Mining Data Streams

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Aarhus U, Spring 2019

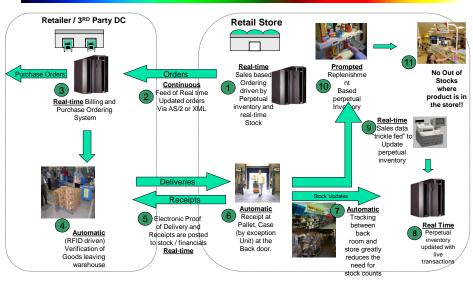
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Today's Agenda

- Understand what a DSMS does.
- Queries on streams.
- Sliding Windows
- Counting on a stream:
 - The DGIM method.
 - How to derive an error bound.
- Counting distinct elements.
- Moments of a stream.

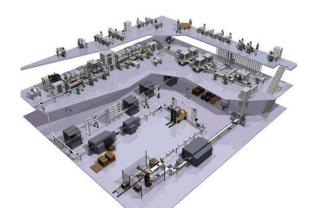
Motivating Example: Store Replenishment Process



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Motivating Example: Production Control System



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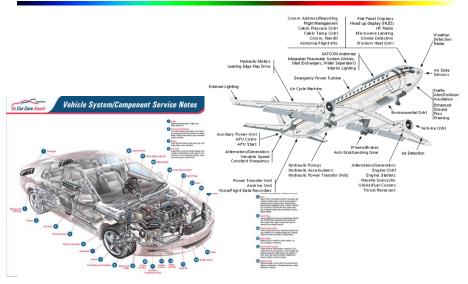
Motivating Example: Production Control System



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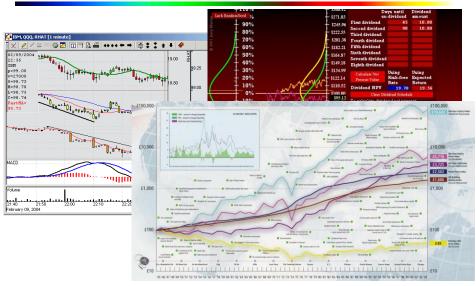
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Motivating Examples: Monitoring Vehicle Operation



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Motivating Example: Financial Applications



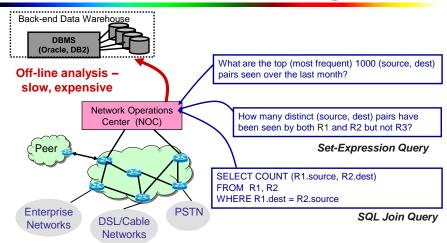
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Motivating Examples: Web Data Streams

- Mining query streams.
 - Google wants to know what queries are more frequent today than yesterday.
- Mining click streams.
 - Yahoo wants to know which of its pages are getting an unusual number of hits in the past hour.

Motivating Examples: Network Monitoring



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Motivating Examples: Sensor Networks

- the sensors era
 - ubiquitous, small, inexpensive sensors
 - bridging physical world and information technology







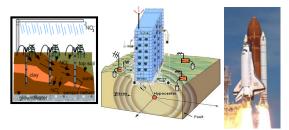


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Motivating Examples: Sensor Networks

- the sensors era
 - ubiquitous, small, inexpensive sensors
 - bridging physical world to information technology
- unveil previously unobservable phenomena





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What all this requires

- Efficient streaming algorithms
 - process this data online
 - allow approximate answers
 - operate in a distributed fashion (network as distributed database)
 - also usable as one-pass algorithms for massive datasets
- new data mining algorithms
 - help in data analysis in the above setting

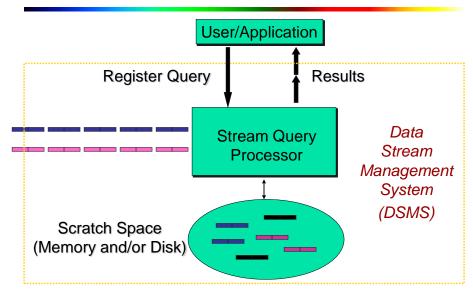
Data Stream Management System?

- Traditional DBMS data stored in finite, persistent data sets
- New Applications data input as continuous, ordered data streams
 - Network monitoring and traffic engineering
 - Telecom call records
 - Network security
 - Financial applications
 - Sensor networks
 - Manufacturing processes
 - Web logs and clickstreams
 - Massive data sets

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Data Stream Management System!



