Tensor Calculus J.L. Synge and A.Shild (Dover Publication) Solutions to exercices

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November 28, 2021

Remarks and warnings

Some notation conventions

$$\partial_r a_{mn} \equiv \frac{\partial a_{mn}}{\partial x^r}$$

$$\Gamma_{mn}^r \equiv \begin{Bmatrix} r \\ mn \end{Bmatrix}$$
 Christoffel symbol of the second kind

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Spaces and Tensors

1.1 p5-exercise

The parametric equations of a hypersurface in V_n are

$$x^{1} = a \cos(u^{1})$$

$$x^{2} = a \sin(u^{1}) \cos(u^{2})$$

$$x^{3} = a \sin(u^{1}) \sin(u^{2}) \cos(u^{3})$$

$$\vdots$$

$$x^{N-1} = a \sin(u^{1}) \sin(u^{2}) \sin(u^{3}) \dots \sin(u^{N-2}) \cos(u^{N-1})$$

$$x^{N} = a \sin(u^{1}) \sin(u^{2}) \sin(u^{3}) \dots \sin(u^{N-2}) \sin(u^{N-1})$$

where a is a constant. Find the single equation of the hyperspace in the form 1.103.

We have:

$$(x^{N})^{2} + (x^{N-1})^{2} = a^{2} \prod_{i=1}^{N-2} \sin^{2}(u^{i})(\cos^{2}(u^{N-1}) + \sin^{2}(u^{N-1}))$$

$$= a^{2} \prod_{i=1}^{N-2} \sin^{2}(u^{i})$$

$$= a^{2} \prod_{i=1}^{N-3} \sin^{2}(u^{i}) \sin^{2}(u^{N-2})$$

$$= a^{2} \prod_{i=1}^{N-3} \sin^{2}(u^{i})(1 - \cos^{2}(u^{N-2}))$$

$$= a^{2} \prod_{i=1}^{N-3} \sin^{2}(u^{i}) - a^{2} \prod_{i=1}^{N-3} \sin^{2}(u^{i}) \cos^{2}(u^{N-2})$$

$$= a^{2} \prod_{i=1}^{N-3} \sin^{2}(u^{i}) - (x^{N-2})^{2}$$

giving

$$(x^N)^2 + (x^{N-1})^2 + (x^{N-2})^2 = a^2 \prod_{i=1}^{N-3} \sin^2(u^i)$$

In general, by recursion

$$\sum_{i=0}^{k} (x^{N-i})^2 = a^2 \prod_{i=1}^{N-k-1} \sin^2(u^i) \quad (k \le N-2)$$

be k = N - 2 (N - k - 1 = 1) and in the left term put j = N - i (j goes from 2 to N), we get

$$\sum_{j=2}^{N} (x^{j})^{2} = a^{2} \prod_{i=1}^{1} \sin^{2}(u^{i})$$
$$= a^{2} (1 - \cos^{2}(u^{1}))$$
$$= a^{2} - (x^{1})^{2}$$

and thus the equation of the hyperspace is given by

$$\sum_{j=1}^{N} (x^{j})^{2} - a^{2} = 0$$

Determine whether the points $(\frac{1}{2}a, 0, 0, ...0)$, (0, 0, ..., 0, 2a) lie on the same or opposite sides of the hyperspace.

For
$$(\frac{1}{2}a, 0, 0, ...0)$$
 we have $\sum_{j=1}^{N} (x^{j})^{2} - a^{2} = -\frac{3a^{2}}{4} < 0$ and for $(0, 0, ..., 0, 2a)$ we have $\sum_{j=1}^{N} (x^{j})^{2} - a^{2} = \frac{3a^{2}}{4} > 0$.

So the points lie on opposite sides of the hyperplane.

1.2 p6-exercise

Let U_2 and W_2 be subspaces of V_N . Show that if N=3 they will in general intersect in a curve; if N=4 they will in general intersect in a finite number of points; and if N>4 they will not in general intersect at all.

We have (see 1.102 page 5):
$$x^r = f^r(u^1, u^2, ..., u^M)$$
 $(r = 1, 2, ..., N)$
Case N=3:

For U_2 we have:

$$x^{r} = \phi^{r}(u^{1}, u^{2})$$
 $(r = 1, 2, 3)$

For W_2 we have:

$$x^{r} = \psi^{r}(v^{1}, v^{2})$$
 $(r = 1, 2, 3)$

The intersect of the two hyperplanes is given by the N equations:

$$\phi^{r}(u^{1}, u^{2}) = \psi^{r}(v^{1}, v^{2}) \quad (r = 1, 2, 3)$$

So we have 3 equations in 4 unknown u^1, u^2, v^1, v^2 and can choose (fix) one e.g. u^1 and solve the set of equations for u^2, v^1, v^2 giving

$$x^{r} = \theta^{r}(u^{1})$$
 $(r = 1, 2, 3)$

This is an equation of a curve in space (1 parameter equation)

Case N=4

Using the same reasoning as with N=3, we get 4 equations for 4 unknown u^1, u^2, v^1, v^2 .

Provided that the set of equation does not degenerate, these 4 equations will determine u^1, u^2, v^1, v^2 without any degree of freedom. So we get points as solutions. This solution does not to be unique, e.g. if the $\phi^r(u^1, u^2)$ are quadratic form, then the solutions

$$(u^{1}, u^{2}, v^{1}, v^{2})$$

$$(-u^{1}, u^{2}, v^{1}, v^{2})$$

$$(u^{1}, -u^{2}, v^{1}, v^{2})$$

$$(-u^{1}, -u^{2}, v^{1}, v^{2})$$

are possible.

Case N=5: There are more equations than variables. If the equations are not linear dependent, no solutions will be found.

