Information Theory

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§ 1 Entropy, Relative Entropy and Matual information

1.1 Entropy

Setting $X \sim P$ discrete random variable "P" is the probability massfunction(PMF) of X. $P_X(X=x) = P_r[X=x]$ $P_X(x) \longleftrightarrow p(x)$

Definition 1.1.1. Entropy:

$$\begin{split} H(X) &= -\sum_{x \in X} p(x) \log p(x) & (log_2:bit \quad log_e:nat) \\ Convention: & 0log0 = 0 \\ Actually, & H(X) = H[P] \\ Accordingly, & \bar{X} = \sum_{x \in X} p(x)x \sim \mathop{\mathbf{E}}_{X \sim p(x)} X \\ & H(X) \sim \mathop{\mathbf{E}}_{X \sim p(x)} log \frac{1}{p(x)} \end{split}$$

Example 1.1.1. Binary Entropy Function:

$$h(p) = \mathop{H}_{x \in \{0,1\}}(X) = -plog_2p - (1-p)log_2(1-p)$$
 Here, $p = P(X = 0)$

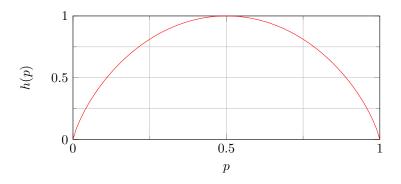


Figure 1: Binary Entropy Function

Each point on the curve represents one distribution of X. H property:

- 1. $H[P] \ge 0$
- 2. $H_b(X) = log_b a H_a(X)$ nat, when a = e

1.2 Joint Entropy and Conditional Entropy

Definition 1.2.1. Joint Entropy:
$$(X,Y) \sim p_{X,Y}(X=x,Y=y)$$

$$H[p_{X,Y}] = -\sum_{x \in \mathfrak{X}, y \in \mathfrak{Y}} p_{X,Y}(x,y) \log p_{X,Y}(x,y)$$

Definition 1.2.2. Conditional Entropy:
$$p_{X|Y}(X = x|Y = y)$$
 $H[X|Y] = -\sum_{x \in \mathfrak{X}, y \in \mathfrak{Y}} p_{X,Y}(x,y) \log p_{X|Y}(x|y)$ \uparrow \uparrow conditional

Chain Rule:
$$P(x,y) = P_Y(y)P_{X|Y}(x|y)$$

Theorem 1.2.1.
$$H(X,Y) = H(Y) + H(X|Y)$$

Proof.

$$\begin{split} H(X,Y) &= -\mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log p_{X,Y}(x,y) \\ &= -\mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log(p_{X|Y}(x|y)p_{Y}(y)) \\ &= -\mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log p_{X|Y}(x|y) - \mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log p_{Y}(y) \\ &= H(X|Y) + H(Y) \end{split}$$

1.3 Mutual Information

$$X, Y \sim p_{X,Y}(x,y)$$

Definition 1.3.1. Mutual Information:

$$I(X;Y) \stackrel{def}{=} \sum_{x,y} p(x,y) \log \frac{p(x,y)}{p_X(x)p_Y(y)}$$
$$= H(X) - H(X|Y)$$
$$= H(Y) - H(Y|X)$$
$$= H(X) + H(Y) - H(X,Y)$$

$$\begin{aligned} \textbf{Property:} &\text{if } X \perp Y \Leftrightarrow I(X,Y) = 0 \\ &I(X,Y) \geq 0 \\ &[I(X,Y)]_{max} = min\{H(X),H(Y)\} \end{aligned}$$

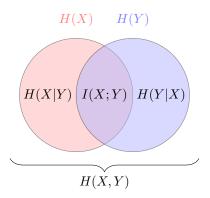


Figure 2: Mutual Information

1.4 KL-Divergence

$$X \sim p_X(x)$$
 $X \sim q_X(x)$

Definition 1.4.1. KL-Divergence (Relative Entropy):

Kullback-Leiblar Divergence between two PMF p(x) and q(x) is defined as:

$$D[p \parallel q] \stackrel{def}{=} \sum_{x \in \mathfrak{X}_p} p(x) \log \frac{p(x)}{q(x)} \in [0, +\infty]$$

KL-Divergence is used to measure the difference between two PMF.

Convention:

1.
$$0 \log 0 = 0$$

$$2. \ 0\log\tfrac{0}{\tilde{q}} = 0$$

3.
$$\tilde{p}\log\frac{\tilde{p}}{0} = +\infty$$

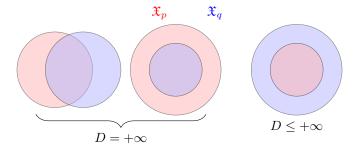


Figure 3: Value selection of KL-Divergence

Property: if $\exists x \in \mathfrak{X}$, st p(x) > 0 while q(x) = 0 then $D[p \parallel q] = +\infty$.

Definition 1.4.2. Conditional Relative Entropy:

The Conditional Relative Entropy between p(x,y) and q(x,y) is defined as the average KL-Divergence between p(y|x) and q(y|x) by p(x):

$$D[p(y|x) \parallel q(y|x)] = \sum_{x} p(x) \sum_{y} p(y|x) \log \frac{p(y|x)}{q(y|x)}$$
$$= \sum_{x,y} p(x,y) \log \frac{p(y|x)}{q(y|x)}$$

1.5 Chain Rule

- $p(x_1, x_2) = p(x_1)p(x_2|x_1)$ $p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)\dots p(x_n|x_1, x_2, \dots, x_{n-1})$
- $H(X_1, X_2, \dots, X_n) = H(X_1) + H(X_2|X_1) + \dots + H(X_n|X_1, X_2, \dots, X_{n-1})$
- Conditional Mutual Information:

$$I(X;Y|Z) = \sum_{X,Y,Z} p(x,y,z) \log \frac{p(x,y|z)}{p(x|z)p(y|z)}$$

means the information of X and Y given Z.

