

EE659 - Assignment 1

Q1) $W_1 = \text{Span} \{ (1, 1, 0, -1), (0, 1, 3, 1) \}$

$W_2 = \text{Span} \{ (0, -1, -2, 1), (1, 2, 2, -2) \}$

Notice that $1 \cdot (0, -1, -2, 1) + 1 \cdot (1, 2, 2, -2) = (1, 1, 0, -1) = (1)$

Suppose $\exists c, d \in \mathbb{R}$ such that $c \cdot (0, -1, -2, 1) + d(1, 2, 2, -2) = (0, 1, 3, 1)$

\rightarrow By 1st Coordinate $\rightarrow d = 0$

\Rightarrow By 2nd Coordinate $\rightarrow c = -1$

But by 3rd Coordinate \rightarrow Left Hand Side of the equation = 2

Right Hand Side of the equation = 3 #

$\therefore (0, 1, 3, 1) \notin \text{Span} \{ (0, -1, -2, 1), (1, 2, 2, -2) \}$ - (2)

$\Rightarrow (0, 1, 3, 1), (0, -1, -2, 1) \& (1, 2, 2, -2)$ are linearly independent & any vector in $W_1 + W_2$ can be written using them as basis - (By ① & ②)

\therefore Basis for $W_1 + W_2 = \{ (0, 1, 3, 1), (0, -1, -2, 1), (1, 2, 2, -2) \}$
Dimension of $W_1 + W_2 = 3$ ✓

~~Now if a vector $v \in W_1 \cap W_2$, then v can be written as $a \cdot (1, 1, 0, -1) + b(0, 1, 3, 1) = c(0, -1, -2, 1) + d(1, 2, 2, -2)$ for some $a, b, c, d \in \mathbb{R}$.~~

$\Rightarrow b(0, 1, 3, 1) = c(0, -1, -2, 1) + d(1, 2, 2, -2) - a(1, 1, 0, -1)$
 $= (c-a)(0, -1, -2, 1) + (d-a)(1, 2, 2, -2)$

But since the 3 vectors are linearly independent,

$b = c - a = d - a = 0$

$\Rightarrow b = 0 \& c = d = a$

$\Rightarrow v = a(1, 1, 0, -1) \quad \forall a \in \mathbb{R}$

\therefore Basis for $W_1 \cap W_2 = \{ (1, 1, 0, -1) \}$
Dimension of $W_1 \cap W_2 = 1$ ✓

Q2) Let $S = \{ (x_1, x_2, x_3, x_4, x_5) \in \mathbb{F}^5 \mid x_1 = 3x_2, x_3 = x_4 = x_5 \} = \text{Null}(T)$

Let T be the linear map from \mathbb{F}^5 to \mathbb{F}^2

Now for some $x \in S$, $x = (3a, a, b, b, b)$ where $x_2 = a$ & $x_3 = b$

$$= 3a(1, 0, 0, 0, 0) + b(0, 1, 1, 1, 1)$$

Linearly Independent. ✓

$$\Rightarrow \dim(S) = 2$$

But by the Fundamental Theorem for linear Maps, we have

$$\dim(\mathbb{F}^5) = \dim(\text{Null}(T)) + \dim(\text{Im}(T))$$

$$\Rightarrow 5 = 2 + \dim(\text{Im}(T))$$

$$\Rightarrow \dim(\text{Im}(T)) = 3$$

But since $T: \mathbb{F}^5 \rightarrow \mathbb{F}^2$, $\dim(\text{Im}(T)) \leq 2$. # ✓

\therefore There cannot exist such a linear map with the mentioned properties.

Q3) a) True

Consider $x \in \ker(NM) \rightarrow NM(x) = 0 \Rightarrow M(x) \in \ker(N)$

Let $b = \{b_1, b_2, \dots, b_r\}$ be a basis for M .

We see that $\ker(M) \subseteq \ker(NM)$ so we can extend b to a basis for $\ker(NM)$

Let $\{b_1, b_2, \dots, b_r, \dots, b_n\}$ be a basis for $\ker(NM) \rightarrow M(b_i) \neq 0$ for $r+1 \leq i \leq n$.

Now we ~~will~~ show that $\{N(b_{r+1}), N(b_{r+2}), \dots, N(b_n)\}$ is linearly independent.

