			Dataset(s) for				Parameters	Performance (Speed / FLOPS)	OpenVino Optmizied			Efficiency	Ideal use cases for the	Reference resource/		Code	Code
	Models	Notes	benchmarking				(M)	FLOPS)	Speed	Pros	Cons	Remarks	models	notebooks	Link to research paper	Complexity	Template
Image Classification				TOP 1 ACCURACY	TOP 5												
				TOP 1 ACCURACY	ACCURACY						It does not use convolutional neural networks,						
										(State of the art) High Accuracy with Less	instead vision transformer uses small patches to apply self attention; the efficacy of using small patches is debatable at the time of writing as it might miss edges		Accuracy is the most critical metric		https://arxiv.org/pdf/2010.		
	Vision Transformer		ImageNet	88.55%			632			to Noisy Studen	as it might miss edges				11929v1.pdf	Hard	
													supervised learning where	e			
	NoisyStudent (EfficientNet-L2)									Augments labeled dataset with unlabeled	Adding "noise" requires careful consideration and configuration; computationally very		getting labelled data		https://arxiv.org/pdf/1911. 04252v4.pdf		
				88.40%	98.70%		480			Uses Neural Architecture Search to	expensive		is hard			Hard	
	EfficientNet-B7		ImageNet	84.4			66			optmize architecture			Both accuracy	,	https://arxiv.org/abs/1905.11946	Medium	
				82.6			19			Uses Neural Architecture Search to optmize architecture; excellent accuracy			and performance				
	EfficientNet-B4		ImageNet	82.6			19			compared to speed			are critical Both accuracy	,	https://arxiv.org/abs/1905.11946	Medium	
	EfficientNet-B2		ImageNet	79.8			9.2			Uses Neural Architecture Search to optmize architecture			performance are critical		https://arxiv.org/abs/1905.11946	Medium	
	Lindenster-DZ		imagerees	75.5			0.2			Uses Neural Architecture Search to			ML on the edge where		Ingastarii orgada 1505.11540	median	
	EfficientNet-B0		ImageNet	76.3			5.3			optmize architecture; highly optimized for ML on edge with increased accuracy			accuracy is important		https://arxiv.org/abs/1905.11946		
										Uses filters of varying sizes to detect different image features for greater					https://arxiv.org/pdf/1602_ 07261v2.pdf		
	Inception V3		ImageNet	78.8	95.10%		55.8			accuracy Highly optimized for performance on ML	Computationally expensive; better models exist					Easy	
	MobileNet v2		ImageNet	71.88	90.29		3.4			on the edge applications; great backbone for CV on the edge tasks	Not as robust as larger models		ML on the edge		https://arxiv.org/pdf/2006. 10702v1.pdf	Medium	
										Very fast and hence great for performance critical applications; works out of the box	Poor performance when used for classification and detection of small objects		ML on the edge; low				
	SqueezeNet		ImageNet	58.1	80.42		1.25			out of the box	Increased complexity of architecture due to skip	Highly efficien	it latency		https://arxiv.org/abs/1602.07360	Medium	
	ResNet 18		ImageNet	69.76	90.08		11.174			Most tried and tested method. Works well.	connections; Implementation of Batch normalization layers				https://arxiv.org/pdf/1512.03385. pdf	Easy	
	replact to		imagenet	00.70	50.00		11.174				Increased complexity of architecture due to skip				NOTE .	Lasy	
	ResNet 34		ImageNet	73.3	91.42		21.282			Most tried and tested method. Works well.	Implementation of Batch normalization layers since ResNet heavily depends on it				https://arxiv.org/pdf/1512.03385.pdf	Easy	
			9							The state of the s	Increased complexity of architecture due to skip				_		
