# **Concurrency**

# **Fundamentals**

# Why we need Concurrency?

- 1. Resposiveness (Concurrency Multitasking)
- 2. Performance (Parallelism)

# **Key Points**

A process is completely isolated from any other process.

In Multithreaded application each thread comes with its own stack and Instruction Pointer.

Multiple threads in a single process share:

- The Heap (Data)
- Code
- The process's open files
- The process's metadata

### **Context Switch**

- Stop Thread 1
- · Scheduled Thread 1 out
- Scheduled Thread 2 in.
- Start Thread 2

Threads consumes less resources than processes. Context Switching between thread from the same process is cheaper.

Too Many Threads - Thrashing - spending more time in management than real productive work.

See Image Gallery for more visualization.

# Thread Creation (Java)

There are two ways to run code on a new thread:

- 1. Implements Runnable interface, and pass to a new Thread Object.
- 2. Extends Thread class, and create and object of that class.

Thread class - Encapsulates all thread related functionality.

# Code Snippet 1:

```
public static void main(String [] args) {
    Thread thread = new TaskThread1();
    thread.start();
}

private static class TaskThread1 extends Thread {
    @Override
    public void run(){
        System.out.println("Hello from new thread");
    }
}
```

# Code Snippet 2:

```
public static void main(String [] args) {
    Thread thread = new Thread(new Task2());
    thread.start();
}

private static class Task2 implements Runnable {
    @Override
    public void run(){
        System.out.println("Hello from new thread");
    }
}
```

# Thread Termination (Interrupt)

# Good to know

- Thread Consumes resources
  - Memory and Kernel Resources
  - CPU cyles and cache Memory
- If a thread finished its work, but the application is still running, we want to clean up the thread's resources. (Memory and Kernel Resources).
- The application will not stop as long as at least one thread is still running.

# Thread.interrupt()

- 1. If the thread is executing a method that throws an InterruptedException.
- 2. If the thread's code is handling the interrupt signal explicitly.

# Daemon Thread

Background threads that do not prevent the application from exiting if the main thread terminates.

```
Thread th = new Thread();
th.setDaemon(true);
```

# Thread Coordination

Why do we need it?

- Different threads run independently.
- Order of execution is out of control.
- Thread Dependency.

Approach 1(Naive Solution): Thread B runs in a loop and keeps checking if Thread A's result is ready. **Cons**: Burn CPU cycles unneccessary.

Approach 2: Thread.join()

```
// method signature
  public final void join();
  public final void join(long millis, int nanos);
  public final void join(long millis);
```

**Tips:-** Threads may take unreasonably long time. Always use the Therad.join(..) with a time limit.

# Performance In Multithreading

Performance Measurement:

- Latency
- Throughput

**Latency:** The time to completion of a task. Measured in time untis.

Throughput: The amount of tasks completed in a given period. Measured in tasks/time unit.

# Improving Latency:

Suppose we a divide the task in N different independent task and for each task create a seperate thread.

Then, Theoretically reduction of latency by N = Performance improvement by a factor of <math>N.

**Cons:** All task can't divided in to N independent task.

Open Question:

- 1. N = ?, How many substasks/thread to break the original task?
- 2. Does breaking original task and aggregation results come for free?

- 3. There is **inherent cost** of running an algorithm by multiple threads.
- 4. Can we break any task into subtasks?

### Inherent cost

- Breaking task into multiple tasks.
- Thread creation, passing tasks to threads
- Time between thread.start() to thread getting scheduled
- Time until the last thread finishes and signals
- Time until the aggregating thread runs.
- Aggreagation of the subresults into a single arttifact.

# Throughput (improvise):

Let's run N task in parallel. So, in this way Theoreticaly, we can do N task in same amount of time.

### Pros:

1. No Need to break the task.

### Open Questiton:

- 1. Value of N?, How many task should run in parellely.
- 2. Can we fixed the cost of creating thread (irrespective of task)?
- 3. Lets there 100 task and I want to run parallely, how to maintain effectively.

### Inherent cost

- · Breaking task into multiple tasks.
- Thread creation, passing tasks to threads
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# Value of N

# threads = # cores is optimally only if all threads are runnable and can run without interruption (no IO/blocking calls/ sleep etc).

