

Gate EE 2023

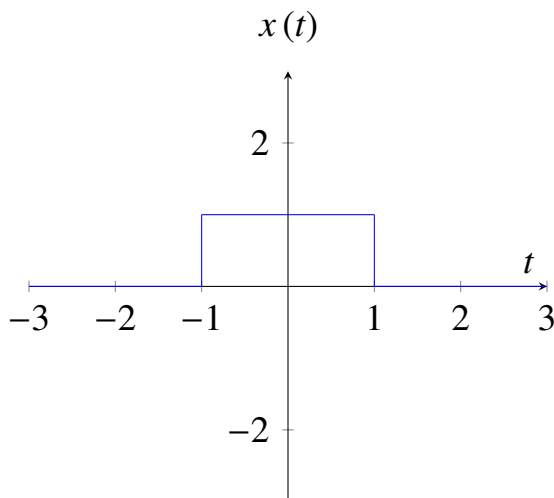
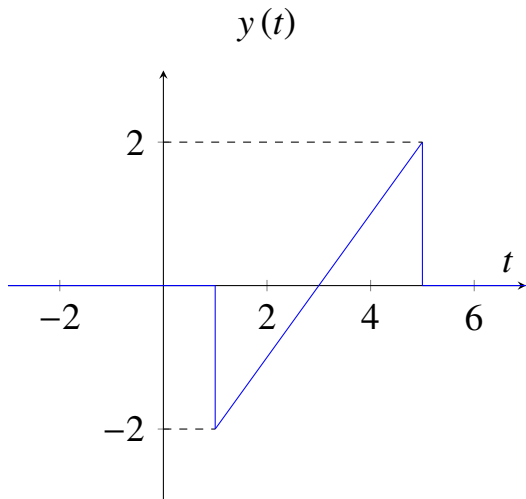
EE1205 Signals and Systems

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Question Gate 2023 EE: For the signals $x(t)$ and $y(t)$ shown in the figure, $z(t) = x(t) * y(t)$ is maximum at $t = T_1$. Then T_1 in seconds is (Round off to the nearest integer)

Variable	values	Description
$x(t)$	$u(t+1) - u(t-1)$	signal 1
$y(t)$	$y(t) = \begin{cases} t-3 & ; 1 \leq t \leq 5 \\ 0 & ; \text{otherwise} \end{cases}$	signal 2
$X(s)$	$\int_0^\infty x(t) e^{-st} dt$	Laplace transform of $x(t)$
$Y(s)$	$\int_0^\infty y(t) e^{-st} dt$	Laplace transform of $y(t)$
$\mathcal{L}^{-1}\{Z(s)\}$	$\frac{f(t-c)u(t-c)}{\mathcal{L}^{-1}(e^{-cs}F(s))} =$	Inverse Laplace transform

TABLE 1
INPUT PARAMETERS



Using laplace transform,

$$z(t) = x(t) * y(t) \quad (1)$$

$$Z(s) = X(s) Y(s) \quad (2)$$

$$X(s) = \frac{1}{s} (e^s - e^{-s}) \quad (3)$$

$$Y(s) = \frac{2s+1}{s^2} (e^{-s} - e^{-5s}) \quad (4)$$

$$Z(s) = \frac{2s+1}{s^3} (1 - e^{-4s} - e^{-2s} + e^{-6s}) \quad (5)$$

Now taking inverse laplace transform for each terms, $\mathcal{L}^{-1}\{Z(s)\}$

$$\begin{aligned} z(t) = & \left(2t + \frac{t^2}{2}\right) u(t) \\ & - \left(2(t-4) + \frac{(t-4)^2}{2}\right) u(t-4) \\ & - \left(2(t-2) + \frac{(t-2)^2}{2}\right) u(t-2) \\ & + \left(2(t-6) + \frac{(t-6)^2}{2}\right) u(t-6) \end{aligned} \quad (6)$$

Solution:

From the plot it is clear that $T_1 = 4$.

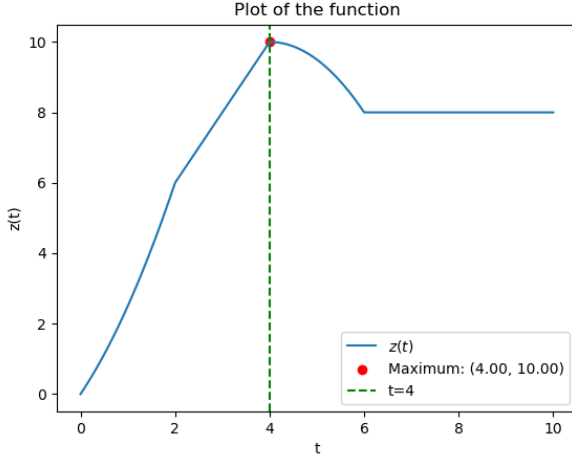


Fig. 1. $z(t)$ vs. t

Now in time domain,

$$z(t) = x(t) * y(t) = y(t) * x(t) \quad (7)$$

$$z(t) = \int_{-\infty}^{\infty} y(\tau) x(t - \tau) d\tau \quad (8)$$

$x(\tau)$ is an even signal,

$$x(\tau) = x(-\tau) \quad (9)$$

$$x(-\tau) = \begin{cases} 1 & ; -1 \leq -\tau \leq 1 \\ 0 & ; \text{otherwise} \end{cases} \quad (10)$$

$$x(-\tau) \xleftrightarrow{\text{Time shifting}} x(t - \tau) \quad (11)$$

$$x(t - \tau) = \begin{cases} 1 & ; t - 1 \leq t - \tau \leq t + 1 \\ 0 & ; \text{otherwise} \end{cases} \quad (12)$$

For $z(t)$ to be maximum both $y(\tau)$ and $x(t - \tau)$ must be maximum,

$$\begin{aligned} \Rightarrow t - 1 = 3 \quad \text{or} \quad t + 1 = 5 \\ t = T_1 = 4 \end{aligned}$$