| Query | With Reranker | Without Reranker | Verdict |
|-----------------|--------------------------------|---|-------------------|
| 1.Give RIA's | RIA's Standards | RIA's Standards Definitions | Both Answers |
| Standards | Definitions are based on | are based on English | are accurate, |
| Definitions | English language/natural | language/natural language | but with |
| | language consensus | consensus definitions. They | reranker the |
| | definitions. They generally | generally follow | response is |
| | follow ISO10218 and | R15.06/10218 and ISO8373 | more descriptive |
| [pdf: 12- | ISO8373, where | where applicable. | and have better |
| FranklinRIA- | applicable. Specifically: | Specifically, RIA's Standards | context to pages. |
| IEEE 2019-05- | | definitions are: | pages. |
| 19_v2.pdf,page: | RIA's Standards definitions | | |
| 13-17] | are adopted from | Adopted from ISO10218 and | |
| _ | ISO10218 and ISO8373. | ISO8373 | |
| | RIA participated in the | Developed through | |
| | development of natural | consensus among group | |
| | language definitions in | members, which then fed into | |
| | ISO10218 by consensus | the first version of ISO8373 | |
| | among group members, | Consult ISO8373:2012, | |
| | which then fed into the first | Robots and Robotic Devices | |
| | version of ISO8373. | - Vocabulary | |
| | RIA's definitions for | Consult ISO10218-1,2:2011, Robots and Robotic Devices | |
| | | - Industrial robots and robot | |
| | specific terms are as follows: | systems – Safety | |
| | Tollows. | requirements | |
| | Automated robot: Not | requirements | |
| | used; all robots are | RIA also actively participates | |
| | considered "automated" in | in IFR's vocabulary efforts for | |
| | RIA's general usage. | the broader industry. | |
| | Teleoperated robot: Not | | |
| | used; related terms are | The definitions include terms | |
| | "teleoperation" (ISO8373) | such as: | |
| | and "manual mode" | - Automated robot: Not used | |
| | (ISO10218). | by RIA; in general usage, all | |
| | Environment: Not used; | robots are "automated"; | |
| | related term is "normal | autonomy is a key part of the | |
| | operating conditions" | conception of a "robot" | |
| | (ISO8373). | - Teleoperated robot: Not | |
| | Robot: Defined through | used by RIA; the closest | |
| | consensus among group | related terms are | |

"teleoperation" (8373) and members and ISO "manual mode" (10218) standards. - Environment: Not used by RIA actively participates in RIA; the closest related term IFR's vocabulary efforts is "normal operating and consults ISO conditions" (8373) standards, including: Thanks for asking! ISO8373:2012, Robots and PDF Title: SICK â€" Guide for Robotic Devices -Vocabulary Safe Machinery: Six Steps to ISO10218-1,2:2011, a Safe Machine PDF Source: Robots and Robotic Devices - Industrial robots https://www.sick.com/media/ docs/8/78/678/special_infor and robot systems -Safety requirements mation_guide_for_safe_machi nery_en_im0014678.pdf Page: 13, 15, 17 Thanks for asking! PDF Title: SICK â€" Guide for Safe Machinery: Six Steps to a Safe Machine PDF Source: https://www.sick.com/med ia/docs/8/78/678/special i nformation_guide_for_safe machinery en im0014678 .pdf Pages: 13, 15, 17, 23 Here, without The steps to meet 2. Give Steps to To meet the Machinery reranker the meet Machinery Machinery Directive Directive requirements, the response is fails requirements are: following nine steps can be **Directive** to describe the followed: requirements steps. 1. Management of functional safety: This 1. Step 1-8 are not [pdf: mentioned in the context. **EN Technicalgu** step involves managing the functional safety of a however ideNo10 REVF.p machine to ensure that it Step 9: Proving compliance: df,page:19]

Before a machine can be

placed on the market, the manufacturer must ensure

meets the required safety

standards.