- $I(X_1, \ldots, X_n; Y) = I(X_1; Y) + I(X_2; Y|X_1) + \ldots + I(X_n; Y|X_1, \ldots, X_{n-1})$
- Chain Rule for KL-Divergence:

$$D[p(x,y)||q(x,y)] = D[p(x)||q(x)] + D[p(y|x)||q(y|x)]$$

Proof.

$$\begin{split} D[p(x,y)||q(x,y)] &\stackrel{def}{=} \sum_{x,y} p(x,y) \log \frac{p(x,y)}{q(x,y)} \\ &= \sum_{x,y} p(x,y) \log \frac{p(x)p(y|x)}{q(x)q(y|x)} \\ &= \sum_{x,y} p(x,y) \log \frac{p(x)}{q(x)} + \sum_{x,y} p(x,y) \log \frac{p(y|x)}{q(y|x)} \\ &= \sum_{x,y} p(x) \log \frac{p(x)}{q(x)} + \sum_{x,y} p(x,y) \log \frac{p(y|x)}{q(y|x)} \\ &= D[p(x)||q(x)] + D[p(y|x)||q(y|x)] \end{split}$$

1.6 Jensen Inequality

Definition 1.6.1. Convex Function:

A function f(x) is convex over (a,b), if $\forall x_1, x_2 \in (a,b)$, $f(\lambda x_1 + (1-\lambda)x_2) \le \lambda f(x_1) + (1-\lambda)f(x_2)$, where $\lambda \in [0,1]$.

Example 1.6.1. Common Convex and Concave Functions:

Convex Functions:
$$f(x) = x^2, e^x \leftrightarrow f^{(2)}(x) \ge 0$$

Concave Functions: $f(x) = \log x \leftrightarrow f^{(2)}(x) \le 0$

Theorem 1.6.1. Jensen Inequality:

For a random variable $x \in \mathfrak{X}$, if f(x) is convex, then:

$$f(\mathbf{E}X) \le \mathbf{E}f(X) \sim \sum_{x} p(x)f(x) \ge f(\sum_{x} p(x)x)$$
 (1)

Proof. Suppose (1) holds for $|X| \leq K - 1$

$$\sum_{i=1}^{K} p(x_i) f(x_i) = p(x_K) f(x_K) + \sum_{i=1}^{K-1} p(x_i) f(x_i)$$

$$= (1 - p(x_K)) \sum_{i=1}^{K-1} \frac{p(x_i)}{1 - p(x_K)} f(x_i) + p(x_K) f(x_K)$$

$$\geq (1 - p(x_K)) f(\sum_{i=1}^{K-1} \frac{p(x_i)}{1 - p(x_K)} x_i) + p(x_K) f(x_K)$$

$$= f(\sum_{i=1}^{K} p(x_i) x_i)$$

Theorem 1.6.2. Information Inequality:

$$D[p \parallel q] \ge 0$$
 with equality iff $p(x) = q(x)$

Proof.

$$D[p \parallel q] = \sum_{x} p(x) \log \frac{p(x)}{q(x)}$$
$$= -\sum_{x} p(x) \log \frac{q(x)}{p(x)}$$
$$\therefore -logx \text{ is convex}$$

$$\therefore D[p \parallel q] \ge -\log \sum_{x} p(x) \frac{q(x)}{p(x)}$$

$$= -\log \sum_{x} q(x)$$

$$= 0$$

Here, the equality holds iff $-log \frac{q(x)}{p(x)} = const \Rightarrow q(x) = p(x)$

Corollary 1.6.1.

$$I[X;Y] = D[p(x,y) || p(x)p(y)] \ge 0$$

Corollary 1.6.2.

$$D(p(X|Y) \parallel q(X|Y)) \ge 0$$

Corollary 1.6.3.

$$I(X;Y|Z) \ge 0$$

Theorem 1.6.3.

$$x \in X$$
 $H(X) \le \log |X|$

Proof.

$$\begin{split} u(x) = &\frac{1}{|X|} \\ D[p \parallel u] = &\sum_{x} p(x) \log \frac{p(x)}{u(x)} \geq 0 \\ = &\sum_{x} p(x) \log |X| + \sum_{x} p(x) log \frac{1}{u(x)} \\ = &\log |X| - H(X) \geq 0 \\ \Rightarrow &H(X) \leq \log |X| \end{split}$$

Theorem 1.6.4.

$$H(X) \ge H(X|Y)$$

Proof.

$$H(X) = I(X;Y) + H(X|Y)$$

$$\therefore I(X;Y) \ge 0$$

$$\therefore H(X) \ge H(X|Y)$$

Example 1.6.2. P(X,Y) is defined as follows:

X	1	2
1	0	$\frac{3}{4}$
2	$\frac{1}{8}$	$\frac{1}{8}$

$$\begin{split} H(X) &= -\sum_x p(x) \log p(x) \\ &= -(\frac{1}{8} \log \frac{1}{8} + \frac{7}{8} \log \frac{7}{8}) \\ &\approx 0.544 (bit) \end{split}$$

$$\begin{split} H(X|Y) &= -\sum_{x,y} p(x,y) \log p(x|y) \\ &= 0 - \frac{3}{4} \log 1 - \frac{1}{8} \log \frac{1}{2} - \frac{1}{8} \log \frac{1}{2} \\ &= 0.25 (bit) \end{split}$$

1.7 log-sum Inequality and convexity of D, H, I

Theorem 1.7.1. log-sum Inequality:

$$\sum_{i=1}^{n} a_i \log \frac{a_i}{b_i} \ge \left(\sum_{i=1}^{n} a_i\right) \log \frac{\sum_{i=1}^{n} a_i}{\sum_{i=1}^{n} b_i} \quad with \ equality \ iff \quad \frac{a_i}{b_i} = const$$

Proof. Define $f(x) = x \log x$, then $f^{(2)}(x) = \frac{1}{x} > 0$, so f(x) is convex.

$$\sum_{i} a_{i} \log \frac{a_{i}}{b_{i}} = \left(\sum_{j} b_{j}\right) \sum_{i} \frac{b_{i}}{\sum_{j} b_{j}} \frac{a_{i}}{b_{i}} \log \frac{a_{i}}{b_{i}}$$

$$\geq \left(\sum_{j} b_{j}\right) \left(\sum_{i} \frac{b_{i}}{\sum_{j} b_{j}} \frac{a_{i}}{b_{i}}\right) \log \left(\sum_{i} \frac{b_{i}}{\sum_{j} b_{j}} \frac{a_{i}}{b_{i}}\right)$$

$$= \sum_{i} a_{i} \log \frac{\sum_{i=1}^{n} a_{i}}{\sum_{j=1}^{n} b_{i}}$$

Theorem 1.7.2. KL-Divergence is a convex function.

