

③

Test - 2

Name: G. Nithish
Regno: 19BC80012
Course: Computer
Networks

①

Define CSMA:

* CSMA (Carrier Sense Multiple Access) is a network protocol for carrier-transmission that operates in the medium Access Control (MAC) layer.

* It senses or listens whether the shared channel for transmission is busy or not, and transmits if the channel is not busy. Using CSMA protocols, more than one users or nodes send and receive data through a shared medium that may be single cable or optical fiber connecting multiple nodes or a portion of wireless spectrum.

Working Principle:-

↳ When a station has frames to transmit, it attempts to detect Presence of the carrier signal from the other nodes connected to the shared Channel.

↳ If a carrier signal is detected it implies that a transmission is in Progress...

↳ The station waits till the ongoing transmission executes to completion and then initiates its own transmission.

↳ Generally transmission by the node are received by all other nodes connected to the Channel.

Algorithm for CSMA:

Algorithm for CSMA are:

- ↳ Non Persistent
- ↳ 1 - Persistent
- ↳ 2 - Persistent

Explanation:

Non Persistent:

If channel is not free then wait for random amount of time then sense the channel, if free then send data.

- 1. Transmit if medium is idle
Otherwise go to 2
- 2. wait for random amount of time and repeat (1) if medium is busy.

1 - Persistent

Continuously sense the channel and when it sense that the channel is

free, it transmits the data.

1. If medium is idle transmit, otherwise go to 2.

2. Wait for random amount of time and repeat (1) if medium is busy.

2- Persistent CSMA:

1. With Probability p , the station sends its frame.

2. With Probability $1-p$, station waits for the beginning of the next time slot and check the line again.

(i) If line is idle go to 1

(ii) If line is busy, it acts as collision has occurred and uses the backoff algorithm.

2) IPv4 Address of class A:

→ IPv4 address are 32 bit numbers that are typically displayed in dotted decimal notation.

→ A 32 bit address contain 2 Primary Parts

i) Network Prefix.

ii) The host number.

→ IPv4 Addressing System is divided into 5 classes of Ip Address. All the 5 classes are identified by the 1st Octet of Ip Address.

1 st octet	2 nd octet	3 rd octet	4 th octet
↓	↓	↓	↓
<u>110000000</u>	<u>10101000</u>	<u>00000001</u>	<u>10011000</u>

192 . 168 . . 1 . 152

no. of networks & the no. of host per class can be derived by this formula

$$\text{no. of networks} = 2^{\text{network_bits}}$$

$$\text{no. of hosts/ network} = 2^{\text{host_bits}} - 2$$

When calculating hosts IP address, 2 IP address are decreased because they can't be assigned to hosts, i.e. the first IP of a network no. and the last IP is reserved for Broadcast IP.

Class A Address.

The first bit of the first octet is always set to 0 (zero). Thus first octet ranges from 1-127 i.e.

$$\begin{array}{c} 00000001 - 01111111 \\ \hline 1 - 127 \end{array}$$

Class A addresses only include IP starting from 1.x.x.x to 126.x.x.x only. The IP range 127.x.x.x is reserved for loopback IP address.

Class A address only indicates IP starting from $1.x.x.x$ to $126...$

The default subnet mask for Class A

IP Address is $255.0.0.0$ which implies

that class A addressing can have

126 networks ($2^7 - 2$) and 1677214 host
($2^{24} - 2$).

Class A IP address format is

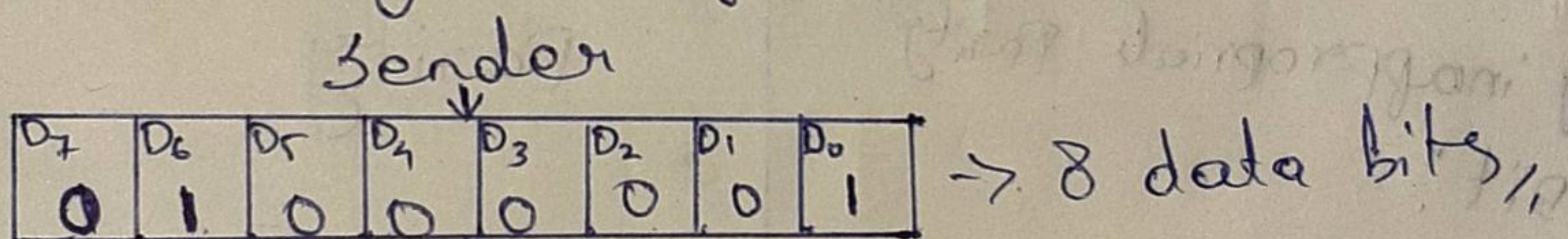
0NNNNNNNN.HHHHHHHH.HHHHHHHH

Q. The ASCII Value for A is 65 convert this ASCII value to binary and store them as 8 bit data;

Answer:-

The ASCII value for 'A' is '65'