- 2. **Risk assessment**: This step involves identifying potential hazards and assessing the risks associated with a machine.
- 3. **Risk reduction**: This step involves reducing or eliminating the risks identified in the risk assessment step.
- 4. Establishing safety requirements: This step involves defining the safety requirements for a machine based on the risk assessment and risk reduction steps.
- 5. Implementing a functional safety system:

This step involves designing and implementing a functional safety system that meets the safety requirements.

- 6. **Verifying a functional safety system**: This step involves verifying that the functional safety system meets the defined safety requirements.
- 7. Validating a functional safety system: This step involves validating that the functional safety system actually succeeds in reducing risks as specified.

that the machine is implemented in conformance with harmonized standards.

To prove the conformance with the Machinery Directive, it must be shown that:

Machinery fulfills the relevant Essential Health and Safety Requirements (EHSR) defined in the Machinery Directive. Machinery fulfills the requirements of other possible Directives related to it.

Conformity with these requirements can be ensured by following the relevant harmonized standards. The technical file is up-to-date and available. The technical file demonstrates that the machine is in accordance with the regulations presented in the Machinery Directive.

Additionally, the following requirements must be met:

Conformity assessment procedures have been applied.
Special requirements for machines listed in the Machinery Directive's Annex IV are met, where appropriate.
* The FC declaration of

* The EC declaration of conformity has been

8. Documenting a functional safety system:

This step involves documenting the design and producing user-documentation for the functional safety system.

9. Providing compliance:

This step involves proving the machine's compliance with Essential Health and Safety Requirements (EHSR) of the Machinery Directive through compliance assessments and technical file.

Additionally, to prove compliance, the following must be shown:

The machinery fulfills the relevant Essential Health and Safety Requirements (EHSR) defined in the Machinery Directive.
The machinery fulfills the requirements of other Directives related to it.
Conformity with these requirements can be ensured by following the relevant harmonized standards.

The technical file is up-todate and available. Conformity assessment procedures have been applied. produced and is delivered with the machine.

Once conformity has been established, a CE marking is affixed. Machinery that carries CE markings and is accompanied by an EC declaration of conformity is presumed to comply with the requirements of the Machinery Directive.

Thanks for asking!

PDF Title: IFA â€" Functional safety of machine controls (Application of EN ISO13849), IFA Report2/2017e

PDF Source:

https://www.dguv.de/medien /ifa/en/pub/rep/pdf/reports-2019/report0217e/rep0217e. pdf

Page: 19, 37

| | The EC declaration of conformity has been produced and is delivered with the machine. Thanks for asking! PDF Title: IFA â€" Functional safety of machine controls (Application of EN ISO13849), IFA Report2/2017e PDF Source: https://www.dguv.de/medien/ifa/en/pub/rep/pdf/reports-2019/report0217e/rep0217 | | |
|------------------------------|--|---|--------------------------|
| | e.pdf | | |
| 0.05 | Pages: 19, 37, 5, 8, 18 | Cub stantial was differentials | Llovo the |
| 3.Give Substantial | Substantial modifications, | Substantial modifications, as | Here, the responses from |
| Substantial modifications | as explained in Article 3 (16), refer to changes | explained in Article 3 (16) of the Machinery Regulation | both are similar. |
| on explanation | made to machinery after it | (EU) 2023/1230, refer to | But the reranker |
| of Article 3 (16) | has been placed on the | changes made to machinery | one have better |
| OI AI LICIE 3 (10) | market or put into service. | after it has been placed on | citation. |
| [pdf: oem- | These modifications can | the market or put into | |
| sp123en- | be physical or digital | service. These modifications | |
| p.pdf, page:9] | (hardware or software) and | can be made through | |
| | are considered substantial if they: | physical or digital means, such as hardware or software changes. | |
| | Were not foreseen by the | | |
| | manufacturer Affect the safety of the product by: | To be considered substantial, the modification must: | |
| | + Creating a new hazard + Increasing an existing risk | Not be foreseen by the manufacturer Affect the safety of the product | |

product

In such cases, significant new protective measures are required. The person carrying out the substantial modification is required to perform a new conformity assessment before:

Placing the modified product on the market Putting it into service

This conformity assessment can be restricted to the part of the production line that has been modified, and does not necessarily need to be completed for the whole assembly.

