Target:

-- Our previous model has 6.3M parameters. I want to reduce these parameters here. I want to make them < 10K

Results:

```
-- Parameters: 9,907
-- Best Training Accuracy: 99.99
-- Best Test Accuracy: 99.05
```

Analysis:

- -- The accuracy has dropped a little (from 99.61 to 99.05) after reducing the number of parameters
- -- traing and test accuracy are increasing with epochs. So we are in the right path. We might improve results by training it for few

- Import libraries

```
from __future__ import print_function
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
from torchvision import datasets, transforms
```

- Data Transformations (without normalization)

Dataset and Creating Train/Test Split (without normalization)

```
train = datasets.MNIST('./data', train=True, download=True, transform=train_transforms)
test = datasets.MNIST('./data', train=False, download=True, transform=test_transforms)
```

- Dataloader Arguments & Test/Train Dataloaders (without normalization)

```
SEED = 1
# CUDA?
cuda = torch.cuda.is available()
print("CUDA Available?", cuda)
# For reproducibility
torch.manual_seed(SEED)
if cuda:
               torch.cuda.manual_seed(SEED)
# dataloader arguments - something you'll fetch these from cmdprmt
dataloader_args = dict(shuffle=True, batch_size=128, num_workers=4, pin_memory=True) if cuda else dict(shuffle=True, batch_size=128, num_workers=4, pin_workers=4, pin_work
# train dataloader
train_loader = torch.utils.data.DataLoader(train, **dataloader_args)
# test dataloader
test loader = torch.utils.data.DataLoader(test. **dataloader args)
                 CUDA Available? True
                 /usr/local/lib/python3.8/dist-packages/torch/utils/data/dataloader.py:554: UserWarning: This DataLoader will create 4
                        warnings.warn( create warning msg(
```

Getting data statistics (without normalization)

We will use the mean and standard deviation that we get from code below to normalize the data

```
import numpy as np
train_data = train.train_data
train data = train.transform(train_data.numpy())
print('[Train]')
print(' - Numpy Shape:', train.train_data.cpu().numpy().shape)
print(' - Tensor Shape:', train.train data.size())
print(' - min:', torch.min(train_data))
print(' - max:', torch.max(train data))
print(' - mean:', torch.mean(train_data))
print(' - std:', torch.std(train_data))
print(' - var:', torch.var(train_data))
dataiter = iter(train_loader)
images, labels = next(dataiter)
print(images.shape)
print(labels.shape)
# Let's visualize some of the images
%matplotlib inline
import matplotlib.pyplot as plt
plt.imshow(images[0].numpy().squeeze(), cmap='gray_r')
```

Data Transformations (with normalization)

- Dataset and Creating Train/Test Split (with normalization)

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train = datasets.MNIST('./data', train=True, download=True, transform=train_transforms)
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- Dataloader Arguments & Test/Train Dataloaders (with normalization)

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# test dataloader
test_loader = torch.utils.data.DataLoader(test, **dataloader_args)

CUDA Available? True
```

- Getting data statistics (with normalization)

We will use the mean and standard deviation that we get from code below to normalize the data

```
import numpy as np

train_data = train.train_data
train_data = train.transform(train_data.numpy())

print('[Train]')
print(' - Numpy Shape:', train.train_data.cpu().numpy().shape)
print(' - Tensor Shape:', train.train_data.size())
print(' - min:', torch.min(train_data))
print(' - max:', torch.max(train_data))
```

```
print(' - mean:', torch.mean(train_data))
print(' - std:', torch.std(train_data))
print(' - var:', torch.var(train_data))

dataiter = iter(train_loader)
images, labels = next(dataiter)

print(images.shape)
print(labels.shape)

# Let's visualize some of the images
%matplotlib inline
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plt.imshow(images[0].numpy().squeeze(), cmap='gray_r')
```

Model

```
dropout_rate = 0.05
class Net(nn.Module):
 def __init__(self):
   super(Net, self).__init__()
   #input block
   self.convblock1 = nn.Sequential(nn.Conv2d(in_channels = 1, out_channels = 16, kernel_size = 3, padding = 1),
                              nn.BatchNorm2d(16),
                              #conv block 1
   self.convblock2 = nn.Sequential(nn.Conv2d(in channels = 16, out channels = 12, kernel size = 3, padding = 1),
                              nn.BatchNorm2d(12),
                              nn.ReLU()) #R in = 3, C in = 28, K = 3, P = 1, S = 1, J in = 1, J out = 1, R out = R i
   #conv block 2
   self.convblock3 = nn.Sequential(nn.Conv2d(in_channels = 12, out_channels = 16, kernel_size = 3, padding = 1),
                              nn.BatchNorm2d(16),
                              #transition block1
   self.convblock4 = nn.Sequential(nn.Conv2d(in_channels = 16, out_channels = 12, kernel_size = 3, padding = 1),
                              nn.BatchNorm2d(12),
                              nn.ReLU()) #R in = 7, C in = 28, K = 3, P = 1, S = 1, J in = 1, J out = 1, R out = R i
   self.pool1 = nn.MaxPool2d(2, 2) #R_in = 9, C_in = 28, K = 2, P = 0, S = 2, J_in = 1, J_out = 2, R_out = R_in + (K-1)*J
   #conv block 3
   self.convblock5 = nn.Sequential(nn.Conv2d(in_channels = 12, out_channels = 15, kernel_size = 3, padding = 1),
                              nn.BatchNorm2d(15),
                              nn.ReLU()) #R_in = 9, C_in = 14, K = 3, P = 1, S = 1, J_in = 2, J_out = 2, R_out = R_i
   #conv block 4
   self.convblock6 = nn.Sequential(nn.Conv2d(in_channels = 15, out_channels = 12, kernel_size = 3, padding = 1),
                              nn.BatchNorm2d(12),
                              #gap layer
```

