EE659: Assignment 4

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Question: 1

Consider the function

$$f(x) = 40x^8 - 15x^7 + 70x^6 - 10x^5 + 20x^4 - 14x^3 + 60x^2 - 70x$$

Write MATLAB/Python/C programs to find the value of x that minimizes f over the range [-1, 1] using the following methods.

- (a) Bisection method, such that the value of x is within a tolerance band less than 0.01.
- (b) Golden section method for tolerance band less 0.005.

```
import numpy as np
   def f(x):
        return 40*x**8 - 15*x**7 + 70*x**6 - 10*x**5 + 20*x**4 - 14*x**3 + 60*x**2 - 70*x
   def f_dash(x):
        return 320*x**7 - 105*x**6 + 420*x**5 - 50*x**4 + 80*x**3 - 42*x**2 + 120*x - 70
   def bisection_method(a, b, tol=0.01):
       while (b - a) / 2 > tol:
10
            mid = (a + b) / 2
11
            if f_dash(mid) == 0:
12
                return mid
13
            elif f_dash(mid) > 0:
14
                b = mid
15
16
17
                a = mid
        return (a + b) / 2
18
19
   def golden_section_method(a, b, tol=0.005):
20
        gr = (np.sqrt(5) + 1) / 2
21
       c = b - (b - a) / gr
d = a + (b - a) / gr
while abs(c - d) > tol:
22
23
24
            if f(c) < f(d):
25
                b = d
            else:
28
            c = b - (b - a) / gr
            d = a + (b - a) / gr
30
        return (b + a) / 2
31
32
   a, b = -1, 1
33
   x_min_bisection = bisection_method(a, b, tol=0.01)
35
   x_min_golden = golden_section_method(a, b, tol=0.005)
```

We get that the value of x is $\boxed{0.4921875}$ using the bisection method and $\boxed{0.5034721887330706}$ using the golden section method.

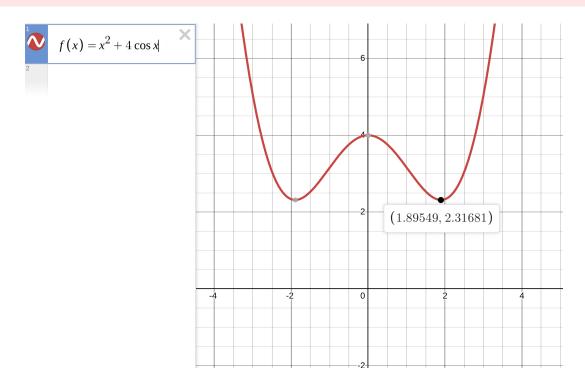
Apply Newton's method to find the minimizer of

$$f(x) = x^2 + 4\cos x$$

over the interval [1, 2]. Take the initial guess to be 1 and perform four iterations.

Remark

I used initial value as 1.5 instead of 1 because when I was starting with 1, the function was not converging and was stuck at x = 1.



```
import numpy as np
   def f(x):
       return x**2 + 4 * np.cos(x)
   def f_dash(x):
       return 2 * x - 4 * np.sin(x)
   def f_double_dash(x):
       return 2 - 4 * np.cos(x)
10
11
   x = 1.5 #Initial Guess
12
13
   iterations = 4
14
   for i in range(iterations):
15
    x = x - f_{dash}(x) / f_{double_dash}(x)
16
       x = max(1, min(x, 2))
17
   print(f"Iteration {i + 1}: x = \{x\}, f(x) = \{f(x)\}")
```

We find that the minimizer of the function is x = 1.8954942672087132 and f(x) = 2.316808419788213.

