## **Lab 4 Questions**

## **Robotics & Automation** Dylan Losey, Virginia Tech

**Instructions.** Print your name at the top of the page. Turn in this sheet at the end of lab: your lab grade will be based on your answers.

**Question 1.** Write each column of the space Jacobian.

$$J_{s1} = \qquad \qquad J_{s2} = \qquad \qquad J_{s3} =$$

**Question 2.** Write each column of the geometric Jacobian.

$$J_1 = J_2 = J_3 =$$

Question 3.

Question 4.

linear velocity	joints contributing	does the answer depend on $\theta$ ?
$\dot{\mathcal{p}}_{\scriptscriptstyle X}$		
$\dot{\mathcal{p}}_{\mathcal{Y}}$		
$\dot{p}_z$		

Question 5.

Signed by lab GTA:

**Question 6.** You can use the back of this page if you need extra space.