1.3 p8-exercise

Show that
$$(a_{rst} + a_{str} + a_{srt})x^rx^sx^t = 3a_{rst}x^rx^sx^t$$

 $(a_{rst} + a_{str} + a_{srt})x^rx^sx^t = a_{rst}x^rx^sx^t + a_{rts}x^rx^sx^t + a_{srt}x^rx^sx^t \quad \text{ so by just renaming the dummy indices e.g. for the second term } r \mapsto s \quad , \ s \mapsto t \quad \text{ and } t \mapsto r \quad \text{ we get the desired result.}$

1.4 p8-exercise

If $\phi = a_{rs}x^rx^s$, show that

$$\frac{\partial \phi}{\partial x^r} = (a_{rs} + a_{sr})x^s \quad , \quad \frac{\partial^2 \phi}{\partial x^r \partial x^s} = a_{rs} + a_{sr}$$

Simplify these expressions in the case where $a^{rs} = a^{sr}$

We have

$$\frac{\partial \phi}{\partial x^t} = \frac{\partial a_{rs}}{\partial x^t} x^r x^s + a_{rs} \frac{\partial x^r}{\partial x^t} x^s + a_{rs} x^r \frac{\partial x^s}{\partial x^t}$$
 (1)

$$= \frac{\partial a_{rs}}{\partial x^t} x^r x^s + a_{rs} \delta_t^r x^s + a_{rs} x^r \delta_t^s \tag{2}$$

$$= \frac{\partial a_{rs}}{\partial x^t} x^r x^s + a_{ts} x^s + a_{rt} x^r \tag{3}$$

$$= \frac{\partial a_{rs}}{\partial x^t} x^r x^s + a_{ts} x^s + a_{st} x^s \quad \text{(rename dummy variable in third term)} \tag{4}$$

$$= \frac{\partial a_{rs}}{\partial x^t} x^r x^s + (a_{ts} + a_{st}) x^s \tag{5}$$

Replace x^t by x^r , we get

$$\frac{\partial \phi}{\partial x^r} = \frac{\partial a_{rs}}{\partial x^r} x^r x^s + (a_{rs} + a_{sr}) x^s \tag{6}$$

So the asked expression is only true if a_{rs} is not a function of the x^s . Assuming that a_{rs} is not a function of the x^s , take the partial derivative of (6) with respect to x^t , we get

$$\frac{\partial^2 \phi}{\partial x^r \partial x^t} = (a_{rs} + a_{sr}) \frac{\partial x^s}{\partial x^t}$$
 (7)

$$= (a_{rs} + a_{sr})\delta_t^s \tag{8}$$

$$= (a_{rt} + a_{tr}) \tag{9}$$

Replace x^t by x^s , and we get the proposed expression.

p8-clarification on expression 1.210 1.5

$$\frac{\partial^2 x^{,q}}{\partial x^p \partial x^s} + \frac{\partial^2 x^r}{\partial x^{,m} \partial x^{,n}} \frac{\partial x^{,m}}{\partial x^p} \frac{\partial x^{,n}}{\partial x^s} \frac{\partial x^{,q}}{\partial x^r} = 0$$

From 1.209:

$$\frac{\partial^2 x^r}{\partial x^m \partial x^n} \frac{\partial x^m}{\partial x^p} \frac{\partial x^n}{\partial x^s} + \frac{\partial x^r}{\partial x^n} \frac{\partial^2 x^n}{\partial x^p \partial x^s} = 0$$
 (1)

multiply (1) with

$$\frac{\partial^2 x^r}{\partial x^m \partial x^n} \frac{\partial x^m}{\partial x^p} \frac{\partial x^n}{\partial x^s} \frac{\partial x^q}{\partial x^r} + \frac{\partial x^r}{\partial x^n} \frac{\partial^2 x^n}{\partial x^p \partial x^s} \frac{\partial x^q}{\partial x^r} = 0$$
 (2)

$$\Leftrightarrow \frac{\partial x^r}{\partial x^{,n}} \frac{\partial^2 x^{,n}}{\partial x^p \partial x^s} \frac{\partial x^{,q}}{\partial x^r} + \frac{\partial^2 x^r}{\partial x^{,m} \partial x^{,n}} \frac{\partial x^{,m}}{\partial x^p} \frac{\partial x^{,n}}{\partial x^s} \frac{\partial x^{,q}}{\partial x^r} = 0$$
 (3)

in the first term we get
$$\frac{\partial x^q}{\partial x^r} \frac{\partial x^r}{\partial x^n} = \frac{\partial x^q}{\partial x^n} = \delta_n^q$$
 (4)

(3) becomes

$$\frac{\partial^{2} x^{,n}}{\partial x^{p} \partial x^{s}} \delta_{n}^{q} + \frac{\partial^{2} x^{r}}{\partial x^{,m} \partial x^{,n}} \frac{\partial x^{,m}}{\partial x^{p}} \frac{\partial x^{,n}}{\partial x^{s}} \frac{\partial x^{,q}}{\partial x^{r}} = 0$$

$$\Leftrightarrow \frac{\partial^{2} x^{,q}}{\partial x^{p} \partial x^{s}} + \frac{\partial^{2} x^{r}}{\partial x^{,m} \partial x^{,n}} \frac{\partial x^{,m}}{\partial x^{p}} \frac{\partial x^{,n}}{\partial x^{s}} \frac{\partial x^{,q}}{\partial x^{r}} = 0$$
(5)

$$\Leftrightarrow \frac{\partial^2 x^{,q}}{\partial x^p \partial x^s} + \frac{\partial^2 x^r}{\partial x^{,m} \partial x^{,n}} \frac{\partial x^{,m}}{\partial x^p} \frac{\partial x^{,n}}{\partial x^s} \frac{\partial x^{,q}}{\partial x^r} = 0$$
 (6)

1.6 p9-exercise

If A_s^r are the elements of a determinant A, and B_s^r the elements of a determinant B, show that the element of the product determinant is $A_n^r B_s^n$. Hence show that the product of the two jacobians

$$J = \left| \frac{\partial x^{r}}{\partial x^{,s}} \right|, \quad J' = \left| \frac{\partial x^{,r}}{\partial x^{s}} \right|$$

is unity.

Remark: Some nitpick about the formulation: A_s^r are not the elements of a determinant A, but elements of the matrix A which gives $\det\{A\}$ provided that A is square (which is not explicitly mentioned.). The same remark for B and $A_n^r B_s^n$.

Be A_k^i the elements of matrix A and B_j^k the elements of matrix B and C = A.B the resulting matrix of the multiplication of A and B, then

$$C_i^i = A_k^i B_i^k$$

are the elements of matrix C. Now, put $A_k^i = \frac{\partial x^i}{\partial x^{,k}}$ and $B_j^k = \frac{\partial x^{,k}}{\partial x^j}$ then

$$C_j^i = A_k^i B_j^k \tag{1}$$

$$= \frac{\partial x^i}{\partial x^{,k}} \frac{\partial x^{,k}}{\partial x^j} \tag{2}$$

$$=\delta_k^i \tag{3}$$

So C = JJ' becomes the unity matrix.