For two pair of PMF (p_1, q_1) and (p_2, q_2) , we have:

$$D[\lambda p_1 + (1 - \lambda)p_2 \parallel \lambda q_1 + (1 - \lambda)q_2] \le \lambda D[p_1 \parallel q_1] + (1 - \lambda)D[p_2 \parallel q_2]$$

Also can be noted as:

$$(D(\lambda \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} + (1-\lambda) \begin{bmatrix} p_2 \\ q_2 \end{bmatrix}) \leq \lambda D(\begin{bmatrix} p_1 \\ q_1 \end{bmatrix}) + (1-\lambda)D(\begin{bmatrix} p_2 \\ q_2 \end{bmatrix}))$$

Proof.

$$left = \sum_{x} (\lambda p_{1} + (1 - \lambda)p_{2}) \log \frac{\lambda p_{1} + (1 - \lambda)p_{2}}{\lambda q_{1} + (1 - \lambda)q_{2}}$$

$$= \sum_{x} (\sum_{l=1}^{2} \lambda_{l} p_{l}) \log \frac{\sum_{l=1}^{2} \lambda_{l} p_{l}}{\sum_{l=1}^{2} \lambda_{l} q_{l}} \quad (\lambda_{1} = \lambda, \lambda_{2} = 1 - \lambda)$$

$$\leq \sum_{x} \sum_{l=1}^{2} \lambda_{l} p_{l} \log \frac{\lambda_{l} p_{l}}{\lambda_{l} q_{l}}$$

$$= \lambda \sum_{x} p_{1} \log \frac{p_{1}}{q_{1}} + (1 - \lambda) \sum_{x} p_{2} \log \frac{p_{2}}{q_{2}}$$

$$= \lambda D[p_{1} \parallel q_{1}] + (1 - \lambda)D[p_{2} \parallel q_{2}] = right$$

$$\therefore D[\lambda p_{1} + (1 - \lambda)p_{2} \parallel \lambda q_{1} + (1 - \lambda)q_{2}] \leq \lambda D[p_{1} \parallel q_{1}] + (1 - \lambda)D[p_{2} \parallel q_{2}]$$

Theorem 1.7.3. Concavity of Entropy:

$$H(\lambda p_1 + (1 - \lambda)p_2) \ge \lambda H(p_1) + (1 - \lambda)H(p_2)$$

Proof.

$$\begin{split} H[p] &= -\sum_x p(x) \log p(x) \qquad u(x) = \frac{1}{M} \quad M = |\mathfrak{X}| \\ D[p \parallel u] &= \sum_x p(x) \log \frac{p(x)}{u(x)} = \sum_x p(x) \log p(x) - \sum_x p(x) \log u(x) \\ &= -H[p] - \log M = -H[p] - \log |\mathfrak{X}| \\ &\because D \text{ is a convex function} \\ &\therefore H \text{ is a concave function} \\ &\therefore H(\lambda p_1 + (1 - \lambda) p_2) \geq \lambda H(p_1) + (1 - \lambda) H(p_2) \end{split}$$

Alternative proof:

Proof.

1.Generate an R.V:
$$\theta = \begin{cases} 1 & \text{with probability: } \lambda \\ 2 & \text{with probability: } 1 - \lambda \end{cases}$$

2.Generate an R.V: $X \sim \begin{cases} p_1 & \text{if } \theta = 1 \\ p_2 & \text{if } \theta = 2 \end{cases}$

$$\Rightarrow p(x) = \sum_{\theta} p(x,\theta) = \sum_{\theta=1}^2 p(x|\theta)p(\theta)$$

$$= \lambda p_1(x) + (1 - \lambda)p_2(x)$$

$$\Rightarrow H[\lambda p_1 + (1 - \lambda)p_2]$$

$$= H(X) \geq H(X|\theta) = -\sum_{x,\theta} p(x,\theta) \log p(x|\theta)$$

$$= -\sum_{x} \sum_{\theta=1}^2 p(x|\theta)p(\theta) \log p(x|\theta)$$

$$= -\lambda \sum_{x} p_1 \log p_1 - (1 - \lambda) \sum_{x} p_2 \log p_2$$

$$= \lambda H(p_1) + (1 - \lambda)H(p_2)$$

$$\therefore H(\lambda p_1 + (1 - \lambda)p_2) \geq \lambda H(p_1) + (1 - \lambda)H(p_2)$$

Theorem 1.7.4. Convexity of Mutual Information:

Let $(X,Y) \sim p(x,y) = p(x)p(y|x)$. The mutual information I(X;Y) is a concave function of p(x) for fixed p(y|x) and a convex function of p(y|x) for fixed p(x).

$$I(X;Y) \begin{cases} concave \ of \ p(x), for \ fixed \ p(y|x) \\ convex \ of \ p(y|x), for \ fixed \ p(x) \end{cases}$$

Proof.

$$\begin{split} I(X;Y) &= \sum_{x,y} p(x,y) \log \frac{p(x,y)}{p(x)p(y)} \\ &= H(Y) - H(Y|X) = H(Y) - \sum_{x} p(x)H(Y|X=x) \end{split}$$

If p(y|x) is fixed, then $p(y) = \int p(x)p(y|x)dx$ is a linear function of p(x). Because H(Y) is a concave function of p(y), so H(Y) is a concave function of p(x). The latter term p(x)H(Y|X=x) is a linear function of p(x), so I(X;Y) is a concave function of p(x).

Fix
$$p(x)$$
, set two CPMF $p_1(y|x), p_2(y|x)$

$$p_{\lambda}(y|x) = \lambda p_1(y|x) + (1 - \lambda)p_2(y|x)$$

$$p_{\lambda}(x,y) = p(x)p_{\lambda}(y|x) = \lambda p_1(x,y) + (1 - \lambda)p_2(x,y)$$

$$p_{\lambda}(y) = \int p_{\lambda}(x,y)dx = \lambda p_1(y) + (1 - \lambda)p_2(y)$$
Set $q_{\lambda}(x,y) = p(x)p_{\lambda}(y)$

$$q_{\lambda}(x,y) = \lambda q_1(x,y) + (1 - \lambda)q_2(x,y)$$

$$I(X;Y) = \sum_{x,y} p_{\lambda}(x,y) \log \frac{p_{\lambda}(x,y)}{p(x)p_{\lambda}(y)} = D[p_{\lambda} \parallel q_{\lambda}]$$

$$\therefore D[p_{\lambda} \parallel q_{\lambda}] \text{ is a convex function of } p_{\lambda}$$

$$p_{\lambda}(x,y) = p(x)p_{\lambda}(y|x) \text{ is a linear function of } p_{\lambda}(y|x)$$

$$\therefore I(X;Y) \text{ is a convex function of } p(y|x)$$

1.8 Data Processing Inequality

Definition 1.8.1. Markov Chain:

 $R. V X, Y, Z \text{ form a } MC: X \to Y \to Z \text{ if } p(x, y, z) = p(x)p(y|x)\frac{p(z|y)}{p(z|y)}, \text{ which also means } p(x, z|y) = p(x|y)p(z|y).$

If any part of a process only depends on the previous part, then any three continuous parts of the process form a Markov Chain.