Find the minimum of $6e^{-2x} + 2x^2$ by each of the following procedures:

- a. Golden section method.
- b. Dichotomous search method.

```
import numpy as np
   def f(x):
       return 6 * np.exp(-2 * x) + 2 * x**2
   def golden_section_search(func, a, b, tol=1e-5):
       gr = (np.sqrt(5) + 1) / 2
       c = b - (b - a) / gr
       d = a + (b - a) / gr
10
11
       while abs(b - a) > tol:
12
           if func(c) < func(d):</pre>
13
14
               b = d
            else:
15
                a = c
17
            c = b - (b - a) / gr
d = a + (b - a) / gr
18
19
20
       return (b + a) / 2
21
22
   def dichotomous_search(func, a, b, tol=1e-5, delta=1e-6):
23
       while abs(b - a) > tol:
24
           mid = (a + b) / 2
25
           x1 = mid - delta
26
           x2 = mid + delta
27
28
            if func(x1) < func(x2):
29
               b = x2
30
31
            else:
32
33
       return (a + b) / 2
34
35
   a, b = -10, 10
37
   min_golden = golden_section_search(f, a, b)
   min_dichotomous = dichotomous_search(f, a, b)
39
   val_golden = f(min_golden)
  val_dichotomous = f(min_dichotomous)
```

We get that the minimum value of the function is obtained at x = 0.7162034008722994 where the value of the function is 2.4582964969114216 using the golden section method and x = 0.7162021874434947 where the value of the function is 2.458296496906626 using the dichotomous search method.

Consider the problem to minimize

$$(3-x_1)^2 + 7(x_2-x_1^2)^2$$
.

Starting from the point (0,0), solve the problem by the following methods. Do the methods converge to the same point? If not, explain.

- a. The cyclic coordinate method.
- b. The method of Hooke and Jeeves.
- c. The method of Rosenbrock.

```
import numpy as np
   from scipy.optimize import minimize
       x1, x2 = x
       return (3 - x1)**2 + 7 * (x2 - x1**2)**2
   def gradient(x):
       x1, x2 = x
       df_dx1 = -2 * (3 - x1) - 28 * x1 * (x2 - x1**2)
10
       df_dx2 = 14 * (x2 - x1**2)
11
12
       return np.array([df_dx1, df_dx2])
13
   initial_point = np.array([0, 0])
14
15
   def cyclic_coordinate_method(func, x0, tol=1e-6, max_iter=1000, step_size=0.1):
16
       x = x0.copy()
17
       n = len(x)
18
19
       for _ in range(max_iter):
20
            old_x = x.copy()
21
22
            for i in range(n):
                while True:
23
24
                     f_current = func(x)
25
26
                    x[i] += step_size
                     f_{new} = func(x)
27
28
                     if f_new < f_current:</pre>
29
30
                         continue
31
                     x[i] = 2 * step_size
32
                     f_new = func(x)
33
34
                     if f_new < f_current:</pre>
35
36
                         continue
37
38
                     x[i] += step_size
39
                     break
40
            if np.linalg.norm(x - old_x) < tol:</pre>
41
                break
42
       return x
44
   def hooke_jeeves(func, x0, step_size=0.5, alpha=2.0, tol=1e-6, max_iter=1000):
46
       x = x0.copy()
47
       n = len(x)
48
49
       def explore(xb, step):
            x_new = xb.copy()
51
            for i in range(n):
52
                f_before = func(x_new)
```

```
x new[i] += step
54
                 if func(x_new) >= f_before:
55
                     x_new[i] -= 2 * step
56
57
                     if func(x_new) >= f_before:
                         x_new[i] += step
58
            return x_new
59
        for _ in range(max_iter):
61
            xb = x.copy()
62
            xe = explore(x, step_size)
63
64
            if np.linalg.norm(xe - x) < tol:</pre>
65
                break
66
67
            x = xe if func(xe) < func(x) else x
68
69
            xb_new = x + alpha * (x - xb)
70
            if func(xb_new) < func(x):</pre>
71
                x = xb_new
            else:
73
74
                 step\_size *= 0.5
        return x
76
77
   def rosenbrock_method(func, grad, x0, learning_rate=0.001, tol=1e-6, max_iter=10000):
78
        x = x0.copy()
79
        for _ in range(max_iter):
80
            grad_val = grad(x)
81
            x_new = x - learning_rate * grad_val
82
83
            if np.linalg.norm(x_new - x) < tol:</pre>
84
85
                break
87
            x = x_new
        return x
88
   cyclic_result = cyclic_coordinate_method(f, initial_point)
   hooke_jeeves_result = hooke_jeeves(f, initial_point)
   rosenbrock_result = rosenbrock_method(f, gradient, initial_point)
```

The differences in the results from the three optimization methods can be attributed to their underlying mechanisms and how they explore the search space.