	ResNet 50		ImageNet	76.15	92.87		25.6			Most tried and tested method. Works well.	connections; Implementation of Batch normalization layers since ResNet heavily depends on it				https://arxiv.org/pdf/1512.03385. pdf	Easy	
											Increased complexity of architecture due to skip connections;						
	ResNet 101		ImageNet	79.20%	94.70%		42.513			Most tried and tested method. Works well.	Implementation of Batch normalization layers since ResNet heavily depends on it				https://arxiv.org/pdf/1512.03385.pdf	Easy	
	VGG 19		ImageNet	74 50%	92 00%		144			Easy to understand architecture	Computationally expensive and gives much lower accuracy in comparison with much smaller models	Low efficienc	Google		https://arxiv.org/pdf/1409.	Easy	
	VGG 19		ImageNet	74.50%	92.00%		144			Easy to understand architecture	Computationally expensive and gives much	Low efficiency				Easy	
	VGG 16		ImageNet	74.40%	91.90%		138			Easy to understand architecture	lower accuracy in comparison with much smaller models	Low efficience	Google deepdream		https://arxiv.org/pdf/1409. 1556v6.pdf	Easy	
Semantic segmentation	FPN		Encoder	MEAN IOU			23.15M	Nil	Nil						http://presentations.cocodataset	Easy	
	FFN		(ImageNet) Encoder	class IoU(76.4)			23.15M	21.2G	Nil	Learns without any significant increase in number of parameters, fast.	Not the most accurate, compromises accuracy for less params and faster fps.			https://github.com/NimbleBox/			
	Linknet		(ImageNet)	Class 100(76.4)			11.5M	21.26	NII	Exploits the impact of global contextual	tor less params and taster tps.			https://github.com/NimbleBox/	https://arxiv.org/abs/1707.03718	Lasy	
										Exploits the impact of global contextual information in semantic segmentation by combining attention mechanism and spatial pyramid to extract precise dense features.							
	PAN		Cityscapes	84.00%			21.4M	Nil	Nil	features.  Exploits the capability of global context				https://github.com/NimbleBox/	https://arxiv.org/abs/1805.10180	Easy	
	PSPNet		Cityscapes	80 20%			21 4M	Nii	Nil	Exploits the capability of global context information by different/region-based context aggregation through our pyramid pooling				https://github.com/NimbleRox/	https://arxiv.org/abs/1612.01105	Fasy	
			Brain MRI							This network can localize, the training data in terms of patches is much larger than the	It is quite slow because the network must be run separately for each patch , and there is a lot of redundancy due to overlapping patches.				-		
	U-Net		segmentation				77.6M	Nil	Nil	number of training images	redundancy due to overlapping patches.			https://github.com/NimbleBox/	https://arxiv.org/abs/1505.04597	Medium	
Human Pose Estimation			MPII Human	PCKH-0.5						i) Light model that runs fast on standard					https://arxiv.org/abs/1901,		
	MSPN		Pose	92.60%				9.6G	Nil	chips as well  i) Maintain high res, representations					00148v4	Medium	
	HRNet-W32		MPII Human Po	92.30%			28.5 M	16.0G	Nil	throughout the the whole process ii) Fuse multi-res representations repeatedly	i) Model is heavier compared to others in the segment				https://arxiv.org/abs/1902, 09212v1	Easy	
	Pyramid Residual Modules		MPII Human	92.00%				1	Nil	,	-				https://arxiv.org/abs/1708. 01101v1	Hard	
	Multi-Context Attention		MPII Human Po						Nil						https://arxiv.org/abs/1702. 07432v1	Hard	
										i) Introduces and uses dense u-net that uses ~70% lower parameters compareed					_		
		Pretrained weights not available. Code for running					(4 Stack) 3.9 (8) 7.9 M (16	M )		to tradional U-Net stack ii) Since this is a U-Net the input and output size if the					https://arxiv.org/abs/1808.		