1.7 p11-exercise

Show that a finite contravariant vector determines the ratios of the components of an infinitesimal displacement. (Consider the transformation of the equation $dx^r = \theta T^r$, where θ is an arbitrary factor which does not change under the transformation. Alternatively, show that the equations $T^r dx^s - T^s x^r = 0$ remain true when we transform the coordinates.)

Be T^q a contravariant vector.

$$T^{,q} = T^r \frac{\partial x^{,q}}{\partial x^r}$$
 (by definition) (1)

Be θ a small infinitesimal factor invariant for a coordinate transformation, define

$$dx^r = \theta T^r \tag{2}$$

(3)

then

$$\frac{dx^r}{dx^s} = \frac{\theta T^r}{\theta T^s} \tag{4}$$

$$\Leftrightarrow T^s dx^r - T^r dx^s = 0 \tag{5}$$

Alternatively, multiply (5) with $\partial_{x^r} x^{,q}$, then

$$\frac{\partial x^{,q}}{\partial x^r} dx^r T^s - \frac{\partial x^{,q}}{\partial x^r} dx^s T^r = 0 \tag{6}$$

$$\Leftrightarrow \frac{\partial x^{q}}{\partial x^{r}} dx^{r} T^{s} - dx^{s} T^{q} = 0 \quad \text{(use (1) in the second term)}$$
 (7)

$$\Leftrightarrow dx^{,q}T^s - dx^sT^{,q} = 0 \tag{8}$$

(9)

Multiply (8) with $\partial_{x^s} x^{p}$, then

$$dx^{q}T^{s}\partial_{x^{s}}x^{p} - dx^{s}T^{q}\partial_{x^{s}}x^{p} = 0$$

$$\tag{10}$$

$$\Leftrightarrow T^{p}dx^{q} - T^{q}dx^{p} = 0 \quad \text{(use (1) in the first term)}$$
 (11)

and thus

$$\frac{dx^{,q}}{dx^{,p}} = \frac{T^{,q}}{T^{,p}}$$

p12-exercise 1.8

Write down the equation of transformation, analogous to 1.305, of a contravariant tensor of the third order. Solve the equation so as to express the unprimed components in terms of the primed components.

Ве

$$T^{,uvw} = T^{rst} \frac{\partial x^{,u}}{\partial x^r} \frac{\partial x^{,v}}{\partial x^s} \frac{\partial x^{,w}}{\partial x^t} \quad \text{(by definition)}$$
 (1)

a contravariant vector.

Multiply (1) by $\frac{\partial x^n}{\partial x^{,u}}$

$$T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} = T^{rst} \frac{\partial x^{,u}}{\partial x^r} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^{,v}}{\partial x^s} \frac{\partial x^{,w}}{\partial x^t}$$
(2)

$$T^{,uvw} \frac{\partial x^{n}}{\partial x^{,u}} = T^{rst} \frac{\partial x^{,u}}{\partial x^{r}} \frac{\partial x^{n}}{\partial x^{,u}} \frac{\partial x^{,v}}{\partial x^{s}} \frac{\partial x^{,w}}{\partial x^{t}}$$

$$\Leftrightarrow T^{,uvw} \frac{\partial x^{n}}{\partial x^{,u}} = T^{rst} \delta_{r}^{n} \frac{\partial x^{,v}}{\partial x^{s}} \frac{\partial x^{,w}}{\partial x^{t}}$$

$$(2)$$

$$\Leftrightarrow T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} = T^{nst} \frac{\partial x^{,v}}{\partial x^s} \frac{\partial x^{,w}}{\partial x^t}$$

$$\tag{4}$$

Multiply (4) by $\frac{\partial x^m}{\partial x^{,v}}$

$$T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^m}{\partial x^{,v}} = T^{nst} \frac{\partial x^{,v}}{\partial x^s} \frac{\partial x^m}{\partial x^{,v}} \frac{\partial x^{,w}}{\partial x^t}$$
 (5)

$$\Leftrightarrow T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^m}{\partial x^{,v}} = T^{nst} \delta_s^m \frac{\partial x^{,w}}{\partial x^t}$$
 (6)

$$\iff T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^m}{\partial x^{,v}} = T^{nmt} \frac{\partial x^{,w}}{\partial x^t}$$
 (7)

Multiply (7) by $\frac{\partial x^p}{\partial x^{,w}}$

$$T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^m}{\partial x^{,v}} \frac{\partial x^p}{\partial x^{,w}} = T^{nmt} \frac{\partial x^{,w}}{\partial x^t} \frac{\partial x^p}{\partial x^{,w}}$$
(8)

$$\Leftrightarrow T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^m}{\partial x^{,v}} \frac{\partial x^p}{\partial x^{,w}} = T^{nmt} \delta_t^p$$

$$\stackrel{\partial}{\partial x^n} \frac{\partial x^m}{\partial x^m} \frac{\partial x^m}{\partial x^m} \frac{\partial x^p}{\partial x^m} = T^{nmt} \delta_t^p$$
(9)

$$\iff T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^m}{\partial x^{,v}} \frac{\partial x^p}{\partial x^{,w}} = T^{nmp} \tag{10}$$

Giving

$$T^{nmp} = T^{,uvw} \frac{\partial x^n}{\partial x^{,u}} \frac{\partial x^m}{\partial x^{,v}} \frac{\partial x^p}{\partial x^{,w}}$$

1.9 p14-exercise

For a transformation from on set of rectangular Cartesian coordinates to another in Euclidean 3-space, show that the law of transformation of a contravariant vector is precisely the same as that of a covariant vector. Can this statements be extended to cover tensor of higher orders?