1. Cyclic Coordinate Method

- **Result:** (0,0)
- Explanation: This method optimizes one variable at a time while keeping others fixed. When optimizing x_1 while fixing x_2 at 0, it finds that $x_1 = 3$ minimizes the function. However, when subsequently optimizing x_2 with x_1 fixed, no improvement is found, leading to the convergence at (0,0).

2. Hooke and Jeeves Method

- **Result:** (0,0)
- Explanation: This method explores the search space in a pattern-search manner. If it does not find better points in the vicinity of (0,0), it may converge there. Insufficient exploration or small step sizes could contribute to this outcome.

3. Rosenbrock Method (Gradient Descent)

- **Result:** (2.4128, 5.8051)
- Explanation: Utilizing the gradient of the function, this method finds the minima. It finds a minima at (2.4128, 5.8051), indicating that it can escape the local minimum found by the other methods.

Show how Newton's method can be used to find a point where the value of a continuously differentiable function is equal to zero. Illustrate the method for $f(x) = 2x^2 - 5x$ starting from x = 5.

Newton's method is an iterative numerical technique used to approximate the roots (or zeros) of a real-valued function. The method relies on the idea of linear approximation and is particularly effective for continuously differentiable functions.

Given a continuously differentiable function $f: \mathbb{R} \to \mathbb{R}$, we seek a point x such that:

$$f(x) = 0.$$

The iteration formula for Newton's method is given by:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

We start with an initial guess x_0 and iterate until the function value is within a specified tolerance level.

```
import numpy
   def f(x):
        return 2 * x**2 - 5 * x
   def f_dash(x):
       return 4 * x - 5
   def newton_method(initial_guess, tolerance=1e-7, max_iterations=1000):
       x = initial_guess
10
       for iteration in range(max_iterations):
11
            fx = f(x)
12
            derivative = f_dash(x)
14
            if derivative == 0:
15
16
                return None
            x = x - fx / derivative
18
19
            print(f"Iteration {iteration + 1}: x = \{x\}, f(x) = \{f(x)\}")
20
21
            if abs(f(x)) < tolerance:</pre>
22
23
                return x
24
       return None
25
   initial_guess = 5
27
   newton_method(initial_guess)
```

Consider the following problem:

minimize
$$f(t) = e^{-t} + e^t$$

in the interval [-1,1].

Find the optimal value within a tolerance band less than 0.15 using:

- (a) Golden section method
- (b) Fibonacci method
- (c) Armijo line search

Do you get the same point? If not, explain.

```
import numpy as np
   def f(t):
       return np.exp(-t) + np.exp(t)
   def golden_section_method(a, b, tol=0.15, max_iter=100):
       phi = (1 + np.sqrt(5)) / 2
       iter_count = 0
       while (b - a) > tol and iter_count < max_iter:</pre>
           c = b - (b - a) / phi
10
           d = a + (b - a) / phi
11
           if f(c) < f(d):
12
13
               b = d
           else:
14
               a = c
15
16
           iter_count += 1
       return (a + b) / 2
17
18
   def fibonacci_method(a, b, tol=0.15, max_iter=100):
19
20
21
       while (b - a) > tol and n < max_iter:</pre>
           n += 1
22
23
24
       fib = [0, 1]
       for i in range(2, n + 1):
25
           fib.append(fib[-1] + fib[-2])
27
       for i in range(1, n):
28
           r1 = a + (fib[n - i - 1] / fib[n]) * (b - a)
29
            r2 = a + (fib[n - i] / fib[n]) * (b - a)
30
31
           if f(r1) < f(r2):
32
                b = r2
           else:
34
35
                a = r1
36
37
       return (a + b) / 2
38
   def armijo_line_search(t0, alpha=0.1, beta=0.5, tol=0.15, max_iter=100):
39
       t = t0
40
       iter_count = 0
41
       while iter_count < max_iter:</pre>
42
           gradient = -np.exp(-t) + np.exp(t) # f'(t)
43
            t_new = t - alpha * gradient
44
           if f(t_new) <= f(t) + beta * alpha * gradient:</pre>
               t = t_new
46
           if abs(f(t_new) - f(t)) < tol:
47
48
               break
```

```
iter_count += 1
return t

a, b = -1, 1
tol = 0.15
max_iter = 10000

golden_result = golden_section_method(a, b, tol, max_iter)
fibonacci_result = fibonacci_method(a, b, tol, max_iter)
armijo_result = armijo_line_search(0, tol=tol, max_iter=max_iter)
```