FTSOC, assume otherwise $\Rightarrow \sum_{i=r+1}^n \gamma_i N(b_i) = 0$. Since N is linear, it is

equal to $\sum_{i=r+1}^n N(\gamma_i b_i) = 0 \Rightarrow \sum_{i=r+1}^n \gamma_i b_i \in \ker(M)$. But since $\{b_1, b_2, \dots, b_n\}$

is an independent set, $\gamma_i = 0 \forall i \in \{r+1, \dots, n\}$. This implies $\dim(\ker(N)) \geq n-r$

$$\Rightarrow \dim(\ker(M)) + \dim(\ker(N)) \geq \dim(\ker(NM)) \quad \text{Hence Proved!} \quad \checkmark$$

$$b) U = \mathbb{R}^4, V = \mathbb{R}^3, W = \mathbb{R}^2$$

$$\begin{array}{ccc} \downarrow & \downarrow & \downarrow \\ \text{Basis } u_i & \text{Basis } v_i & \text{Basis } w_i \\ M(u_1) = M(u_2) = v_1, & M(u_3) = M(u_4) = v_2 & \end{array}$$

$$N(v_1) = N(v_2) = w_1, \quad N(v_3) = w_2$$

$$\dim(\text{Im}(NM)) = 1$$

$$\dim(\text{Im}(N)) = 2$$

$$\dim(\text{Im}(M)) = 2$$



Q3) c) $Tv = \lambda v$

$T^{-1}Tv = T^{-1}(\lambda v)$

$\Rightarrow v = \lambda (T^{-1}v)$

$\Rightarrow T^{-1}v = \frac{1}{\lambda}v$

3.1

d) Let v_1, v_2, \dots, v_p be a basis of $\text{Null}(T)$, extend it to a basis of V
 $v_1, v_2, \dots, v_p, u_1, u_2, \dots, u_q$. Thus $\dim(\text{Null}(T)) = p$ & $\dim(V) = p+q$.

Denote $U = \text{Span}\{u_1, u_2, \dots, u_q\}$. Clearly $\text{Span}\{v_1, v_2, \dots, v_p\} \oplus \text{Span}\{u_1, \dots, u_q\} = V = \text{Null}(T) \oplus U$. The restriction $T|_U$ is injective, because $U \cap \text{Null}(T) = \emptyset$.

Hence Tu_1, Tu_2, \dots, Tu_q is a basis of $\text{Range}(T|_U)$.

Notice $\text{Range}(T) = T(V) = T(\text{Null}(T) \oplus U) = 0 + T(U) = \text{Range}(T|_U)$

$\Rightarrow \dim(\text{Range}(T)) = \dim(\text{Range}(T|_U)) = q$

Hence, $\dim(V) = p+q = \dim(\text{Null}(T)) + \dim(\text{Range}(T))$

Q4) To prove V is a subspace \rightarrow ① $0 \in V$

② $\kappa v_1 + (1-\kappa)v_2 \in V \quad \forall v_1, v_2 \in V \text{ \& } \kappa \in \mathbb{R}$

Since $x_0 \in C \rightarrow x_0 - x_0 = 0 \in V$

~~$v_1 \in V \rightarrow v_1 + x_0 \in C$~~

$v_2 \in V \rightarrow v_2 + x_0 \in C$

$\Rightarrow \kappa(v_1 + x_0) + (1-\kappa)(v_2 + x_0) \in C$

$\Rightarrow \kappa v_1 + (1-\kappa)v_2 + x_0 \in C$

$\Rightarrow \kappa v_1 + (1-\kappa)v_2 \in C$

Hence Proved!

Q5) a) let x_1, λ_1 be such that $Ax_1 = \lambda_1 x_1$

let x_2, λ_2 ($\lambda_1 \neq \lambda_2$) be such that $Ax_2 = \lambda_2 x_2$

$A(\kappa x_1 + \kappa_2 x_2) = \kappa \lambda_1 x_1 + \kappa_2 \lambda_2 x_2 \neq \lambda'(\kappa x_1 + \kappa_2 x_2)$

Not a cone.

