

Group

associative

A set G with a binary operation $g \cdot h = gh$ ("multiplication") is said to be a group if

$g, h \in G$

① The multiplication is close: $gh \in G \quad \forall g, h \in G$

② There exists an identity element e s.t.

$$eg = ge = g, \quad \forall g \in G$$

③ For all $g \in G$, there exists $g^{-1} \in G$ s.t.

$$gg^{-1} = g^{-1}g = e$$

Examples

- Finite groups: permutation, dihedral

- Infinite groups: rotation, unitary

Representation

A (unitary) representation of G on a vector space

V is a map $\varphi: G \rightarrow U(V)$ s.t.

Group of unitary matrices on V

$$\varphi(g)\varphi(h) = \varphi(gh)$$

$$\varphi(e) = \hat{1}$$

$$\varphi(g^{-1}) = [\varphi(g)]^{-1} = [\varphi(g)]^{\dagger}$$

Group action on functions

If G is able to act on a set X , G also acts on functions over X as follow

$$g f(x) = f(g^{-1}x)$$

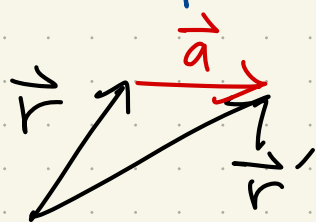
Proof that this definition preserves group composition

$$(gh) f(x) = g(h f(x)) = g f(h^{-1}x)$$

Define $\tilde{f}(x) = f(h^{-1}x)$

$$\begin{aligned} g \tilde{f}(x) &= \tilde{f}(g^{-1}x) = f(h^{-1}g^{-1}x) \\ &= f[(gh)^{-1}x] \end{aligned}$$

Examples Translating wave functions $X = \mathbb{R}^3$



$$|\psi\rangle \mapsto |\psi'\rangle = \hat{T}_{\vec{a}} |\psi\rangle$$

$$\psi(\vec{r} - \vec{a}) = \langle \vec{r} | \hat{T}_{\vec{a}} | \psi \rangle$$

Rep of translation group

$$\hat{T}_{\vec{a}} \hat{T}_{\vec{b}} = \hat{T}_{\vec{a} + \vec{b}}$$

$$\hat{T}_{\vec{a}}^{-1} = \hat{T}_{\vec{a}}^{\dagger} = \hat{T}_{-\vec{a}}$$

$$\therefore \hat{T}_{\vec{a}} |\vec{r}\rangle = |\vec{r} + \vec{a}\rangle$$

$$= \langle \hat{T}_{\vec{a}}^{\dagger} \vec{r} | \psi \rangle$$

$$= \langle \vec{r} - \vec{a} | \psi \rangle$$

(Active vs Passive transformations)

$$\psi(\vec{r}-\vec{a}) = \sum_{n=0}^{\infty} \frac{1}{n!} (-a\vec{\nabla})^n \langle \vec{r} | \psi \rangle$$

$$= \langle \vec{r} | e^{-a\vec{\nabla}} | \psi \rangle$$

$$= \langle \vec{r} | e^{-i\vec{p}\cdot\vec{a}/\hbar} | \psi \rangle$$

$$\vec{p} = \frac{\hbar}{i} \vec{\nabla}$$

$$e^A e^B = e^{A+B+[A,B]/2 + ([A,[A,B]] - [B,[A,B]])/12 + \dots}$$

Group multiplication only depends on commutators of generators \Rightarrow Lie algebra A vector space V equipped with a (non-associative) binary operation $[A,B]$ s.t.

$$[A,B] = -[B,A] \quad \text{bilinear too}$$

$$[A,[B,C]] + [C,[A,B]] + [B,[C,A]] = 0$$

(Jacobi identity)

$$T_a^\dagger \hat{x} T_a = \left(1 + i\frac{a\hat{p}}{\hbar}\right) \hat{x} \left(1 - i\frac{a\hat{p}}{\hbar}\right) + \mathcal{O}(a^2)$$

$$= \hat{x} + \frac{ia}{\hbar} (\hat{p}\hat{x} - \hat{x}\hat{p}) + \mathcal{O}(a^2)$$

$$= \hat{x} - \frac{ia}{\hbar} [\hat{x}, \hat{p}] + \mathcal{O}(a^2)$$

But we know this is $\hat{x} + a \Rightarrow [\hat{x}, \hat{p}] = -\frac{\hbar}{i} = i\hbar$

What's important is to notice which properties are rep-dependent and which are rep-independent.