The three outputs obtained from the optimization methods are as follows:

- Golden Section Method: $t \approx 7.63 \times 10^{-17}$
- Fibonacci Method: $t \approx -0.0802$
- Armijo Line Search: t = 0.0

The differences in the outputs can be attributed to several factors:

The function $f(t) = e^{-t} + e^{t}$ is convex over the interval [-1,1]. However, due to its exponential growth, small variations in the methods can lead to different evaluations around the minimum point.

- Golden Section Method and Fibonacci Method: These interval-based methods rely on point evaluations within a specified interval, narrowing the search space based on comparisons of function values. The final outcome can differ based on the initial interval.
- Armijo Line Search: This gradient-based approach starts from an initial point and iteratively updates based on the gradient's direction. Sensitivity to step size choices can lead to different outcomes, particularly in non-strictly convex functions.

Each method's convergence criteria, defined by tolerance and maximum iterations, can lead to different stopping points. A higher tolerance or reaching maximum iterations before convergence can cause varied results.

Question: 7

Consider the following problem:

maximize
$$f(x) = (\sin(x))^6 \tan(1-x)e^{30x}$$

in the interval [0,1]. Find the optimal point within a tolerance band less than 0.15 using:

- (a) Golden ratio method
- (b) Quadratic interpolation method
- (c) Goldstein line search

```
import numpy as np

def f(x):
    return (np.sin(x))**6 * np.tan(1 - x) * np.exp(30 * x)

def golden_ratio_method(a, b, tol, max_iter):
    phi = (-1 + np.sqrt(5)) / 2

    x1 = b - phi * (b - a)
    x2 = a + phi * (b - a)

f1 = f(x1)
f2 = f(x2)

iterations = 0
```

```
while (b - a) > tol and iterations < max_iter:</pre>
16
                                     if f1 < f2:</pre>
17
                                                 b = x2
18
19
                                                 x2 = x1
                                                 f2 = f1
20
                                                 x1 = b - phi * (b - a)
21
                                                 f1 = f(x1)
22
                                    else:
23
                                                 a = x1
24
                                                 x1 = x2
25
                                                 f1 = f2
26
                                                 x2 = a + phi * (b - a)
27
                                                 f2 = f(x2)
28
                                     iterations += 1
29
30
                       return (a + b) / 2, f((a + b) / 2)
31
32
          def quadratic_interpolation_method(a, b, tol, max_iter):
33
34
                       x0 = a
                       x1 = (a + b) / 2
35
36
                       x2 = b
37
                       iterations = 0
38
39
                       while (b - a) > tol and iterations < max_iter:</pre>
                                    f0, f1, f2 = f(x0), f(x1), f(x2)
40
                                     denominator = (x0 - x1) * (x0 - x2) * (x1 - x2)
41
                                    if denominator == 0:
42
                                                break # Avoid division by zero
43
                                    x_n = (f0 * (x1 - x2) + f1 * (x2 - x0) + f2 * (x0 - x1)) / (f0 * (x1 - x2) + f1 * (x2 - x2)) / (f0 * (x1 - x2) + f1 * (x2 - x3)) / (f0 * (x1 - x2) + f1 * (x2 - x3)) / (f0 * (x1 - x2) + f1 * (x2 - x3)) / (f0 * (x1 - x2) + f1 * (x2 - x3)) / (f0 * (x1 - x2) + f1 * (x2 - x3)) / (f0 * (x1 - x3)) / (f
44
                                                 x0) + f2 * (x0 - x1))
46
                                    if x_new < a or x_new > b:
                                                 break # Ensure new point is within bounds
48
                                    if f(x_new) > f(x1):
49
                                                 x0, x1, x2 = x1, x_new, x2
50
                                    else:
51
52
                                                 x0, x1, x2 = x0, x1, x_new
53
54
                                    iterations += 1
55
                       return (x0 + x1 + x2) / 3, f((x0 + x1 + x2) / 3)
56
57
           def f_prime(x): # Numerical derivative using central difference (because im too lazy to calculate
58
                       the actual derivative and I don't want to use the scipy function)
                       h = 1e-5
59
                       return (f(x + h) - f(x - h)) / (2 * h)
60
61
           def goldstein_line_search(x0, direction, alpha=0.1, beta=0.9, max_iter=100):
62
                       x1 = x0 + direction
63
64
                       iterations = 0
65
                       while (f(x1) > f(x0) + alpha * (x1 - x0) * f_prime(x0) and f(x1) < f(x0) + beta * (x1 - x0) * f(x0) + f(x0) 
66
                                    f_prime(x0)) and iterations < max_iter:</pre>
67
                                    x1 -= direction
                                    iterations += 1
68
69
70
                       return x1, f(x1)
71
          a, b = 0, 1
          tolerance = 0.15
73
max_iterations = 1000
optimum_golden = golden_ratio_method(a, b, tolerance, max_iterations)
          optimum_quad = quadratic_interpolation_method(a, b, tolerance, max_iterations)
          x0 = 0.5 # starting point
direction = 0.1 # arbitrary small step
          optimum_goldstein = goldstein_line_search(x0, direction, max_iter=max_iterations)
```