b) $(\kappa_1 x_1^T + \kappa_2 x_2^T) A (\kappa_1 x_1 + \kappa_2 x_2)$

$= \kappa_1^2 x_1^T A x_1 + \kappa_2^2 x_2^T A x_2 + \dots < 0$

May be more negative

Not a cone

c) $x^T (\kappa A_1 + \kappa_2 A_2) x = x^T A_1 x \cdot \kappa_1 + x^T A_2 x \cdot \kappa_2 \leq 0$

cone

d) $(\kappa A^T)(\kappa A) = \kappa^2 (A^T A) = \kappa^2 I \neq I$ Not a cone

3.2

Q6) $(A, B, C, D, E) = (x_1, x_2, x_3, x_4, x_5)$

minimize $-20x_1 + 5x_2 + 5x_3 + 2x_4 + 7x_5$

subject to $\rightarrow 0.4x_1 + 1.2x_2 + 0.6x_3 + 0.6x_4 + 12.2x_5 \geq 70$

$\rightarrow 6x_1 + 10x_2 + 3x_3 + x_4 + 0x_5 \geq 50$

$\rightarrow 0.4x_1 + 0.6x_2 + 0.4x_3 + 0.2x_4 + 2.6x_5 \geq 12$

$\rightarrow x_i \geq 0 \quad \forall i \in [5]$

Adding Slack Variables \rightarrow Matrix looks like

$$\begin{bmatrix} 0.4 & 1.2 & 0.6 & 0.6 & 12.2 & 1 & 0 & 0 & 0 \\ -6 & -10 & -3 & -1 & 0 & 0 & 1 & 0 & 0 \\ -0.4 & -0.6 & -0.4 & -0.2 & -2.6 & 0 & 0 & 1 & 0 \end{bmatrix} \begin{matrix} -70 \\ -50 \\ -12 \end{matrix}$$

$-20 \quad -5 \quad -5 \quad -2 \quad -7$

4.1

$\rightarrow \frac{50}{6}, \frac{70}{0.4}, \frac{12}{0.4}$

Solving it (I solved in rough & don't have time to complete it),

we get $(x_1, x_2, x_3, x_4, x_5) = (0, 5, 0, 0, \frac{320}{61})$

& min. cost = $\frac{3765}{61}$ ★

Q7) The convex polygon can be modelled as a linear programming problem with $2n$ conditions,

$$\begin{aligned} y_i &\geq a_i x + b_i \quad \forall i \in [1, t] \\ y &\leq a_i x + b_i \quad \forall i \in [t+1, n] \end{aligned} \quad i \in \mathbb{N}$$

So, to find the max. radius, we just need to solve the following problem

$$\begin{aligned} \max r & \quad (x, y) \in P \\ \text{subject to} \quad r &\leq \frac{|y - a_i x - b_i|}{\sqrt{a_i^2 + b_i^2}} \quad \forall i \in [n] \end{aligned}$$

Q8) The convex hull $\text{conv}\{x_1, x_2, \dots, x_k\}$ is the smallest convex set containing the points $\{x_1, x_2, \dots, x_k\}$. Since each x_i is on the boundary of C , and C is convex, any combination of x_1, x_2, \dots, x_k must also lie in C .

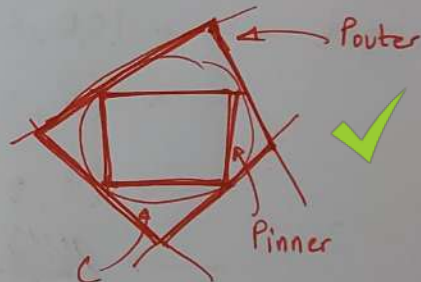
$$\Rightarrow P_1 \subseteq C.$$

$$\text{Now } P_{\text{outer}} = \{x \mid a_i^T (x - x_i) \leq 0, i = 1, 2, \dots, k\}$$