We have to prove that, given that,

$$T^{,i} = T^{j} \frac{\partial x^{,i}}{\partial x^{j}} \quad T_{i}^{,} = T_{j} \frac{\partial x^{j}}{\partial x^{,i}}$$

that also

$$T^{,i} = T^{j} \frac{\partial x^{j}}{\partial x^{,i}} \quad T_{i}^{,} = T_{j} \frac{\partial x^{,i}}{\partial x^{j}}$$
 (1)

$$\Leftrightarrow \frac{\partial x^j}{\partial x^{,i}} = \frac{\partial x^{,i}}{\partial x^j} \tag{2}$$

Be

$$e^{\hat{i}} = g_k^i e^{\hat{k}} \quad \text{and } e^{\hat{i}} = h_k^i e^{\hat{k}} \tag{3}$$

the transformation rules from one set of (rectangular Cartesian) basis vectors to another set of (rectangular Cartesian) basis vectors. Then,

$$\langle \hat{e^i}, \hat{e^j} \rangle = \langle g_k^i \hat{e^k}, g_k^j \hat{e^k} \rangle \text{ and } \langle \hat{e^i}, \hat{e^j} \rangle = \langle h_k^i \hat{e^{jk}}, h_k^j \hat{e^{jk}} \rangle$$
 (4)

$$\Leftrightarrow \delta_i^p = g_k^p g_k^j \text{ and } \delta_i^p = h_k^p h_k^j$$
 (5)

(6)

Be \vec{v} a random vector in the Euclidean space,

$$\vec{v} = x^j \hat{e^j} = x^{,j} \hat{e^{,j}}$$
 (7)

then

(3)
$$\Rightarrow x^{j} \hat{e^{j}} = x^{j} h_{k}^{j} \hat{e^{,k}} \text{ and } x^{,j} \hat{e^{,j}} = x^{,j} g_{k}^{j} \hat{e^{k}}$$
 (8)

$$\Rightarrow x^{,j} = x^m h_i^m \text{ and } x^m = x^{,j} g_m^j$$
 (9)

$$\Rightarrow x^{,j} = x^{,i} g_m^i h_i^m \text{ and } x^m = x^k h_i^k g_m^j$$
 (10)

$$\Rightarrow \delta_i^p = g_k^p h_i^k \text{ and } \delta_i^p = g_i^k h_k^p \tag{11}$$

$$(5) \Rightarrow g_k^p g_k^j = g_k^p h_j^k \text{ and } h_k^p h_k^j = g_j^k h_k^p$$

$$(12)$$

$$\Rightarrow g_k^j = h_j^k \text{ and } h_k^j = g_j^k \tag{13}$$

From (9)

$$x^{j} = x^{m} g_{j}^{m} \text{ and } x^{k} = x^{n} h_{k}^{n}$$
 (14)

$$\Rightarrow \frac{\partial x^{,k}}{\partial x^{j}} = \frac{\partial x^{n}}{\partial x^{j}} h_{k}^{n} \text{ and } \frac{\partial x^{j}}{\partial x^{,k}} = \frac{\partial x^{,m}}{\partial x^{,k}} g_{j}^{m}$$
(15)

$$\Leftrightarrow \frac{\partial x^{,k}}{\partial x^{j}} = \delta_{j}^{n} h_{k}^{n} \text{ and } \frac{\partial x^{j}}{\partial x^{,k}} = \delta_{k}^{m} g_{j}^{m}$$
(16)

$$\Leftrightarrow \frac{\partial x^{,k}}{\partial x^j} = h_k^j \text{ and } \frac{\partial x^j}{\partial x^{,k}} = g_j^k$$
 (17)

$$(13) \Rightarrow \frac{\partial x^{,k}}{\partial x^{j}} = \frac{\partial x^{j}}{\partial x^{,k}} \tag{18}$$

So (13) matches (2), proving the assertion.

Can this statements be extended to cover tensor of higher orders? Consider

$$T^{,i,j,...,n} = T^{r,s,...w} \frac{\partial x^{,i}}{\partial x^{r}} \frac{\partial x^{,j}}{\partial x^{s}} \dots \frac{\partial x^{,n}}{\partial x^{w}} \text{ and } T^{r,s,...w} = T^{,i,j,...,n} \frac{\partial x^{r}}{\partial x^{,i}} \frac{\partial x^{s}}{\partial x^{,j}} \dots \frac{\partial x^{w}}{\partial x^{,n}}$$

Using the same reasoning as in (1) to (2) we need

$$\frac{\partial x^{,i}}{\partial x^{r}}\frac{\partial x^{,j}}{\partial x^{s}}\dots\frac{\partial x^{,n}}{\partial x^{w}}=\frac{\partial x^{r}}{\partial x^{,i}}\frac{\partial x^{s}}{\partial x^{,j}}\dots\frac{\partial x^{w}}{\partial x^{,n}}$$

As the conclusion (18) is independent of the order of the tensor, it is obvious that the above equality yields. Hence, the answer is YES.

1.10 p16-exercise

In a space of 4 dimensions, the tensor A_{rst} is skew-symmetric in the last pair of suffixes. Show that only 24 of the 64 components may be chosen arbitrarily. If the further condition $A_{rst} + A_{str} + A_{trs} = 0$ is imposed, show that that only 20 components may be chosen arbitrarily.

We have, as A is skew-symmetric in the last pair of suffixes

$$A_{rst} = -A_{rts} \Rightarrow s = t$$
: $A_{rst} = 0$

So, for each r (4 possible choices as N=4) we have 4x4/2 - 4 = 6 degrees of freedom. [we have the term 4x4/2 as the tensor is (skew-)symmetric, e.g. once we choose element a_{12} , then a_{21} is also known. The term -4 takes into account the diagonal element which are 0 and thus cannot be chosen.] So, we have 4x6 = 24 degrees of freedom.

What about the supplementary constraint $A_{rst} + A_{str} + A_{trs} = 0$:

Consider the two possible excluding cases:

i)
$$r = s \neq t \ (\iff r = t \neq s)$$

This case gives - without the additional constraint (1) - 4x(4x3/2-4) = 8 degrees of freedom. Does the constraint (1) reduces this degree of freedom?

We have,

$$A_{rst} + A_{str} + A_{trs} = 0 ag{1}$$

$$\Rightarrow \underbrace{A_{rrt} + A_{rtr}}_{\text{= 0 (non-diagonal terms)}} + \underbrace{A_{trr}}_{\text{= 0 (diagonal terms)}} = 0$$
 (2)

So, no additional constraints are added by (1) to the restriction i) and the DOF remains 8.

ii)
$$t \neq r \neq s \neq t$$

This case means that we have to choose a set of 3 elements out of 4 elements without repetition. This a *variation* of 3 elements out of 4.

$$V_k^n = \frac{n!}{(n-k)!}$$
 giving $V_3^4 = \frac{4!}{(4-3)!} = 24$

The constraint (1) gives us 24 equations but as $A_{rst} = -A_{rts}$ only 12 equations have to be considered. So, with the additional constraints the DOF becomes 24-12 = 12.

