

map::computeFrontierCentroid



```
graph LR; A[map::computeFrontierCentroid] --> B[map::nearest]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray fill and a black border, containing the text 'map::computeFrontierCentroid'. The right box has a white fill and a black border, containing the text 'map::nearest'. A dark blue arrow points from the right side of the left box to the left side of the right box.

map::nearest