Information Theory

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Information Theory

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§ 1 Entropy, Relative Entropy and Matual information

1.1 Entropy

Setting $X \sim P$ discrete random variable "P" is the probability massfunction(PMF) of X. $P_X(X=x) = P_r[X=x]$ $P_X(x) \longleftrightarrow p(x)$

Definition 1.1.1. Entropy:

$$H(X) = -\sum_{x \in X} p(x) \log p(x) \qquad (log_2 : bit \quad log_e : nat)$$

$$Convention: \ 0log0 = 0$$

$$Actually, H(X) = H[P]$$

$$Accordingly, \bar{X} = \sum_{x \in X} p(x)x \sim \underset{X \sim p(x)}{\mathbf{E}} X$$

$$H(X) \sim \underset{X \sim p(x)}{\mathbf{E}} \log \frac{1}{p(x)}$$

Example 1.1.1. Binary Entropy Function:

$$h(p) = \underset{x \in \{0,1\}}{H}(X) = -plog_2p - (1-p)log_2(1-p)$$

Here, $p = P(X = 0)$

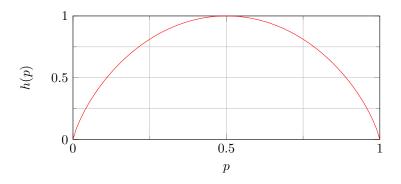


Figure 1: Binary Entropy Function

Each point on the curve represents one distribution of X. H property:

- 1. $H[P] \ge 0$
- 2. $H_b(X) = log_b a H_a(X)$ nat, when a = e

1.2 Joint Entropy and Conditional Entropy

Definition 1.2.1. Joint Entropy:
$$(X,Y) \sim p_{X,Y}(X=x,Y=y)$$

$$H[p_{X,Y}] = -\sum_{x \in \mathfrak{X}, y \in \mathfrak{Y}} p_{X,Y}(x,y) \log p_{X,Y}(x,y)$$

Definition 1.2.2. Conditional Entropy:
$$p_{X|Y}(X = x|Y = y)$$

$$H[X|Y] = -\sum_{x \in \mathfrak{X}, y \in \mathfrak{Y}} p_{X,Y}(x,y) \log p_{X|Y}(x|y)$$

$$\uparrow \qquad \uparrow$$

$$ioint \qquad conditional$$

Chain Rule:
$$P(x,y) = P_Y(y)P_{X|Y}(x|y)$$

Theorem 1.2.1.
$$H(X,Y) = H(Y) + H(X|Y)$$

Proof.

$$\begin{split} H(X,Y) &= -\mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log p_{X,Y}(x,y) \\ &= -\mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log(p_{X|Y}(x|y)p_{Y}(y)) \\ &= -\mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log p_{X|Y}(x|y) - \mathop{\mathbf{E}}_{X,Y \sim p_{X,Y}} \log p_{Y}(y) \\ &= H(X|Y) + H(Y) \end{split}$$

1.3 Mutual Information

$$X, Y \sim p_{X,Y}(x,y)$$

Definition 1.3.1. Mutual Information:

$$I(X;Y) \stackrel{def}{=} \sum_{x,y} p(x,y) \log \frac{p(x,y)}{p_X(x)p_Y(y)}$$
$$= H(X) - H(X|Y)$$
$$= H(Y) - H(Y|X)$$
$$= H(X) + H(Y) - H(X,Y)$$

$$\begin{aligned} \textbf{Property:} &\text{if } X \perp Y \Leftrightarrow I(X,Y) = 0 \\ &I(X,Y) \geq 0 \\ &[I(X,Y)]_{max} = min\{H(X),H(Y)\} \end{aligned}$$

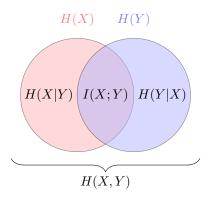


Figure 2: Mutual Information

1.4 KL-Divergence

$$X \sim p_X(x)$$
 $X \sim q_X(x)$

Definition 1.4.1. KL-Divergence (Relative Entropy):

Kullback-Leiblar Divergence between two PMF p(x) and q(x) is defined as:

$$D[p \parallel q] \stackrel{def}{=} \sum_{x \in \mathfrak{X}_p} p(x) \log \frac{p(x)}{q(x)} \in [0, +\infty]$$

KL-Divergence is used to measure the difference between two PMF.

Convention:

1.
$$0 \log 0 = 0$$

$$2. \ 0\log\tfrac{0}{\tilde{q}} = 0$$

3.
$$\tilde{p}\log\frac{\tilde{p}}{0} = +\infty$$

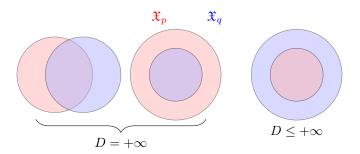


Figure 3: Value selection of KL-Divergence

Property: if $\exists x \in \mathfrak{X}$, st p(x) > 0 while q(x) = 0 then $D[p \parallel q] = +\infty$.

Definition 1.4.2. Conditional Relative Entropy:

The Conditional Relative Entropy between p(x,y) and q(x,y) is defined as the average KL-Divergence between p(y|x) and q(y|x) by p(x):

$$D[p(y|x) \parallel q(y|x)] = \sum_{x} p(x) \sum_{y} p(y|x) \log \frac{p(y|x)}{q(y|x)}$$
$$= \sum_{x,y} p(x,y) \log \frac{p(y|x)}{q(y|x)}$$

1.5 Chain Rule

- $p(x_1, x_2) = p(x_1)p(x_2|x_1)$ $p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2|x_1)p(x_3|x_1, x_2)\dots p(x_n|x_1, x_2, \dots, x_{n-1})$
- $H(X_1, X_2, \dots, X_n) = H(X_1) + H(X_2|X_1) + \dots + H(X_n|X_1, X_2, \dots, X_{n-1})$
- Conditional Mutual Information:

$$I(X;Y|Z) = \sum_{X,Y,Z} p(x,y,z) \log \frac{p(x,y|z)}{p(x|z)p(y|z)}$$

means the information of X and Y given Z.

- $I(X_1, \ldots, X_n; Y) = I(X_1; Y) + I(X_2; Y|X_1) + \ldots + I(X_n; Y|X_1, \ldots, X_{n-1})$
- Chain Rule for KL-Divergence:

$$D[p(x,y)||q(x,y)] = D[p(x)||q(x)] + D[p(y|x)||q(y|x)]$$

Proof.

$$\begin{split} D[p(x,y)||q(x,y)] &\stackrel{def}{=} \sum_{x,y} p(x,y) \log \frac{p(x,y)}{q(x,y)} \\ &= \sum_{x,y} p(x,y) \log \frac{p(x)p(y|x)}{q(x)q(y|x)} \\ &= \sum_{x,y} p(x,y) \log \frac{p(x)}{q(x)} + \sum_{x,y} p(x,y) \log \frac{p(y|x)}{q(y|x)} \\ &= \sum_{x,y} p(x) \log \frac{p(x)}{q(x)} + \sum_{x,y} p(x,y) \log \frac{p(y|x)}{q(y|x)} \\ &= D[p(x)||q(x)] + D[p(y|x)||q(y|x)] \end{split}$$

1.6 Jensen Inequality

Definition 1.6.1. Convex Function:

A function f(x) is convex over (a,b), if $\forall x_1, x_2 \in (a,b)$, $f(\lambda x_1 + (1-\lambda)x_2) \le \lambda f(x_1) + (1-\lambda)f(x_2)$, where $\lambda \in [0,1]$.

Example 1.6.1. Common Convex and Concave Functions:

Convex Functions:
$$f(x) = x^2, e^x \leftrightarrow f^{(2)}(x) \ge 0$$

Concave Functions: $f(x) = \log x \leftrightarrow f^{(2)}(x) \le 0$

Theorem 1.6.1. Jensen Inequality:

For a random variable $x \in \mathfrak{X}$, if f(x) is convex, then:

$$f(\mathbf{E}X) \le \mathbf{E}f(X) \sim \sum_{x} p(x)f(x) \ge f(\sum_{x} p(x)x)$$
 (1)

Proof. Suppose (1) holds for $|X| \leq K - 1$

$$\sum_{i=1}^{K} p(x_i)f(x_i) = p(x_K)f(x_K) + \sum_{i=1}^{K-1} p(x_i)f(x_i)$$

$$= (1 - p(x_K)) \sum_{i=1}^{K-1} \frac{p(x_i)}{1 - p(x_K)} f(x_i) + p(x_K)f(x_K)$$

$$\geq (1 - p(x_K))f(\sum_{i=1}^{K-1} \frac{p(x_i)}{1 - p(x_K)} x_i) + p(x_K)f(x_K)$$

$$= f(\sum_{i=1}^{K} p(x_i)x_i)$$

Theorem 1.6.2. Information Inequality:

$$D[p \parallel q] \ge 0$$
 with equality iff $p(x) = q(x)$

Proof.

$$D[p \parallel q] = \sum_{x} p(x) \log \frac{p(x)}{q(x)}$$
$$= -\sum_{x} p(x) \log \frac{q(x)}{p(x)}$$
$$\therefore -logx \text{ is convex}$$

$$\therefore D[p \parallel q] \ge -\log \sum_{x} p(x) \frac{q(x)}{p(x)}$$

$$= -\log \sum_{x} q(x)$$

$$= 0$$

Here, the equality holds iff $-log \frac{q(x)}{p(x)} = const \Rightarrow q(x) = p(x)$

Corollary 1.6.1.

$$I[X;Y] = D[p(x,y) || p(x)p(y)] \ge 0$$

Corollary 1.6.2.

$$D(p(X|Y) \parallel q(X|Y)) \ge 0$$

Corollary 1.6.3.

$$I(X;Y|Z) \ge 0$$

Theorem 1.6.3.

$$x \in X$$
 $H(X) \le \log |X|$

Proof.

$$\begin{split} u(x) = &\frac{1}{|X|} \\ D[p \parallel u] = &\sum_{x} p(x) \log \frac{p(x)}{u(x)} \geq 0 \\ = &\sum_{x} p(x) \log |X| + \sum_{x} p(x) log \frac{1}{u(x)} \\ = &\log |X| - H(X) \geq 0 \\ \Rightarrow &H(X) \leq \log |X| \end{split}$$

