Compiler Design BCSE307L

Digital Assignment:3

Implementation of ISA code generation using LLVM



Under the guidance of DR. MANJU G [Associate Professor]

Team members

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IMPLEMENTATION OF ISA CODE GENERATION USING LLVM

Step 1: Update Your System

sudo apt update && sudo apt upgrade -y

This updates all installed packages and dependencies.

sudo apt update: Refreshes the package lists.

sudo apt upgrade -y: Installs available updates for all packages.

This step is crucial to ensure compatibility when installing LLVM and other required tools.

```
hp@Niranjan:~$ sudo apt update && sudo apt upgrade -y
Hit:1 https://packages.microsoft.com/repos/code stable InRelease
Hit:2 https://dl.google.com/linux/chrome/deb stable InRelease
Hit:3 http://packages.ros.org/ros2/ubuntu jammy InRelease
Hit:4 https://librealsense.intel.com/Debian/apt-repo jammy InRelease
Hit:5 http://packages.osrfoundation.org/gazebo/ubuntu-stable jammy InRelease
Hit:6 http://us.archive.ubuntu.com/ubuntu jammy InRelease
Get:7 http://us.archive.ubuntu.com/ubuntu jammy-updates InRelease [128 kB]
Hit:9 https://ppa.launchpadcontent.net/deadsnakes/ppa/ubuntu jammy InRelease
Hit:8 https://hub-dist.unity3d.com/artifactory/hub-debian-prod-local stable InRelease
Hit:10 https://linux.teamviewer.com/deb stable InRelease
Hit:11 http://us.archive.ubuntu.com/ubuntu jammy-backports InRelease
Get:12 http://us.archive.ubuntu.com/ubuntu jammy-security InRelease [129 kB]
Get:13 http://us.archive.ubuntu.com/ubuntu jammy-updates/main amd64 Packages [2,422 kB]
Get:14 http://us.archive.ubuntu.com/ubuntu
Get:15 http://us.archive.ubuntu.com/ubuntu
                                               jammy-updates/main i386 Packages [777 kB]
jammy-updates/main Translation-en [400 kB]
Get:16 http://us.archive.ubuntu.com/ubuntu jammy-security/main amd64 Packages [2,178 kB]
Get:17 http://us.archive.ubuntu.com/ubuntu jammy-security/main i386 Packages [608 kB]
Get:18 http://us.archive.ubuntu.com/ubuntu jammy-security/main Translation-en [337 kB]
Get:19 http://us.archive.ubuntu.com/ubuntu jammy-security/restricted amd64 Packages [3,053 kB]
Get:20 http://us.archive.ubuntu.com/ubuntu jammy-security/restricted Translation-en [541 kB]
Get:21 http://us.archive.ubuntu.com/ubuntu jammy-security/universe i386 Packages [654 kB]
Get:22 http://us.archive.ubuntu.com/ubuntu jammy-security/universe amd64 Packages [969 kB]
Get:23 http://us.archive.ubuntu.com/ubuntu jammy-security/universe Translation-en [208 kB]
Fetched 12.4 MB in 8s (1,651 kB/s)
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
1 package can be upgraded. Run 'apt list --upgradable' to see it.
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Calculating upgrade... Done
```

```
The following packages were automatically installed and are no longer required:
fonts-open-sans libabsl-dev libamd2 libbenchmark-dev libbenchmark1 libbtf1 libcamd2 libccolamd2
liblua5.2-dev libmetis5 libmongoose2 libncurses5-dev libomp-14-dev libomp-dev libomp5-14 librbio
      linux-headers-6.5.0-35-generic linux-headers-6.5.0-41-generic linux-hwo-fo-5-headers-6.5.0-35 lin linux-twage-6.5.0-41-generic linux-modules-6.5.0-35-generic linux-modules-6.5.0-35-generic linux-modules-6.5.0-35-generic linux-modules-6.5.0-35-generic linux-modules-extra-6.5.0-41-generic nlohmann-json3-dev qml-module-qtquick-extras ros-humble-beh ros-humble-dwb-critics ros-humble-dwb-msgs ros-humble-dwb-plugins ros-humble-ign-ros2-control ro ros-humble-irobot-create-description ros-humble-irobot-create-ignition-bringup ros-humble-irobot
        ros-humble-irobot-create-nodes ros-humble-irobot-create-toolbox ros-humble-nav-2d-msgs ros-humb