The assumption is nothing else is running that consumes a lot of CPU.

# Data Sharing between Threads

The Memory Region where Data Resides

- Stack Memory Region
- Heap Memory Region

Each Thread has it's own stack. Stack is a memory region where:

· Methods are called.

- Arguments are passed.
- Local variables are stored.

**Stack + Instruction Pointer** = State of each thread's execution.

# **Stack's Properties:**

- All variables belong to the thread executing on that stack.
- Statically allocated when the thread is created.
- The stack's size is fixed, and relatively small (platform specific).
- If our calling hierarchy is too deep. We may get an StackOverflow Exception.(Risky with recursive calls).

### **Heap Memory**

Heap Memory is a shared memory region belongs to the process.

What is allocated on the Heap?

- Objects(anything created with the new operator)
- Members of classes.
- Static Variables.

# Heap Memory Management

- Governed and managed by Garbage Collector.
- Objects- stay as long as we have a reference to them.
- Members of classes exist as long as their parent objects exist (same life cycle as their parents).
- Static variables- stay forever.

### References Allocation:

- Can be allocated on the stack.
- Can be allocated on the *heap* if they are members of a class.

# Objects Allocation:

Always allocated on the heap.

## Summary:

# Memory Regions - Summary Heap (shared) Objects Class members Stack (exclusive) Local primitive types types Local references

# **Concurrency Challenges**

What is Resource?

- Variables (Integers, Strings ..)
- Data Structure
- File or connection handles
- Message or work queues
- · Any Objects ...

# **Atomic Operation:**

- **Def:** An operation or a set of operation is considered atomic, if it appears to the rest of the system as if it occurred at once.
- Single step "all or nothing"

# Synchronization in Java:

1. First way of using *synchronized* keyword:

```
public class ClassWithCriticalSection {
   public synchronized void method1() {
        ... Thread A
   }
   public synchronized void method2() {
        ...
   }
}
```

Only one thread will able to execute either of these two methods.

Let Thread A is using method1 then, Thread B will be deprived of using method1 as well as method2.

2. Second way of using *synchronized* keyword:

Here lockingObject can be any object. Only one thread can access a critical section locked by a single object.

Gives more flexiblity, can have multiple different critical section and multiple thread can access it.

# Summary:

- We can identify the code that we need to execute atomically, by declaring that code as critical section.
- Use of synchronized keyword to protect the critical section in two ways
  - Simple way (in front of a method)
  - On an explicit Object- More flexible and granular, but also more verbose.

# Solution to Concurrency

# **Naive Solution**

- Every method which has accessed to share variable make it as synchronous method. (Excessive Synchronization)
- Cons: No use of multithreading, rather it will detroiate the performance.

# **Atomic Operation**

- All reference assignment are atomic.
- We can get and set references to objects atomically.
- All getters and setters.
- All assignments to primitive types are safe except long and double.

Use volatile keyword for long and double to make it atomic.

### **Race Condition:**

- Condition when multiple threads are accessing a shared resource.
- At least one thread is modifying the resource.
- The timing of threads scheduling may casuse incorrect results.
- The core of the problem is non atomic operations performed.

# **Race Condition - Solution**

- Identification of critical section where the reace condition is happening.
- Protection of the critical section by a synchronized block.

**Data Race: Problem** May Lead to unexpected, paradoxical and incorrect results!.

- Compiler and CPU may execute the instruction Out or Order to optimize performance and utilization.
- They will do so while maintaining the logical correctness of the code.
- Out of Order of execution by the compiler and CPU are important features to speed up the code.

# Why compiler and CPU re-arranges the code: The compiler re-arranges instructions for better

- Branch predication (Optimized loops, "if" statements etc.)
- Vectorization parallel instruction execution (SIMD)
- Prefetching instructions- better cache performance.

CPU re-arranges instructions for better hardware units utilization.

Solutions: Two ways to solve the Data Race Problem

- Synchronization of methods which modify shared variables.
- Declaration of shared variables with the *volatile* keyword.

# Summary:

- Two problems with multithreaded applications
  - Race Conditions
  - Data Races
- · Both involve
  - Multiple threads.
  - At least one is modifying a shared variable.
- Both problems may result in unexpected and incorrect results.