Thanks for asking!

PDF Title: Rockwell â€" A Guide to the Machinery Regulation (EU)2023/1230 PDF Source: https://literature.rockwellau tomation.com/idc/groups/li terature/documents/sp/oe m-sp123_-en-p.pdf

Page: 9 4. what are the The two new standards in safety and functional safety are:

> 1. **EN ISO13849-1**: Safety of machinery - Safetyrelated parts of control system - General Principles for design

3. Create a new hazard or increase an existing risk

When a substantial modification is made, the person carrying out the modification is required to perform a new conformity assessment before placing the modified product on the market or putting it into service. This conformity assessment can be restricted to the part of the production line that has been modified. rather than requiring a full assessment of the entire assembly.

The substantial modification is considered significant when new protective measures are required to mitigate the new hazard or increased risk.

Thanks for asking!

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Page: Various

The two new standards in safety and functional safety are:

1. **EN ISO 13849-1**: Safety of machinery - Safety-related parts of control system -General Principles for design

Here the response are exactly similar. because the query was too simple.

Two new standards in safety and functional safety

[pdf: Safety and functional

| safety, A |
|-----------------|
| general |
| guide.pdf,page: |
| 9] |
| |

2. **EN62061**: Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems

These standards replace the old standard **EN954-1**, which became obsolete on December 31, 2011, after a 3+2-year allowable transition period.

Thanks for asking!

PDF Title: ABB brochure 1SFC001008B0201 PDF Source: https://www

ABB.com Page: 6 2. **EN 62061**: Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems

These standards replace the old standard EN 954-1, which became obsolete on December 31, 2011, after a 3+2-year allowable transition period.

Thanks for asking!

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5. what are the Methods of Safegaurding?

[pdf: Safety Committee Handout 1 Machine Guarding.pdf, page: 2] The methods of safeguarding are:

- 1. **Guards**: physical barriers that prevent contact, which can be fixed, interlocked, adjustable, or selfadjusting.
- 2. **Devices**: limit or prevent access to the hazardous area, such as presencesensing devices, pullback or restraint straps, safety trip controls, two-hand controls, or gates.
- 3. Automated Feeding and Ejection

Mechanisms: eliminate the operator's exposure to

The methods of safeguarding are:

- 1. **Guards**: physical barriers that prevent contact with hazardous machine parts. They can be fixed, interlocked, adjustable, or self-adjusting.
- 2. **Devices**: limit or prevent access to the hazardous area. Examples include: *Presence-sensing devices* Pullback or restraint straps *Safety trip controls* Two-hand controls *Gates*
- 3. Automated Feeding and Ejection Mechanisms: eliminate the operator's

Here again the responses are similar due to chunks are splitted correctly.

the point of operation while handling materials.

- 4. **Machine Location or Distance**: remove the hazard from the operator's work area.
- 5. Miscellaneous Aids: methods that can be used to protect both operators and people in the immediate vicinity of operating machinery, such as shields to contain chips, sparks, sprays or other forms of flying debris; holding tools that an operator can use to handle materials going into the point of operation; and awareness barriers to warn people about hazards in the area.

Additionally, some specific safeguarding devices include:

Safety mats to detect persons approaching, standing in or climbing into the danger area Light curtains to detect approach to dangerous areas Interlock switches to detect the position of movable guards for control interlocking Presence-sensing devices Two-hand control devices

Safety trip controls

exposure to the point of operation while handling materials.