        ros-humble-nav2-bt-navigator ros-humble-nav2-collision-monitor ros-humble-nav2-controller ros-hu
       ros-humble-nav2-lifecycle-manager ros-humble-nav2-mppi-controller ros-humble-nav2-navfn-planner
       ros-humble-nav2-rotation-shim-controller ros-humble-nav2-rviz-pluging ros-humble-nav2-simple-com ros-humble-nav2-velocity-smoother ros-humble-nav2-voxel-grid ros-humble-nav2-waypoint-follower ros-humble-nav2-wa
       ros-humble-turtlebot4-description ros-humble-turtlebot4-ignition-gui-plugins ros-humble-turtlebo
Use 'sudo apt autoremove' to remove them.
Get more security updates through Ubuntu Pro with 'esm-apps' enabled:
libpcl-stereo1.12 libgsl-dev libopencv4.5d-jni libpostproc-dev
         libopencv-videoio4.5d libzvbi-common liburiparser1 libde265-dev
       libopencv-videoio4.5d libzvbi-common liburiparser1 libde265-dev libopencv-objdetect4.5d libopencv-videoio-dev libopencv-superres4.5d libopencv-objdetect-dev libopencv-contrib4.5d libopencv-superres-dev libopencv-contrib-dev libpcl-keypoints1.12 opencv-data libheif1 libpcl-common1.12 libopencv-imgcodecs4.5d libpcl-recognition1.12 libpcl-sample-consensus1.12 libopencv-imgcodecs-dev libjs-jquery-ui libpathplan4 libmaven3-core-java libopenexr-dev graphviz libavdevice58
         libgvpr2 libgvc6 ffmpeg libopencv-video4.5d libpcl-people1.12
       libpcl-tracking1.12 libopencv-shape4.5d libopencv-video-dev libopencv4.5-java libopencv2.5 libopencv2.6 libopencv2.6 libopencv2.6 libopencv3.5d libopenc
         libopencv-highgui-dev libopencv-core-dev libswscale-dev
         libopencv-stitching-dev libcdt5 libpcl-surface1.12 libavdevice-dev
        libpcl-io1.12 libavcodec58 libpcl-visualization1.12 libpcl-ml1.12
libavutil56 libpcl-kdtree1.12 libswscale5 libpcl-search1.12 libheif-dev
libopencv-viz4.5d libavutil-dev libopencv-viz-dev libopencv-features2d4.5d
      libopencv-viz4.5d libavutil-dev libopencv-viz-dev libopencv-features2d4.5d libgsl27 libopencv-dev liblab-gamut1 libopencv-features2d-dev libswresample3 libopencv-dnn4.5d libavfilter-dev libpcl-outofcore1.12 libopencv-dnn-dev libopencv-ml4.5d libpcl-segmentation1.12 libpcl-apps1.12 libavformat58 libzvbi0 libopencv-ml-dev libopencv-calib3d4.5d libpcl-registration1.12 libopencv-flann4.5d libopencv-calib3d-dev libpmix-dev libopencv-videostab4.5d libopencv-impproc4.5d libgslcblas0
         libopencv-flann-dev libpcl-octree1.12 libpcl-dev libavformat-dev
         libopencv-videostab-dev libavcodec-dev libopencv-imgproc-dev libde265-0
         libpmix2 libopencv-photo4.5d libswresample-dev liburiparser-dev
       libopencv-photo-dev libavfilter7
 Learn more about Ubuntu Pro at https://ubuntu.com/pro
# Patch available for a potential RCE vulnerability
       in FreeType, tracked by CVE-2025-27363.
# For more see: https://ubuntu.com/security/CVE-2025-27363
```

```
The following packages will be upgraded:
    tzdata

1 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.

1 standard LTS security update
Need to get 347 kB of archives.
After this operation, 4,096 B of additional disk space will be used.
Get:1 http://us.archive.ubuntu.com/ubuntu jammy-updates/main amd64 tzdata all 2025a-0ubuntu0.22.04 [347 kB]
Fetched 347 kB in 2s (157 kB/s)
Preconfiguring packages ...
(Reading database ... 478945 files and directories currently installed.)
Preparing to unpack .../tzdata_2025a-0ubuntu0.22.04_all.deb ...
Unpacking tzdata (2025a-0ubuntu0.22.04) over (2024b-0ubuntu0.22.04.1) ...
Setting up tzdata (2025a-0ubuntu0.22.04) ...

Current default time zone: 'Asia/Kolkata'
Local time is now: Wed Mar 26 23:00:50 IST 2025.
Universal Time is now: Wed Mar 26 17:30:50 UTC 2025.
Run 'dpkg-reconfigure tzdata' if you wish to change it.

hp@Niranjan:~$ []
```

