

Nishanth J. Kumar

njk@csail.mit.edu | +1 (781) 588 9735

nishanthjkumar.com | <https://linkedin.com/in/nishanth-kumar/> | github.com/NishanthJKumar/ | <https://scholar.google.com/citations?user=FE512o4AAAAJ&hl=en>

EDUCATION

Massachusetts Institute of Technology – S.M. and Ph.D. in EECS

Cambridge, MA | 09/2021 –

- **GPA: 5.00/5.00.** Research: Combining learning and planning for long-horizon, complex robotics and general agentic decision-making. Advisors: Tomás Lozano-Pérez and Leslie Kaelbling.
- **Selected Coursework:** Robotic Manipulation, Theory of Computation, Computational Sensorimotor Learning.

Brown University – Sc.B. in Computer Engineering with Honors

Providence, RI | 09/2017 – 05/2021

- **GPA: 3.95/4.00.** Named *Outstanding Senior* for graduating as the top student in my concentration. Research advisors: Stefanie Tellex, George Konidaris.
- **Selected Coursework:** Machine Learning, Learning and Sequential Decision Making, 3D Vision and Deep Learning.

INDUSTRY EXPERIENCE

Research Intern- NVIDIA [[website](#)]

Seattle, WA | Summer 2024

- Led development and deployment of ‘OWL-TAMP’ – a novel method combining VLM’s and TAMP.
- Submitted 3 conference papers [[1](#), [2](#), [3](#)] to RSS and ICLR respectively.
- Managers: Caelan Garrett, Fabio Ramos, Dieter Fox.

Research Intern – RAI Institute [[website](#)]

Cambridge, MA | 11/2022 –

- Co-developed ‘EES’ a novel method to enable efficient, reset-free online learning on real Boston Dynamics Spot robots. Paper [[link](#)] accepted at RSS 2024. Manager: Jennifer Barry.

Research Intern – Vicarious AI (now part of DeepMind) [[website](#)]

Union City, CA | Summer 2021

- Led development of an open-source framework [[link](#)] for efficient inference on Probabilistic Graphical Models (PGM’s) in JAX. Journal paper accepted at JMLR [[paper](#)]. Managers: Stannis Zhou, Miguel Lázaro-Gredilla.

Research Intern Uber ATG (now Waabi AI) [[website](#)]

Toronto, ON | Summer 2020

- Independent research project [[link](#)] on Active Learning to improve sample-efficiency and reduce data-labelling costs for a key neural network model. Paper accepted at CoRL 2021. Managers: Sean Segal, Raquel Urtasun.

AWARDS AND HONORS

- **RSS Workshop on Learning for TAMP Best Paper Award** 2023
- **Qualcomm Innovation Fellowship Finalist** (1 of 46 teams nationwide) 2022
- **NSF GRFP Fellow** 2021
- **CRA Outstanding Undergrad Research Award Finalist** (1 of 23 nationwide) 2021
- **Goldwater Scholarship** (1 of 396 nationwide) 2020
- **Heidelberg Laureate** 2020

SELECTED PUBLICATIONS

- **Predicate Invention from Pixels via Pretrained Vision-Language Models.** A. Athalye*, **N. Kumar***, T. Silver, Y. Liang, T. Lozano-Pérez, L.P. Kaelbling. AAAI LM4Plan Workshop, 2025.
 - **Open-World Task and Motion Planning via Vision-Language Model Inferred Constraints.** **N. Kumar**, F. Ramos, D. Fox, C.R. Garrett. CoRL LangRob Workshop, 2024.
 - **Trust the PRoC3S: Solving Long-Horizon Robotics Problems with LLMs and Constraint Satisfaction.** A. Curtis*, **N.Kumar***, J. Cao, T. Lozano-Pérez, L.P. Kaelbling. CoRL, 2024.
 - **Practice makes Perfect: Planning to Learn Skill Parameter Policies.** **N. Kumar***, T. Silver*, W. McClinton, L. Zhao, S. Proulx, T. Lozano-Pérez, L.P. Kaelbling, J. Barry. RSS, 2024.
 - **Learning Efficient Abstract Planning Models that Choose What to Predict.** **N. Kumar***, W. McClinton*, R. Chitnis, T. Silver, T. Lozano-Pérez, L.P. Kaelbling. CoRL, 2023.
 - **Predicate Invention for Bilevel Planning.** T. Silver*, R. Chitnis*, **N. Kumar**, W. McClinton, T. Lozano-Pérez, L.P. Kaelbling, J. Tenenbaum. AAAI, 2023 (Oral).
- (* indicates equal contribution)

SKILLS & INTERESTS

- **Programming Skills**
 - **Over 5000 lines:** Python.
 - **Over 1000 lines:** PyTorch, Bash, JAX, C, Robot Operating System (ROS), Java, MATLAB, LaTeX.
 - **Familiar:** TensorFlow, OpenCV, Verilog, Scala, OCaml, Racket, MySQL.
- **Miscellaneous Skills and Interests:** Fiction Writing, Blogging, Basketball, Public Speaking, Philosophy.