- 4. Machine Location or Distance: remove the hazard from the operator's work area.
- 5. Miscellaneous Aids: methods that can be used to protect both operators and people in the immediate vicinity of operating machinery. Examples include: Shields to contain chips, sparks, sprays, or other forms of flying debris Holding tools that an operator can use to handle materials going into the point of operation Awareness barriers to warn people about hazards in the area

Additionally, primary safeguarding methods include:

- 1. **Guards**: physical barriers that prevent access to danger areas.
- 2. **Safeguarding Devices**: controls or attachments that prevent or detect operator contact with hazardous machine areas.

Secondary safeguarding methods, work practices, and complementary equipment may also be used to

| | | supplement primary | |
|------------------|------------------------------|---------------------------------|------------------------------|
| | Thanks for asking! | safeguarding. | |
| | | | |
| | PDF Title: OSHA3170 â€" | Thanks for asking! | |
| | Safeguarding Equipment | | |
| | and Protecting Employees | PDF Title: OSHA3170 â€" | |
| | from Amputations | Safeguarding Equipment and | |
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| | Page: 2,12,15,19,44,46,49 | efault/files/publications/osha | |
| | | 3170.pdf | |
| | | Page:2,12,15,19,44,46,49 | |
| 6. Give the | The procedure for | The procedure for structural | Here both |
| Procedure for | structural analysis is as | analysis, as per the provided | responses |
| structural | follows: | context, involves the | seems similar |
| analysis. | | following steps: | but reranker |
| | Step 1: Formation of a | | have access to |
| [pdf:SISTEMA | sequence of the | Step 1: Formation of a | exact pages that contain the |
| Cookbook | components in a | sequence of components in | answer. While |
| (Version1.0),pag | functional channel | a functional channel | non reranker |
| e: 11] | | | one have some |
| _ | All components along the | Write all components along | incorrect pages. |
| | first functional channel | the first functional channel | |
| | (that with the fewest | (with the fewest components) | |
| | components) are written as | as blocks from left to right | |
| | blocks from left to right | (from sensor to actuator). | |
| | (from the sensor to the | | |
| | actuator). | Step 2: Considering the | |
| | | first block | |
| | Step 2: Considering the | | |
| | first block | Assign each individual block | |
| | | of the first functional channel | |
| | Each individual block of | to subsystems of the relevant | |
| | the first functional channel | Category, based on | |
| | is now assigned in turn to | characteristic features of the | |
| | subsystems of the relevant | Categories. | |
| | Category, according to the | | |
| | characteristic features of | Step 3: Does the | |
| | the Categories. | component manufacturer | |

Step 3: Does the component manufacturer state the PL and PFH (and Category)?

An encapsulated subsystem can be recognized as such by the fact that it is already characterized by the manufacturer by a PL (or SIL in accordance with IEC standards), PFH and Category (internal structure). The internal structure of the encapsulated

Step 4: Can all component faults be excluded?

subsystem need not be

deconstructed further.

All assumed faults for the component in the block under analysis are considered in turn. For this purpose, the annex of EN ISO13849-2 contains the fault models of a number of components used in machine controls. Owing to justified fault exclusions, certain component faults can be discounted. For each fault case, it must be considered whether the

state the PL and PFH (and Category)?

Check if the component manufacturer has stated the PL, PFH, and Category. If so, the internal structure of the encapsulated subsystem need not be deconstructed further.

Step 4: Can all component faults be excluded?

Consider all assumed faults for the component in the block under analysis. For each fault case, determine if the intended safety-related functionality of the component is retained (harmless fault) or fails (dangerous fault).