As i) and ii) are independent and excluding events we can add the DOF of both events and we get 8+12=20 DOF.

1.11 p16-exercise

If A^{rs} is skew-symmetric and B_{rs} is symmetric, prove that $A^{rs}B_{rs}=0$. Hence show that the quadratic form $a_{ij}x^ix^j$ is unchanged if a_{ij} is replaced by its symmetric part.

We can split the summation $A^{rs}B_{rs}$ in three subsummations:

$$A^{rs}B_{rs} = A^{rs}B_{rs}|_{r=s} \tag{1}$$

$$+A^{rs}B_{rs}|_{r>s} \tag{2}$$

$$+A^{rs}B_{rs}|_{r \leqslant s} \tag{3}$$

We have:

(1) = 0 as $A^{kk} = 0$ (skew-symmetric)

$$(2)+(3) = A^{rs}B_{rs}|_{r>s} + A^{rs}B_{rs}|_{r$$

As $A^{rs} = -A^{sr}$ and $B^{rs} = B^{sr}$ we can write (2)+(3) as :

$$A^{rs}B_{rs}|_{r>s} + (-A^{sr})B_{sr}|_{r>s} = 0$$

So,
$$A^{rs}B_{rs} = 0$$

Consider the quadratic form $\phi = a_{ij}x^ix^j$

Be $A_{ij} = (a_{ij})$ and $B_{ij} = (x^i x^j)$, then it is obvious that B_{ij} is symmetric and that $C_{ij} = -A_{ij}$ is the form where $-a_{ij}$ is replaced by its symmetric part (skew-symmetric). Hence $\phi = a_{ij}x^i x^j = a_{ij}b^{ij} = 0$ and so is $\phi = c_{ij}b^{ij} = 0$

1.12 p18-exercise

What are the values (in a space of N dimensions) of the following contractions formed from the Kronecker delta?

$$\boldsymbol{\delta}_m^m, \boldsymbol{\delta}_n^m \boldsymbol{\delta}_m^n, \boldsymbol{\delta}_n^m \boldsymbol{\delta}_r^n \boldsymbol{\delta}_m^r$$

We can split the summation $A^{rs}B_{rs}$ in three subsummations:

$$\delta_m^m = N \tag{1}$$

$$\delta_n^m \delta_m^n = \delta_m^m = N \tag{2}$$

$$\delta_{m}^{m} = N \tag{1}$$

$$\delta_{n}^{m} \delta_{m}^{n} = \delta_{m}^{m} = N \tag{2}$$

$$\delta_{n}^{m} \delta_{r}^{n} \delta_{m}^{r} = \delta_{n}^{m} \delta_{m}^{n} = \delta_{m}^{m} = N \tag{3}$$

1.13 p19-exercise

If X^r , Y^r are arbitrary contravariant vectors and $a_{rs}X^rY^s$ is an invariant, then a_{rs} are the components of a covariant tensor of the second order.

We have to prove that

$$a'_{rs} = a_{ij} \frac{\partial x^i}{\partial x^{r}} \frac{\partial x^j}{\partial x^{s}} \text{ or } a_{ij} = a'_{rs} \frac{\partial x^r}{\partial x^i} \frac{\partial x^s}{\partial x^j}$$
 (1)

 $a_{rs}X^{r}Y^{s}$ is an invariant, means

$$a_{rs}^{,}X^{,r}Y^{,s} = a_{rs}X^{r}Y^{s} \tag{2}$$

As X^r , Y^r are arbitrary contravariant vectors, we have

$$X^{r} = X^{i} \frac{\partial x^{r}}{\partial x^{i}}$$
 and $Y^{s} = Y^{j} \frac{\partial x^{s}}{\partial x^{j}}$ (3)

(3) in (2) gives

$$a_{rs}^{'}X^{i}\frac{\partial x^{'r}}{\partial x^{i}}Y^{j}\frac{\partial x^{'s}}{\partial x^{j}} = a_{rs}X^{r}Y^{s}$$

$$\tag{4}$$

$$\Leftrightarrow a_{rs}^{,} \frac{\partial x^{,r}}{\partial x^{i}} \frac{\partial x^{,s}}{\partial x^{j}} X^{i} Y^{j} = a_{ij} X^{i} Y^{j}$$

$$(5)$$

$$\Leftrightarrow \left(a_{rs}^{i} \frac{\partial x^{r}}{\partial x^{i}} \frac{\partial x^{s}}{\partial x^{j}} - a_{ij}\right) X^{i} Y^{j} = 0$$
(6)

As X^r , Y^r are arbitrary contravariant vectors, we conclude that

$$a_{rs}^{\prime} \frac{\partial x^{\prime r}}{\partial x^{i}} \frac{\partial x^{\prime s}}{\partial x^{j}} - a_{ij} = 0 \tag{7}$$

$$\Leftrightarrow a_{ij} = a_{rs}^{\prime} \frac{\partial x^{\prime r}}{\partial x^{i}} \frac{\partial x^{\prime s}}{\partial x^{j}}$$
(8)

(8) = (1): OK

1.14 p19-exercise

If X_{rs} is an arbitrary covariant tensor of the second order, and $A_r^{mn}X_{mn}$ is a covariant vector, then A_r^{mn} has the mixed tensor character indicated by the positions of its suffixes

We have to prove that

$$A_r^{,vw} = A_k^{mn} \frac{\partial x^k}{\partial x^{,r}} \frac{\partial x^{,v}}{\partial x^m} \frac{\partial x^{,w}}{\partial x^n}$$

$$\tag{1}$$

We have

$$P_r = A_r^{mn} X_{mn} \tag{2}$$

is a covariant vector

$$\Rightarrow P_r' = A_k^{mn} X_{mn} \frac{\partial x^k}{\partial x^r} \tag{3}$$

but X_{mn} is a covariant tensor

$$\Rightarrow X_{mn} = X_{ps}^{,} \frac{\partial x^{,p}}{\partial x^m} \frac{\partial x^{,s}}{\partial x^n}$$
 (4)

So (4) in (3) gives

$$P_r^{,} = A_k^{mn} X_{ps}^{,} \frac{\partial x^{,p}}{\partial x^m} \frac{\partial x^{,s}}{\partial x^n} \frac{\partial x^k}{\partial x^{,r}}$$
 (5)

$$\Leftrightarrow P_r^{,} = \underbrace{A_k^{mn} \frac{\partial x^{,p}}{\partial x^m} \frac{\partial x^{,s}}{\partial x^n} \frac{\partial x^k}{\partial x^{,r}}}_{(*)} X_{ps}^{,}$$

$$(6)$$

Putting (*) as $A_r^{ps} = A_k^{mn} \frac{\partial x^{,p}}{\partial x^m} \frac{\partial x^{,s}}{\partial x^n} \frac{\partial x^{,s}}{\partial x^{,r}}$ we see that (6) has the form (2) and that $A_r^{,ps}$ obeys the rule of a mixed tensor (1).