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DBMS versus DSMS

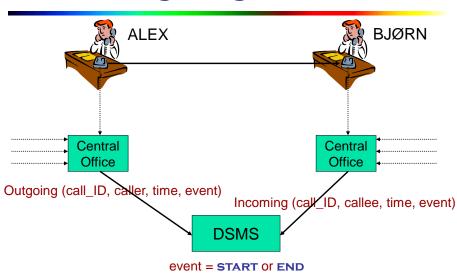
- Persistent relations
- One-time queries
- Random access
- "Unbounded" disk store
- Only current state matters
- Passive repository
- Relatively low update rate
- No real-time services
- Precise answers
- Access plan determined by query processor, physical DB design

- Transient streams
- Continuous queries
- Sequential access
- Bounded main memory
- History/arrival-order is critical
- Active stores
- Possibly multi-GB arrival rate
- Real-time requirements
- Imprecise/approximate answers
- Access plan dependent on variable data arrival and data characteristics

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Making Things Concrete



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Query 1 (SELF-JOIN)

Find all outgoing calls longer than 2 minutes

- Result requires unbounded storage
- Can provide result as data stream
- Can output after 2 min, without seeing END

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Query 2 (JOIN)

Pair up callers and callees

```
SELECT O.caller, I.callee
FROM Outgoing O, Incoming I
WHERE O.call_ID = I.call_ID
```

- Can still provide result as data stream
- Requires unbounded temporary storage ...
- ... unless streams are near-synchronized

Query 3 (group-by aggregation)

Total connection time for each caller

SELECT O1.caller, sum(O2.time – O1.time)
FROM Outgoing O1, Outgoing O2
WHERE (O1.call_ID = O2.call_ID
AND O1.event = START
AND O2.event = END)

GROUP BY O1.caller

- Cannot provide result in (append-only) stream
 - Output updates?
 - Provide current value on demand?
 - Memory?

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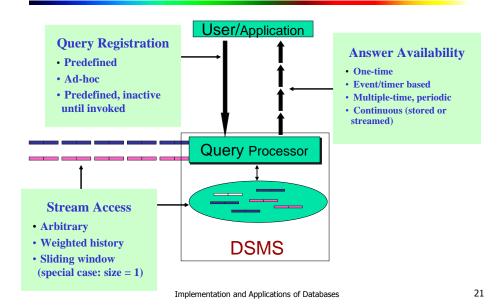
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Data Model

- Append-only
 - Call records
- Updates
 - Stock tickers
- Deletes
 - Transactional data
- Meta-Data
 - Control signals, punctuations

System Internals – probably need all of the above

Query Model



Related Database Technology

- DSMS must use ideas, but none is substitute
 - Triggers, Materialized Views in Conventional DBMS
 - Main-Memory Databases
 - Distributed Databases
 - Pub/Sub Systems
 - Active Databases
 - Sequence/Temporal/Timeseries Databases
 - Realtime Databases
 - Adaptive, Online, Partial Results

Novelty in DSMS

- Semantics: input ordering, streaming output, ...
- State: cannot store unending streams, yet need history
- Performance: rate, variability, imprecision, ...

Unrestricted Window

 Queries refer to all data in a window that starts at the "beginning of time", extends up to the current time, and expands with time (potentially infinite length).

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Unrestricted Window

q wertyuiopasdfghjklzxcvbnm

----- Past Future –

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Unrestricted Window

q w e r t y u i o p a s d f g h j k l z x c v b n m

qwertyuiopasdfghjklzxcvbnm

← Past Future →

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Unrestricted Window

q w e r t y u i o p a s d f g h j k l z x c v b n m

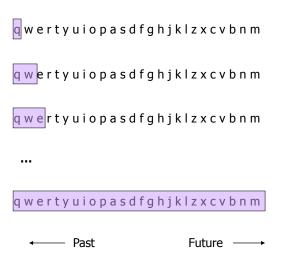
qwertyuiopasdfghjklzxcvbnm

q w e r t y u i o p a s d f g h j k l z x c v b n m

← Past Future →

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Unrestricted Window



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Unrestricted Window

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- Queries refer to all data in a window that starts at the "beginning of time", extends up to the current time, and expands with time (potentially infinite length).
- What happens when we try to compute joins in this model?
 - Join results involving some piece of data may appear at any time in the future
 - In order to correctly compute the result, we need to store all values that have appeared in the past!

Shifting Window

 Queries are about a window of length N, which advances by N, where N are the most recent elements received, or the most recent time units.