Theorem 1.6.4.

$$H(X) \ge H(X|Y)$$

Proof.

$$H(X) = I(X;Y) + H(X|Y)$$

$$\therefore I(X;Y) \ge 0$$

$$\therefore H(X) \ge H(X|Y)$$

Example 1.6.2. P(X,Y) is defined as follows:

X	1	2
1	0	$\frac{3}{4}$
2	$\frac{1}{8}$	$\frac{1}{8}$

$$H(X) = -\sum_{x} p(x) \log p(x)$$
$$= -\left(\frac{1}{8} \log \frac{1}{8} + \frac{7}{8} \log \frac{7}{8}\right)$$
$$\approx 0.544(bit)$$

$$\begin{split} H(X|Y) &= -\sum_{x,y} p(x,y) \log p(x|y) \\ &= 0 - \frac{3}{4} \log 1 - \frac{1}{8} \log \frac{1}{2} - \frac{1}{8} \log \frac{1}{2} \\ &= 0.25 (bit) \end{split}$$

1.7 log-sum Inequality and convexity of D, H, I

Theorem 1.7.1. log-sum Inequality:

$$\sum_{i=1}^{n} a_i \log \frac{a_i}{b_i} \ge \left(\sum_{i=1}^{n} a_i\right) \log \frac{\sum_{i=1}^{n} a_i}{\sum_{i=1}^{n} b_i} \quad with \ equality \ iff \quad \frac{a_i}{b_i} = const$$

Proof. Define $f(x) = x \log x$, then $f^{(2)}(x) = \frac{1}{x} > 0$, so f(x) is convex.

$$\sum_{i} a_{i} \log \frac{a_{i}}{b_{i}} = \left(\sum_{j} b_{j}\right) \sum_{i} \frac{b_{i}}{\sum_{j} b_{j}} \frac{a_{i}}{b_{i}} \log \frac{a_{i}}{b_{i}}$$

$$\geq \left(\sum_{j} b_{j}\right) \left(\sum_{i} \frac{b_{i}}{\sum_{j} b_{j}} \frac{a_{i}}{b_{i}}\right) \log \left(\sum_{i} \frac{b_{i}}{\sum_{j} b_{j}} \frac{a_{i}}{b_{i}}\right)$$

$$= \sum_{i} a_{i} \log \frac{\sum_{i=1}^{n} a_{i}}{\sum_{j=1}^{n} b_{i}}$$

Theorem 1.7.2. KL-Divergence is a convex function.

For two pair of PMF (p_1, q_1) and (p_2, q_2) , we have:

$$D[\lambda p_1 + (1 - \lambda)p_2 \parallel \lambda q_1 + (1 - \lambda)q_2] \le \lambda D[p_1 \parallel q_1] + (1 - \lambda)D[p_2 \parallel q_2]$$

Also can be noted as:

$$\left(D(\lambda \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} + (1 - \lambda) \begin{bmatrix} p_2 \\ q_2 \end{bmatrix}\right) \le \lambda D(\begin{bmatrix} p_1 \\ q_1 \end{bmatrix}) + (1 - \lambda)D(\begin{bmatrix} p_2 \\ q_2 \end{bmatrix})\right)$$

Proof.

$$left = \sum_{x} (\lambda p_{1} + (1 - \lambda)p_{2}) \log \frac{\lambda p_{1} + (1 - \lambda)p_{2}}{\lambda q_{1} + (1 - \lambda)q_{2}}$$

$$= \sum_{x} (\sum_{l=1}^{2} \lambda_{l} p_{l}) \log \frac{\sum_{l=1}^{2} \lambda_{l} p_{l}}{\sum_{l=1}^{2} \lambda_{l} q_{l}} \quad (\lambda_{1} = \lambda, \lambda_{2} = 1 - \lambda)$$

$$\leq \sum_{x} \sum_{l=1}^{2} \lambda_{l} p_{l} \log \frac{\lambda_{l} p_{l}}{\lambda_{l} q_{l}}$$

$$= \lambda \sum_{x} p_{1} \log \frac{p_{1}}{q_{1}} + (1 - \lambda) \sum_{x} p_{2} \log \frac{p_{2}}{q_{2}}$$

$$= \lambda D[p_{1} \parallel q_{1}] + (1 - \lambda)D[p_{2} \parallel q_{2}] = right$$

$$\therefore D[\lambda p_{1} + (1 - \lambda)p_{2} \parallel \lambda q_{1} + (1 - \lambda)q_{2}] \leq \lambda D[p_{1} \parallel q_{1}] + (1 - \lambda)D[p_{2} \parallel q_{2}]$$

Theorem 1.7.3. Concavity of Entropy:

$$H(\lambda p_1 + (1 - \lambda)p_2) \ge \lambda H(p_1) + (1 - \lambda)H(p_2)$$

Proof.

$$\begin{split} H[p] &= -\sum_x p(x) \log p(x) \qquad u(x) = \frac{1}{M} \quad M = |\mathfrak{X}| \\ D[p \parallel u] &= \sum_x p(x) \log \frac{p(x)}{u(x)} = \sum_x p(x) \log p(x) - \sum_x p(x) \log u(x) \\ &= -H[p] - \log M = -H[p] - \log |\mathfrak{X}| \\ &\because D \text{ is a convex function} \\ &\therefore H \text{ is a concave function} \\ &\therefore H(\lambda p_1 + (1 - \lambda) p_2) \geq \lambda H(p_1) + (1 - \lambda) H(p_2) \end{split}$$

Alternative proof:

Proof.

1.Generate an R.V:
$$\theta = \begin{cases} 1 & \text{with probability: } \lambda \\ 2 & \text{with probability: } 1 - \lambda \end{cases}$$

2.Generate an R.V: $X \sim \begin{cases} p_1 & \text{if } \theta = 1 \\ p_2 & \text{if } \theta = 2 \end{cases}$

$$\Rightarrow p(x) = \sum_{\theta} p(x,\theta) = \sum_{\theta=1}^2 p(x|\theta)p(\theta)$$

$$= \lambda p_1(x) + (1 - \lambda)p_2(x)$$

$$\Rightarrow H[\lambda p_1 + (1 - \lambda)p_2]$$

$$= H(X) \geq H(X|\theta) = -\sum_{x,\theta} p(x,\theta) \log p(x|\theta)$$

$$= -\sum_{x} \sum_{\theta=1}^2 p(x|\theta)p(\theta) \log p(x|\theta)$$

$$= -\lambda \sum_{x} p_1 \log p_1 - (1 - \lambda) \sum_{x} p_2 \log p_2$$

$$= \lambda H(p_1) + (1 - \lambda)H(p_2)$$

$$\therefore H(\lambda p_1 + (1 - \lambda)p_2) \geq \lambda H(p_1) + (1 - \lambda)H(p_2)$$

Theorem 1.7.4. Convexity of Mutual Information:

Let $(X,Y) \sim p(x,y) = p(x)p(y|x)$. The mutual information I(X;Y) is a concave function of p(x) for fixed p(y|x) and a convex function of p(y|x) for fixed p(x).

$$I(X;Y) \begin{cases} \text{concave of } p(x), \text{for fixed } p(y|x) \\ \text{convex of } p(y|x), \text{for fixed } p(x) \end{cases}$$

Proof.

$$\begin{split} I(X;Y) &= \sum_{x,y} p(x,y) \log \frac{p(x,y)}{p(x)p(y)} \\ &= H(Y) - H(Y|X) = H(Y) - \sum_{x} p(x)H(Y|X=x) \end{split}$$

If p(y|x) is fixed, then $p(y) = \int p(x)p(y|x)dx$ is a linear function of p(x). Because H(Y) is a concave function of p(y), so H(Y) is a concave function of p(x). The latter term p(x)H(Y|X=x) is a linear function of p(x), so I(X;Y) is a concave function of p(x).

Fix
$$p(x)$$
, set two CPMF $p_1(y|x), p_2(y|x)$

$$p_{\lambda}(y|x) = \lambda p_1(y|x) + (1 - \lambda)p_2(y|x)$$

$$p_{\lambda}(x,y) = p(x)p_{\lambda}(y|x) = \lambda p_1(x,y) + (1 - \lambda)p_2(x,y)$$

$$p_{\lambda}(y) = \int p_{\lambda}(x,y)dx = \lambda p_1(y) + (1 - \lambda)p_2(y)$$
Set $q_{\lambda}(x,y) = p(x)p_{\lambda}(y)$

$$q_{\lambda}(x,y) = \lambda q_1(x,y) + (1 - \lambda)q_2(x,y)$$

$$I(X;Y) = \sum_{x,y} p_{\lambda}(x,y)\log\frac{p_{\lambda}(x,y)}{p(x)p_{\lambda}(y)} = D[p_{\lambda} \parallel q_{\lambda}]$$

$$\therefore D[p_{\lambda} \parallel q_{\lambda}] \text{ is a convex function of } p_{\lambda}$$

$$p_{\lambda}(x,y) = p(x)p_{\lambda}(y|x) \text{ is a linear function of } p_{\lambda}(y|x)$$

$$\therefore I(X;Y) \text{ is a convex function of } p(y|x)$$

1.8 Data Processing Inequality

Definition 1.8.1. Markov Chain:

R. V X, Y, Z form a MC: $X \to Y \to Z$ if $p(x, y, z) = p(x)p(y|x)\frac{p(z|y)}{p(z|y)}$, which also means p(x, z|y) = p(x|y)p(z|y).

If any part of a process only depends on the previous part, then any three continuous parts of the process form a Markov Chain.

Example 1.8.1. If a Checker is placed on a chessboard, and the probability of next move is:

$$P(X) = \begin{cases} p_1, X = up \\ p_2, X = down \\ p_3, X = left \\ p_4, X = right \end{cases}$$

any three continuous moves form a Markov Chain.

Theorem 1.8.1. Data Processing Inequality:

If $X \to Y \to Z$ form a Markov Chain, then $I(X;Y) \ge I(X;Z)$.