Example 1.8.1. If a Checker is placed on a chessboard, and the probability of next move is:

$$P(X) = \begin{cases} p_1, X = up \\ p_2, X = down \\ p_3, X = left \\ p_4, X = right \end{cases}$$

any three continuous moves form a Markov Chain.

Theorem 1.8.1. Data Processing Inequality:

If $X \to Y \to Z$ form a Markov Chain, then $I(X;Y) \ge I(X;Z)$.

Proof.

$$I(X;Y,Z) = I(X;Z) + I(X;Y|Z)$$

$$= I(X;Y) + I(X;Z|Y)$$

$$\therefore X|Y \perp Z|Y \Rightarrow X \perp Z|Y \Rightarrow I(X;Z|Y) = 0$$

$$\therefore I(X;Y,Z) = I(X;Y) = I(X;Z) + I(X;Y|Z)$$

$$\therefore I(X;Y|Z) \ge 0$$

$$\therefore I(X;Y) \ge I(X;Z)$$

Corollary 1.8.1. If $Z = f(Y) \Rightarrow I(X;Y) \geq I(X;f(Y))$

1.9 Fano's Inequality

We want to estimate an unknown R.V X with a distribution p(x). We observe an R.V Y that is related to X by the conditional distribution p(y|x). From Y, we caculate a function $f(Y) = \hat{X}$. X, Y, \hat{X} form a MC $X \to Y \to \hat{X}$.

Define the probability of error:

$$P_e = P(\hat{X} \neq X)$$
 $Y \sim P(Y|X)$

We can set the R.V E:

$$E = \begin{cases} 1 & \text{if } \hat{X} \neq X \\ 0 & \text{if } \hat{X} = X \end{cases} \qquad P_e = P(E = 1)$$

Theorem 1.9.1. Fano's Inequality:

$$H(P_e) + P_e \log |\mathfrak{X}| \ge H(X|\hat{X}) \ge H(X|Y)$$

$$\Rightarrow 1 + P_e \log |\mathfrak{X}| \ge H(X|Y)$$

$$\Rightarrow P_e \ge \frac{H(X|Y) - 1}{\log |\mathfrak{X}|}$$

Proof.

$$H(E, X|\hat{X}) = H(X|\hat{X}) + H(E|X, \hat{X})$$
$$= H(E|\hat{X}) + H(X|E, \hat{X})$$

If X, \hat{X} is fixed, then E is also fixed, so

$$H(E|X,\hat{X}) = 0 \Rightarrow H(E,X|\hat{X}) = H(X|\hat{X})$$

Since conditioning reduces entropy, we have:

$$H(E|\hat{X}) \le H(E) = H(P_e)$$

It is easy to see that E is a binary-valued R.V, so $H(X|E,\hat{X})$ can be bounded as:

$$H(X|E,\hat{X}) = P_r(E=0)H(X|\hat{X},E=0) + P_r(E=1)H(X|\hat{X},E=1)$$

Since E=0 means $\hat{X}=X,$ so $H(X|\hat{X},E=0)=0.$

Since the upper bound of H is $\log |\mathfrak{X}|$, so: $H(X|E,\hat{X}) \leq P_e \log |\mathfrak{X}|$

Combine the above results, we have:

$$H(E|\hat{X}) + H(X|E, \hat{X}) \le H(E) + (1 - P_e)0 + P_e \log |\mathfrak{X}|$$
$$\Rightarrow H(X|\hat{X}) \le H(P_e) + P_e \log |\mathfrak{X}|$$

§ 2 AEP(Asymptotic Equipartition Property)

2.1 AEP

Review:Law of large numbers:

For X_1, X_2, \ldots, X_n i.i.d $\sim P \rightarrow$ note as \underline{X}_n :

$$\frac{1}{n} \sum_{i} X_{i} \overset{n \to \infty}{\underset{p.}{\longrightarrow}} \mathbf{E} X = \sum_{x} x p(x)$$

Theorem 2.1.1. AEP:

$$\frac{1}{n}\log\frac{1}{p(\underline{X}_n)} = \frac{1}{n}\sum_{i=1}^n\log\frac{1}{p(X_i)} \stackrel{n\to\infty}{\underset{p.}{\longrightarrow}} \mathbf{E}\log\frac{1}{p(x)} = H(X)$$

Definition 2.1.1. Typical Set:

 $A_{\epsilon}^{(n)}$ is a set of sequences $(x_1, x_2, \dots, x_n) \in X^{(n)}$ with the property that:

$$2^{-n(H(X)+\epsilon)} < p(x_1, x_2, \dots, x_n) < 2^{-n(H(X)-\epsilon)}$$

$$1. \left| A_{\epsilon}^{(n)} \right| = 2^{nH(X)}$$

2.
$$(1 - \epsilon)2^{nH(X)} \le P(A_{\epsilon}^{(n)}) \to 1$$

Example 2.1.1.

$$X_i \sim Bernollip = \begin{cases} 1 & with \ probability: \ p = 0.9 \\ 0 & with \ probability: \ p = 0.1 \end{cases}$$

Now we sample n = 100 times, then we have:

$$(1, 1, 1, \dots, 1, 1)$$
 with 100 "1"

$$(1,0,1,1,0,\ldots,0,1)$$
 with 90 "1" and 10 "0"

Obviously, the second one is more likely to happen.

Theorem 2.1.2. Property of the typical set:

(1) If
$$(x_1, \ldots, x_n) \in A_{\epsilon}^{(n)}$$
 then

$$H(X) - \varepsilon \le -\frac{1}{n}\log p(x_1, \dots, x_n) \le H(X) + \varepsilon$$

(2)
$$P_r(X_1,...,X_n) \in A_{\epsilon}^{(n)} \ge 1 - \varepsilon$$
 for n sufficiently large.