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Shifting Window

q w e r t y u i o p a s d f g h j k l z x c v b n m

← Past Future →

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Shifting Window

q w e r t y u i o p a s d f g h j k l z x c v b n m q w e r t y u i o p a s d f g h j k l z x c v b n m

← Past Future →

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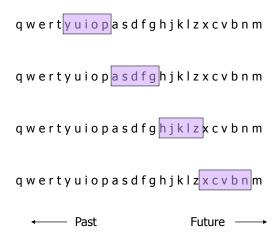
Shifting Window

q w e r t y u i o p a s d f g h j k l z x c v b n m q w e r t y u i o p a s d f g h j k l z x c v b n m q w e r t y u i o p a s d f g h j k l z x c v b n m

— Past Future →

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Shifting Window



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Shifting Window

- Queries are about a window of length N, which advances by N, where N are the most recent elements received, or the most recent time units.
- Useful queries within this model:
 - average number of calls every day
 - std deviation of packet losses every 10 minutes
 - etc.

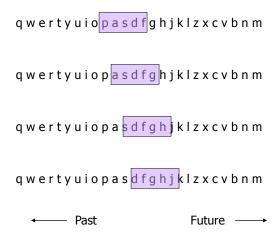
Sliding Window

Queries are about a window of length N, covering the N most recent elements received, or most recent time units.

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Sliding Window



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Sliding Window

- Queries are about a window of length N, covering the N most recent elements received, or most recent time units.
- Interesting case: N is so large it cannot be stored in memory, or even on disk.
 - Or, there are so many streams that we cannot store the values for all windows.

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Counting Bits --- (1)

- Problem: given a stream of 0's and 1's, be prepared to answer queries of the form "how many 1's in the last k bits?" where k ≤ N.
- Obvious solution: store the most recent N bits.
 - When new bit comes in, discard the *N*+1st bit.

Counting Bits --- (2)

- You can't get an exact answer without storing the entire window.
- Real Problem: what if we cannot afford to store N bits?
 - E.g., we are processing 1 trillion streams and N = 1 trillion, but we're happy with an approximate answer.

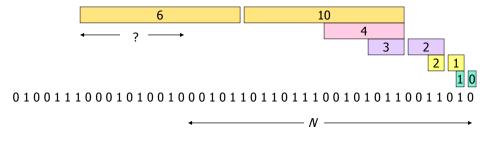
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Something That Doesn't (Quite) Work

- Summarize exponentially increasing regions of the stream, looking backward.
- Drop small regions if they begin at the same point as a larger (included) region.

We can construct the count of the last N bits, except we're not sure how many of the last 6 are included.



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What's Good?

- Stores only O(log²N) bits.
 - O(log N) counts of log₂ N bits each.
- Easy update as more bits enter.
- Error in count no greater than the number of 1's in the "unknown" area.

What's Not So Good?

- As long as the 1's are fairly evenly distributed, the error due to the unknown region is small --- no more than 50%.
- But it could be that all the 1's are in the unknown area at the end.
- In that case, the (relative) error is unbounded! (we may miss them all and get 0 as an answer).

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Fixup

- Instead of summarizing fixed-length blocks, summarize blocks with a fixed number of 1's.
 - Let the block "sizes" (number of 1's) increase exponentially.
- By controlling the number of 1's in the window, we ensure errors are small.

The DGIM* Method

- Store O(log²N) bits per stream.
- Gives approximate answer, never off by more than 50%.
 - Error factor can be reduced to any fraction > 0, with more complicated algorithm and proportionally more stored bits.

*Datar, Gionis, Indyk, and Motwani

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Timestamps

- Each bit in the stream has a *timestamp*, starting 1, 2, ...
- Record timestamps modulo N (the window size), so we can represent any relevant timestamp in O(log₂N) bits.

Buckets

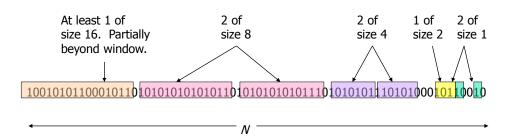
- A bucket in the DGIM method is a record consisting of:
 - 1. The timestamp of its end $[O(\log N)]$ bits].
 - The number of 1's between its beginning and end $[O(\log \log N)]$ bits].
- Constraint: number of 1's must be a power of 2.
 - That explains the log log *N* in (2). (**how?**)
 - It suffices to store its log only.