Proof.

$$\begin{split} I(X;Y,Z) = & I(X;Z) + I(X;Y|Z) \\ = & I(X;Y) + I(X;Z|Y) \\ & \because X|Y \perp Z|Y \Rightarrow X \perp Z|Y \Rightarrow I(X;Z|Y) = 0 \\ & \therefore I(X;Y,Z) = I(X;Y) = I(X;Z) + I(X;Y|Z) \\ & \because I(X;Y|Z) \geq 0 \\ & \therefore I(X;Y) \geq I(X;Z) \end{split}$$

Corollary 1.8.1. If $Z = f(Y) \Rightarrow I(X;Y) \geq I(X;f(Y))$

1.9 Fano's Inequality

We want to estimate an unknown R.V X with a distribution p(x). We observe an R.V Y that is related to X by the conditional distribution p(y|x). From Y, we caculate a function $f(Y) = \hat{X}$. X, Y, \hat{X} form a MC $X \to Y \to \hat{X}$.

Define the probability of error:

$$P_e = P(\hat{X} \neq X)$$
 $Y \sim P(Y|X)$

We can set the R.V E:

$$E = \begin{cases} 1 & \text{if } \hat{X} \neq X \\ 0 & \text{if } \hat{X} = X \end{cases} \qquad P_e = P(E = 1)$$

Theorem 1.9.1. Fano's Inequality:

$$H(P_e) + P_e \log |\mathfrak{X}| \ge H(X|\hat{X}) \ge H(X|Y)$$

$$\Rightarrow 1 + P_e \log |\mathfrak{X}| \ge H(X|Y)$$

$$\Rightarrow P_e \ge \frac{H(X|Y) - 1}{\log |\mathfrak{X}|}$$

Proof.

$$H(E, X|\hat{X}) = H(X|\hat{X}) + H(E|X, \hat{X})$$
$$= H(E|\hat{X}) + H(X|E, \hat{X})$$

If X, \hat{X} is fixed, then E is also fixed, so

$$H(E|X,\hat{X}) = 0 \Rightarrow H(E,X|\hat{X}) = H(X|\hat{X})$$

Since conditioning reduces entropy, we have:

$$H(E|\hat{X}) \le H(E) = H(P_e)$$

It is easy to see that E is a binary-valued R.V, so $H(X|E,\hat{X})$ can be bounded as:

$$H(X|E,\hat{X}) = P_r(E=0)H(X|\hat{X},E=0) + P_r(E=1)H(X|\hat{X},E=1)$$

Since E=0 means $\hat{X}=X,$ so $H(X|\hat{X},E=0)=0.$

Since the upper bound of H is $\log |\mathfrak{X}|$, so: $H(X|E,\hat{X}) \leq P_e \log |\mathfrak{X}|$

Combine the above results, we have:

$$H(E|\hat{X}) + H(X|E, \hat{X}) \le H(E) + (1 - P_e)0 + P_e \log |\mathfrak{X}|$$
$$\Rightarrow H(X|\hat{X}) \le H(P_e) + P_e \log |\mathfrak{X}|$$

§ 2 AEP(Asymptotic Equipartition Property)

2.1 AEP

Review:Law of large numbers:

For X_1, X_2, \ldots, X_n i.i.d $\sim P \rightarrow$ note as \underline{X}_n :

$$\frac{1}{n} \sum_{i} X_{i} \overset{n \to \infty}{\underset{p.}{\longrightarrow}} \mathbf{E} X = \sum_{x} x p(x)$$

Theorem 2.1.1. AEP:

$$\frac{1}{n}\log\frac{1}{p(\underline{X}_n)} = \frac{1}{n}\sum_{i=1}^n\log\frac{1}{p(X_i)} \stackrel{n\to\infty}{\underset{p.}{\longrightarrow}} \mathbf{E}\log\frac{1}{p(x)} = H(X)$$

Definition 2.1.1. Typical Set:

 $A_{\epsilon}^{(n)}$ is a set of sequences $(x_1, x_2, \dots, x_n) \in X^{(n)}$ with the property that:

$$2^{-n(H(X)+\epsilon)} < p(x_1, x_2, \dots, x_n) < 2^{-n(H(X)-\epsilon)}$$

$$1. \left| A_{\epsilon}^{(n)} \right| = 2^{nH(X)}$$

2.
$$(1 - \epsilon)2^{nH(X)} \le P(A_{\epsilon}^{(n)}) \to 1$$

Example 2.1.1.

$$X_i \sim Bernollip = \begin{cases} 1 & \textit{with probability: } p = 0.9 \\ 0 & \textit{with probability: } p = 0.1 \end{cases}$$

Now we sample n = 100 times, then we have:

$$(1, 1, 1, \dots, 1, 1)$$
 with 100 "1"

$$(1,0,1,1,0,\ldots,0,1)$$
 with 90 "1" and 10 "0"

Obviously, the second one is more likely to happen.

Theorem 2.1.2. Property of the typical set:

(1) If
$$(x_1, \ldots, x_n) \in A_{\epsilon}^{(n)}$$
 then

$$H(X) - \varepsilon \le -\frac{1}{n}\log p(x_1, \dots, x_n) \le H(X) + \varepsilon$$

(2)
$$P_r(X_1, ..., X_n) \in A_{\epsilon}^{(n)} \ge 1 - \varepsilon$$
 for n sufficiently large.

(3)
$$\left| A_{\epsilon}^{(n)} \right| \leq 2^{n(H(X) + \varepsilon)}$$

$$(4) \left| A_{\epsilon}^{(n)} \right| \ge 2^{n(H(X) - \varepsilon)}$$

From (3) and (4), we have:

$$\left| A_{\epsilon}^{(n)} \right| \approx 2^{nH(X)}$$

Proof. (2) From AEP, $-\frac{1}{n}\log p(x_1,\ldots,x_n) \stackrel{p}{\to} H(X)$

 \therefore For any $\delta > 0, \varepsilon > 0, \exists n_0, \forall n \geq n_0$:

$$P_r\left\{\left|-\frac{1}{n}\log p(x_1,\ldots,x_n)-H(X)\right|<\varepsilon\right\}\geq 1-\delta$$

set
$$\delta = \varepsilon$$
, then: $P_r\{A_{\varepsilon}^{(n)}\} \ge 1 - \varepsilon$

(3)

$$1 = \sum_{\underline{x}_n \in X^{(n)}} P(x) \ge P_r \{A_{\varepsilon}^{(n)}\} = \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} P(x) \ge \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} 2^{-n(H(X) + \varepsilon)}$$
$$= \left| A_{\varepsilon}^{(n)} \right| 2^{-n(H(X) + \varepsilon)}$$

$$\Rightarrow \left| A_{\epsilon}^{(n)} \right| \le 2^{n(H(X) + \varepsilon)}$$

(4)
$$1 - \varepsilon \le P_r \{ \left| A_{\epsilon}^{(n)} \right| \} \le \sum_{\underline{x}_n \in A_{\epsilon}^{(n)}} 2^{-n(H(X) - \varepsilon)} = \left| A_{\epsilon}^{(n)} \right| 2^{-n(H(X) - \varepsilon)}$$

$$\Rightarrow \left| A_{\epsilon}^{(n)} \right| \ge (1 - \varepsilon) 2^{n(H(X) - \varepsilon)}$$

2.2 Consequences of AEP:Data Compression

Compression Scheme:

- 1. If $\underline{x}_n=(x_1,\ldots,x_n)\in A_{\varepsilon}^{(n)}$, we use $\lceil n(H(X)+\varepsilon) \rceil$ to encode \underline{x}_n ;
- 2. If $\underline{x}_n \notin A_{\varepsilon}^{(n)}$, we use $\lceil n \log |X| \rceil$ to encode \underline{x}_n ;
- 3. Use extra 1 bit to identify whether $\underline{x}_n \in A_{\varepsilon}^{(n)}$ or not.

$$\underline{x}_n \to b_1 b_2 \cdots b_{l(\underline{x}_n)}$$

Here,
$$b_1=1$$
 or 0 , $l(\underline{x}_n) \leq \begin{cases} n(H(X)+\varepsilon)+2 & (1) \\ n\log|X|+2 & (2) \end{cases}$

Theorem 2.2.1.

$$\mathbf{E}[\frac{1}{n}l(\underline{x}_n)] \le H(X) + \varepsilon$$

Proof.

$$\begin{split} \mathbf{E}[\frac{1}{n}l(\underline{x}_n)] &= \sum_{\underline{x}_n} p(\underline{x}_n) \cdot \frac{1}{n}l(\underline{x}_n) \\ &= \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}l(\underline{x}_n) + \sum_{\underline{x}_n \notin A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}l(\underline{x}_n) \\ &\leq \sum_{\underline{x}_n \in A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}(n(H(X) + \varepsilon) + 2) + \sum_{\underline{x}_n \notin A_{\varepsilon}^{(n)}} p(\underline{x}_n) \cdot \frac{1}{n}(n\log|X| + 2) \\ &= P_r\{A_{\varepsilon}^{(n)}\} \cdot \frac{1}{n}(n(H(X) + \varepsilon) + 2) + (1 - P_r\{A_{\varepsilon}^{(n)}\}) \cdot \frac{1}{n}(n\log|X| + 2) \\ &\leq \frac{1}{n}(n(H(X) + \varepsilon) + 2) + \varepsilon \frac{1}{n}(n\log|X| + 2) \\ &= H(X) + \varepsilon + \frac{2}{n} + \frac{\varepsilon}{n}\log|X| + \frac{2\varepsilon}{n} \\ &= H(X) + \varepsilon' \qquad \text{Here,we set } \varepsilon' = \varepsilon + \frac{2}{n} + \frac{\varepsilon}{n}\log|X| + \frac{2\varepsilon}{n} \end{split}$$

§ 3 Data Compression

3.1 Code

Definition 3.1.1. Source Code:

(1) For a R.V. X is a map

$$C: X \to D^*$$
 $x \mapsto d_1 d_2 \cdots d_{l(x)} = c(x)$

- (2) c(x) is called **codeword** of x.
- (3) l(x) is called **length** of the codeword, $l(x) \leq \infty$.