	CU-Net Stacked hourglass 4	ready.	MPII Human Po				15.9 M		Nil	same and there is no need to upscaling					02194v2 https://arxiv.org/abs/1705. 02407v2	Medium	
	Inception-resnet		MPII Human Po						Nil	Very small orders of magnitude smaller	Single person only ii) Relies on upscaling which can reduce the effectiveness.				02407v2 https://arxiv.org/abs/2004, 12186v1	Hard	
	EfficientPose IV EfficientPose RT		MPII Human Po MPII Human Po	91.20% 88.40%			6.56 M 0.46 M		Nil	than comparable models  Order of mag. smaller than IV version	which can reduce the effectiveness.				12186v1 *	Easy *	
Activity Recognition				3-FOLD													
Action Recognition		Only following weights are		ACCURACY													
		available: https://1drv. ms/u/sl AqKP51Rikz1Gaifd54VbdR								Uses BERT for Bi-directional embedding ii) BERT output is standard and thus can be utilised with other tasks							
	R2+1D BERT	Bn6qM?e=7OxYLa	UCF101	98.69%			66.67 M	152.97 G	Nil	and thus can be utilised with other tasks such as image/video captioning, etc.	i) Super heavy model				https://arxiv.org/abs/2008. 01232v3	Medium	
		This discusses more about a new data source															
		augmentation than about the model itsef. Models are simple Teach er Student								i) Uses a way to convert images to videos	i) The videos generated do not look like actual				https://arxiv.org/abs/2003.		
	OmniSource	models		98.60%			-	-	Nil	that is applicable for other uses as well i) Uses two streams 3D conv blocks one	i) The videos generated do not look like actual videos				13042v2	Easy	
	Two-stream I3D		UCF101	98%			25M	-	Nil	that is applicable for other uses as well i) Uses two streams 3D conv blocks one for RGB Images and other for Flow	Slow, not suitrable for real time inference				https://arxiv.org/abs/1705, 07750v3 https://openaccess.thecvf.	Easy	
		RGB Implementation complete. FLOW is only an													com/content_CVPR_2019/paper s/Crasto_MARS_Motion- Augmented_RGB_Stream_for_/	t .	
		complete. FLOW is only an extension that can be implemented further when								to a single step process. ii) Demostrates ability to use Cross Entropy and MSE loss together iii) Simple RGB performs better than Flow + RGB or Flow only.	•				cilon Recognition CVPR 2019	Δ	
Multimodal Activity	MARS+RGB/Flow	needed.	UCF101	97.80%			-	-	Nil	than Flow + RGB or Flow only.					_paper.pdf	Medium	
Accognition				ACCURACY													

	TCN	EV-Ar	ction	80.10%								Nil					https://arxiv.org/abs/1704, 04516v1	Medium
	ST-GCN	EV-A	ction	79.60%								Nil					https://arxiv.org/abs/1801, 07455v2	Easy
	TSN	EV-A	Action	73.60%								Nil					https://arxiv.org/abs/1608. 00859v1	Hard
Text Recognition				PRECISION	RECALL	F-MEASURE												
	TextFuseNet	ICDA	R 2015	93.96	90.56	92.23						Nil					https://www.ijcai. org/Proceedings/2020/72	Hard
	CharNet H-88	ICDAIL I	R 2015	02.65	90.47	91.55				89.21M	Nii	Nil	one-stage model that can process two tasks simultaneously in one pass. ChanNet directly outputs bounding boxes of words and characters, with corresponding character labe	CharNet H-88 has more params than CharNet H-57	merges two tasks: bounding bo: and text prediciton	https://github. com/NimbleBoxAl/box_of_ai tools/tree/main/Text_Reco gnitlon/charnet	https://arxiv.org/abs/1910, 07954v1	Medium
	SBD		R 2015		88.2	90.1				05.2 TW	NII	Nil	characters, with corresponding character label	is becaue of the backbone used	prediction	gnition/charnet	https://arxiv.org/abs/1912, 09629v2	Medium
																	https://arxiv.org/abs/1801.	