Alternatively, a schematic table can be used for structure analysis, which involves:

- Entering all components shown on the schematic circuit diagram in a table.
 Determining if the
- 2. Determining if the Category is stated by the component manufacturer.
- 3. Identifying the component(s) in the test channel (fault detection and disconnection).

| | intended safety-related functionality of the component is retained (harmless fault) or fails (dangerous fault). Thanks for asking! PDF Title: SISTEMA Cookbook (Version1.0) PDF Source: https://www.osha.gov/site s/default/files/2020-05/Machine%20Guarding %20Checklist.pdf Pages: 11-12 | 4. Determining the possible Category and block presentation. Thanks for asking! PDF Title: OSHA â€" Machine Guarding Checklist PDF Source: https://www.osha.gov/sites/default/files/2020-05/Machine%20Guarding%20Checklist.pdf Page: 10-11, 27 | |
|--|---|--|--|
| 7. give information on Specific Machine Hazards and Safeguarding | Here are some specific machine hazards and safeguarding methods: Specific Machine Hazards: | Based on the provided context, here are some specific machine hazards and safeguarding methods: Specific Machine Hazards: | Here the answer is again similar and correct. The difference is between the access to correct pages. |
| Methods. [pdf:osha3170.p df ,page: 22] | 1. Mechanical Hazards: Entanglement, drawing in, trapping, crushing, cutting, shearing, and puncturing. 2. Electrical Hazards: Electrocution, discharge of dangerous substances, and electrical shock. 3. Thermal Hazards: Burns, fires, and explosions. 4. Noise Hazards: Hearing loss and tinnitus. 5. Vibration Hazards: Hand-arm vibration syndrome and whole-body vibration. | Mechanical Hazards: crushing, cutting, shearing, entanglement, and drawing-in. Electrical Hazards: electrocution, electrical shock, and arc flashes. Thermal Hazards: burns, fires, and explosions. Noise Hazards: hearing loss and tinnitus. Vibration Hazards: handarm vibration syndrome and whole-body vibration. Safeguarding Methods: | |

Safeguarding Methods:

- 1. **Guards**: Physical barriers that prevent access to danger areas.
- 2. **Safety Devices**: Devices that detect presence of individuals in danger areas, such as light curtains, pressure mats, and safety sensors.
- 3. Awareness Devices: Barriers, signals, or signs that warn individuals of an impending, approaching, or present hazard.
- 4. **Safe Work Procedures**: Formal written instructions developed by the user that describe how a task is to be performed.
- 5. Personal Protective Equipment (PPE):

Equipment worn by individuals to protect themselves from hazards, such as safety glasses, gloves, and hearing protection.

6. Machine Safeguarding: Safeguarding implemented to protect individuals from hazards by the physical arrangement of distance, holding, openings, or positioning of the machine or machine production system.

Risk Reduction Measures:

- 1. **Guards**: physical barriers that prevent access to hazardous areas.
- 2. **Safety Devices**: devices that detect or prevent operator contact with hazardous areas, such as light curtains, safety mats, and safety scanners.
- 3. Awareness Devices: devices that alert operators to potential hazards, such as warning lights, horns, and sirens.
- 4. Safeguarding Methods: methods that protect operators from hazards through the physical arrangement of distance, holding, openings, or positioning of the machine or machine production system.
- 5. **Safe Work Procedures**: formal written instructions that describe how to perform tasks safely.

Examples of Safeguarding Methods for Specific Machine Hazards:

1. Mechanical Hazards:

Guards: enclosing hazardous machine parts, such as gears and shafts.

Safety Devices: light curtains or safety mats to detect operator presence.

2. Electrical Hazards:

1. Design and Safety:

Risk reduction through design and safety measures.

- 2. Functional Safety: Risk reduction through functional safety systems.
- 3. Process and **Information**: Risk reduction through process and information measures. such as safe work procedures and training.

Thanks for asking!

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Pages:7-11

Guards: enclosing electrical components, such as electrical panels and wiring. Safety Devices: circuit breakers and fuses to prevent electrical shock.

3. Thermal Hazards:

Guards: insulating hot surfaces, such as pipes and equipment. Safety Devices: temperature sensors and thermocouples to detect overheating.

Thanks for asking!