Examples

Rep-independent

$$[\hat{J}_j, \hat{J}_k] = i\hbar \epsilon_{jkl} \hat{J}_l$$

$$[\hat{\sigma}_j, \hat{\sigma}_k] = 2i\epsilon_{jkl} \hat{\sigma}_l$$

$$\Rightarrow \left[\frac{\hbar \hat{\sigma}_j}{2}, \frac{\hbar \hat{\sigma}_k}{2} \right] = \frac{\hbar^2}{4} 2i\epsilon_{jkl} \hat{\sigma}_l = i\hbar \epsilon_{jkl} \frac{\hbar \hat{\sigma}_l}{2}$$

Rep-dependent

$$\left(\frac{\hbar \hat{\sigma}_j}{2} \right)^2 = \frac{1}{2} \left(\frac{1}{2} + 1 \right) \hbar^2 \mathbb{1} \text{ for any } j$$

$$\hat{L}_x^2 = \frac{\hbar^2}{2} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 1 \end{pmatrix},$$

$$\hat{L}_y^2 = \frac{\hbar^2}{2} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$\hat{L}_z^2 = \hbar^2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

$$\hat{L}^2 = 1(1+1)\hbar^2 \mathbb{1}$$

The usual matrix multiplication is not defined in the Lie algebra. Thus, multiplication of matrix rep of Lie algebra needs not agree in different representations.

Theorem The group $SO(3)$ is a representation of $SU(2)$.

- Let φ denotes the defining rep of $SU(2)$ (as a $\det 1$, 2×2 unitary matrices). The action of $\varphi(g)$ on a two-dim Hilbert space induces an action on the space of traceless Hermitian matrices by conjugation.

Indeed the fact that this is also a representation of $SU(2)$ follows from the representation property of φ :

$$\begin{aligned} \varphi(g) \varphi(h) H [\varphi(h)]^{-1} [\varphi(g)]^{-1} \\ \parallel \\ \varphi(gh) H [\varphi(gh)]^{-1} \end{aligned}$$

But we have learned that any $\overset{2 \times 2}{\text{traceless Hermitian}}$ matrix is in one-to-one correspondence with a 3D unit vector

$$H = \begin{pmatrix} z & x - iy \\ x + iy & -z \end{pmatrix} \longleftrightarrow \hat{n} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\varphi(g) \longleftrightarrow R(g)$$

Thus, the conjugation action of $SU(2)$ can represent all 3D rotations R \square

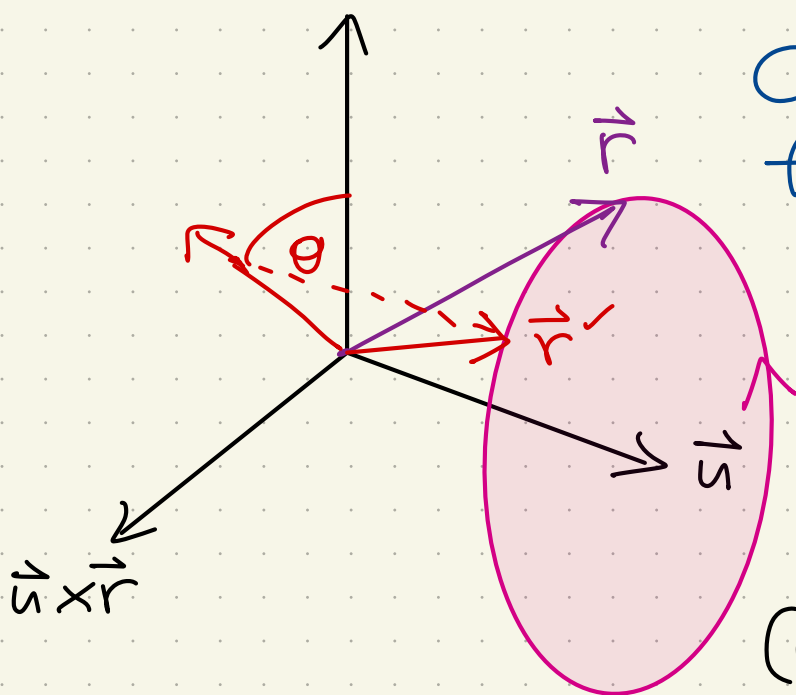
But note the double-valuedness

$$\begin{aligned} R(\mathbb{1}_{2 \times 2}) &\rightarrow \mathbb{1}_{3 \times 3} \\ R(-\mathbb{1}_{2 \times 2}) &\rightarrow \mathbb{1}_{3 \times 3} \end{aligned}$$