(3)
$$\left| A_{\epsilon}^{(n)} \right| \leq 2^{n(H(X) + \varepsilon)}$$

$$(4) \left| A_{\epsilon}^{(n)} \right| \ge 2^{n(H(X) - \varepsilon)}$$

From (3) and (4), we have:

$$\left| A_{\epsilon}^{(n)} \right| \approx 2^{nH(X)}$$

Proof. (2) From AEP, $-\frac{1}{n}\log p(x_1,\ldots,x_n) \stackrel{p}{\to} H(X)$

 \therefore For any $\delta > 0, \varepsilon > 0, \exists n_0, \forall n \geq n_0$:

$$P_r\left\{\left|-\frac{1}{n}\log p(x_1,\ldots,x_n)-H(X)\right|<\varepsilon\right\}\geq 1-\delta$$

set
$$\delta = \varepsilon$$
, then: $P_r\{A_{\varepsilon}^{(n)}\} \ge 1 - \varepsilon$

(3)

$$1 = \sum_{\underline{x}_n \in X^{(n)}} P(x) \ge P_r \{A_{\varepsilon}^{(n)}\} = \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} P(x) \ge \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} 2^{-n(H(X) + \varepsilon)}$$
$$= \left| A_{\epsilon}^{(n)} \right| 2^{-n(H(X) + \varepsilon)}$$

$$\Rightarrow \left| A_{\epsilon}^{(n)} \right| \le 2^{n(H(X) + \varepsilon)}$$

(4) $1 - \varepsilon \le P_r \{ \left| A_{\epsilon}^{(n)} \right| \} \le \sum_{\underline{x}_n \in A_{\epsilon}^{(n)}} 2^{-n(H(X) - \varepsilon)} = \left| A_{\epsilon}^{(n)} \right| 2^{-n(H(X) - \varepsilon)}$ $\Rightarrow \left| A_{\epsilon}^{(n)} \right| \ge (1 - \varepsilon) 2^{n(H(X) - \varepsilon)}$

2.2 Consequences of AEP:Data Compression

Compression Scheme:

- 1. If $\underline{x}_n=(x_1,\ldots,x_n)\in A_{\varepsilon}^{(n)}$, we use $\lceil n(H(X)+\varepsilon) \rceil$ to encode \underline{x}_n ;
- 2. If $\underline{x}_n \notin A_{\varepsilon}^{(n)}$, we use $\lceil n \log |X| \rceil$ to encode \underline{x}_n ;
- 3. Use extra 1 bit to identify whether $\underline{x}_n \in A_{\varepsilon}^{(n)}$ or not.

$$\underline{x}_n \to b_1 b_2 \cdots b_{l(\underline{x}_n)}$$

Here,
$$b_1=1$$
 or 0 , $l(\underline{x}_n) \leq \begin{cases} n(H(X)+\varepsilon)+2 & (1) \\ n\log|X|+2 & (2) \end{cases}$

Theorem 2.2.1.

$$\mathbf{E}[\frac{1}{n}l(\underline{x}_n)] \le H(X) + \varepsilon$$

Proof.

$$\begin{split} \mathbf{E}[\frac{1}{n}l(\underline{x}_n)] &= \sum_{\underline{x}_n} p(\underline{x}_n) \cdot \frac{1}{n}l(\underline{x}_n) \\ &= \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}l(\underline{x}_n) + \sum_{\underline{x}_n \notin A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}l(\underline{x}_n) \\ &\leq \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}(n(H(X) + \varepsilon) + 2) + \sum_{\underline{x}_n \notin A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}(n\log|X| + 2) \\ &= P_r\{A_{\varepsilon}^{(n)}\} \cdot \frac{1}{n}(n(H(X) + \varepsilon) + 2) + (1 - P_r\{A_{\varepsilon}^{(n)}\}) \cdot \frac{1}{n}(n\log|X| + 2) \\ &\leq \frac{1}{n}(n(H(X) + \varepsilon) + 2) + \varepsilon \frac{1}{n}(n\log|X| + 2) \\ &= H(X) + \varepsilon + \frac{2}{n} + \frac{\varepsilon}{n}\log|X| + \frac{2\varepsilon}{n} \\ &= H(X) + \varepsilon' \qquad \text{Here,we set } \varepsilon' = \varepsilon + \frac{2}{n} + \frac{\varepsilon}{n}\log|X| + \frac{2\varepsilon}{n} \end{split}$$

§ 3 Data Compression

3.1 Code

Definition 3.1.1. Source Code:

(1) For a R.V. X is a map

$$C: X \to D^*$$
 $x \mapsto d_1 d_2 \cdots d_{l(x)} = c(x)$

- (2) c(x) is called **codeword** of x.
- (3) l(x) is called **length** of the codeword, $l(x) \leq \infty$.

Example 3.1.1. $\mathcal{X} = \{1, 2, 3, 4\}$

x	p(x)	Codeword(*)	Codeword(Native)
1	$\frac{1}{2}$	0	00
2	$\frac{\mathbb{I}}{4}$	10	01
3	$\frac{1}{8}$	110	10
4	$\frac{1}{8}$	111	11

$$\bar{l}(x) = H(X) = -\frac{1}{2}\log\frac{1}{2} - \frac{1}{4}\log\frac{1}{4} - \frac{1}{8}\log\frac{1}{8} - \frac{1}{8}\log\frac{1}{8} = 1.75 \ bit$$

Definition 3.1.2. Nonsigular Code:

A code C is nonsigualr, if $\forall x \neq x'$ then $C(x) \neq C(x')$.

Definition 3.1.3. Extension of Code:

For a code:

$$C: x \longmapsto C(x)$$

The extension of code is defined as:

$$C^*: x_1x_2\cdots x_n \longmapsto C(x_1)C(x_2)\cdots C(x_n)$$

Definition 3.1.4. Uniquely Codable:

A code is uniquely codable if C^* is nonsigular.

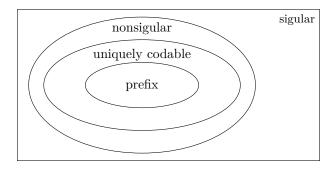
Example 3.1.2. Here are some examples of codes:

x	singular	nonsigualr	uniquely codable but no prefix	prefix
1	0	0	10	0
2	0	010	00	10
3	1	01	11	110
4	1	10	110	111
$C^*(324)$	101	0101010	1100110	11010111

Obviously, the nonsigular code 0101010 can be decoded as 324 or 3331.

Definition 3.1.5. Prefix Code/Instantaneous Code:

A code is a prefix code if no codeword is a prefix of any other code.



3.2 Kraft Inequality

Theorem 3.2.1. Kraft Inequality:

1) For any prefix code over an alphabet of size D. The code length l_1, l_2, \ldots, l_m must satisfy:

$$\sum_{i=1}^{m} D^{-l_i} \le 1$$

2) Conversely, given a set of word length $\{l_1, \ldots, l_m\}$ then there exists a prefix code with those lengths, if the set satisfies the Kraft inequality.

