

Bayesian Lipschitz Constant Estimation and Quadrature

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Overview

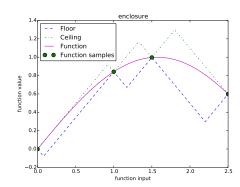
- Lipschitz quadrature
- Bayesian Lipschitz constant estimation method
- 3 Combination: Bayesian Lipschitz quadrature
- Extensions and future work

Lipschitz quadrature

Recap: Lipschitz continuity

f Lipschitz with constant $L \Leftrightarrow \forall x, x' : |f(x) - f(x')| \le L\mathfrak{d}(x, x')$.

- Given: sample \mathcal{D} of integrand f.
- f has Lipschitz constant $L \Rightarrow$ can compute integrals of bounds $\mathfrak{u}(\cdot;L)$ ("ceiling") and $\mathfrak{l}(\cdot;L)$ ("floor") (e.g. [Baran et. al. '08]).



- $\int_{L} \mathfrak{l}(x; L) dx \leq \int_{L} f(x) dx \leq \int_{L} \mathfrak{u}(x; L) dx$.
- $\mathfrak{l}, \mathfrak{u} \stackrel{unif.}{\to} f$ as the data becomes dense [Calliess '14].

Lipschitz quadrature

Recap: Lipschitz continuity

f Lipschitz with constant $L \Leftrightarrow \forall x, x' : |f(x) - f(x')| \le L \mathfrak{d}(x, x')$.

Practical problem:

• Lipschitz constant L may be unknown a priori.

Task:

- Infer subjective belief over (the smallest) L from a sample.
- Fold in uncertainty into integral estimates.
- Obtain Bayesian uncertainty bounds around integral estimates.

Recap: Lipschitz continuity

f Lipschitz with constant $L \Leftrightarrow \forall x, x' : |f(x) - f(x')| \le L\mathfrak{d}(x, x')$.

Best Lipschitz constant

- $L^* := \sup_{x,x', \, \mathfrak{d}(x,x') > 0} R(x,x') \le L$, where $R(x,x') = \frac{|f(x) f(x')|}{\mathfrak{d}(x,x')}$.
- $L^* =$ "best" (i.e. smallest) Lipschitz constant.

Bayesian inference:

Calculate posterior:
$$\pi(L^* = \ell | \mathcal{D}) = \frac{\pi(\mathcal{D}|L^* = \ell)\pi_0(L^* = \ell)}{\int_0^\infty \pi(\mathcal{D}|L^* = \ell)\pi_0(L^* = \ell) d\ell}$$
.

Best Lipschitz constant

$$L^* := \sup_{x,x',\,\mathfrak{d}(x,x')>0} R(x,x'), \text{ where } R(x,x') = \frac{|f(x)-f(x')|}{\mathfrak{d}(x,x')}.$$

L^* as a r.v. and its likelihood

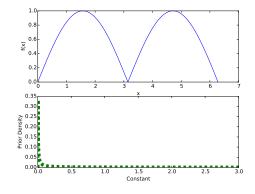
Inputs
$$x_i \sim \text{Unif.} \rightarrow \text{data } \mathcal{D} = \{(x_i, f(x_i)) | i = 1, ..., n\} \rightarrow S := \{R(x_i, x_j) | i < j, \mathfrak{d}(x_i, x_j) > 0\} \text{ set of r.v.}$$
 with $R(x_i, x_j) \sim \text{Unif}(0, L^*) \rightarrow \pi(S|L^*).$

Bayesian inference:

$$\pi(L^* = \ell | \mathcal{D}) \stackrel{!}{=} \pi(L^* | S) = \frac{\pi(S | L^*) \pi_0(L^*)}{\int_0^\infty \pi(S | L^*) \pi_0(L^*) \, dL^*}.$$

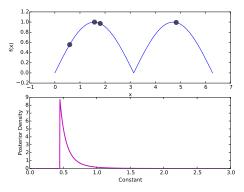
• We place a Pareto prior over the best Lipschitz constant...

- Prior: *Pa*(*b*, *K*).
- Uninformative prior: limit case $\mu, b \rightarrow 0$.
- Pareto prior and uniform likelihood are conjugate
 → closed-form inference.



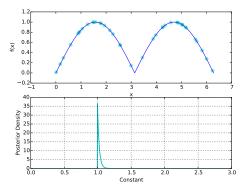
- We place a Pareto prior over the best Lipschitz constant...
- ... we observe a (small) sample $\mathcal D$ and update our subjective belief...

- Posterior: $\pi(L^*|S) = \frac{\pi(S|L^*)\pi_0(L^*)}{\int_0^\infty \pi(S|L^*)\pi_0(L^*) dL^*}$.
- Pareto prior and uniform likelihood are conjugate
 → closed-form inference.



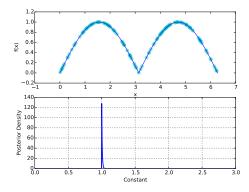
- We place a Pareto prior over the best Lipschitz constant...
- ... we observe a (larger) sample $\mathcal D$ and update our subjective belief...

- Posterior: $\pi(L^*|S) = \frac{\pi(S|L^*)\pi_0(L^*)}{\int_0^\infty \pi(S|L^*)\pi_0(L^*) dL^*}$.



- We place a Pareto prior over the best Lipschitz constant...
- ... we observe a $(-n \ even \ larger)$ sample $\mathcal D$ and update our subjective belief...

- Posterior: $\pi(L^*|S) = \frac{\pi(S|L^*)\pi_0(L^*)}{\int_0^\infty \pi(S|L^*)\pi_0(L^*) dL^*}$.



Integral estimate with Bayesian confidence bounds

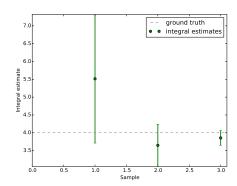
- For $\theta \in (0, 1)$, find: $L_{\theta} = \min\{L \geq 0 | \int_{0}^{L} \pi(L^* = \ell | \mathcal{D}) d\ell \geq 1 - \theta\}.$
- With probability at least 1θ the true smallest Lipschitz constant is less than or equal to L_{θ} .
- Using this L_{θ} as the Lipschitz constant parameter in Lipschitz quadrature implies:

Bayesian confidence bounds on the integral:

- $\Pr\Big(\int_I f(x) dx \in \big[S_I(L_\theta), S_u(L_\theta)\big]\Big) \ge 1 \theta$
- where $S_l(L) = \int_I \mathfrak{l}_n(x; L) \, dx$ and $S_u(L) = \int_I \mathfrak{u}_n(x; L) \, dx$ are the integrals of the upper and lower bound functions, respectively.

Integral estimate with Bayesian confidence bounds

• Integral bounds for our examples with confidence parameter $\theta = 0.001$.



Extensions and Future Work

- $\pi(L^* = \ell | \mathcal{D}) \stackrel{!?}{=} \pi(L^* = \ell | S).$
- Cubature.
- Indefinite integrals.
- Hoelder continuous functions.
- Applications to Bayesian risk estimates in sparse data scenarios.
- Optimisation and control.
- Local Lipschitz continuity and constant estimates.
- Suggestions?