1.15 p21-exercise

If A_{rs} is a skew-symmetric covariant tensor, prove that B_{rst} defined as

$$B_{rst} = \partial_r A_{st} + \partial_s A_{tr} + \partial_t A_{rs}$$

is a covariant tensor, and that it is skew-symmetric in all pairs of suffixes.

We have A_{rs} is a covariant tensor

$$A_{ij} = A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{i}} \frac{\partial x^{\beta}}{\partial x^{j}} \tag{1}$$

$$\Rightarrow B_{rst} = \partial_r (A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^s} \frac{\partial x^{\beta}}{\partial x^t}) + \partial_s (A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^t} \frac{\partial x^{\beta}}{\partial x^r}) + \partial_t (A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^r} \frac{\partial x^{\beta}}{\partial x^s})$$
(2)

Note that

$$\partial_{k} \left(A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \frac{\partial x^{\beta}}{\partial x^{t}} \right) = \partial_{k} \left(A_{\alpha\beta} \right) \frac{\partial x^{\alpha}}{\partial x^{s}} \frac{\partial x^{\beta}}{\partial x^{t}} + A_{\alpha\beta} \partial_{k} \left(\frac{\partial x^{\alpha}}{\partial x^{s}} \right) \frac{\partial x^{\beta}}{\partial x^{t}} + A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{k} \left(\frac{\partial x^{\beta}}{\partial x^{t}} \right) \tag{3}$$

so,

$$B_{rst} = \partial_{r} A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \frac{\partial x^{\beta}}{\partial x^{t}} + \underbrace{A_{\alpha\beta} \partial_{r} \frac{\partial x^{\alpha}}{\partial x^{s}} \frac{\partial x^{\beta}}{\partial x^{t}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{r} \frac{\partial x^{\alpha}}{\partial x^{t}}}_{**} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{r} \frac{\partial x^{\beta}}{\partial x^{t}}}_{**} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \frac{\partial x^{\beta}}{\partial x^{r}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{t}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{t}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{t}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{t}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\beta}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\beta}}{\partial x^{s}} \partial_{s} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\beta}}{\partial x^{s}}}_{*} + \underbrace{A_{\alpha\beta} \frac{\partial x^{\beta}}{\partial x^{$$

In (5) consider the two terms with (*)

$$T = A_{\alpha\beta}\partial_r \frac{\partial x^{\alpha}}{\partial x^s} \frac{\partial x^{\beta}}{\partial x^t} + A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^t} \partial_s \frac{\partial x^{\beta}}{\partial x^r}$$
 (6)

$$=A_{\alpha\beta}\frac{\partial^2 x^{\alpha}}{\partial x^s \partial x^r}\frac{\partial x^{\beta}}{\partial x^t} + A_{\alpha\beta}\frac{\partial x^{\alpha}}{\partial x^t}\frac{\partial^2 x^{\beta}}{\partial x^r \partial x^s} \tag{7}$$

$$= A_{\alpha\beta} \frac{\partial^2 x^{\alpha}}{\partial x^s \partial x^r} \frac{\partial x^{\beta}}{\partial x^t} + A_{\beta\alpha} \frac{\partial x^{\beta}}{\partial x^t} \frac{\partial^2 x^{\alpha}}{\partial x^r \partial x^s}$$
(by renaming dummy variables) (8)

As $A_{ij} = -A_{ji}$ (skew-symmetric tensor), we get T = 0. The same yields for the (**) and (***) terms. So, B_{rst} reduces to

$$B_{rst} = \partial_r A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^s} \frac{\partial x^{\beta}}{\partial x^t} + \partial_s A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^t} \frac{\partial x^{\beta}}{\partial x^r} + \partial_t A_{\alpha\beta} \frac{\partial x^{\alpha}}{\partial x^r} \frac{\partial x^{\beta}}{\partial x^s}$$
(9)

$$\Leftrightarrow B_{rst} = \frac{\partial A_{\alpha\beta}}{\partial x^{\gamma}} \frac{\partial x^{\gamma}}{\partial x^{r}} \frac{\partial x^{\alpha}}{\partial x^{s}} \frac{\partial x^{\beta}}{\partial x^{t}} + \frac{\partial A_{\alpha\beta}}{\partial x^{\gamma}} \frac{\partial x^{\gamma}}{\partial x^{s}} \frac{\partial x^{\alpha}}{\partial x^{t}} \frac{\partial x^{\beta}}{\partial x^{r}} + \frac{\partial A_{\alpha\beta}}{\partial x^{\gamma}} \frac{\partial x^{\gamma}}{\partial x^{t}} \frac{\partial x^{\alpha}}{\partial x^{r}} \frac{\partial x^{\beta}}{\partial x^{s}}$$
(10)

By adequate renaming of the dummy variable in the 3 terms:

$$\begin{bmatrix} 1^{st}term \\ 2^{nd}term \\ 3^{rd}term \end{bmatrix} \longrightarrow \begin{bmatrix} \gamma \to \alpha & \alpha \to \beta & \beta \to \gamma \\ \beta \to \alpha & \gamma \to \beta & \alpha \to \gamma \\ \alpha \to \alpha & \beta \to \beta & \gamma \to \gamma \end{bmatrix}$$

we get

$$B_{rst} = \left(\frac{\partial A_{\beta\gamma}}{\partial x^{\alpha}} + \frac{\partial A_{\gamma\alpha}}{\partial x^{\beta}} + \frac{\partial A_{\alpha\beta}}{\partial x^{\gamma}}\right) \frac{\partial x^{\alpha}}{\partial x^{r}} \frac{\partial x^{\beta}}{\partial x^{s}} \frac{\partial x^{\gamma}}{\partial x^{t}}$$
(11)

$$\Leftrightarrow B_{rst} = (\underbrace{\partial_{\alpha} A_{\beta\gamma} + \partial_{\beta} A_{\gamma\alpha} + \partial_{\gamma} A_{\alpha\beta}}_{(****)}) \underbrace{\partial x^{\alpha}}_{\partial x^{r}} \underbrace{\partial x^{\beta}}_{\partial x^{s}} \underbrace{\partial x^{\gamma}}_{\partial x^{t}}$$
(12)

The expression (****) has exactly the required form $B_{rst} = \partial_r A_{st} + \partial_s A_{tr} + \partial_t A_{rs}$ and is transformed (12) according the rules of a covariant tensor.