Example 3.1.1. $\mathcal{X} = \{1, 2, 3, 4\}$

\boldsymbol{x}	p(x)	Codeword(*)	Codeword(Native)
1	$\frac{1}{2}$	0	00
2	$\frac{I}{4}$	10	01
3	$\frac{1}{8}$	110	10
4	$\frac{1}{8}$	111	11

$$\bar{l}(x) = H(X) = -\frac{1}{2}\log\frac{1}{2} - \frac{1}{4}\log\frac{1}{4} - \frac{1}{8}\log\frac{1}{8} - \frac{1}{8}\log\frac{1}{8} = 1.75 \ bit$$

Definition 3.1.2. Nonsigular Code:

A code C is nonsigualr, if $\forall x \neq x'$ then $C(x) \neq C(x')$.

Definition 3.1.3. Extension of Code:

For a code:

$$C: x \longmapsto C(x)$$

The extension of code is defined as:

$$C^*: x_1x_2\cdots x_n \longmapsto C(x_1)C(x_2)\cdots C(x_n)$$

Definition 3.1.4. Uniquely Codable:

A code is uniquely codable if C^* is nonsigular.

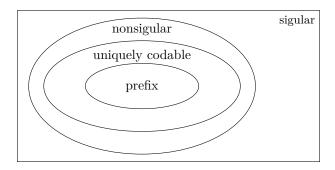
Example 3.1.2. Here are some examples of codes:

x	singular	nonsigualr	uniquely codable but no prefix	prefix
1	0	0	10	0
2	0	010	00	10
3	1	01	11	110
4	1	10	110	111
$C^*(324)$	101	0101010	1100110	11010111

Obviously, the nonsigular code 0101010 can be decoded as 324 or 3331.

Definition 3.1.5. Prefix Code/Instantaneous Code:

A code is a prefix code if no codeword is a prefix of any other code.



3.2 Kraft Inequality

Theorem 3.2.1. Kraft Inequality:

1) For any prefix code over an alphabet of size D. The code length l_1, l_2, \ldots, l_m must satisfy:

$$\sum_{i=1}^{m} D^{-l_i} \le 1$$

2) Conversely, given a set of word length $\{l_1, \ldots, l_m\}$ then there exists a prefix code with those lengths, if the set satisfies the Kraft inequality.

3.3 Optimal Codes

Here we will show some inferences:

$$x \in \{x_1, \dots, x_m\} \quad p(x) = p_1, \dots, p_m$$

$$C(x_1), \dots, C(x_m) \quad l(x_1), \dots, l(x_m) \quad \bar{l} = \sum_{i=1}^m p_i l(x_i)$$
We want to find:
$$\min_{l_i} \bar{l} = \sum_{i=1}^m p_i l(x_i) \quad s.t. \sum_i D^{-l_i} \le 1$$

$$l_i \in \mathbf{Z}^* \Rightarrow l_i \in \mathbf{R}^*$$

$$J = \sum_i p_i l_i + \lambda (\sum_i D^{-l_i} - 1)$$

$$\frac{\partial J}{\partial l_j} = p_j - \lambda D^{-l_j} \ln D = 0 \Rightarrow D^{-l_j} = \frac{p_j}{\lambda \ln D}$$

$$\frac{\partial J}{\partial lambda} = \sum_i D^{-l_i} - 1 = 0 \Rightarrow \frac{\sum_i p_i}{\lambda \ln D} = 1 \Rightarrow \lambda = \frac{1}{\ln D}$$

$$D^{-l_j} = \frac{p_j}{\lambda \ln D} = p_j \Rightarrow l_j^* = -\log_D p_j$$

$$\bar{l}^* = \sum_i p_i l_i^* = \sum_i p_i (-\log_D p_i) = -\sum_i p_i \log_D p_i = H_D[X]$$

Theorem 3.3.1. The expected length L of any prefix D-adic code satisfies:

$$L \geq H_D[X]$$

3.4 Upper bound on the optimal code length

Theorem 3.4.1.

$$H_D[X] \le \bar{l}^* \le H_D[X] + 1$$

Proof.

$$l_i^* \in \mathbf{R}^* \Rightarrow l_i = \lceil l_i^* \rceil \in \mathbf{Z}^*$$

$$\sum_i D^{-l_i} \le \sum_i D^{-l_i^*} = 1 \quad \text{Kraft Inequality holds}$$

$$\sum_i p_i \lceil l_i^* \rceil \le \sum_i p_i (l_i^* + 1) = \sum_i p_i l_i^* + \sum_i p_i = H_D[X] + 1$$

*Wrong Code:If we use anothor distribution q(x) instead of the true p(x), then we will get:

Theorem 3.4.2. Wrong Code:

$$l(x) = \left\lceil \log \frac{1}{q(x)} \right\rceil$$

$$\bar{l} = \mathbf{E}l(x) = \sum_{i} p(x_i)l(x_i) = \sum_{i} p(x_i) \left\lceil \log \frac{1}{q(x)} \right\rceil$$

$$\sum_{i} p(x_i) \left\lceil \log \frac{1}{q(x)} \right\rceil < \sum_{i} p(x_i) (\log \frac{1}{q(x)} + 1)$$

$$= \sum_{i} p(x_i) \log \frac{p(x_i)}{q(x_i)} - \sum_{i} p(x_i) \log p(x_i) + \sum_{i} p(x_i)$$

$$= D(p \parallel q) + H[p] + 1$$

$$\sum_{i} p(x_i) \left\lceil \log \frac{1}{q(x)} \right\rceil > D(p \parallel q) + H[p]$$

We call $D(p \parallel q)$ the puhishment of wrong code.

3.5 Huffman Code

Observation:

- 1. Smaller probability \Rightarrow longer codeword.
- 2. The two longest codewords must have the same length.
- 3. Two longest codewords merges to one single source symbol, with the probability being the sum of the replaced two symbols.

Here we have the Huffman algorithm:

Input: $\{(x_i, p_i)|i = 1, 2, \cdots, n\}$

Output: $\{C(x_i)\}\$ A tree representing Huffman code.

Algorithm:

Initialize Q as the PriorityQueue $(\{p_i,x_i,N_i\})/N_i$ is the tree node While Q.size()>1:

§ 4 Entropy Rate of a stochastic process

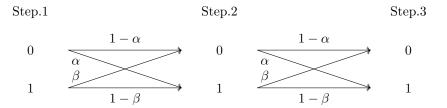
$$X \leftarrow H[X]$$

$$X_1, X_2, \dots, X_n i.i.d \sim p(x) \leftarrow H[X_1, X_2, \dots, X_n] = nH[X]$$
 Normally, $X_1, \dots, X_n, X_i \not\perp X_j, H[X_1, \dots, X_n] = ? \propto n \cdot h$ Here, h is called the entropy rate of the process.

4.1 Markove Chain

$$P(X_n|X_1, X_2, \dots, X_{n-1}) = P(X_n|X_{n-1})$$

Example 4.1.1. $x \in \{0, 1\}$

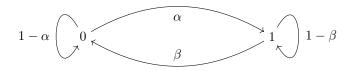


This is a Markov Chain with 3 steps. To describe a Markov Chain, we need:

1. $P_0(X_0)$

2.
$$P(X_{n+1}|X_n) = \begin{bmatrix} P(0|0) = 1 - \alpha & P(1|0) = \alpha \\ P(0|1) = \beta & P(1|1) = 1 - \beta \end{bmatrix}$$

We can also use a map to describe a Markov Chain:



Definition 4.1.1. Time invariant Markov Chain:

A Markov Chain is time invariant if the transition probability does not depend on time:

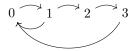
$$P_{k+1}(X_{k+1}|X_k) = P_k(X_k|X_{k-1})$$

Notions of Markov Chain:

1. **State:** X_i is a state of the Markov Chain, X_0 is the initial state.

- 2. Irreducable: $\forall i, j, \exists n, s.t. P(X_n = j | X_i = i) > 0$
- 3. **Aperiodic:**The largest common factor of the length of paths from a state to itself is 1.

Example 4.1.2. Here is a Markov Chain with 4 states:

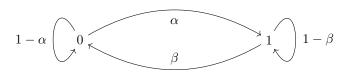


Length of path 1 is 2, length of path 2 is 4, the largest common factor is 2.

This Markov Chain is not aperiodic.

4. Probability trainsition matrix: $p_{ij} = P(X_{n+1} = X_j | X_n = X_i)$ $P = [p_{ij}] \qquad P(X_{n+1}) = \sum_{X_n} P(X_{n+1}, X_n) = [P(X_1) \dots P(X_n)]P$

Example 4.1.3.
$$P(X_{n+1}|X_n) = \begin{bmatrix} P(0|0) = 1 - \alpha & P(1|0) = \alpha \\ P(0|1) = \beta & P(1|1) = 1 - \beta \end{bmatrix}$$



$$V_{n} = \frac{P(X_{n} = 0)}{P(X_{n} = 1)} = \frac{0.1}{0.9} \qquad V_{n+1} = V_{n}^{T}P \qquad V_{\infty} = ?$$

$$V_{\infty} = V_{\infty}P \Rightarrow \begin{cases} (1 - \alpha)V_{1} + \beta V_{2} = V_{1} \\ \alpha V_{1} + (1 - \beta)V_{2} = V_{2} \\ V_{1} + V_{2} = 1 \end{cases} \Rightarrow \begin{cases} (1 - \alpha)V_{1} + \beta V_{2} = V_{1} \\ V_{1} + V_{2} = 1 \end{cases}$$

$$\Rightarrow \frac{V_{1}}{V_{2}} = \frac{\beta}{\alpha}$$

4.2 Entropy Rate

Definition 4.2.1. Entropy Rate:

1) The entropy rate of a stochastic process $\{X_i\}$ is defined as:

$$H[\mathcal{X}] = \lim_{n \to \infty} \frac{1}{n} H[X_1, \dots, X_n]$$

2) Conditional entropy rate:

$$H'[\mathcal{X}] = \lim_{n \to \infty} H[X_n | X_1, \dots, X_{n-1}]$$

Definition 4.2.2. Stationary stochastic process:

A stochastic process $\{X_i\}$ is stationary if the joint distribution of X_1, \ldots, X_n does not depend on n:

$$P(X_{l+1},...,X_{l+n}) = P(X_{l+2},...,X_{l+n+1})$$

Theorem 4.2.1. For a stationary stochastic process:

$$H[X_n|X_1,\ldots,X_{n-1}] \ge H[X_{n+1}|X_1,\ldots,X_n]$$

 $\Rightarrow H'[\mathcal{X}] \text{ exists a limit}$

Proof.

