetic
* Modular multiplication
* Modular inverses
* Modular exponentiation by squaring
Chinese remainder theorem
Fermat's little theorem
Euler's theorem
Phi function
Frobenius number
Quadratic reciprocity
Pollard-Rho
Miller-Rabin
Hensel lifting
Vieta root jumping
Game theory
Combinatorial games
Game trees
Mini-max
Nim
Games on graphs
Games on graphs with loops
Grundy numbers
Bipartite games without repetition
General games without repetition
Alpha-beta pruning
Probability theory
Optimization
Binary search
Ternary search
Unimodality and convex functions
Binary search on derivative
Numerical methods
Numeric integration
Newton's method
Root-finding with binary/ternary search
Golden section search
Matrices
Gaussian elimination
Exponentiation by squaring
Sorting
Radix sort
Geometry
Coordinates and vectors
* Cross product
* Scalar product
Convex hull
Polygon cut
Closest pair
Coordinate-compression
Quadtrees
KD-trees
All segment-segment intersection
Sweeping
Discretization (convert to events and sweep)
Angle sweeping
Line sweeping
Discrete second derivatives
Strings
Longest common substring
Palindrome subsequences

Knuth-Morris-Pratt
Tries
Rolling polynomial hashes
Suffix array
Suffix tree
Aho-Corasick
Manacher's algorithm
Letter position lists
Combinatorial search
Meet in the middle
Brute-force with pruning
Best-first (A*)
Bidirectional search
Iterative deepening DFS / A*
Data structures
LCA (2^k-jumps in trees in general)
Pull/push-technique on trees
Heavy-light decomposition
Centroid decomposition
Lazy propagation
Self-balancing trees
Convex hull trick (wcipeg.com/wiki/Convex_hull_trick)
Monotone queues / monotone stacks / sliding queues
Sliding queue using 2 stacks
Persistent segment tree