```
self.gap = nn.Sequential(
         nn.AvgPool2d(kernel size=4)) #R in = 17, C in = 14, K = 4, P = 1, S = 1, J in = 2, J out = 2, R out = R in +
  #output block
  self.convblock7 = nn.Sequential(nn.Conv2d(in_channels = 12, out_channels = 10, kernel_size = 3, padding = 0)) #R_in =
def forward(self, x):
 x = self.convblock1(x)
  x = self.convblock2(x)
 x = self.convblock3(x)
 x = self.convblock4(x)
 x = self.pool1(x)
 x = self.convblock5(x)
 x = self.convblock6(x)
  x = self.gap(x)
 x = self.convblock7(x)
  x = x.view(-1, 10)
 return F.log softmax(x, dim=-1)
```

Model parameters

```
!pip install torchsummary
from torchsummary import summary

use_cuda = torch.cuda.is_available()
device = torch.device("cuda" if use_cuda else "cpu")

model = Net().to(device)
summary(model, input size = (1, 28, 28))
```

Looking in indexes: https://us-python.pkg.dev/colab-wheels/public/simple/ Requirement already satisfied: torchsummary in /usr/local/lib/python3.8/dist-packages (1.5.1)

Layer (type)	Output Shape	Param #
Conv2d-1	[-1, 16, 28, 28]	160
BatchNorm2d-2	[-1, 16, 28, 28]	32
ReLU-3	[-1, 16, 28, 28]	0
Conv2d-4	[-1, 12, 28, 28]	1,740
BatchNorm2d-5	[-1, 12, 28, 28]	24
ReLU-6	[-1, 12, 28, 28]	0
Conv2d-7	[-1, 16, 28, 28]	1,744
BatchNorm2d-8	[-1, 16, 28, 28]	32
ReLU-9	[-1, 16, 28, 28]	0
Conv2d-10	[-1, 12, 28, 28]	1,740
BatchNorm2d-11	[-1, 12, 28, 28]	24
ReLU-12	[-1, 12, 28, 28]	0
MaxPool2d-13	[-1, 12, 14, 14]	0
Conv2d-14	[-1, 15, 14, 14]	1,635
BatchNorm2d-15	[-1, 15, 14, 14]	30
ReLU-16	[-1, 15, 14, 14]	0
Conv2d-17	[-1, 12, 14, 14]	1,632
BatchNorm2d-18	[-1, 12, 14, 14]	24
ReLU-19	[-1, 12, 14, 14]	0
AvgPool2d-20	[-1, 12, 3, 3]	0
Conv2d-21	[-1, 10, 1, 1]	1,090

Total params: 9,907
Trainable params: 9,907
Non-trainable params: 0
Input size (MB): 0.00
Forward/backward pass size (MB): 1.14
Params size (MB): 0.04
Estimated Total Size (MB): 1.19

Training and Testing

```
from tqdm import tqdm

train_losses = []
test_losses = []
train_acc = []

test_acc = []

def train(model, device, train_loader, optimizer, epoch):
   model.train()
   pbar = tqdm(train_loader)
   correct = 0
```