3.3 Optimal Codes

Here we will show some inferences:

$$x \in \{x_1, \dots, x_m\} \quad p(x) = p_1, \dots, p_m$$

$$C(x_1), \dots, C(x_m) \quad l(x_1), \dots, l(x_m) \quad \bar{l} = \sum_{i=1}^m p_i l(x_i)$$
We want to find:
$$\min_{l_i} \bar{l} = \sum_{i=1}^m p_i l(x_i) \quad s.t. \sum_i D^{-l_i} \le 1$$

$$l_i \in \mathbf{Z}^* \Rightarrow l_i \in \mathbf{R}^*$$

$$J = \sum_i p_i l_i + \lambda (\sum_i D^{-l_i} - 1)$$

$$\frac{\partial J}{\partial l_j} = p_j - \lambda D^{-l_j} \ln D = 0 \Rightarrow D^{-l_j} = \frac{p_j}{\lambda \ln D}$$

$$\frac{\partial J}{\partial lambda} = \sum_i D^{-l_i} - 1 = 0 \Rightarrow \frac{\sum_i p_i}{\lambda \ln D} = 1 \Rightarrow \lambda = \frac{1}{\ln D}$$

$$D^{-l_j} = \frac{p_j}{\lambda \ln D} = p_j \Rightarrow l_j^* = -\log_D p_j$$

$$\bar{l}^* = \sum_i p_i l_i^* = \sum_i p_i (-\log_D p_i) = -\sum_i p_i \log_D p_i = H_D[X]$$

Theorem 3.3.1. The expected length L of any prefix D-adic code satisfies:

$$L \geq H_D[X]$$

3.4 Upper bound on the optimal code length

Theorem 3.4.1.

$$H_D[X] \le \bar{l}^* \le H_D[X] + 1$$

Proof.

$$l_i^* \in \mathbf{R}^* \Rightarrow l_i = \lceil l_i^* \rceil \in \mathbf{Z}^*$$

$$\sum_i D^{-l_i} \le \sum_i D^{-l_i^*} = 1 \quad \text{Kraft Inequality holds}$$

$$\sum_i p_i \lceil l_i^* \rceil \le \sum_i p_i (l_i^* + 1) = \sum_i p_i l_i^* + \sum_i p_i = H_D[X] + 1$$

*Wrong Code:If we use anothor distribution q(x) instead of the true p(x), then we will get:

Theorem 3.4.2. Wrong Code:

$$l(x) = \left\lceil \log \frac{1}{q(x)} \right\rceil$$

$$\bar{l} = \mathbf{E}l(x) = \sum_{i} p(x_i)l(x_i) = \sum_{i} p(x_i) \left\lceil \log \frac{1}{q(x)} \right\rceil$$

$$\sum_{i} p(x_i) \left\lceil \log \frac{1}{q(x)} \right\rceil < \sum_{i} p(x_i) (\log \frac{1}{q(x)} + 1)$$

$$= \sum_{i} p(x_i) \log \frac{p(x_i)}{q(x_i)} - \sum_{i} p(x_i) \log p(x_i) + \sum_{i} p(x_i)$$

$$= D(p \parallel q) + H[p] + 1$$

$$\sum_{i} p(x_i) \left\lceil \log \frac{1}{q(x)} \right\rceil > D(p \parallel q) + H[p]$$

We call $D(p \parallel q)$ the puhishment of wrong code.

3.5 Huffman Code

Observation:

- 1. Smaller probability \Rightarrow longer codeword.
- 2. The two longest codewords must have the same length.
- 3. Two longest codewords merges to one single source symbol, with the probability being the sum of the replaced two symbols.

Here we have the Huffman algorithm:

Input: $\{(x_i, p_i)|i = 1, 2, \cdots, n\}$

Output: $\{C(x_i)\}\$ A tree representing Huffman code.

Algorithm:

Initialize Q as the PriorityQueue $(\{p_i,x_i,N_i\})/N_i$ is the tree node While Q.size()>1:

§ 4 Entropy Rate of a stochastic process

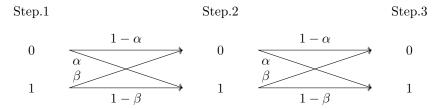
$$X \leftarrow H[X]$$

$$X_1, X_2, \dots, X_n i.i.d \sim p(x) \leftarrow H[X_1, X_2, \dots, X_n] = nH[X]$$
 Normally, $X_1, \dots, X_n, X_i \not\perp X_j, H[X_1, \dots, X_n] = ? \propto n \cdot h$ Here, h is called the entropy rate of the process.

4.1 Markove Chain

$$P(X_n|X_1, X_2, \dots, X_{n-1}) = P(X_n|X_{n-1})$$

Example 4.1.1. $x \in \{0, 1\}$

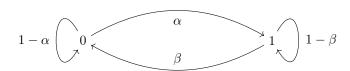


This is a Markov Chain with 3 steps. To describe a Markov Chain, we need:

1. $P_0(X_0)$

2.
$$P(X_{n+1}|X_n) = \begin{bmatrix} P(0|0) = 1 - \alpha & P(1|0) = \alpha \\ P(0|1) = \beta & P(1|1) = 1 - \beta \end{bmatrix}$$

We can also use a map to describe a Markov Chain:



Definition 4.1.1. Time invariant Markov Chain:

A Markov Chain is time invariant if the transition probability does not depend on time:

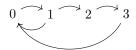
$$P_{k+1}(X_{k+1}|X_k) = P_k(X_k|X_{k-1})$$

Notions of Markov Chain:

1. **State:** X_i is a state of the Markov Chain, X_0 is the initial state.

- 2. Irreducable: $\forall i, j, \exists n, s.t. P(X_n = j | X_i = i) > 0$
- 3. **Aperiodic:**The largest common factor of the length of paths from a state to itself is 1.

Example 4.1.2. Here is a Markov Chain with 4 states:

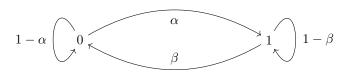


Length of path 1 is 2, length of path 2 is 4, the largest common factor is 2.

This Markov Chain is not aperiodic.

