Digital Differential Analyzer (DDA) :- Digital Differential

Analyzer (DDA) algorithm is the simple line generation algorithm which is explained herce.

The carctesian slop-intercept equation for straight line is ->

$$x_1 = x + 1$$
 And $y_1 = mx_1 + e$
 $x_2 = x + 2$ $y_2 = mx_2 + e$
 $\therefore \Delta x = x_2 - x_1$
 $= x + 2 - x - 1$ $\therefore \Delta y = y_2 - y_1$

= 1

 $\begin{array}{c} A_1 = 42 - 41 \\ = 20 \times 2 + 2 - 1 \\ mx_1 - 2 \end{array}$

Line path between end point positions

(x1, y1) and (x2, y2)

$$= m(x_2 - x_1)$$

$$= m \Delta x$$

$$= m.$$

where, $m = \frac{72-71}{x_2-x_1}$ [: m representing the slop of the line]

void line (int xy, int x1, int x2, int y2, int value)

double y = y0;

double m = (x2-y1)/(x2-x1);

for (x=x1; x2=x2; x++)/

wreite Pixel (x, round(y), value);

y + = m;

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Digital Differential Analyzer (DDA) :- Digital Differential
Analyzer (DDA) algorithm is the simple line generation
algorithm which is explained step by step here.
step-1:- Get the input of two end points (xo, yo)
 step-2:- Calculate the difference between two end
and (x1, /1).
        dx = X_1 - X_0;
         dy = $1-70;
 Step3: - Based on the calculated difference in
  step-2, need to identify the numbers of steps
 to put pixel. If (dx > dy), then need more
  steps in x-corrdinate; otherwise in y courc-
           if (absolute (dx) 7 absolute (dy))
 dinates.
               steps = absolute(dx);
            else steps = absolute (dy);
  step 4: Calculate the increment in X-coordinate
  and y-coordinate
       Xincrement = dx/(float) steps;
       Yincrement = dy/ (float) steps;
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etep5 of ful the pixel by succenfully inercementing x and y coordinates accordingly and complete the drawing of the line.

The drawing of the line.

The fore (int K 0; KL steps; k++)

X = X + Xincrement;

Y = Y + Yincrement;

getpixel (ROUND(X), ROUND(Y));
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void draw DDA (int xo, int yo, intx1, int y1)?
  int dx = x1-x0, dy = y1-y0, steps, k;
  float Xinercement, Yinercement, x=x0, y=y0;
  if (abs (dx) > abs (dy))
         steps = abs(dx);
  else steps = abs (dy);
  Xinercement = dx/(float) steps;
  Yincrement = dy/ (float) steps;
   setPixel (ROUND(X), ROUND(Y));
  forc (int k=0; k L steps; k++)}
     X+ = Xincrement;
     y+= Yinercement;
     set Pixel (X, Y);
```