## 1

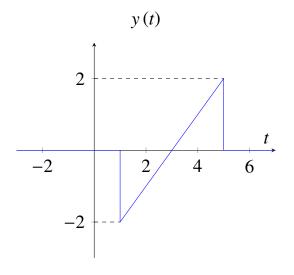
## Gate EE 2023 EE1205 Signals and Systems

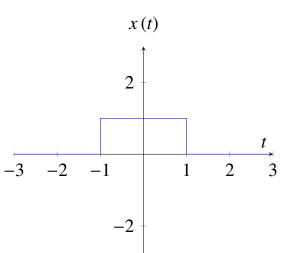
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**Question Gate 2023 EE:** For the signals x(t) and y(t) shown in the figure, z(t) = x(t) \* y(t) is maximum at  $t = T_1$ . Then  $T_1$  in seconds is .......... (Round off to the nearest integer)

Variable	values	Description
x(t)	u(t+1) - u(t-1)	signal 1
y(t)	$y(t) = \begin{cases} t - 3 & ; 1 \le n \le 5 \\ 0 & ; otherwise \end{cases}$	signal 2
X(s)	$\int_0^\infty x(t) e^{-st} dt$	Laplace transform of $x(t)$
Y(s)	$\int_0^\infty y(t) e^{-st} dt$	Laplace transform of $y(t)$
$\mathscr{L}^{-}\{Z(s)\}$	$f(t-c)u(t-c) = \mathcal{L}^{-}(e^{-cs}F(s))$	Inverse Laplace transform

TABLE 1 Input Parameters





Using laplace transform,

$$z(t) = x(t) * y(t)$$
 (1)

$$Z(s) = X(s)Y(s)$$
 (2)

$$X(s) = \frac{1}{s} (e^{s} - e^{-s})$$
 (3)

$$Y(s) = \frac{2s+1}{s^2} \left( e^{-s} - e^{-5s} \right) \tag{4}$$

$$Z(s) = \frac{2s+1}{s^3} \left( 1 - e^{-4s} - e^{-2s} + e^{-6s} \right)$$
 (5)

Now taking inverse laplace transform for each terms,  $\mathcal{L}^{-}\{Z(s)\}$ 

$$z(t) = \left(2t + \frac{t^2}{2}\right)u(t)$$

$$-\left(2(t-4) + \frac{(t-4)^2}{2}\right)u(t-4)$$

$$-\left(2(t-2) + \frac{(t-2)^2}{2}\right)u(t-2)$$

$$+\left(2(t-6) + \frac{(t-6)^2}{2}\right)u(t-6)$$

## **Solution:**

## From the plot it is clear that $T_1 = 4$ .

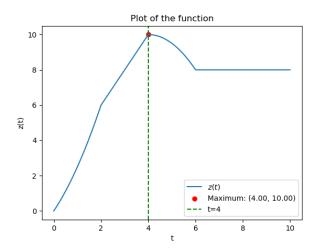


Fig. 1. z(t) vs. t