	FOTS MS		R 2015		87.92	89.84				34.98 M	Nil	Nil					01671v2 https://arxiv.org/abs/1911	Hard
	DB-ResNet-50	ICDA	R 2015	91.8	83.2	87.3						Nil					08947v2	Easy
	Mask TextSpotter	ICDA	R 2015	91.6	81	86				Nii		Nil	takes advantage of simple and smooth end-to-endlearning procedure, in which precise text detection and recognition areacquired via semantic segmentation	proposes region, box classification and word segementation differently		https://github. com/NimbleBoxAl/box of ai _tools/tree/main/Text_Reco gnition/MaskTextSpotter	https://arxiv.org/abs/1807, 02242v2	Easy
	Charles 157			04.40	88.74	90.06				34.96M	Nii	Nil	one-stage model that can process two tasks simultaneously in one pass. CharNet directly outputs bounding boxes of words and	CharNet H-57 has comparatively less params then	and text	https://github. com/NimbleBoxAl/box_of_ai_ topls/tree/main/Text_Reco	https://arxiv.org/abs/1910.	Medium
	CharNet H-57	ICDA	R 2015	91.43	00.74	90.06				34.90M	NII	NII	The CTPN detects a text line in a sequence of	ds Charnet H-88 but compromises on the performance	prediciton	gnition/charnet	07954v1	Medium
	PMTD	ICDA	R 2015	91.3	87.43	89.33						Nil	fine-scale text proposals directly in convolution feature maps.	n; it is not an end to end solution a CRNN needs to be attached to to predict text.			https://arxiv.org/abs/1903, 11800v1	Medium
	CTPN+CRNN															https://github. com/NimbleBoxAl/box_of_ai_ tools/tree/main/Text_Reco- gnition/CTPN%2BCRNN		
Object Detection				BOX AP	AP50	AP75	APS	APM	APL									
Object Detection																	https://arxiv.org/pdf/2011.	
	YOLO V4 P7 DetectoRS	MS C	coco	55.8	73.2	61.2	38.8	60.1	68.2	287.4							08036v1.pdf	Medium
	(ResNeXt-101- 64x4d, multi-scale)	MS C	coco	55.7	74.2	61.1	37.7	58.4	68.1								https://arxiv.org/pdf/2006. 02334v2.pdf	Medium
	EfficientDet-D7x	MSC	coco	55.1	74.3	59.9	37.2	57.9	68								https://arxiv.org/pdf/1911, 09070v7.pdf	Medium
	YOLO V4 P6	MS C	coco	54.3	72.3	59.5	36.6	58.2	65.5								https://arxiv.org/pdf/2011. 08036v1.pdf	Medium
	SpineNet-190	MS C	coco	54.3													https://arxiv.org/pdf/1912_ 05027v3.pdf	Medium
	Cascade MaskRCNN	MS C	coco	53.3	71.9	58.5	35.5	55.8	66.7								https://arxiv.org/pdf/1909. 03625v1.pdf	Medium
	ResNeSt-200DCN	MSC	coco	53.3	72	58	35.1	56.2	66.8								https://arxiv.org/pdf/2004. 08955v1.pdf	Medium
	Probabilistic Anchor Assignment with IoU Prediction for Object Detection (PAA)	MS C	0000	53.5	71.6	59.1	36	56.3	66.9								https://arxiv.org/pdf/2007_ 08103v2.pdf	High
	Faster RCNN ResNet 101	MS C	coco	43.9	65.7	48.1	25.4	46.7	56.3								https://arxiv.org/pdf/1908. 04156v3.pdf	Easy
	RetinaNet (ResNext-101)	MS C	coco	40.8	61.1	44.1	24.1	44.2	51.2								https://arxiv.org/pdf/1708. 02002v2.pdf	Easy
	SSD 512	MS C	coco	28.8	48.5	30.3											https://arxiv.org/pdf/1512. 02325v5.pdf	Easy