Step 2: Install LLVM and Clang

To begin, create a new C++ file that will be compiled into LLVM IR

Code:

nano program.cpp

nano: Opens a simple text editor.

•program.cpp: The filename for our C++ source code.

```
hp@Niranjan:~$ sudo apt install llvm clang lldb lld libc++-dev libc++abi-dev -y
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
clang is already the newest version (1:14.0-55~exp2).
libc++-dev is already the newest version (1:14.0-55~exp2).
libc++abi-dev is already the newest version (1:14.0-55~exp2).
lld is already the newest version (1:14.0-55~exp2).
lldb is already the newest version (1:14.0-55~exp2).
llvm is already the newest version (1:14.0-55~exp2).
The following packages were automatically installed and are no longer required:
  fonts-open-sans libabsl-dev libamd2 libbenchmark-dev libbenchmark1 libbtf1 libcamd2 libccolamd2 libceres2
  liblua5.2-dev libmetis5 libmongoose2 libncurses5-dev libomp-14-dev libomp-dev libomp5-14 librbio2 libslip
  linux-headers-6.5.0-35-generic linux-headers-6.5.0-41-generic linux-hwe-6.5-headers-6.5.0-35 linux-hwe-6.
  linux-image-6.5.0-41-generic linux-modules-6.5.0-28-generic linux-modules-6.5.0-35-generic linux-modules-
  linux-modules-extra-6.5.0-41-generic nlohmann-json3-dev qml-module-qtquick-extras ros-humble-behaviortree
  ros-humble-dwb-critics ros-humble-dwb-msgs ros-humble-dwb-plugins ros-humble-ign-ros2-control ros-humble-
  ros-humble-irobot-create-description ros-humble-irobot-create-ignition-bringup ros-humble-irobot-create-
  ros-humble-irobot-create-nodes ros-humble-irobot-create-toolbox ros-humble-nav-2d-msgs ros-humble-nav-2d-
  ros-humble-nav2-bt-navigator ros-humble-nav2-collision-monitor ros-humble-nav2-controller ros-humble-nav2
  ros-humble-nav2-lifecycle-manager ros-humble-nav2-mppi-controller ros-humble-nav2-navfn-planner ros-humbl
  ros-humble-nav2-rotation-shim-controller ros-humble-nav2-rviz-plugins ros-humble-nav2-simple-commander ro
  ros-humble-nav2-velocity-smoother ros-humble-nav2-voxel-grid ros-humble-nav2-waypoint-follower ros-humble
  ros-humble-turtlebot4-description ros-humble-turtlebot4-ignition-qui-plugins ros-humble-turtlebot4-igniti
Use 'sudo apt autoremove' to remove them.
O upgraded, O newly installed, O to remove and O not upgraded.
hp@Niranjan:~$
```

```
hp@Niranjan:~$ sudo apt install llvm clang lldb lld libc++-dev libc++abi-dev -y
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
clang is already the newest version (1:14.0-55~exp2).
libc++-dev is already the newest version (1:14.0-55~exp2).
libc++abi-dev is already the newest version (1:14.0-55~exp2).
lld is already the newest version (1:14.0-55~exp2).
lldb is already the newest version (1:14.0-55~exp2).
llvm is already the newest version (1:14.0-55~exp2).
The following packages were automatically installed and are no longer required:
  fonts-open-sans libabsl-dev libamd2 libbenchmark-dev libbenchmark1 libbtf1 libcamd2 libccolamd2 libceres2
  liblua5.2-dev libmetis5 libmongoose2 libncurses5-dev libomp-14-dev libomp-dev libomp5-14 librbio2 libslip
  linux-headers-6.5.0-35-generic linux-headers-6.5.0-41-generic linux-hwe-6.5-headers-6.5.0-35 linux-hwe-6.
  linux-image-6.5.0-41-generic linux-modules-6.5.0-28-generic linux-modules-6.5.0-35-generic linux-modules-
  linux-modules-extra-6.5.0-41-generic nlohmann-json3-dev qml-module-qtquick-extras ros-humble-behaviortree
  ros-humble-dwb-critics ros-humble-dwb-msgs ros-humble-dwb-plugins ros-humble-ign-ros2-control ros-humble-
  ros-humble-irobot-create-description ros-humble-irobot-create-ignition-bringup ros-humble-irobot-create-
  ros-humble-irobot-create-nodes ros-humble-irobot-create-toolbox ros-humble-nav-2d-msgs ros-humble-nav-2d-
  ros-humble-nav2-bt-navigator ros-humble-nav2-collision-monitor ros-humble-nav2-controller ros-humble-nav2
  ros-humble-nav2-lifecycle-manager ros-humble-nav2-mppi-controller ros-humble-nav2-navfn-planner ros-humbl
  ros-humble-nav2-rotation-shim-controller ros-humble-nav2-rviz-plugins ros-humble-nav2-simple-commander ro
  ros-humble-nav2-velocity-smoother ros-humble-nav2-voxel-grid ros-humble-nav2-waypoint-follower ros-humble
  ros-humble-turtlebot4-description ros-humble-turtlebot4-ignition-gui-plugins ros-humble-turtlebot4-igniti
Use 'sudo apt autoremove' to remove them.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
hp@Niranjan:~$
```