The Binary value for '65' = 11000001

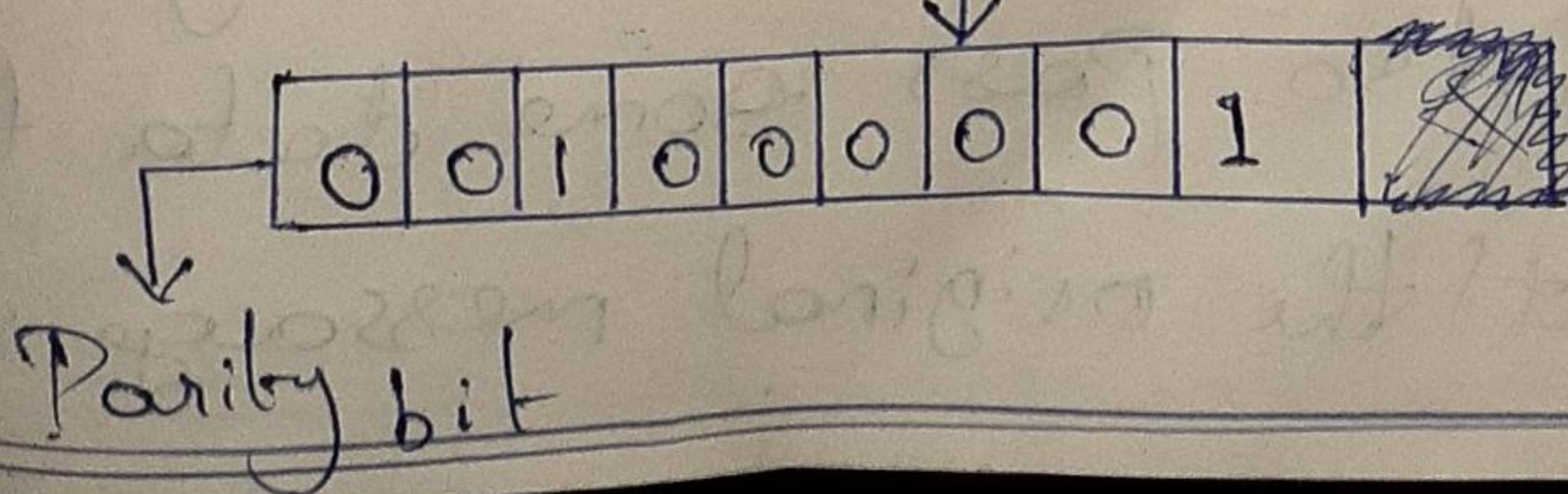


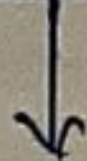
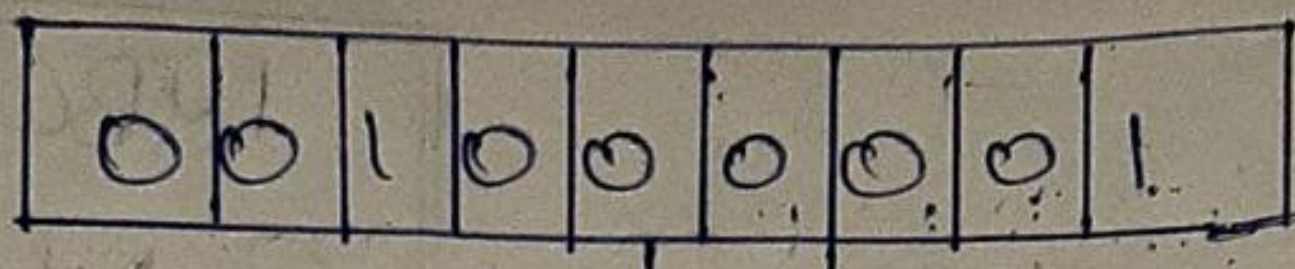
↓

Compute Parity bit

↓

The total no. of 1's in the data unit is 2
So '0' is add to the data unit as even parity.

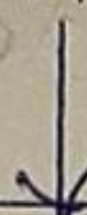
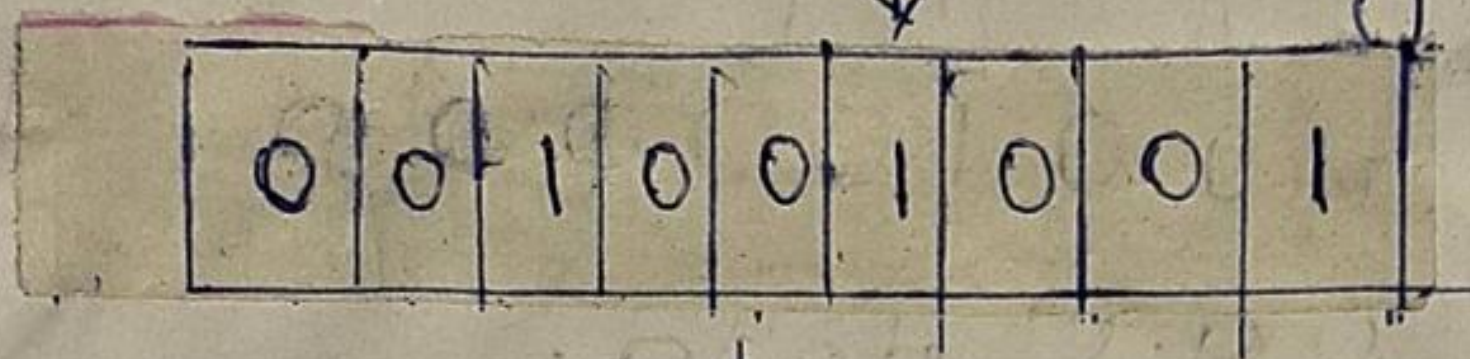




transmitted



By wrongly the
'D₃' location bit is
changed to '1'



Compute Parity bit

So the "error
is detected" Because
of inappropriate Parity
bit.

Now the no. of bit's '1'
is 3 but is odd
but it has even
Parity

reject

No

even

Yes

Accept

Hence the error detected:-

Error - Correcting:

→ Along with error-detecting code,
we can also pass some data to
figure out the original message.

from the corrupt message that we received

A) In error-correcting, Parity Check has a simple way to detect errors along with a sophisticated mechanism to determine the corrupt bit location.

Once the corrupt bit is located, its value is reverted (from 0 to 1 or 1 to 0) to get the original message.

By the use of error-correcting code it detects the exact location of the corrupt bits here as "D₃"

Change it '1' to '0'