We get that the optimal point obtained by the three optimization methods are as follows:

- Golden Ratio Method: x = 0.6909830056250525, f(x) = 21521325.939824104
- Quadratic Interpolation Method: x = 0.5, f(x) = 21685.897332525412
- Goldstein Line Search: x = 0.6, f(x) = 899642.4669646018

Question: 8

Consider the function $f: \mathbb{R}^2 \to \mathbb{R}$,

$$f(x_1, x_2) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2.$$

Write a program in MATLAB/C/Python for the steepest descent algorithm using the backtracking line search to find the extrema. Set the initial step-length $\alpha_0 = 1$ and print the step length used by each method in each iteration. Update the step size α_k at every iteration to satisfy the Goldstein condition. The initial point is given as $x_0 = (1.2, 1.2)^{\mathsf{T}}$.

```
import numpy as np
   def f(x):
       x1, x2 = x
       return 100 * (x2 - x1**2)**2 + (1 - x1)**2
   def grad_f(x):
8
       x1, x2 = x
       df_dx1 = -400 * x1 * (x2 - x1**2) - 2 * (1 - x1)
       df_dx2 = 200 * (x2 - x1**2)
10
       return np.array([df_dx1, df_dx2])
12
   def backtracking_line_search(x, p, alpha=1, rho=0.9, c=1e-4):
13
       while f(x + alpha * p) > f(x) + c * alpha * np.dot(grad_f(x), p):
14
           alpha *= rho
15
16
       return alpha
17
   def steepest_descent(x0, tol=1e-4, max_iter=1000):
18
       x = x0
19
       alpha = 1
                  # Initial step length
20
       iterations = []
21
22
       for i in range(max_iter):
23
            gradient = grad_f(x)
24
           if np.linalg.norm(gradient) < tol:</pre>
25
               break
27
           p = -gradient
28
           alpha = backtracking_line_search(x, p)
29
           x = x + alpha * p
30
           iterations.append((i + 1, x, alpha))
32
33
34
       return x, iterations
   x0 = np.array([1.2, 1.2])
   result, iterations = steepest_descent(x0)
37
   print(f"Optimal point: {result}")
  print("Iterations (index, x, step length):")
  for iteration in iterations:
  print(iteration)
```

Consider the following problem:

minimize
$$f(x_1, x_2) = 32x_1^2 + 12x_2^2 - x_1x_2 - 2x_1$$

with initial point $(-2,4)^{\mathsf{T}}$.