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Representing a Stream by Buckets

- 1 or 2 buckets with the same power-of-2 number of 1's.
- Buckets <u>do not</u> overlap in timestamps.
- Buckets are sorted by size (# of 1's).
 - Earlier buckets are not smaller than later buckets.
- Buckets disappear when their end-time is > N time units in the past.



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Updating Buckets --- (1)

- When a new bit comes in, drop the last (oldest) bucket if its end-time is prior to N time units before the current time.
- If the current bit is 0, no other changes are needed.

Updating Buckets --- (2)

- If the current bit is 1:
 - 1. Create a new bucket of size 1, for just this bit.
 - End timestamp = current time.
 - 2. If there are now three buckets of size 1, combine the oldest two into a bucket of size 2.
 - 3. If there are now three buckets of size 2, combine the oldest two into a bucket of size 4.
 - 4. And so on...

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Example

001010110001011 010101010101011 0101010101111 01010101111 000101110101 00010111 00010111 0001011 0001011 0



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Example



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Example

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Example

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Example

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Example

1001010110001011 0 1010101010101 0 10101010111 0 101010111010100 0 1011001 0 1

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Answering Queries

- To estimate the number of 1's in the most recent N bits:
 - 1. Sum the sizes of all buckets but the last.
 - 2. Add in half the size of the last bucket.
- Remember, we don't know how many 1's of the last bucket are still within the window.

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Error Bound

- Suppose the last bucket has size 2^k.
- Then, when we assume 2^{k-1} of its 1's are still within the window, we make an error of **at most** 2^{k-1} .
- Since there is at least one bucket for each size from 1 to 2^{k-1} , the true sum is **no less** than 2^k-1 .
- Thus, the relative error is at most 50%.

Counting Distinct Elements

- Problem: a data stream consists of elements chosen from a set of size n. Maintain a count of the number of distinct elements seen so far.
- Obvious approach: maintain the set of elements seen.

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Applications

- How many different words are found among the Web pages being crawled at a site?
 - Unusually low or high numbers could indicate artificial pages (spam).
- How many different Web pages does each customer request in a week?

Using Small Storage

- Real Problem: what if we do not have space to store the complete set?
- Estimate the count in an unbiased way.
- Accept that the count may be in error, but limit the probability that the error is large.

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Flajolet-Martin* Approach

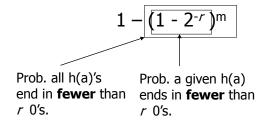
- Pick a hash function h that maps each of the n elements to at least log₂n bits.
- For each stream element a, let r(a) be the number of trailing 0's in h(a).
- Record R = the maximum r(a) seen.
- Estimate = 2^R .

* Really based on a variant due to AMS (Alon, Matias, and Szegedy)

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Why It Works

- The probability that a given h (a) ends in at least r 0's is 2^{-r}.
- If there are m different elements, the probability that $R \ge r$ is:



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Why It Works -(2)

- Since 2-r is small, 1 $(1-2-r)^m \approx 1 e^{-m\bar{2}^r}$.
- If $2^r >> m$, $1 (1 2^{-r})^m \approx 1 (1 m2^{-r})$ $\approx m/2^r \approx 0$. First 2 terms of the Taylor expansion of e^x
- If $2^r << m$, $1 (1 2^{-r})^m \approx 1 e^{-m2^r} \approx 1$.
- Thus, 2^R will almost always be around m.

Why It Does not Work

- E(2^R) is actually infinite.
 - When *R* becomes *R* +1, probability halves, but value doubles.
- Workaround: use many hash functions, get many samples.
- How are samples combined?
 - Average? What if one very large value?
 - Median? All values are a power of 2.

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Solution

- Partition your samples into small groups.
- Take the average of groups.
- Then take the **median** of the averages.

Generalization: Moments

- Suppose a stream has elements chosen from a set of n values.
- Let m_i be the number of times value i occurs.
- The k^{th} moment is the sum of $(m_i)^k$ over all i.

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Special Cases

- 0th moment = number of different elements in the stream.
 - The problem just considered.
- 1st moment = count of the numbers of elements = length of the stream.
 - Easy to compute.
- 2nd moment = surprise number = a measure of how uneven the distribution is.

Example: Surprise Number

- Stream of length 100; 11 values appear.
- Unsurprising: 10, 9, 9, 9, 9, 9, 9, 9, 9, 9.Surprise # = 910.
- Surprising: 90, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1. Surprise # = 8,110.

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