Let's prove now that it is skew-symmetric in all pairs of suffixes. We have to consider the following permutations

$$\left[egin{array}{c} rst \\ rts \\ srt \\ str \\ trs \\ tsr \end{array}
ight]$$

E.g. srt

$$B_{rts} = \partial_r A_{ts} + \partial_t A_{sr} + \partial_s A_{rt} \tag{13}$$

$$= -\partial_r A_{st} - \partial_t A_{rs} - \partial_s A_{tr} \tag{14}$$

$$= -B_{rst} \tag{15}$$

The same calculations can be done for the other permutations.

1.16 p23-exercise 1.

In a V_4 there are two 2-spaces with equations

$$x^{r} = f^{r}(u^{1}, u^{2}), x^{r} = g^{r}(u^{3}, u^{4})$$

Prove that if these 2-spaces have a curve of intersection, then the determinal equation

$$\left| \frac{\partial x^r}{\partial u^s} \right| = 0$$

is satisfied along the curve.

Having a curve means that one of the parameters u^i can be freely chosen while the other 3 are determined by the chosen parameter.

We have,

$$\left| \frac{\partial x^r}{\partial u^s} \right| = \begin{vmatrix} \frac{\partial x^1}{\partial u^1} & \frac{\partial x^1}{\partial u^2} & \frac{\partial x^1}{\partial u^3} & \frac{\partial x^1}{\partial u^4} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial x^4}{\partial u^1} & \frac{\partial x^4}{\partial u^2} & \frac{\partial x^4}{\partial u^3} & \frac{\partial x^4}{\partial u^4} \end{vmatrix}$$
(1)

Suppose we choose u^4 as parameter. This means $u^i = \phi^i(u^4)$ for i=1,2,3 and thus we can write

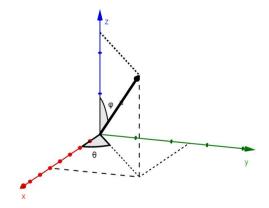
$$\frac{\partial x^{i}}{\partial u^{4}} = \frac{\partial x^{i}}{\partial u^{j}} \frac{d\phi^{j}}{du^{4}} + \frac{\partial x^{i}}{\partial u^{4}} \quad \text{with j=1,2,3} \quad i = 1,2,3,4$$
 (2)

$$\Rightarrow \frac{\partial x^i}{\partial u^j} \frac{d\phi^j}{du^4} = 0 \tag{3}$$

This means that in (1) the three first columns a not linearly independent and thus have $\left|\frac{\partial x^r}{\partial u^s}\right| = 0$

1.17 p23-exercise 2.

In Euclidean space of three dimensions, write down the equations of transformation between rectangular Cartesian coordinates x, y, z and spherical polar coordinates r, θ, ϕ . Find the Jacobian of the transformation. Where is it zero or infinite?



We use the latitude ψ instead of the co-latitude ϕ .

$$\left\{ \begin{array}{l} x = r\cos(\psi)\cos(\theta) \\ y = r\cos(\psi)\sin(\theta) \\ z = r\sin(\psi) \end{array} \right\}$$

Partial differentiating of (x,y,z) with respect to (r,ψ,θ) gives the Jacobian

$$J = \begin{vmatrix} \cos(\psi)\cos(\theta) & -r\sin(\psi)\cos(\theta) & -r\cos(\psi)\sin(\theta) \\ \cos(\psi)\sin(\theta) & -r\sin(\psi)\sin(\theta) & r\cos(\psi)\cos(\theta) \\ \sin(\psi) & r\cos(\psi) & 0 \end{vmatrix}$$
(1)

$$J = \cos(\psi)\cos(\theta)(-r^2)\cos^2(\psi)\cos(\theta)) \tag{2}$$

+
$$r\sin(\psi)\cos(\theta)(-r\cos(\psi)\cos(\theta)\sin(\psi))$$
 (3)

$$- r\cos(\psi)\sin(\theta)(r\cos^2(\psi)\sin(\theta) + r\sin^2(\psi)\sin(\theta))$$
 (4)

$$= -r^{2}\cos^{3}(\psi)\cos^{2}(\theta) - r^{2}\sin^{2}(\psi)\cos^{2}(\theta)\cos(\psi) - r^{2}\cos(\psi)\sin^{2}(\theta)$$
 (5)

Noting that the 2^{nd} term in (5) can be written as $-r^2\cos^2(\theta)\cos(\psi) + r^2\cos^2(\theta)\cos^3(\psi)$, we get

$$J = -r^{2}(\cos^{3}(\psi)\cos^{2}(\theta) + \cos^{2}(\theta)\cos(\psi) - \cos^{3}(\psi)\cos^{2}(\theta) + \cos(\psi)\sin^{2}(\theta))$$
 (6)

$$= -r^2 \cos(\psi) \tag{7}$$

J=0: for r = 0 or $\psi = \frac{\pi}{2}|_{r \in (-\infty, +\infty)}$ and $J \to \pm \infty$ or $\mp \infty$ for $r \to \pm \infty|_{\psi \neq 0}$. But what about the case $r \to \pm \infty|_{\psi \to 0}$? This case is not determined as long as no path is chosen in the (r, ψ) configuration space.

1.18 p23-exercise 3.

If X, Y, Z are the components of a contravariant vector for rectangular Cartesian coordinates in Euclidean 3-space, find it's components for spherical polar coordinates.