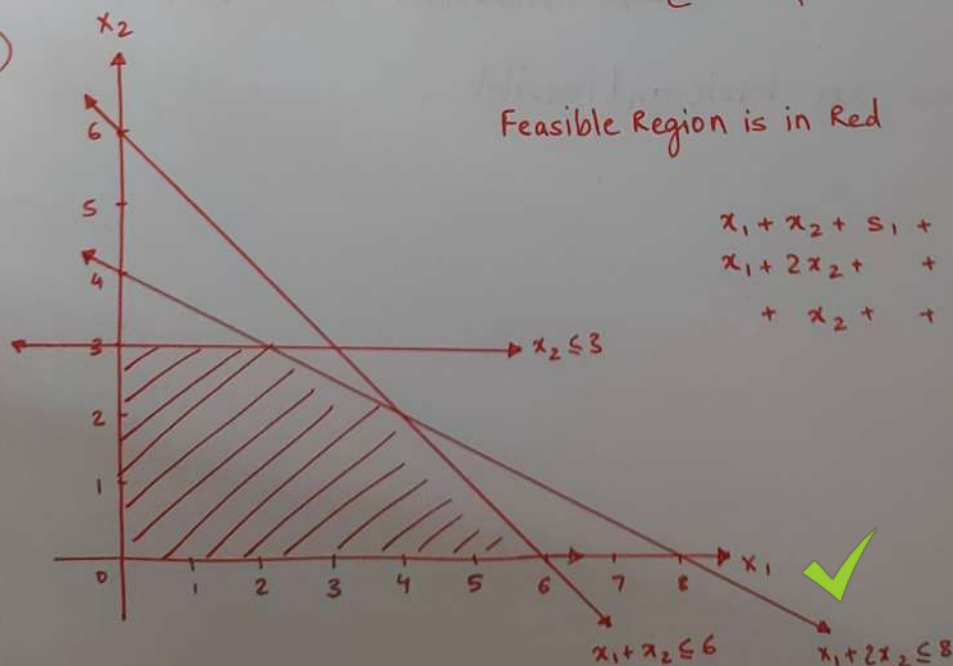
$$= \bigcap_{i=1}^k \{x \mid a_i^T (x - x_i) \leq 0\} \supseteq C$$

$$\Rightarrow C \subseteq P_{\text{outer}}$$

Hence Proved.



Q9)



$$\begin{aligned} x_1 + x_2 + s_1 &= 6 \\ x_1 + 2x_2 + s_2 &= 8 \\ x_2 + s_3 &= 3 \end{aligned}$$

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 & | & 6 \\ 1 & 2 & 0 & 1 & 0 & | & 8 \\ 0 & 1 & 0 & 0 & 1 & | & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & | & 6 \\ 0 & 1 & -1 & 1 & 0 & | & 2 \\ 0 & 1 & 0 & 0 & 1 & | & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 0 & 1 & -1 & | & 5 \\ 0 & 1 & -1 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & -1 & 0 & | & 1 \end{bmatrix} \leftarrow \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & | & 6 \\ 0 & 1 & -1 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & -1 & 1 & | & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & -2 & | & 5 \\ 0 & 1 & 0 & 0 & 1 & | & 3 \\ 0 & 0 & 1 & -1 & 0 & | & 1 \end{bmatrix}$$

→ solution → $(\frac{2}{3}, \frac{3}{2}, 1, 0, 0)$

similarly, we get → $(0, 0, 6, 8, 3)$

→ $(4, 2, 0, 0, 1)$

→ $(0, 3, 3, 2, 0)$

→ ~~$(6, 0, 0, 2, 1)$~~

All these 5 solutions are basic and feasible. ✓

Q10) (\Rightarrow) If P has extreme point x^*

At x^* , some subset of the inequality constraints will become equalities

\rightarrow let the number be $k \Rightarrow k \geq n$

These constraints can be written as $Ax^* = b$

\downarrow
 $k \times n$ matrix

Since x^* is an extreme point, it must be feasible & ~~must~~ should lie on the intersection of the hyperplanes defined by the k equality constraints. Therefore, A must have full rank \Rightarrow ~~must~~ Vectors out of the k equalities should span the n -dimensional space.
 $\Rightarrow \exists$ a subset of n linearly independent vectors.

(\Leftarrow) Assume that among the vectors $\{a_j\}$, \exists subset of n -LI vectors.

Consider matrix A formed by those n -vectors.

We find point P as solution of $Ax = b$

7.1

\uparrow RHS of the constraint equations

Since A is of full rank, the system has a unique solution (P) which is the extreme point.

Index of comments

- 3.1 Q3(c,d) those statement are true or false.
- 3.2 The justification for cone and convex cone have been used wrongly
- 4.1 Q6. The formulation of LP is correct. However, the intermediate steps of solving the LP are required.
- 6.1 Q9. there are a total of 9 basic solutions. And 5 basic feasible solutions. You found basic feasible solutions only.
- 7.1 Q10. try to prove using mathematical arguments rather than giving more statements. Also, the arguments are not enough to prove the claim.