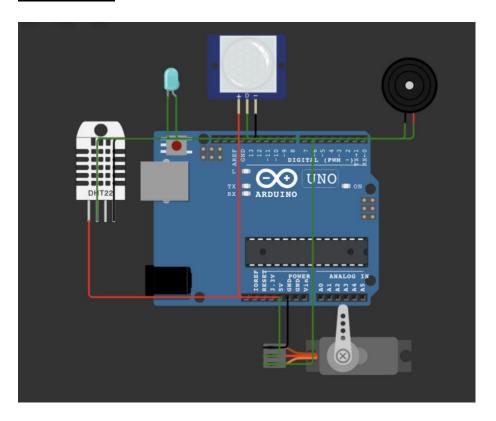
ASSIGNMENT 3

Schematic:



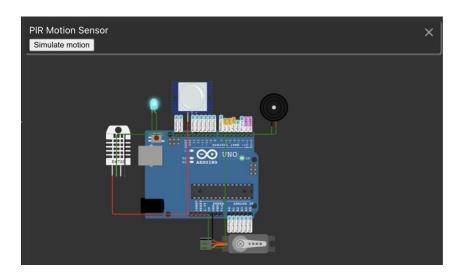
CODE:

```
#include <Servo.h>
#include <Adafruit_Sensor.h>
#include <DHT.h>
#define DHTPIN 2
                    // Digital pin connected to the DHT sensor
#define DHTTYPE DHT11 // DHT 11
#define LEDPIN 4
                     // Digital pin connected to the LED
#define BUZZERPIN 5
#define SERVOPIN 6
                       // Digital pin connected to the Servo motor
int pirpin = 3; // Digital pin connected to the PIR sensor
int pirstate = LOW;
int val = 0;
                   // variable for reading the pin status
DHT dht(DHTPIN, DHTTYPE); // Create a DHT object
```

```
Servo servo;
int doorClosedAngle = 0;
                             // Angle for closed door position
int doorOpenAngle = 90;
                             // Angle for open door position
void setup() {
 Serial.begin(9600);
 dht.begin();
 pinMode(LEDPIN, OUTPUT);
 pinMode(BUZZERPIN, OUTPUT);
 pinMode(pirpin, INPUT); // declare sensor as input
 servo.attach(SERVOPIN);
 servo.write(doorClosedAngle);
void loop() {
 val = digitalRead(pirpin); // read input value
 float temperature = dht.readTemperature();
 float humidity = dht.readHumidity();
 Serial.print("Temperature: ");
 Serial.print(temperature);
 Serial.print(" *C\t Humidity: ");
 Serial.print(humidity);
 Serial.println(" %");
  Serial.println("Motion detected!");
  digitalWrite(LEDPIN, HIGH); // Turn on the LED
  pirstate = HIGH;
  tone(BUZZERPIN, 500, 1000); // Play a 1-second tone on the buzzer
  servo.write(doorOpenAngle); // Unlock the door
  delay(5000);
                         // Wait for 5 seconds
  servo.write(doorClosedAngle); // Lock the door
 } else {
  Serial.println("No motion detected.");
  pirstate = LOW;
  digitalWrite(LEDPIN, LOW); // Turn off the LED
  noTone(BUZZERPIN); // Turn off the buzzer
```

```
delay(1000); // Wait for 1 second before taking the next measurement
}
```

RESULTS:



```
No motion detected.

Temperature: -1.00 *C Humidity: 15.40 %

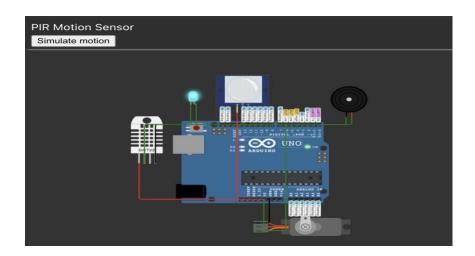
No motion detected.

Temperature: -1.00 *C Humidity: 15.40 %

Motion detected!

Temperature: -1.00 *C Humidity: 15.40 %

No motion detected.
```



SERVO MOTOR CLOSES THE DOOR AFTER FIVE SECONDS.