$$H[X_n|X_1,\ldots,X_{n-1}] = H[X_{n+1}|X_1,\ldots,X_n] \ge H[X_{n+1}|X_1,\ldots,X_n]$$

Theorem 4.2.2. Cesáro mean:

If
$$a \to a_n, b_n = \frac{1}{n} \sum_{i=1}^n a_i$$
, then $b_n \to a$

Based on the above theorem, we can get:

$$H[\mathcal{X}] = \lim_{n \to \infty} \frac{1}{n} H[X_1, \dots, X_n]$$

$$= \lim_{n \to \infty} (H[X_1] + H[X_2|X_1] + \dots + H[X_n|X_1, \dots, X_{n-1}])$$

$$H[X_n|X_1, \dots, X_{n-1}] \stackrel{def}{=} b_n$$

$$H[\mathcal{X}] = \lim_{n \to \infty} \frac{1}{n} \sum_{m=1}^{n} b_m = \lim_{n \to \infty} b_n = H'[\mathcal{X}]$$

Theorem 4.2.3. Entropy rate of a Markov Chain:

Obviously, the entropy rate only depends on the transition probability matrix:

$$H[\mathcal{X}] = F(P)$$

$$H[\mathcal{X}] = H'[\mathcal{X}] = \lim_{n \to \infty} H[X_n | X_1, \dots, X_{n-1}] = \lim_{n \to \infty} H[X_n | X_{n-1}]$$

$$= H[X_2 | X_1] \qquad X \sim V_{\infty} \qquad V_{\infty} = V_{\infty} P$$

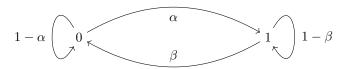
$$= -\sum_{X_1} V_{\infty} P(X_2 | X_1) \log P(X_2 | X_1)$$

Theorem 4.2.4. Let u and P be the stationary distribution and transition probability matrix respectively, then the entropy rate:

$$H[\mathcal{X}] = -\sum_{i,j} u_i P_{ij} \log P_{ij}$$

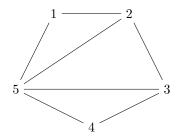
where $u_j = \sum_i u_i p_{ij}$

Example 4.2.1. For the Markov Chain:



$$\begin{split} H[\mathcal{X}] = & H[X_2|X_1] \\ = & -\frac{\beta}{\alpha+\beta} ((1-\alpha)\log(1-\alpha) + \alpha\log\alpha) - \frac{\alpha}{\alpha+\beta} ((1-\beta)\log(1-\beta) + \beta\log\beta) \\ = & \frac{\beta}{\alpha+\beta} H[X_1] + \frac{\alpha}{\alpha+\beta} H[X_2] \end{split}$$

Example 4.2.2. Random walk on a graph:



$$\begin{split} X_k &\in \{1,2,3,4,5\} \quad k = 0,1,2 \quad X_0 = l \\ P(X_{k+1} = j | X_k = i) &= \frac{A_{ij}}{d_i} \quad A_{ij} = \begin{cases} 1 & \text{if } (i,j) \in E \\ 0 & \text{otherwise} \end{cases} \\ P_0(X_0) &= \begin{cases} 1 & \text{if } X_0 = l \\ 0 & \text{otherwise} \end{cases} \quad v^* = v^* P \quad v^* = [v_1, v_2, \dots, v_5] \\ v^* P &= [v_1 \frac{A_{11}}{d_1} + v_2 \frac{A_{21}}{d_2} + v_3 \frac{A_{31}}{d_3} + v_4 \frac{A_{41}}{d_4} + v_5 \frac{A_{51}}{d_5}, \dots] \\ \Rightarrow v_i^* &= \frac{d_i}{2D} \quad D = |E| \\ H[\mathcal{X}] &= -\sum_{i,j} v_i^* p_{ij} \log p_{ij} = -\sum_{i,j} \frac{d_i}{2D} \frac{A_{ij}}{d_i} \log \frac{A_{ij}}{d_i} = -\sum_{i,j} \frac{A_{ij}}{2D} \log (\frac{A_{ij}}{2D} \frac{2D}{d_i}) \\ &= -\sum_{i,j} \frac{A_{ij}}{2D} \log \frac{A_{ij}}{2D} - \sum_{i,j} \frac{A_{ij}}{2D} \log \frac{2D}{d_i} \\ &= -\sum_{i,j} \frac{A_{ij}}{2D} \log \frac{A_{ij}}{2D} + \sum_{i} \frac{d_i}{2D} \log \frac{d_i}{2D} \\ &= \log(2D) - H[v^*] \end{split}$$

§ 5 Mutual Information Estimation

5.1 Fenchel-Legendre Transform

Definition 5.1.1. F-L transform

For a given f(u), Fenchel-Legredre transform of f is defined by:

$$f^*(t) = \sup_{u} \{ut - f(u)\}$$

Corollary 5.1.1. If f is convex, the ut - f(u) is concave.

$$u^*: \frac{d(ut - f(u))}{du} = 0 \Rightarrow t = f'(u^*) \Rightarrow u^* = f'^{-1}(t)$$

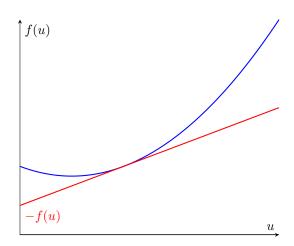
therefore, $f^*(t) = u^*t - f(u^*), u^* = f'^{-1}(t)$

Definition 5.1.2. Inverse FL transform

$$f^{**}(u) = (f^*)^* = \sup_{t} \{ut - f^*(t)\}$$

Example 5.1.1. Obviously, the tangent line of f(u) at u^* is:

$$g(u) = ut^* - f(u^*)$$



Each t corresponds to a tangent line of f(u).

Theorem 5.1.1. *F-L transform for a convex* If f(u) is strictly convex, then $f^{**} = f$.

Proof.

$$f^{*}(t) = u^{*}t - f(u^{*}) \quad \text{where } t = f'(u^{*})$$

$$f^{**}(u) = (f^{*}(t))^{*} = \sup_{t} \{ut - u^{*}t + f(u^{*})\}$$

$$= \sup_{u^{*}} \{uf'(u^{*}) - u^{*}f'(u^{*}) + f(u^{*})\}$$

$$\frac{d[f'(u^{*})(u - u^{*}) + f(u^{*})]}{du^{*}} = f''(u^{*})(u - u^{*}) - f'(u^{*}) + f'(u^{*})$$

$$= f''(u^{*})(u - u^{*}) = 0$$

$$\therefore f \text{ is strictly convex } \Rightarrow f''(u^{*}) > 0 \Rightarrow u = u^{*}$$

$$\therefore f^{**}(u) = \sup_{t} \{ut - u^{*}t + f(u^{*})\} = f(u)$$

5.2 Estimate Mutual Information/K-L Divergence via maximizing lower bound

• Setting:Suppose we have a set of observed data:

$$\{(Y_1, Z_1), (Y_2, Z_2), \dots, (Y_m, Z_m)\} = D \quad (Y_i, Z_i) \sim P(Y, Z) \to \text{Unkown}$$

• Task:The objective is to estimate:

$$I[Y;Z] = \sum_{Y,Z} p(Y,Z) \log \frac{p(Y,Z)}{p(Y)p(Z)} = D[p(Y,Z) \parallel (p(Y)p(Z))]$$

Example 5.2.1.

$$Y \in \{0, 1\}$$
 $Z \in \{0, 1\}$

$$P(Y,Z) = \frac{\#(Y,Z)}{\#total}$$

When the dimension of observed data is too large, it is hard to estimate the distribution by the frequency.

Theorem 5.2.1. Nguyen 2010:

$$D[P(X) \parallel Q(X)] = \mathop{\mathbf{E}}_{X \sim P} \log \frac{P(X)}{Q(X)} \geq \sup_{T \in \mathcal{T}} \{ \mathop{\mathbf{E}}_{X \sim P} T(X) - \mathop{\mathbf{E}}_{X \sim Q} e^{T(X) - 1} \}$$

Through this theorem, we can estimate the mutual information by machine learning.

Proof.

$$D[P(X) \parallel Q(X)] = \sum_{X} P(X) \log \frac{P(X)}{Q(X)} = \sum_{X} Q(X) \frac{P(X)}{Q(X)} \log \frac{P(X)}{Q(X)}$$

$$= \sum_{X} Q(X) f(u) \begin{cases} u = \frac{P(X)}{Q(X)} \\ f(u) = u \log u \end{cases}$$

$$f'(u) = \log u + 1 \quad f'(u^*) = t = \log u^* + 1 \Rightarrow u^* = e^{t-1}$$

$$f^*(t) = u^*t - f(u^*) = te^{t-1} - f(e^{t-1}) = e^{t-1}$$

$$\therefore \sum_{X} Q(X) f(u) = \sum_{X} Q(X) (f^*)^* = \sum_{X} Q(X) \sup_{t} \{ut - f^*(t)\}$$

$$= \sum_{X} Q(X) \sup_{t} \{\frac{P(X)}{Q(X)}t - f^*(t)\}$$

 $f = u \log u$ is convex $\Rightarrow f^*$ is concave $\Rightarrow f^{**}$ is convex

$$\therefore \sum_{X} Q(X)f(u) \ge \sup_{t} \{ \sum_{X} Q(X) \left[\frac{P(X)}{Q(X)} t - f^{*}(t) \right] \}$$

$$= \sup_{t} \{ \sum_{X} P(X)t - \sum_{X} Q(X)f^{*}(t) \}$$

$$= \sup_{X} \{ \sum_{X \sim P} t_{X} - \sum_{X \sim Q} f^{*}(t) \}$$

$$= \sup_{X} \{ \sum_{X \sim P} t_{X} - \sum_{X \sim Q} e^{t_{X} - 1} \}$$

5.3 Implement the estimation of I using lower bound

Let
$$X = (Y, Z)$$
 $P(X) = P(Y, Z)$ $Q(X) = P(Y)P(Z)$

Critic function $T_{\theta}(X)$:Define a neural network $T_{\theta}(X)$ with parameter $\theta = \{\omega_1, \omega_2\}.T_{\theta} = f(\omega_2 f(\omega_1 X))$ while f is a non-linear function.