$$(\vec{u} \times \vec{r}) \times \vec{u}$$

Rotation of \vec{r} about \vec{u}

Construct orthogonal axes
from \vec{u} , $\vec{u} \times \vec{r}$, $(\vec{u} \times \vec{r}) \times \vec{u}$



Can check that
 $(\vec{u} \times \vec{r}) \times \vec{u} = \vec{r} - (\vec{u} \cdot \vec{r}) \vec{u}$

$$R_{\vec{u}}(\theta) \vec{r} = (\vec{u} \cdot \vec{r}) \vec{u} + \cos \theta (\vec{u} \times \vec{r}) \times \vec{u} + \sin \theta \vec{u} \times \vec{r}$$

$$R_{\vec{u}}(\theta) x_j \hat{e}_j = x_j [R_{\vec{u}}(\theta) \hat{e}_j]$$

$$= x_j \hat{e}_k [\hat{e}_k R_{\vec{u}}(\theta) \hat{e}_j]$$

Insert the identity

Matrix element

Infinitesimal rotation $d\theta$

$$R_{\vec{u}}(d\theta) \vec{r} = \vec{r} + d\theta \vec{u} \times \vec{r}$$

Compare

$$[R_{\vec{u}}(d\theta)]_{jk} = \delta_{jk} + d\theta \epsilon_{jkl} u_l$$

What are generators of rotations?

$$\begin{aligned} R_{\vec{u}}(d\theta) \psi(\vec{r}) &= \langle R_{\vec{u}}(-d\theta) \vec{r} | \psi \rangle \\ &= \langle \vec{r} - d\theta \vec{u} \times \vec{r} | \psi \rangle \end{aligned}$$

Special case $\vec{u} = \hat{e}_z$

$$\Rightarrow \hat{e}_z \times \vec{r} = \epsilon_{3jk} x_j \hat{e}_k = x \hat{e}_y - y \hat{e}_x$$

$$\begin{aligned} \therefore \langle \vec{r} | R_{\hat{e}_z}(d\theta) | \psi \rangle &= \langle \vec{r} - d\theta (x \hat{e}_y - y \hat{e}_x) | \psi \rangle \\ &= \psi(x + y d\theta, y - x d\theta, z) \\ &= \psi(x, y, z) + \left(y \frac{\partial \psi}{\partial x} - x \frac{\partial \psi}{\partial y} \right) d\theta \\ &= \langle \vec{r} | \left[\hat{1} - \frac{i}{\hbar} \hat{L}_z(d\theta) \right] | \psi \rangle \end{aligned}$$

To obtain the commutation relation, proceed as in the case of translations. Generally, suppose that we have **vector operators** $\hat{\vec{V}}$

$$\hat{R}(d\theta) \hat{\vec{V}} \hat{R}(d\theta) = \hat{\vec{V}} + d\theta \vec{u} \times \hat{\vec{V}}$$

$$= \left(1 + \frac{i}{\hbar} d\theta \hat{J}_j\right) \hat{\vec{V}} \left(1 - \frac{i}{\hbar} d\theta \hat{J}_j\right)$$

$$= \hat{\vec{V}} + \frac{i}{\hbar} d\theta (\hat{J}_j \hat{\vec{V}} - \hat{\vec{V}} \hat{J}_j)$$

Compare

$$\therefore [\hat{J}_j, \hat{V}_k] = i\hbar \epsilon_{jkl} \hat{V}_l$$

Thus, the angular momentum commutation relation can be understood as a consequence of the \hat{J}_j 's being vector operators.