Be x^{α} the components of a contravariant vector in spherical polar coordinates and x^{i} it's components in rectangular Cartesian coordinates. As we have

$$x^{\rho} = \sqrt{x^{j}x^{j}}$$

$$x^{\theta} = \operatorname{atan} \frac{x^{2}}{x_{3}^{1}} \quad \text{and} \quad A^{\alpha} = A^{i} \frac{\partial x^{\alpha}}{\partial x^{i}}$$

$$x^{\phi} = \operatorname{asin} \frac{x}{\sqrt{x^{j}x^{j}}}$$

$$(1)$$

$$\Rightarrow \left[A^{\alpha}\right] = \begin{bmatrix} A^{i} \frac{\partial x^{\alpha}}{\partial x^{i}} \end{bmatrix} = \begin{bmatrix} \frac{x^{1}}{\sqrt{x^{j}x^{j}}} & \frac{x^{2}}{\sqrt{x^{j}x^{j}}} & \frac{x^{3}}{\sqrt{x^{j}x^{j}}} \\ -\frac{x^{2}}{(x^{1})^{2} + (x^{2})^{2}} & \frac{x^{1}}{(x^{1})^{2} + (x^{2})^{2}} & 0 \\ -\frac{x^{3}x^{1}}{(x^{j}x^{j})\sqrt{(x^{1})^{2} + (x^{2})^{2}}} & -\frac{x^{3}x^{2}}{(x^{j}x^{j})\sqrt{(x^{1})^{2} + (x^{2})^{2}}} & \frac{\sqrt{(x^{1})^{2} + (x^{2})^{2}}}{(x^{j}x^{j})} \end{bmatrix} \begin{bmatrix} A^{1} \\ A^{2} \\ A^{3} \end{bmatrix}$$
 (2)

1.19 p23-exercise 4.

In a space of three dimensions, how many different expressions are represented by the product $A_{np}^m B_{rs}^{pq} C_{tu}^s$? How many terms occur in each such expression, when written out explicitly?

As we have V_3 and considering that in $A_{np}^m B_{rs}^{pq} C_{tu}^s$ the six indices m, n, q, r, t, u are not dummy indices, we get 3^6 different expressions (first choose m: you have three choices, then n: also three choices giving 3x3 possibilities, etc for q, r, t, u).

For the second question, as in $A_{np}^m B_{rs}^{pq}$ there is only summation on over index (p) we get three terms for this part. As the summation with $A_{np}^m B_{rs}^{pq}$ and C_{tu}^s occurs only on one index also (s) we get 3x3 terms in the expression.

1.20 p23-exercise 5.

If A is an invariant in V_n , are the second derivatives $\frac{\partial^2 A}{\partial x^r \partial x^s}$ the components of a tensor?

As A is invariant (note: different alphabets in the indices indicates different coordinate systems):

$$A(x^{\rho}) = A(x^{i}) \tag{1}$$

$$\Rightarrow \frac{\partial A(x^{\rho})}{\partial x^{i}} = \frac{\partial A(x^{j})}{\partial x^{i}} \tag{2}$$

To simplify the notation, we put $A(x^{\rho}) = A'$ and $A(x^{j}) = A'$ then (2) can be written as

$$\frac{\partial A'}{\partial x^{\rho}} \frac{\partial x^{\rho}}{\partial x^{i}} = \frac{\partial A}{\partial x^{i}} \tag{3}$$

Conclusion: $\frac{\partial A}{\partial x^i}$ is a covariant tensor.

Consider now $\frac{\partial A}{\partial x^i} = \frac{\partial A^i}{\partial x^\rho} \frac{\partial x^\rho}{\partial x^i}$. Then,

$$\frac{\partial^2 A}{\partial x^i \partial x^j} = \frac{\partial^2 A'}{\partial x^\rho \partial x^j} \frac{\partial x^\rho}{\partial x^i} + \frac{\partial A'}{\partial x^\rho} \frac{\partial^2 x^\rho}{\partial x^i \partial x^j}$$
(4)

$$\Leftrightarrow \frac{\partial^2 A}{\partial x^i \partial x^j} = \frac{\partial^2 A}{\partial x^\rho \partial x^\gamma} \frac{\partial x^\gamma}{\partial x^j} \frac{\partial x^\rho}{\partial x^i} + \frac{\partial A}{\partial x^\rho} \frac{\partial^2 x^\rho}{\partial x^i \partial x^j}$$
(5)

The first term on the right side, behaves as covariant tensor but the presence of the second term makes that generally, $\frac{\partial^2 A}{\partial x^i \partial x^j}$ has not a tensor character. This is only when $\frac{\partial A^i}{\partial x^\rho} \frac{\partial^2 x^\rho}{\partial x^i \partial x^j} = 0$, which means that x^ρ, x^i are a linear map of each other.

p23-exercise 6. 1.21

Suppose that in V_2 the components of a contravariant tensor field T^{mn} in a coordinate system

$$T^{11} = 1$$
 $T^{12} = 0$

$$T^{21} = 1$$
 $T^{22} = 0$

Find the components $T^{,mn}$ in a coordinate system $x^{,r}$, where

$$x^{,1} = (x^1)^2$$
 $x^{,2} = (x^2)^2$

Write down the values of these components in particular at the point $x^1 = 1, x^2 = 1$.

As we have a contravariant tensor field:

$$T^{,mn} = T^{ij} \frac{\partial x^{,m}}{\partial x^i} \frac{\partial x^{,n}}{\partial x^j} \tag{1}$$

$$T^{,mn} = T^{ij} \frac{\partial x^{,m}}{\partial x^{i}} \frac{\partial x^{,n}}{\partial x^{j}}$$

$$x^{,1} = (x^{1})^{2} \Rightarrow \frac{\partial x^{,1}}{\partial x^{1}} = 2x^{1} \quad \frac{\partial x^{,1}}{\partial x^{2}} = 0$$

$$x^{,2} = (x^{2})^{2} \Rightarrow \frac{\partial x^{,2}}{\partial x^{1}} = 0 \quad \frac{\partial x^{,2}}{\partial x^{2}} = 2x^{2}$$

$$(2)$$

(3)

$$\Rightarrow T^{,11} = 4(x^1)^2 + 4(x^2)^2 \tag{4}$$

$$\Rightarrow T^{,12} = T^{,21} = 0 \tag{5}$$

$$\Rightarrow T^{,22} = 4(x^1)^2 + 4(x^2)^2 \tag{6}$$

The components in at the point $x^1 = 1, x^2 = 0$ are

$$T'(1,0) = \left[\begin{array}{cc} 4 & 0 \\ 0 & 4 \end{array} \right]$$