$$\begin{split} & \max_{\theta} \{ \sum_{Y,Z} P(Y,Z) T_{\theta}(Y,Z) - \sum_{Y,Z} P(Y) P(Z) e^{T_{\theta}(Y,Z) - 1} \} \\ & \approx \max_{\theta} \{ \frac{1}{N} \sum_{i=1}^{N} T_{\theta}(Y_{i},Z_{i}) - \frac{1}{N^{2}} \sum_{i=1}^{N} \sum_{j=1}^{N} e^{T_{\theta}(Y_{i},Z_{j}) - 1} \} \\ & \approx \max_{\theta} \{ \frac{1}{N} \sum_{i=1}^{N} T_{\theta}(Y_{i},Z_{i}) - \frac{1}{M} \sum_{k=1}^{M} e^{T_{\theta}(Y_{i_{k}}Z_{j_{k}}) - 1} \} \quad i_{k}, j_{k} \quad i.i.d. \sim (1,\ldots,N) \end{split}$$

§ 6 Information Theory and Statistics

6.1 Method of type

Definition 6.1.1. Type:

$$P_x = \frac{Number\ of\ X_i\ equal\ to\ a}{Total\ number\ of\ sample\ \underline{x}_n} = P_x(a)$$

Example 6.1.1.

$$\mathcal{X} = \{1,2,3\} \qquad \underline{x}_n = [1,1,3,2,1] \qquad n = 5$$

$$P_x(a=1) = \frac{3}{5} \qquad P_x(a=2) = \frac{1}{5} \qquad P_x(a=3) = \frac{1}{5}$$

Definition 6.1.2. The probability simplex in \mathbf{R}^m is the set of points $\mathbf{x} = (x_1, x_2, \dots, x_m) \in \mathbf{R}^m$ such that: $x_i \geq 0, \sum_{i=1}^m x_i = 1$

Definition 6.1.3. \mathcal{P}_n denotes the set of all empirial distributions with number of samples n.

Example 6.1.2. $\mathcal{X} = \{0, 1\}, \, \mathcal{P}_n \, is:$

$$\mathcal{P} = \{ (P(0), P(1)) : (\frac{0}{n}, \frac{n}{n}), (\frac{1}{n}, \frac{n-1}{n}), \dots, (\frac{n}{n}, \frac{0}{n}) \}$$

Definition 6.1.4. Type class:

$$T(P) = \{x \in \mathcal{X}^n : P_x = P\}$$

Example 6.1.3.

$$\mathcal{X} = \{1, 2, 3\}$$
 $P = \{\frac{3}{5}, \frac{1}{5}, \frac{1}{5}\}$
 $|T(P)| = \frac{5!}{3!1!1!} = 20$

Theorem 6.1.1.

$$|\mathcal{P}_n| \le (n+1)^{|\mathcal{X}|}$$

Proof.

$$P_x(a) = \frac{n_a}{n} \qquad n_a = 0, 1, \dots, n$$

 $\therefore a \text{ has } |\mathcal{X}| \text{ possible values.}$

The elements in \mathcal{P}_n are like $(P(a_1), \dots, P(a_{|\mathcal{X}|}))$

$$\therefore |\mathcal{P}_n| \le (n+1)^{|\mathcal{X}|}$$

Actually, $\sum_{x} P_x(a) = 1$, when we fix $a_1, \ldots, a_{|\mathcal{X}|-1}$, the $a_{|\mathcal{X}|}$ is fixed. Therefore, $|\mathcal{P}_n| \leq (n+1)^{|\mathcal{X}|-1}$

Theorem 6.1.2. Let $x_1, x_2, \ldots, x_n \overset{i.i.d}{\sim} Q(x)$

$$Q(\underline{x}_n) = 2^{-n(H[P_x] + D[P_x \parallel Q])}$$

Proof.

$$\begin{split} Q(\underline{\mathbf{x}}_n) &= Q(x_1) \dots Q(x_n) = \prod_{i=1}^n Q(x_i) = \prod_{k=1}^{|\mathcal{X}|} Q(a_k)^{n_k} \qquad n_k = \#(x = a_k) \\ &= 2^{\sum_{k=1}^{|\mathcal{X}|} n_k \log Q(a_k)} = 2^{n \sum_{k=1}^{|\mathcal{X}|} \frac{n_k}{n} \log Q(a_k)} = 2^{n \sum_{k=1}^{|\mathcal{X}|} P_x(a_k) \log Q(a_k)} \\ &= 2^{n \sum_{k=1}^{|\mathcal{X}|} P_x(a_k) \log \frac{Q(a_k)}{P_x(a_k)} + n \sum_{k=1}^{|\mathcal{X}|} P_x(a_k) \log P_x(a_k)} \\ &= 2^{-n(H[P_x] + D[P_x \| Q])} \end{split}$$

Theorem 6.1.3. Size of a type class: $T(P), P \in \mathcal{P}_n$:

$$\frac{1}{(n+1)^{|\mathcal{X}|}} 2^{nH(P)} \le |T(P)| \le 2^{nH(P)}$$

Proof. Here, we only prove the upper bound.

$$\begin{split} 1 &\geq P[\underline{\mathbf{x}}_n \in T(P)] = \sum_{\underline{\mathbf{X}}_n \in T(P)} P^n(\underline{\mathbf{x}}_n) \\ P^n(\underline{\mathbf{x}}_n) &= \prod_{i=1}^n P(x_i) = 2^{\sum_{i=1}^n \log P(x_i)} = 2^{\sum_{a \in \mathcal{X}} n_a \log P(a)} \\ &= 2^{n \sum P(a \log P(a))} = 2^{-nH(P)} \\ &\therefore 1 \geq \sum_{\underline{\mathbf{X}}_n \in T(P)} 2^{-nH(P)} = |T(P)| \, 2^{-nH(P)} \\ &\therefore |T(P)| \leq 2^{nH(P)} \end{split}$$

Example 6.1.4.

Theorem 6.1.4. Probability of type class:

For any $P \in \mathcal{P}_n$, and any distribution Q:

$$\frac{1}{(n+1)^{|\mathcal{X}|}} 2^{-nD[P||Q]} \le Q[\underline{x}_n \in T(P)] \le 2^{-nD[P||Q]}$$

Proof. Theorem 6.1.2 multiplies Theorem 6.1.3.

6.2 Law of large numbers

For $X_1, \ldots, X_n \sim^{i.i.d} Q$

•
$$\frac{1}{n} \sum_{i=1}^{n} X_i \xrightarrow{p} \mathbf{E}_{X \sim Q} X$$

•
$$\frac{1}{n} \sum_{i=1}^{n} f(X_i) \xrightarrow{p} \underset{X \sim Q}{\mathbf{E}} f(X)$$

•
$$P_x(X=a) = \frac{n_a}{n} \stackrel{n \to \infty}{\to} Q(a)$$

Theorem 6.2.1. Formally, for any $\epsilon > 0$: $\lim_{n \to \infty} PrD(P_x \parallel Q) > \epsilon = 0$

Proof.

$$PrD(P_x \parallel Q) > \epsilon = \sum_{P:D(P\parallel Q) > \epsilon} Q(\underline{\mathbf{x}}_n \in P) \le 2^{-nD[P\parallel Q]}$$
$$\le (n+1)^{|\mathcal{X}|} 2^{-n\epsilon} = 2^{-n(\epsilon - \frac{|\mathcal{X}|}{n+1})} \to 0$$

6.3 Universal source coding

Definition 6.3.1. Universal source coding:

1) A fix-rate block code of rate R for a source $X_1, \ldots, X_n \overset{i.i.d.}{\sim} Q$:

$$f_n: \mathcal{X}^n \longrightarrow \{1, 2, \dots, 2^{-nR}\}$$
 encode

$$\phi_n: \{1, 2, \dots, 2^{-nR}\} \longrightarrow \mathcal{X}^n \quad decode$$

- 2) R is called the rate of the code.
- 3) The prob of error for the code is defined as:

$$P_e^(n) = Q^n(\phi_n(f_n(x^n)) \neq x^n)$$

Theorem 6.3.1. There exist a sequence of $(2^{-nR}, n)$ universal source code, such that for every source Q, satisfying H(Q) < R, $P_e^{(n)} \to 0$.

Proof. Let $R_n = R - |\mathcal{X}| \frac{\log(n+1)}{n}$

Consoder the set of sequence:

$$A_n = \{x^n \in \mathcal{X}^n | H(P_x) \le R_n\}$$

$$|A_n| = \sum_{P:H(P) \le R_n} |T(P)| \le \sum_{P:H(P) \le R_n} 2^{nR_n}$$

$$\leq (n+1)^{|\mathcal{X}|} 2^{nR_n} = 2^{|\mathcal{X}|\log(n+1) + nR - n|\mathcal{X}|\frac{\log(n+1)}{n}}$$

= 2^{nR}

Any sequence $x^n \notin A_n$ will result in an error, hence the probability of error is:

$$\begin{split} P_e^{(n)} &= \sum_{P: H(P > R_n)} Q^n(T(P)) \leq (n+1)^{|\mathcal{X}|} \max_{P: H(P) > R_n} Q^n(T(P)) \\ &\text{Due to the Theorem } 6.1.4 \\ : Q^n(T(P)) \leq 2^{-nD(P \parallel Q)} \\ P_e^{(n)} &\leq (n+1)^{|\mathcal{X}|} 2^{-n} \min_{P: H(P) > R_n} D(P \parallel Q) \\ &\lim_{n \to \infty} (n+1)^{|\mathcal{X}|} 2^{-n} \min_{P: H(P) > R_n} D(P \parallel Q) \\ &= 0 \end{split}$$

6.3.1 Fisher Information and Cramér-Rao Lower Bound

For $\underline{X}_n = X_1, X_2, \dots, X_n \overset{i.i.d}{\sim} P_{\theta}$:

$$\{\underline{\mathbf{X}}_n\} \stackrel{estimate}{\longrightarrow} parameter : \theta$$

The error of the estimate T is:

$$\mathbf{E}[T(\underline{\mathbf{X}}_n) - \theta]^2 \qquad MSE$$

$$\mathbf{E}[T(\underline{\mathbf{X}}_n) - \theta] = 0 \qquad unbias$$

Theorem 6.3.2. Cramér-Rao Lower Bound:

The MSE of any unbias estimator T(X) of the parameter θ is lower bounded by:

$$var(T) \ge \frac{1}{J(\theta)}$$
 where $J(\theta) \stackrel{def}{=} \mathbf{E}_X [\frac{\partial}{\partial \theta} \ln f(X, \theta)]^2$

Here, $f(X, \theta)$ is the probability density function of X, $J(\theta)$ is called the Fisher information.