Example

$$\begin{aligned} [\hat{L}_j, \hat{x}_k] &= [\epsilon_{jlm} \hat{x}_l \hat{p}_m, \hat{x}_k] \\ &= \epsilon_{jlm} \hat{x}_l [\hat{p}_m, \hat{x}_k] \\ &= -i\hbar \epsilon_{jlk} \hat{x}_l \\ &= i\hbar \epsilon_{jkl} \hat{x}_l \end{aligned}$$

Orbital angular momentum

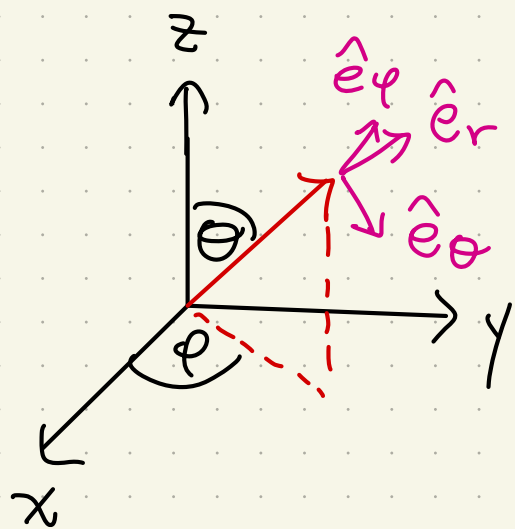
We will now show that the Hilbert space of wave functions $\psi(\vec{r})$ over \mathbb{R}^3 decomposes into a direct sum of all irreps of $SO(3)$ with integral values of j .

(C-T VI.D pp. 663-664)

$$\hat{L}_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}$$

$$\hat{L}_{\pm} = \hbar e^{\pm i\phi} \left(\pm \frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right)$$

l and m must be integral



$$\frac{\hbar}{i} \frac{\partial}{\partial \phi} Y_l^m(\theta, \phi) = m \hbar Y_l^m(\theta, \phi)$$

Assuming separable solutions

$$Y_l^m(\theta, \phi) = F_l^m(\theta) e^{im\phi}$$

Then the continuity at $\phi=0$ and $\phi=2\pi$ implies that m is an integer $\Rightarrow l$ is also an integer

All integral values of l appear

$$\begin{aligned} 0 &= \hat{L}_+ Y_l^l(\theta, \varphi) = \hbar e^{i\varphi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right) Y_l^l(\theta, \varphi) \\ &= \hbar e^{i\varphi} \left\{ \left[\frac{dF_l^l(\theta)}{d\theta} \right] e^{il\varphi} + i \cot \theta F_l^l(\theta) \frac{d e^{il\varphi}}{d\varphi} \right\} \end{aligned}$$

$$\Leftrightarrow \left(\frac{d}{d\theta} - l \cot \theta \right) F_l^l(\theta) = 0$$

$$dF = l \cot \theta d\theta F$$

$$\frac{dF}{F} = l \frac{d(\sin \theta)}{\sin \theta}$$

$$d(\ln F) = l d[\ln(\sin \theta)]$$

$$\ln F = l \ln(\sin \theta) + C$$

$$F \propto e^{l \ln \sin \theta} = (\sin \theta)^l$$

Clearly, for each l , there exists a unique

$$Y_l^l(\theta, \varphi) \propto (\sin \theta)^l e^{il\varphi}$$

The rest of Y_l^m can be obtained from applying \hat{L}_- to Y_l^l . (C-T Complement A_{VI})

Orthonormality

$$\int_0^{2\pi} d\varphi \int_0^\pi d\theta \sin\theta \, Y_{l'}^{m'}{}^*(\theta, \varphi) Y_l^m(\theta, \varphi) = \delta_{l'l} \delta_{m'm}$$

Completeness (Closure relation)

$$\sum_{l=0}^{\infty} \sum_{m=-l}^l Y_l^m{}^*(\theta', \varphi') Y_l^m(\theta, \varphi) = \frac{\delta(\theta - \theta') \delta(\varphi - \varphi')}{\sin\theta}$$

3D delta function

$$\delta(x-x') \delta(y-y') \delta(z-z') = \frac{\delta(r-r')}{r} \frac{\delta(\theta-\theta')}{r \sin\theta} \delta(\varphi-\varphi')$$

Parity

Under reflection $\left\{ \begin{array}{l} \theta \mapsto \pi - \theta \\ \varphi \mapsto \pi + \varphi \end{array} \right.$

$$Y_l^m(\pi - \theta, \pi + \varphi) = (-1)^l Y_l^m(\theta, \varphi)$$

$$Y_l^m{}^*(\theta, \varphi) = (-1)^m Y_l^{-m}(\theta, \varphi)$$