```
processed = 0
  for batch idx, (data, target) in enumerate(pbar):
   # get samples
   data, target = data.to(device), target.to(device)
   # Init
   optimizer.zero_grad()
   # In PyTorch, we need to set the gradients to zero before starting to do backpropragation because PyTorch accumulates
   # Because of this, when you start your training loop, ideally you should zero out the gradients so that you do the par
   # Predict
   y pred = model(data)
   # Calculate loss
   loss = F.nll loss(y pred, target)
   train losses.append(loss)
   # Backpropagation
   loss.backward()
   optimizer.step()
   # Update pbar-tgdm
   pred = y pred.argmax(dim=1, keepdim=True) # get the index of the max log-probability
   correct += pred.eq(target.view_as(pred)).sum().item()
   processed += len(data)
    pbar.set_description(desc= f'Loss={loss.item()} Batch_id={batch_idx} Accuracy={100*correct/processed:0.2f}')
   train acc.append(100*correct/processed)
def test(model, device, test_loader):
   model.eval()
   test_loss = 0
   correct = 0
   with torch.no_grad():
        for data, target in test loader:
           data, target = data.to(device), target.to(device)
           output = model(data)
           test_loss += F.nll_loss(output, target, reduction='sum').item() # sum up batch loss
           pred = output.argmax(dim=1, keepdim=True) # get the index of the max log-probability
           correct += pred.eq(target.view_as(pred)).sum().item()
    test loss /= len(test loader.dataset)
    test_losses.append(test_loss)
    print('\nTest set: Average loss: {:.4f}, Accuracy: {}/{} ({:.2f}%)\n'.format(
       test_loss, correct, len(test_loader.dataset),
        100. * correct / len(test loader.dataset)))
    test_acc.append(100. * correct / len(test_loader.dataset))
from torch.optim.lr scheduler import StepLR
model = Net().to(device)
optimizer = optim.SGD(model.parameters(), lr=0.01, momentum=0.9)
# scheduler = StepLR(optimizer, step_size=6, gamma=0.1)
EPOCHS = 15
for epoch in range(EPOCHS):
   print("EPOCH:", epoch)
   train(model, device, train_loader, optimizer, epoch)
   # scheduler.step()
   test(model, device, test_loader)
    EPOCH: 0
    Loss=0.12683193385601044 Batch_id=468 Accuracy=92.11: 100% 469 469 [00:20<00:00, 22.48it/s]
    Test set: Average loss: 0.0998, Accuracy: 9706/10000 (97.06%)
    EPOCH: 1
    Loss=0.09563467651605606 Batch_id=468 Accuracy=98.14: 100% 469 469 [00:17<00:00, 27.53it/s]
    Test set: Average loss: 0.0539, Accuracy: 9832/10000 (98.32%)
    EPOCH: 2
    Loss=0.039049576967954636 Batch id=468 Accuracy=98.51: 100% 469/469 [00:14<00:00, 31.98it/s]
    Test set: Average loss: 0.0937, Accuracy: 9731/10000 (97.31%)
    EPOCH: 3
```

```
469/469 [00:14<00:00, 32.28it/s]
    Loss=0.0362037755548954 Batch_id=468 Accuracy=98.84: 100%
    Test set: Average loss: 0.0563, Accuracy: 9814/10000 (98.14%)
    Loss=0.025478513911366463 Batch id=468 Accuracy=98.91: 100% 469/469 [00:14<00:00, 32.17it/s]
    Test set: Average loss: 0.0471, Accuracy: 9846/10000 (98.46%)
    Loss=0.03193654492497444 Batch_id=468 Accuracy=99.06: 100%| 469/469 [00:14<00:00, 32.13it/s]
    Test set: Average loss: 0.0390, Accuracy: 9867/10000 (98.67%)
    Loss=0.021154969930648804 Batch id=468 Accuracy=99.14: 100% 469/469 [00:15<00:00, 31.19it/s]
    Test set: Average loss: 0.0325, Accuracy: 9906/10000 (99.06%)
    Loss=0.05115535482764244 Batch id=468 Accuracy=99.24: 100% | 469/469 [00:14<00:00, 32.04it/s]
    Test set: Average loss: 0.0365, Accuracy: 9891/10000 (98.91%)
    Loss=0.0016950649442151189 Batch id=468 Accuracy=99.26: 100% 469/469 [00:15<00:00, 30.91it/s]
    Test set: Average loss: 0.0279, Accuracy: 9912/10000 (99.12%)
    Loss=0.005443142727017403 Batch id=468 Accuracy=99.33: 100% 469/469 [00:14<00:00, 31.89it/s]
    Test set: Average loss: 0.0300, Accuracy: 9894/10000 (98.94%)
    Loss=0.011261711828410625 Batch_id=468 Accuracy=99.41: 100%| 469/469 [00:14<00:00, 32.27it/s]
    Test set: Average loss: 0.0333, Accuracy: 9888/10000 (98.88%)
    Loss=0.00586252985522151 Batch_id=468 Accuracy=99.41: 100% 469/469 [00:16<00:00, 29.11it/s]
train losses = [i.item() for i in train losses]
%matplotlib inline
import matplotlib.pyplot as plt
fig, axs = plt.subplots(2,2,figsize=(15,10))
axs[0, 0].plot(train_losses)
axs[0, 0].set title("Training Loss")
axs[1, 0].plot(train_acc[4000:])
axs[1, 0].set_title("Training Accuracy")
axs[0, 1].plot(test_losses)
axs[0, 1].set title("Test Loss")
axs[1, 1].plot(test_acc)
axs[1, 1].set_title("Test Accuracy")
```

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