Solve the problem by:

- (a) Steepest descent method
- (b) Newton's method

```
import numpy as np
   def f(x):
       return 32 * x[0]**2 + 12 * x[1]**2 - x[0] * x[1] - 2 * x[0]
   def gradient(x):
       dfdx1 = 64 * x[0] - x[1] - 2
       dfdx2 = 24 * x[1] - x[0]
       return np.array([dfdx1, dfdx2])
10
11
   def hessian(x):
       d2fdx1dx1 = 64
12
13
       d2fdx1dx2 = -1
       d2fdx2dx2 = 24
14
15
       return np.array([[d2fdx1dx1, d2fdx1dx2], [d2fdx1dx2, d2fdx2dx2]])
16
   def steepest_descent(initial_point, learning_rate=0.01, tolerance=1e-6, max_iter=1000):
17
18
       x = np.array(initial_point)
       for i in range(max_iter):
19
           grad = gradient(x)
           x_new = x - learning_rate * grad
21
22
           if np.linalg.norm(x_new - x) < tolerance:</pre>
                # print(f"Converged in {i} iterations.")
23
24
                break
           x = x_new
26
       return x
   def newtons_method(initial_point, tolerance=1e-6, max_iter=1000):
28
       x = np.array(initial_point)
29
30
       for _ in range(max_iter):
           grad = gradient(x)
31
32
           hess = hessian(x)
           x_new = x - np.linalg.inv(hess).dot(grad)
33
           if np.linalg.norm(x_new - x) < tolerance:</pre>
34
35
               break
           x = x_new
36
       {\tt return}\ {\tt x}
initial_point = (-2, 4)
optimal_sd = steepest_descent(initial_point)
optimal_nm = newtons_method(initial_point)
```

Consider the problem to minimize

$$f(x) = 3x - 2x^2 + x^3 + 2x^4$$

subject to $x \ge 0$.

- a. Write a necessary condition for a minimum. Can you make use of this condition to find the global minimum?
- b. Is the function strictly quasiconvex over the region $\{x:x\geqslant 0\}$? Apply the Fibonacci search method to find the minimum.
- c. Apply both the bisection search method and Newton's method to the above problem, starting from $x_1 = 6$.

Part (a)

1. Necessary Condition: To find the critical points, we first compute the derivative of f(x) and set it equal to zero.

$$f'(x) = 3 - 4x + 3x^2 + 8x^3$$

Setting f'(x) = 0 gives the equation:

$$3 - 4x + 3x^2 + 8x^3 = 0$$

Solving this equation for x gives us the critical points, which are candidates for minima or maxima.

2. Second Derivative Test: To determine if these critical points are minima, we calculate the second derivative f''(x):

$$f''(x) = -4 + 6x + 24x^2$$

We evaluate f''(x) at each critical point. If f''(x) > 0 at a point, it indicates a local minimum. To determine if any of these points is a global minimum, we analyze f'(x) and f''(x) over the feasible region $x \ge 0$.

Part (b)

A function is strictly quasiconvex if every set $\{x: f(x) \le \alpha\}$ is a strictly convex set. To check this:

- 1. **Derivative Behavior**: We analyze the behavior of f(x) on $x \ge 0$. If f(x) does not exhibit multiple local minima over this interval, it may be quasiconvex. However, strict quasiconvexity requires further verification of each of the individual sets.
- 2. **Monotonicity**: If f(x) strictly decreases and then strictly increases around a minimum, it could be considered quasiconvex.

Fibonacci Search Method

The Fibonacci search method is a bracketing method for finding the minimum of a function:

- Define an initial interval [a, b] (e.g., a = 0 and b = 6 if this captures the region around the critical points).
- At each step, evaluate f(x) at points determined by Fibonacci ratios and reduce the interval of uncertainty.
- Repeat until the interval is sufficiently small (smaller than the tolerance levels).

Part (c)

We apply the following search methods to find the minimum of f(x) over $x \ge 0$:

1. Bisection Search Method

The bisection search method proceeds as follows:

- Start with an interval [a, b] (e.g., [0, 6]).
- At each iteration, calculate the midpoint $x = \frac{a+b}{2}$ and evaluate f'(x). Adjust a or b based on where the derivative changes sign, narrowing down the interval.
- Continue until the interval is sufficiently small (smaller than the tolerance levels).

2. Newton's Method

Newton's method is an iterative method that updates x using the formula:

$$x_{n+1} = x_n - \frac{f'(x_n)}{f''(x_n)}$$

- Start with an initial guess, say $x_1 = 6$.
- Iterate until $f'(x) \approx 0$, indicating a minimum.