LLVM Configuration version

Clang Version

```
hp@Niranjan:~$ llvm-config --version
14.0.0
hp@Niranjan:~$ clang --version
Ubuntu clang version 14.0.0-1ubuntu1.1
Target: x86_64-pc-linux-gnu
Thread model: posix
InstalledDir: /usr/bin
hp@Niranjan:~$
```

Step 3: Implementation of Matrix Multiplication in C++

Create a New File:

```
hp@Niranjan:~$ nano matrix.cpp
```

Implement Matrix Multiplication in C++

Write a simple program that multiplies two matrices of size $N \times M$:

Save and exit: Press CTRL + X, then Y, then ENTER. Compile and Run

This step ensures we have a source file ready for compilation.

```
hp@Niranjan:~$ nano matrix.cpp
hp@Niranjan:~$ g++ matrix.cpp -o matrix
hp@Niranjan:~$ ./matrix
Result Matrix:
19 22
43 50
hp@Niranjan:~$ [
```

Step 4: Parse the C++ Code into LLVM IR

LLVM converts C++ into an intermediate representation (IR).

1. Compile C++ to LLVM IR:

clang -S -emit-llvm matrix.cpp -o matrix.ll

2. View the LLVM IR Code:

cat matrix.ll

```
19:
    %11 = load i32, i32* %7, align 4
    %12 = icmp slt i32 %11, 2
    br i1 %12, label %13, label %66

13:
    store i32 0, i32* %8, align 4
    br label %14

14:
    %15 = load i32, i32* %8, align 4
    %16 = icmp slt i32 %15, 2
    br i1 %16, label %17, label %62

17:
    %18 = load [2 x i32]*, [2 x i32]* %6, align 8
    %19 = load i32, i32* %9, align 4
    %20 = sext i32 %19 to i64
    %21 = getelementptr inbounds [2 x i32], [2 x i32]* %18, i64 %20
    %22 = load i32, %22 * %9, align 4
    %24 = getelementptr inbounds [2 x i32], [2 x i32]* %21, i64 0, i64 %23
    store i32 0, i32* %9, align 4
    store i32 0, i32* %9, align 4
    %27 = icmp slt i32 %26, 2
    br i1 %27, label %28, label %58

28:
    %29 = load [2 x i32]*, [2 x i32]* %4, align 8
    %30 = load i32, i32* %9, align 4
    %31 = sext i32 %30 to i64
    %31 = sext i32 %30 to i64
    %32 = getelementptr inbounds [2 x i32], [2 x i32]* %29, i64 %31
    %33 = load i32, i32* %9, align 4
    %31 = sext i32 %33 to i64
    %35 = getelementptr inbounds [2 x i32], [2 x i32]* %29, i64 %31
    %33 = load i32, i32* %9, align 4
    %31 = sext i32 %33 to i64
    %35 = getelementptr inbounds [2 x i32], [2 x i32]* %32, i64 0, i64 %34
    %36 = load i32, i32* %9, align 4
    %37 = load [2 x i32]*, [2 x i32]* %5, align 8
    %38 = load i32, i32* %9, align 4