4. Probability trainsition matrix: $p_{ij} = P(X_{n+1} = X_j | X_n = X_i)$ $P = [p_{ij}] \qquad P(X_{n+1}) = \sum_{X_n} P(X_{n+1}, X_n) = [P(X_1) \dots P(X_n)]P$

Example 4.1.3.
$$P(X_{n+1}|X_n) = \begin{bmatrix} P(0|0) = 1 - \alpha & P(1|0) = \alpha \\ P(0|1) = \beta & P(1|1) = 1 - \beta \end{bmatrix}$$



$$V_{n} = \frac{P(X_{n} = 0)}{P(X_{n} = 1)} = \frac{0.1}{0.9} \qquad V_{n+1} = V_{n}^{T}P \qquad V_{\infty} = ?$$

$$V_{\infty} = V_{\infty}P \Rightarrow \begin{cases} (1 - \alpha)V_{1} + \beta V_{2} = V_{1} \\ \alpha V_{1} + (1 - \beta)V_{2} = V_{2} \\ V_{1} + V_{2} = 1 \end{cases} \Rightarrow \begin{cases} (1 - \alpha)V_{1} + \beta V_{2} = V_{1} \\ V_{1} + V_{2} = 1 \end{cases}$$

$$\Rightarrow \frac{V_{1}}{V_{2}} = \frac{\beta}{\alpha}$$

4.2 Entropy Rate

Definition 4.2.1. Entropy Rate:

1) The entropy rate of a stochastic process $\{X_i\}$ is defined as:

$$H[\mathcal{X}] = \lim_{n \to \infty} \frac{1}{n} H[X_1, \dots, X_n]$$

2) Conditional entropy rate:

$$H'[\mathcal{X}] = \lim_{n \to \infty} H[X_n | X_1, \dots, X_{n-1}]$$

Definition 4.2.2. Stationary stochastic process:

A stochastic process $\{X_i\}$ is stationary if the joint distribution of X_1, \ldots, X_n does not depend on n:

$$P(X_{l+1},...,X_{l+n}) = P(X_{l+2},...,X_{l+n+1})$$

Theorem 4.2.1. For a stationary stochastic process:

$$H[X_n|X_1,\ldots,X_{n-1}] \ge H[X_{n+1}|X_1,\ldots,X_n]$$

 $\Rightarrow H'[\mathcal{X}] \text{ exists a limit}$

Proof.

$$H[X_n|X_1,\ldots,X_{n-1}] = H[X_{n+1}|X_1,\ldots,X_n] \ge H[X_{n+1}|X_1,\ldots,X_n]$$

Theorem 4.2.2. Cesáro mean:

If
$$a \to a_n, b_n = \frac{1}{n} \sum_{i=1}^n a_i$$
, then $b_n \to a$

Based on the above theorem, we can get:

$$H[\mathcal{X}] = \lim_{n \to \infty} \frac{1}{n} H[X_1, \dots, X_n]$$

$$= \lim_{n \to \infty} (H[X_1] + H[X_2|X_1] + \dots + H[X_n|X_1, \dots, X_{n-1}])$$

$$H[X_n|X_1, \dots, X_{n-1}] \stackrel{def}{=} b_n$$

$$H[\mathcal{X}] = \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^{n} b_m = \lim_{n \to \infty} b_n = H'[\mathcal{X}]$$

Theorem 4.2.3. Entropy rate of a Markov Chain:

Obviously, the entropy rate only depends on the transition probability matrix:

$$H[\mathcal{X}] = F(P)$$

$$H[\mathcal{X}] = H'[\mathcal{X}] = \lim_{n \to \infty} H[X_n | X_1, \dots, X_{n-1}] = \lim_{n \to \infty} H[X_n | X_{n-1}]$$

$$= H[X_2 | X_1] \qquad X \sim V_{\infty} \qquad V_{\infty} = V_{\infty} P$$

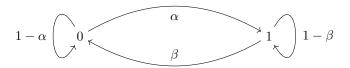
$$= -\sum_{X_1} V_{\infty} P(X_2 | X_1) \log P(X_2 | X_1)$$

Theorem 4.2.4. Let u and P be the stationary distribution and transition probability matrix respectively, then the entropy rate:

$$H[\mathcal{X}] = -\sum_{i,j} u_i P_{ij} \log P_{ij}$$

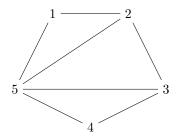
where $u_j = \sum_i u_i p_{ij}$

Example 4.2.1. For the Markov Chain:



$$\begin{split} H[\mathcal{X}] = & H[X_2|X_1] \\ = & -\frac{\beta}{\alpha+\beta} ((1-\alpha)\log(1-\alpha) + \alpha\log\alpha) - \frac{\alpha}{\alpha+\beta} ((1-\beta)\log(1-\beta) + \beta\log\beta) \\ = & \frac{\beta}{\alpha+\beta} H[X_1] + \frac{\alpha}{\alpha+\beta} H[X_2] \end{split}$$

Example 4.2.2. Random walk on a graph:



$$\begin{split} X_k &\in \{1,2,3,4,5\} \quad k = 0,1,2 \quad X_0 = l \\ P(X_{k+1} = j | X_k = i) &= \frac{A_{ij}}{d_i} \quad A_{ij} = \begin{cases} 1 & \text{if } (i,j) \in E \\ 0 & \text{otherwise} \end{cases} \\ P_0(X_0) &= \begin{cases} 1 & \text{if } X_0 = l \\ 0 & \text{otherwise} \end{cases} \quad v^* = v^* P \quad v^* = [v_1, v_2, \dots, v_5] \\ v^* P &= [v_1 \frac{A_{11}}{d_1} + v_2 \frac{A_{21}}{d_2} + v_3 \frac{A_{31}}{d_3} + v_4 \frac{A_{41}}{d_4} + v_5 \frac{A_{51}}{d_5}, \dots] \\ \Rightarrow v_i^* &= \frac{d_i}{2D} \quad D = |E| \\ H[\mathcal{X}] &= -\sum_{i,j} v_i^* p_{ij} \log p_{ij} = -\sum_{i,j} \frac{d_i}{2D} \frac{A_{ij}}{d_i} \log \frac{A_{ij}}{d_i} = -\sum_{i,j} \frac{A_{ij}}{2D} \log (\frac{A_{ij}}{2D} \frac{2D}{d_i}) \\ &= -\sum_{i,j} \frac{A_{ij}}{2D} \log \frac{A_{ij}}{2D} - \sum_{i,j} \frac{A_{ij}}{2D} \log \frac{2D}{d_i} \\ &= -\sum_{i,j} \frac{A_{ij}}{2D} \log \frac{A_{ij}}{2D} + \sum_{i} \frac{d_i}{2D} \log \frac{d_i}{2D} \\ &= \log(2D) - H[v^*] \end{split}$$