Proof.

$$v \stackrel{def}{=} \frac{\partial \ln f(X, \theta)}{\partial \theta} = \frac{\frac{\partial}{\partial \theta} f(X, \theta)}{f(X, \theta)}$$
$$\mathbf{E}[v] = \int v f(X, \theta) dX = \int \frac{\partial}{\partial \theta} f(X, \theta) dX$$
$$= \frac{\partial}{\partial \theta} \int f(X, \theta) dX = \frac{\partial}{\partial \theta} 1 = 0$$
$$\therefore J(\theta) = \mathbf{E}_X[v^2]$$

Due to the Cauchy-Schwarz inequality:

$$\begin{split} [\mathbf{E}(v-\mathbf{E}v)(T-\mathbf{E}T)]^2 &\leq \mathbf{E}(v-\mathbf{E}v)^2 \mathbf{E}(T-\mathbf{E}T)^2 = \mathbf{E}[v^2] var(T) \\ \Rightarrow [\mathbf{E}(vT)]^2 &\leq J(\theta) var(T) \\ \mathbf{E}(vT) &= \int vT f(X,\theta) dX = \int \frac{\partial}{\partial \theta} f(X,\theta) T dX \\ &= \frac{\partial}{\partial \theta} \int f(X,\theta) T dX = \frac{\partial}{\partial \theta} \mathbf{E}[T] = \frac{\partial}{\partial \theta} \theta = 1 \\ &\Rightarrow J(\theta) var(T) \geq 1 \Rightarrow var(T) \geq \frac{1}{J(\theta)} \end{split}$$

Example 6.3.1. Let $X_1, X_2, \ldots, X_n \stackrel{i.i.d}{\sim} N(\theta, \sigma^2)$ with a known σ^2 .

$$T_1 = \frac{1}{n} \sum_{i=1}^n X_i \quad T_2 = X_1 \quad f(X, \theta) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(X-\theta)^2}{2\sigma^2}}$$
$$\frac{\partial}{\partial \theta} \ln f(X, \theta) = \frac{\partial}{\partial \theta} \left[-\frac{(X-\theta)^2}{2\sigma^2} - \ln(\sqrt{2\pi}\sigma) \right] = -\frac{x-\theta}{\sigma^2}$$
$$T_2 : MSE = \mathbf{E}(T_2 - \theta)^2 = \mathbf{E}(X - \theta)^2 = \sigma^2$$
$$J(\theta) = \mathbf{E}(v^2) = \mathbf{E}(\frac{(X-\theta)^2}{\sigma^4}) = \frac{\sigma^2}{\sigma^4} = \frac{1}{\sigma^2}$$

Here, T_2 is not an unbias estimator, but reaches the lower bound.

§ 7 Maximum Entropy Principle

For a r.v. X:

1.
$$\mu = \mathbf{E}X$$
;

2.
$$\sigma^2 = var(X) = \mathbf{E}(X - \mu)^2$$
;

3.
$$X \in \mathbf{R}/X \in \{0, 1, 2, \ldots\}.$$

Objective: Given a set of constants, the aim to get the distribution via MEP.

Example 7.0.1.

$$\max_{p(x)} H[p(x)] \quad s.t. \begin{cases} \sum_{x} r_j(x) p(x) = \mu_j & j = 1, 2, \dots, m \\ \sum_{x} p(x) = 1 \\ p(x) \ge 0 & \forall x \in \mathcal{X} \end{cases}$$

$$\begin{split} L[\{p(x)\}, \{\lambda_j\}] &= -\sum_x p(x) \log p(x) + \sum_j \lambda_j (\sum_x r_j(x) p(x) - \mu_j) + \lambda_0 (\sum_x p(x) - 1) \\ \frac{\partial L}{\partial p(x_i)} &= -(\log p(x_i) + 1) + \sum_j \lambda_j r_j(x_i) + \lambda_0 = 0 \Rightarrow p(x_i) = e^{-1 + \lambda_0 + \sum_j \lambda_j r_j(x_i)} \\ &= \frac{1}{Z} e^{\sum_j \lambda_j r_j(x_i)} \quad Z = e^{\lambda_0 - 1} \quad p_i \text{ is called Bolzmann distribution} \\ \frac{\partial L}{\partial \lambda_0} &= \sum_x p(x) - 1 = 0 \Rightarrow Z = \sum_x e^{\sum_j \lambda_j r_j(x)} \\ \frac{\partial L}{\partial \lambda_j} &= \sum_x r_j(x) p(x) - \mu_j = 0 \Rightarrow \lambda_j \end{split}$$

1.
$$\mathbf{E}X = 0$$
 $var(X) = \sigma^2$ $X \in \mathbf{R}$
 $p(x) = \frac{1}{Z}e^{\lambda_1 x^2 + \lambda_2 x} = \frac{1}{\sqrt{2\pi}\sigma}e^{-\frac{x^2}{2\sigma^2}}$

2.
$$\mathbf{E}X = \mu \quad X \in [0, +\infty)$$

 $p(x) = \frac{1}{Z}e^{-|\lambda_1|x}$

3.
$$\mathbf{E}X = \mu \quad X \in \mathbf{R}$$

$$p(x) = unknown$$

4.
$$X \in [a, b]$$

$$p(x) = \frac{1}{b-a}$$

Theorem 7.0.1. Let
$$f^*(x) = e^{\lambda_0 + \sum_j \lambda_j r_j(x)}$$
, $\lambda_0, \lambda_1 \dots, \lambda_m$ are chosen s.t.
$$\begin{cases} \int f(x) dx = 1 \\ \int r_j(x) f(x) dx = \alpha_j \quad j = 1, 2, \dots, m \end{cases}$$
 f^* uniquely maximize the entropy $f(x) \geq 0$

H[f] over all possible f satisfies the constraints.

Proof. For any g(x) satisfies the constraints, we have:

$$H[g] - H[f^*] = -\int g(x) \log g(x) dx + \int f^*(x) \log f^*(x) dx$$

$$= -\int g(x) \log \frac{g(x)}{f^*(x)} dx - \int g(x) \log f^*(x) dx + \int f^*(x) \log f^*(x) dx$$

$$= -D[g \parallel f^*] - \int g(x) \log f^*(x) dx + \int f^*(x) \log f^*(x) dx$$

$$\int f^*(x) \log f^*(x) dx = \int f^*(x) [\lambda_0 + \sum_j \lambda_j r_j(x)] dx$$

$$= \lambda_0 + \sum_j \lambda_j \alpha_j$$

$$\int g(x) \log f^*(x) dx = \int g(x) [\lambda_0 + \sum_j \lambda_j r_j(x)] dx$$

$$= \lambda_0 + \sum_j \lambda_j \alpha_j$$

$$\therefore H[g] - H[f^*] = -D[g \parallel f^*] \le 0$$

$$\therefore H[f^*] \ge H[g] \quad \forall g \text{ satisfies the constraints}$$
i.i.f $g = f^*, H[g] = H[f^*]$

§ 8 Channel Coding

$$W \underset{message}{\overset{encoder}{\longrightarrow}} \underline{X}^n \overset{channel}{\overset{channel}{\longrightarrow}} \underline{Y}^n \overset{decoder}{\overset{\longrightarrow}{\longrightarrow}} \hat{W}$$

8.1 Information Channel Capacity

Definition 8.1.1. Information channel capacity:

$$C \stackrel{def}{=} \max_{p(x)} I[X;Y] = \max_{p(x)} \sum p(x,y) \log \frac{p(x,y)}{p(x)p(y)} = \max_{p(x)} \sum p(x)p(y|x) \log \frac{p(y|x)}{p(y)}$$

Here, p(y|x) is given by the channel, $p(y) = \sum p(x)p(y|x)$. Hence, the only variable is p(x), which is given by the encoder.

Example 8.1.1. Noiseless channel:

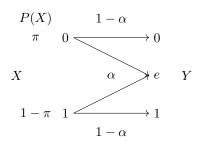
$$\begin{array}{ccc}
0 & \longrightarrow & 0 \\
X & & & Y \\
1 & \longrightarrow & 1
\end{array}$$

$$C = \max_{p(x)} I(X;Y) = \max_{p(x)} H(X) - H(X|Y)$$
$$= \max_{p(x)} H(X) = 1$$

Example 8.1.2. Binary symetric channel:

$$\begin{split} I(X;Y) &= H(Y) - H(Y|X) = H(Y) - \sum_{x} p(X=x)H(Y|X=x) \\ &= H(Y) - \sum_{x} p(X=x)h(p) \qquad h(p) = -p\log p - (1-p)\log(1-p) \\ &= H(Y) - h(p) \\ C &= \max_{p(x)} I(X;Y) = \max_{p(x)} H(Y) - h(p) = 1 - h(p) \end{split}$$

Example 8.1.3. Binary erasure channel:



If follow the method of Exmaple 8.1.2:

$$I(X;Y) = H(Y) - h(\alpha)$$
 $C = 1 - h(\alpha)$

Set E = even(Y = e)

$$H(Y) = H(Y, E) - H(E|Y) \quad H(E|Y) = 0$$

$$= H(E) + H(Y|E)$$

$$= h(\alpha) + \sum_{e} P(E = e)H(Y|E = e)$$

$$= h(\alpha) + (1 - \alpha)h(\pi)$$

$$\therefore \quad C = \max H(Y) - h(\alpha) = (1 - \alpha) \max_{\pi} h(\pi)$$

8.2 Channel Code

- 1. An (M, n) code for the channel $\{X, Y, P(Y|X)\}$ includes:
 - (a) An index set $\{1, 2, ..., M\}$
 - (b) An encoder: $\{1, 2, ..., M\} \to \underline{X}^n, X \in \{0, 1\}$
 - (c) A decoder: $\underline{\mathbf{Y}}^n \to \{1, 2, \dots, M\}$
- 2. The rate of a code (M, n) is $R = \frac{\log_2 M}{n}$, for a no-error transmission:

$$R \leq C$$

Here, C is the channel capacity.