    %37 = load i32, i32* %9, align 4
    %31 = sext i32 %33 to i64
    %33 = sext i32 %33 to i64
    %35 = getelementptr inbounds [2 x i32], [2 x i32]* %37, i64 %39
    %41 = load i32, i32* %9, align 4
    %39 = sext i32 %38 to i64
    %38 = load i32, i32* %9, align 4
    %39 = sext i32 %38 to i64
    %31 = getelementptr inbounds [2 x i32], [2 x i32]* %37, i64 %39
    %41 = load i32, i32* %7, align 4
    %42 = sext i32 %31 to i64
    %43 = sext i32 %47 to i64
    %43 = sext i32 %47 to i64
    %44 = sext i32 %47 to i64
    %45 = sext i32 %47 to i64
    %46 = sext i32 %47 to i64
    %48 = sex
```

Step 5: Translate LLVM IR to Custom ISA:

LLVM Intermediate Representation

(IR) is a low-level representation of our program, allowing optimizations and translations to various architectures.

We need to convert LLVM IR into custom ISA instructions.

Create a Python Script

```
hp@Niranjan:~$ nano translate.py
hp@Niranjan:~$
```

Run the Translator:

```
hp@Niranjan:~$ nano translate.py
hp@Niranjan:~$ python3 translate.py
Custom ISA Generated! Check output.isa
hp@Niranjan:~$
```

View Generated ISA:

```
cat output.isa
 hp@Niranjan:~$
ADD R3, R4, R5
MUL R1. R2 R3
ADD R3, R4, R5
MUL R1, R2, R3
STORE R3, MEM2
STORE R3, MEM2
STORE R3, MEM2
LOAD R1, MEM1
STORE R3, MEM2
LOAD R1, MEM1
LOAD R1, MEM1
LOAD R1, MEM1
 LOAD R1, MEM1
LOAD R1, MEM1
LOAD R1, MEM1
STORE R3, MEM2
STORE R3, MEM2
LOAD R1, MEM1
  LOAD R1,
                                                 MEM1
   LOAD R1,
                                                 MEM1
 LOAD R1,
LOAD R1,
                                                  MEM1
                                                  MEM1
  LOAD R1,
                                                  MEM1
  LOAD R1, MEM1
  LOAD R1, MEM1
 LOAD R1, MEM1
LOAD R1, MEM1
MUL R1, R2, R3
LOAD R1, MEM1
ADD R3, R4, R5
STORE R3, MEM2
LOAD R1, MEM1
ADD R3, R4, R5
STORE R3, MEM2
LOAD R1, MEM1
ADD R3, R4, R5
STORE R3, MEM2
LOAD R1, MEM1
ADD R3, R4, R5
STORE R3, MEM2
LOAD R1, MEM1
ADD R3, R4, R5
STORE R3, MEM2
STORE R3, MEM2
MUL R1, R2, R3
STORE R3, MEM2
LOAD R1, MEM1
STORE R3, MEM2
LOAD R1, MEM1
STORE R3, MEM2
```

```
MUL R1, R2, R3
STORE R3, MEM2
LOAD R1, MEM1
STORE R3, MEM2
LOAD R1, MEM1
ADD R3, R4, R5
STORE R3, MEM2
LOAD R1, MEM1
ADD R3, R4, R5
STORE R3, MEM2
LOAD R1, MEM1
```