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| | PDF Title: ABB brochure1SFC001008B020 1 PDF Source: https://www ABB.com Pages:5-6 | | |
|---|--|--|---|
| 8. Give information on some secondary safeguarding methods, work practices, and complementary equipment [pdf:osha3170.pdf,page:49] | Secondary safeguarding methods, work practices, and complementary equipment are used to supplement primary safeguarding methods or used alone when primary safeguarding methods are not feasible. Some of these methods include: Secondary Safeguarding Methods: 1. Awareness Devices: Installation of barriers and warning signs around the machine, such as milling tables, to alert operators of potential hazards. 2. Probe Detection Devices: Devices that detect the presence or absence of a person's hand or finger, such as ring guards, to prevent entry into hazardous areas. 3. Safety Edge Devices: Devices that detect the presence of an employee in a hazardous machine cycle or stroke. | Secondary Safeguarding Methods, Work Practices, and Complementary Equipment In addition to primary safeguarding methods, the following secondary safeguarding methods, work practices, and complementary equipment can be used to supplement or replace primary safeguarding methods when they are not feasible: Secondary Safeguarding Methods: 1. Splash shields, chip shields, or barriers: Use these devices to provide effective protection to the operator if it is impractical to guard cutters without interfering with normal production operations or creating a more hazardous situation. 2. Awareness devices: Install awareness devices, such as barriers and warning signs, around the machine to alert operators of potential | Here reranker one has accurate answer. Non reranker one also have correct answer but not everything is correct. |
| | | hazards. | |

Work Practices:

1. Safe Work Procedures:

Formal, written instructions that describe how a task is to be performed, including procedures for installing and using fixtures and tooling.

- 2. **Operator Training:**Ensuring that all operators receive appropriate safe work procedure training by experienced operators until they can work safely on their own.
- 3. Prohibiting Unsafe
 Actions: Prohibiting
 operators from reaching
 around the cutter or hob to
 remove chips while the
 machine is in motion or not
 locked or tagged out.

Complementary Equipment:

- 1. Work-Holding
 Equipment: Equipment such as clamps, jigs, fixtures, and back gauges that hold the work-piece in place during the hazardous portion of the machine cycle.
- 2. Feeding and Ejection Systems: Systems such as gravity-fed chutes, semi-automatic and automatic feeding and ejection equipment that

Work Practices:

1. Safe work procedures:

Develop and implement safe work procedures for machine operators, such as safe work procedures for installing and using fixtures and tooling.

- 2. **Operator training**: Ensure that all operators receive appropriate safe work procedure training by experienced operators until they can work safely on their own.
- 3. **Prohibiting hazardous behaviors**: Prohibit operators
 from reaching around the
 cutter or hob to remove chips
 while the machine is in
 motion or not locked or
 tagged out.

Complementary Equipment:

- 1. **Jigs or vises**: Instruct operators not to use a jig or vise (work-holding equipment) that prevents the point of operation guard from being adjusted appropriately.
- 2. Work-holding device: Instruct operators to place the jig or vise locking arrangement so that force must be exerted away from the cutter.

Additional Measures:

minimize or eliminate the need for employees to be in a hazard area during the hazardous motion of the machine.

3. Emergency Stop

Devices: Devices such as buttons, rope-pulls, cable-pulls, or pressure-sensitive body bars that initiate an action to stop hazardous motion when an employee recognizes a hazard.

Other Measures:

- 1. Instructing Operators: Instructing operators not to wear gloves, jewelry, or loose-fitting clothing while operating a machine and to secure long hair in a net or cap.
- 2. Conducting Periodic Inspections: Conducting periodic inspections to ensure compliance with safety procedures.

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PDF Source:

https://www.osha.gov/site s/default/files/publications/ osha3170.pdf 1. Periodic inspections:

Conduct periodic inspections to ensure compliance.

2. Servicing and

maintenance: Perform servicing and maintenance under an energy control program in accordance with the Control of hazardous energy (lockout/tagout), 29 CFR 1910.147, standard.

Thanks for asking!

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Safeguarding Equipment and
Protecting Employees from
Amputations

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