8.3 Hamming Code

Set a matrix H as follows:

$$H = \begin{bmatrix} 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 & 1 \end{bmatrix}$$

For this matrix, the Null space(kernel) is Null(H), the Rank(H) = 3For all $x \in Null(H)$, we have:

$$Hx = 0$$
 $|Null(H)| = 2^4 = 16$

Now we can encode a message using the $x \in Null(H)$, it is easy to find that any two different codes $x_1, x_2 \in Null(H)$ satisfy:

$$d(x_1, x_2) = |x_1 - x_2| \ge 3$$

So when we transmit a code $x \in Null(H)$ with one bit error, we have:

$$x \to x + e = y \qquad e = \begin{bmatrix} 0 \\ \dots \\ 0 \\ 1 \\ 0 \\ \dots \\ 0 \end{bmatrix}$$

To find the index of the error bit, we can use the following method:

$$Hy = Hx + He = He$$

The index of the error bit is the index of the column in H with the same value as He.

In this example, we can find the rate of the code is:

$$R = \frac{\log_2 2^4}{7} = \frac{4}{7}$$

8.4 Joint Typical Set and Joint AEP

Definition 8.4.1. Joint typical set:

$$A_{\epsilon}^{n} = \{(\underline{X}^{n}, \underline{Y}^{n}) | \begin{cases} \left| -\frac{1}{n} \log P(\underline{X}^{n}) - H(X) \right| < \epsilon \\ \left| -\frac{1}{n} \log P(\underline{Y}^{n}) - H(Y) \right| < \epsilon \end{cases} \}$$
$$\left| -\frac{1}{n} \log P(\underline{X}^{n}, \underline{Y}^{n}) - H(X, Y) \right| < \epsilon$$

- 1. $|A_{\epsilon}^n| = 2^{n(H(X,Y)+\epsilon)}$;
- 2. $P(A_{\epsilon}^n) \to 1$, as $n \to \infty$;
- 3. If $\underline{\mathbf{X}}^n, \underline{\mathbf{Y}}^n \sim P(\underline{\mathbf{X}}^n)P(\underline{\mathbf{Y}}^n)$, which means $\underline{\mathbf{X}}^n \perp \underline{\mathbf{Y}}^n$, then:

$$P(A_{\epsilon}^n) \le 2^{-n(I(X;Y) - 3\epsilon)}$$

Proof.

$$\begin{split} P[(\underline{\mathbf{X}}^n,\underline{\mathbf{Y}}^n) \in A^n_{\epsilon}] &= \sum_{(\underline{\mathbf{X}}^n,\underline{\mathbf{Y}}^n) \in A^n_{\epsilon}} P(\underline{\mathbf{x}}^n) P(\underline{\mathbf{y}}^n) \\ &\leq \sum_{(\underline{\mathbf{X}}^n,\underline{\mathbf{Y}}^n) \in A^n_{\epsilon}} 2^{-n(H(X)+\epsilon)} 2^{-n(H(Y)+\epsilon)} \\ &\leq |A^n_{\epsilon}| \, 2^{-n(H(X)+H(Y)+2\epsilon)} \\ &= 2^{n(H(X,Y)+\epsilon)} 2^{-n(H(X)+H(Y)+2\epsilon)} \\ &= 2^{-n(I(X;Y)-3\epsilon)} \end{split}$$

8.5 Channel Coding Theorem

Definition 8.5.1. Decode Error:

Here, we have three types of decode error:

1.
$$\lambda_i = Pr\{g(Y^n) \neq i | X^n(i)\};$$

2.
$$\bar{\lambda}_i = \frac{1}{m} \sum_{i=1}^m \lambda_i$$
;

3. $\lambda_{max} = \max\{\lambda_i\}$

Theorem 8.5.1. Channel coding theorem:

- 1. For every rate R < C, there exists a sequence $(M = 2^{nR}, n)$ code with $\lambda_{max}^{(n)} \to 0$.
- 2. Conversely, any sequence $(2^{nR}, n)$ code with $\lambda_{max}^{(n)} \to 0$, must have $R \leq C$.

Proof. 1. $W \in \{1, 2, ..., M = 2^{nR}\}$ ~ uniform distribution.

2. Channel Code: $C: \{1, 2, ..., M\} \to \underline{X}^n = (x_1, x_2, ..., x_n), x_i \in \{0, 1\}$

$$C = \begin{bmatrix} X_1(1) & \dots & X_n(1) \\ \dots & & \dots \\ X_1(M) & \dots & X_n(M) \end{bmatrix}_{M \times n}$$

- 3. Channel: $P(Y^n|X^n(w)) = \prod_{i=1}^n P(y_i|x_i(w))$ (Memoryless)
- 4. Decode(Jointly typical decoder):

From recieved \underline{Y}^n , estimate $\hat{W}(\underline{Y}^n)$ based on the joint typical set $A_{\epsilon}^{(n)}$:

$$\hat{W}(\underline{Y}^n) = \begin{cases} \hat{w} & \text{if } \exists \text{ unique } \hat{w} \text{ s.t. } (X^n(\hat{w}), Y^n) \in A_{\epsilon}^{(n)} \\ 0 & otherwise \end{cases}$$

- 5. The probability of decode error is:
 - $P_e^n(C) = Pr\{W \neq \hat{W}(\underline{Y}^n)\}$ for any given random code C.
 - $\bar{P}_e^n = \sum_C Pr(C) P_e^n(C)$

We will prove if $R < I(X;Y) - 3\epsilon$, then $\bar{P}_e^n < 2\epsilon$. If $R > C - \epsilon$ holds, then we have those corollaries:

- 1. Choose P(X) to maximize I(X;Y), then we have $R < C 2\epsilon$;
- 2. There exists one code C^* s.t. $\bar{P}_e^n(C^*) = \frac{1}{2^{nR}} \sum \lambda_i < 2\epsilon$;
- 3. There are at least $\frac{2^{nR}}{2}$ codes with decode error $\lambda_i \leq 4\epsilon$.

Due to corollary 3, if we just use the $\frac{2^{nR}}{2}$ codes, the code rate is $R - \frac{1}{n} \to R$, and the maximum decode error is $\lambda_{max} \le 4\epsilon$.

WLOG, we just discuss the error rate of code "1" in all random codes:

$$E_{i} = \{(\underline{X}^{n}(i), \underline{Y}^{n}) \in A_{\epsilon}^{(n)} | W = i\}$$

$$P_{e,1} = \sum_{C} Pr(C)\lambda_{1} = Pr[E_{1}^{C} \cup E_{2} \cup \ldots \cup E_{M}]$$

$$\leq Pr[E_{1}^{C}] + Pr[E_{2} \cup \ldots \cup E_{M}]$$

We have two results:

- 1. $Pr[E_1^C] \leq \epsilon$ due to AEP Theorem;
- 2. $P(\underline{X}^n(i),\underline{Y}^n) = P(\underline{X}^n(i))P(\underline{Y}^n), i \neq 1$ due to the random code C.

If the recieved \underline{Y}^n is not transmitted from $\underline{X}^n(1)$, then $\underline{Y}^n \perp \underline{X}^n(1)$.

$$Pr[E_2 \cup \ldots \cup E_M] \le \epsilon + 2^{-n(I(X;Y) - 3\epsilon)} P(\underline{X}^n(2), \underline{Y}^n(\underline{X}^n(1)))$$

$$\le 2^{-n(I(X;Y) - 3\epsilon)} P(\underline{X}^n(2)) P(\underline{Y}^n(\underline{X}^n(1)))$$

There are 2^{nR} codes, the average error rate is:

$$Pr[E_1^C] + 2^{nR} Pr[E_2 \cup \ldots \cup E_M] \le \epsilon + 2^{-n(I(X;Y) - 3\epsilon - R)} P(\underline{X}^n(2)) P(\underline{Y}^n(\underline{X}^n(1)))$$

If $R < I(X;Y) - 3\epsilon$, then we have:

$$2^{nR}Pr[E_2 \cup \ldots \cup E_M] \to 0, n \to \infty$$

 $\therefore P_{e,1} < \epsilon$

§ 9 Differential Entropy

9.1 Definition

1. continuous random variable X;

2. C.D.F : $F(x) = Pr(X \le x)$

3. P.D.F: $f(x) = \frac{dF(x)}{dx}$

Definition 9.1.1. Differential entropy:

$$h(X) = -\int f(x) \log f(x) dx = \mathbf{E} \log \frac{1}{f(x)}$$

Example 9.1.1. $X \sim U[0, a]$ $f(x) = \frac{1}{a}$

$$h(X) = -\int_0^a \frac{1}{a} \log \frac{1}{a} dx = \log a$$

If a < 1, then h(X) < 0.

• Y = X + C, h(Y) = h(X + C) = h(X), C = const

• $h(aX) = h(X) + \log |a|, a = const$

9.2 Mutual Information, Joint Entropy and Conditional Entropy

- $I(X;Y) = \mathbf{E} \log \frac{f(X)f(Y)}{f(X,Y)}$;
- $h(X,Y) = \mathbf{E} \log \frac{1}{f(X,Y)}$;
- $h(X|Y) = \mathbf{E} \log \frac{1}{f(X|Y)}$.

9.3 K-L Divergence

$$X \sim f \qquad X \sim g$$

$$D[f \parallel g] = \mathop{\mathbf{E}}_{f(x)} \log \frac{f(x)}{g(x)} = \int f(x) \log \frac{f(x)}{g(x)} dx$$

Theorem 9.3.1.

$$D[f \parallel g] \geq 0$$

Proof.

$$-D[f \parallel g] = -\int f(x) \log \frac{f(x)}{g(x)} dx$$

$$= \int f(x) \log \frac{g(x)}{f(x)} dx$$

$$\leq \log (\mathbf{E}_{x \sim f(x)} \frac{g(x)}{f(x)})$$

$$= \log \int g(x) dx = \log 1 = 0$$

$$\therefore D[f \parallel g] \geq 0$$