Step 6: Automate the Entire Process

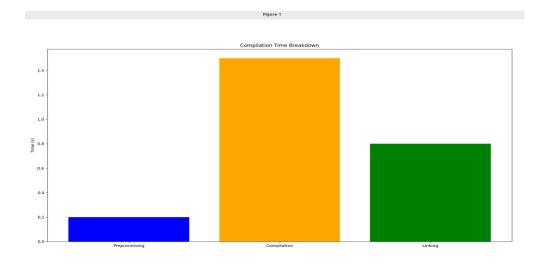
Now, we need to convert LLVM IR into our custom Instruction Set Architecture (ISA) format.

Create a Shell Script

Give Execute Permissions

```
hp@Niranjan:~$ nano compile_and_translate.sh
hp@Niranjan:~$ chmod +x compile_and_translate.sh
hp@Niranjan:~$ ./compile_and_translate.sh
• Compiling C++ to LLVM IR...
• Translating LLVM IR to Custom ISA...
Custom ISA Generated! Check output.isa
Compilation and Translation Done! Check output.isa
hp@Niranjan:~$
```

Compilation time vs Breakdown vs preprocessing



Look up table:

Using an LUT simplifies instruction mapping.

```
hp@Niranjan:~/Compiler_DA3$ ./isa_lookup.sh
LOOKUP TABLE (LUT) FOR MATRIX MULTIPLICATION ISA
Instruction
               Opcode | Operands
                                                     Description
LOAD
               0001
                         R1, MATRIX_A
                                                       Load MATRIX_A into Register R1
                         R2, MATRIX_B
R3, R1[row,:], R2[:,col] |
R3, RESULT[row,col]
LOAD
                0001
                                                       Load MATRIX_B into Register R2
                                                       Multiply a row from MATRIX_A with a column from MATRIX_B
                0011
                                                       Store computed value from R3 into RESULT
STORE
               0010
                         MATRIX_MULT
                                                       Start program execution
PROG
               0100
FXF
                0101
                         None
                                                        Execute computation
END
               0110
                         None
                                                       End program execution
hp@Niranjan:~/Compiler_DA3$
```

Step7: Interactive Frontend for Compiler Design with ISA Visualization

This project implements a web-based interface for visualizing **Three-Address Code** (**3AC**) and **Instruction Set Architecture** (**ISA**) using **LLVM**. The frontend, built with **React.js**, dynamically generates and displays intermediate and low-level representations for matrix operations.

LLVM & 3AC Integration

- Three-Address Code (TAC) is generated using LLVM IR, breaking down matrix computations into low-level operations.
- **ISA Code Emission** translates TAC into machine-level instructions for execution.
- **Memory Address Mapping** helps visualize how data is stored and accessed at a hardware level.

This project bridges high-level programming with system-level execution, making compiler design concepts more interactive and accessible.



LOAD R00, 0 LOAD R00, 0×1004 LOAD R00, 0×1008 MUL R00, R00, R00 LOAD R10, 0×1010 LOAD R10, 0×1010 LOAD R10, 0×1014 MUL R00, R01, R10 STORE R00, 0×1004 LOAD R01, 0×101c MUL R01, 0×101c MUL R01, 0×1010 LOAD R01, 0×1010 LOAD R01, 0×1010 LOAD R11, 0×1024 MUL R01, R01, R11 STORE R01, 0×1020 LOAD R10, 0 LOAD R10, 0×1020 LOAD R11, 0×1034 LOAD R10, 0×1014 MUL R10, R11, R10 STORE R10, 0×1030 LOAD R11, 0 LOAD R11, 0×1034 LOAD R11, 0×1034