§ 5 Mutual Information Estimation

5.1 Fenchel-Legendre Transform

Definition 5.1.1. F-L transform

For a given f(u), Fenchel-Legredre transform of f is defined by:

$$f^*(t) = \sup_{u} \{ut - f(u)\}$$

Corollary 5.1.1. If f is convex, the ut - f(u) is concave.

$$u^*: \frac{d(ut - f(u))}{du} = 0 \Rightarrow t = f'(u^*) \Rightarrow u^* = f'^{-1}(t)$$

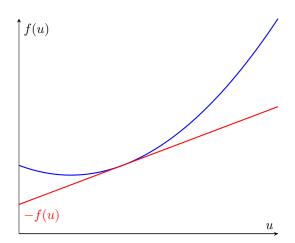
therefore, $f^*(t) = u^*t - f(u^*), u^* = f'^{-1}(t)$

Definition 5.1.2. Inverse FL transform

$$f^{**}(u) = (f^*)^* = \sup_{t} \{ut - f^*(t)\}$$

Example 5.1.1. Obviously, the tangent line of f(u) at u^* is:

$$g(u) = ut^* - f(u^*)$$



Each t corresponds to a tangent line of f(u).

Theorem 5.1.1. F-L transform for a convex

If f(u) is strictly convex, then $f^{**} = f$.

Proof.

$$f^*(t) = u^*t - f(u^*) \quad \text{where } t = f'(u^*)$$

$$f^{**}(u) = (f^*(t))^* = \sup_{t} \{ut - u^*t + f(u^*)\}$$

$$= \sup_{u^*} \{uf'(u^*) - u^*f'(u^*) + f(u^*)\}$$

$$\frac{d[f'(u^*)(u - u^*) + f(u^*)]}{du^*} = f''(u^*)(u - u^*) - f'(u^*) + f'(u^*)$$

$$= f''(u^*)(u - u^*) = 0$$

$$\therefore f \text{ is strictly convex} \Rightarrow f''(u^*) > 0 \Rightarrow u = u^*$$

$$\therefore f^{**}(u) = \sup_{t} \{ut - u^*t + f(u^*)\} = f(u)$$

5.2 Estimate Mutual Information/K-L Divergence via maximizing lower bound

• Setting:Suppose we have a set of observed data:

$$\{(Y_1, Z_1), (Y_2, Z_2), \dots, (Y_m, Z_m)\} = D \quad (Y_i, Z_i) \sim P(Y, Z) \to \text{Unkown}$$

• Task:The objective is to estimate:

$$I[Y;Z] = \sum_{Y,Z} p(Y,Z) \log \frac{p(Y,Z)}{p(Y)p(Z)} = D[p(Y,Z) \parallel (p(Y)p(Z))]$$

Example 5.2.1.

$$Y \in \{0, 1\}$$
 $Z \in \{0, 1\}$

$$P(Y,Z) = \frac{\#(Y,Z)}{\#total}$$

When the dimension of observed data is too large, it is hard to estimate the distribution by the frequency.

Theorem 5.2.1. Nguyen 2010:

$$D[P(X) \parallel Q(X)] = \mathop{\mathbf{E}}_{X \sim P} \log \frac{P(X)}{Q(X)} \geq \sup_{T \in \mathcal{T}} \{ \mathop{\mathbf{E}}_{X \sim P} T(X) - \mathop{\mathbf{E}}_{X \sim Q} e^{T(X) - 1} \}$$

Through this theorem, we can estimate the mutual information by machine learning.

Proof.

$$D[P(X) \parallel Q(X)] = \sum_{X} P(X) \log \frac{P(X)}{Q(X)} = \sum_{X} Q(X) \frac{P(X)}{Q(X)} \log \frac{P(X)}{Q(X)}$$

$$= \sum_{X} Q(X) f(u) \quad \begin{cases} u = \frac{P(X)}{Q(X)} \\ f(u) = u \log u \end{cases}$$

$$f'(u) = \log u + 1 \quad f'(u^*) = t = \log u^* + 1 \Rightarrow u^* = e^{t-1}$$

$$f^*(t) = u^* t - f(u^*) = t e^{t-1} - f(e^{t-1}) = e^{t-1}$$

$$\therefore \sum_{X} Q(X) f(u) = \sum_{X} Q(X) (f^*)^* = \sum_{X} Q(X) \sup_{t} \{ut - f^*(t)\}$$

$$= \sum_{X} Q(X) \sup_{t} \{\frac{P(X)}{Q(X)} t - f^*(t)\}$$

 $f = u \log u$ is convex $\Rightarrow f^*$ is concave $\Rightarrow f^{**}$ is convex

$$\therefore \sum_{X} Q(X)f(u) \ge \sup_{t} \{ \sum_{X} Q(X) \left[\frac{P(X)}{Q(X)} t - f^{*}(t) \right] \}$$

$$= \sup_{t} \{ \sum_{X} P(X)t - \sum_{X} Q(X)f^{*}(t) \}$$

$$= \sup_{X} \{ \sum_{X \sim P} t_{X} - \sum_{X \sim Q} f^{*}(t) \}$$

$$= \sup_{X} \{ \sum_{X \sim P} t_{X} - \sum_{X \sim Q} e^{t_{X} - 1} \}$$

5.3 Implement the estimation of I using lower bound

Let
$$X = (Y, Z)$$
 $P(X) = P(Y, Z)$ $Q(X) = P(Y)P(Z)$

Critic function $T_{\theta}(X)$:Define a neural network $T_{\theta}(X)$ with parameter $\theta = \{\omega_1, \omega_2\}.T_{\theta} = f(\omega_2 f(\omega_1 X))$ while f is a non-linear function.

$$\begin{split} & \max_{\theta} \{ \sum_{Y,Z} P(Y,Z) T_{\theta}(Y,Z) - \sum_{Y,Z} P(Y) P(Z) e^{T_{\theta}(Y,Z) - 1} \} \\ & \approx \max_{\theta} \{ \frac{1}{N} \sum_{i=1}^{N} T_{\theta}(Y_{i},Z_{i}) - \frac{1}{N^{2}} \sum_{i=1}^{N} \sum_{j=1}^{N} e^{T_{\theta}(Y_{i},Z_{j}) - 1} \} \\ & \approx \max_{\theta} \{ \frac{1}{N} \sum_{i=1}^{N} T_{\theta}(Y_{i},Z_{i}) - \frac{1}{M} \sum_{k=1}^{M} e^{T_{\theta}(Y_{i_{k}}Z_{j_{k}}) - 1} \} \quad i_{k}, j_{k} \quad i.i.d. \sim (1,\ldots,N) \end{split}$$