



SZABIST
UNIVERSITY

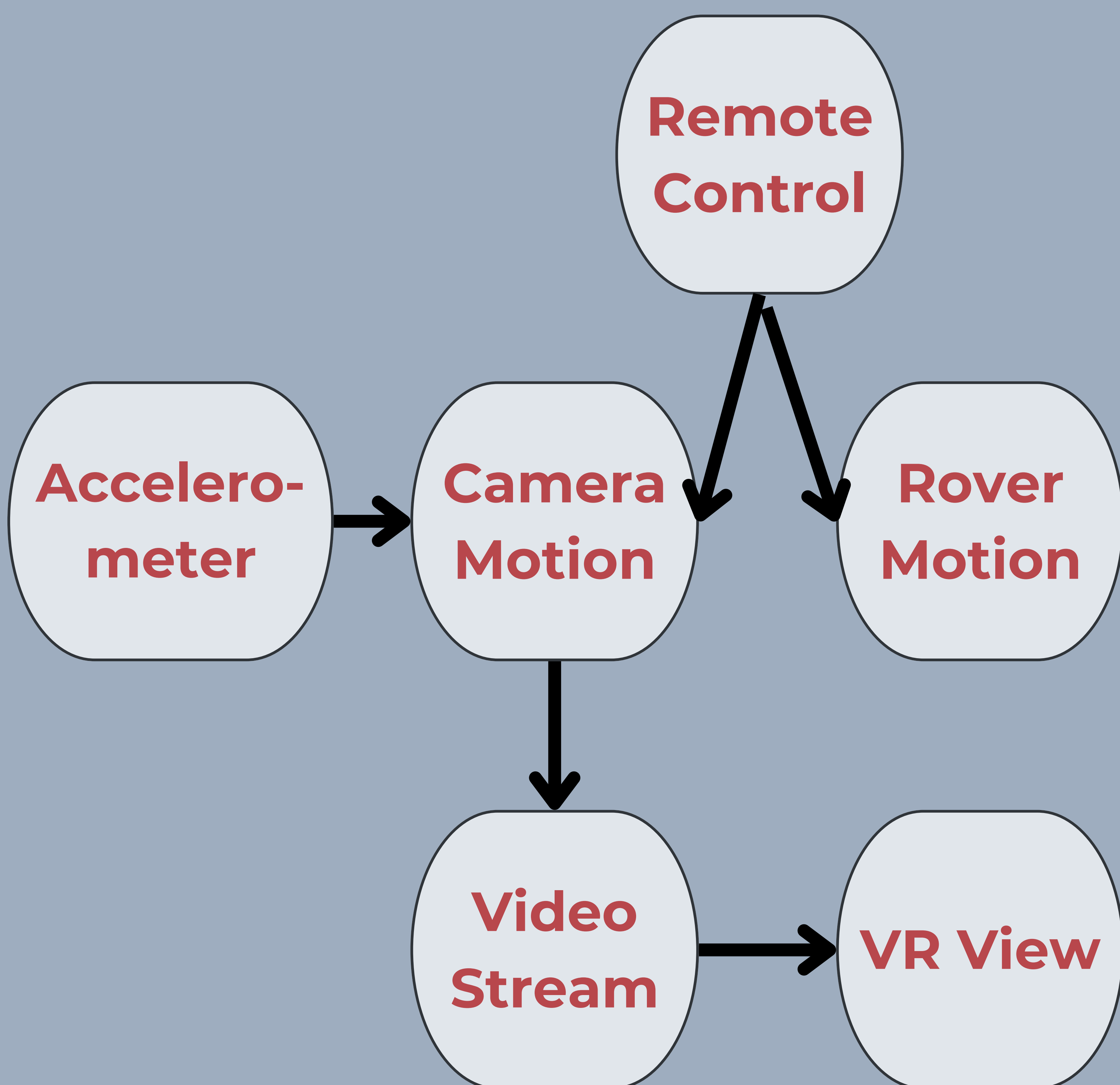


VISIONROVER

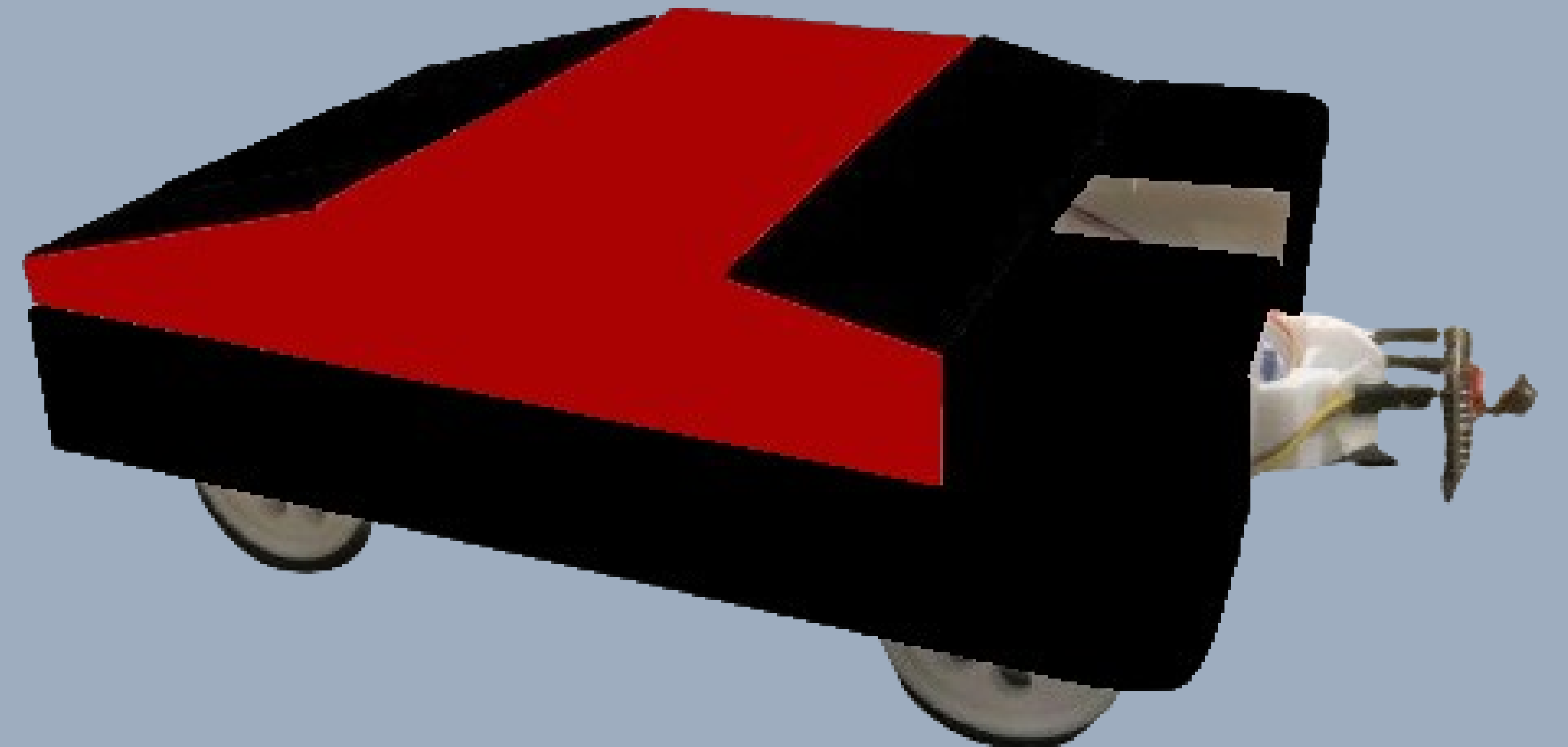
PROJECT OBJECTIVE

The “**VisionRover**” is designed to perform inspections, navigate industrial environments, and provide real-time data for safety and operational monitoring.

BASIC FUNCTIONING



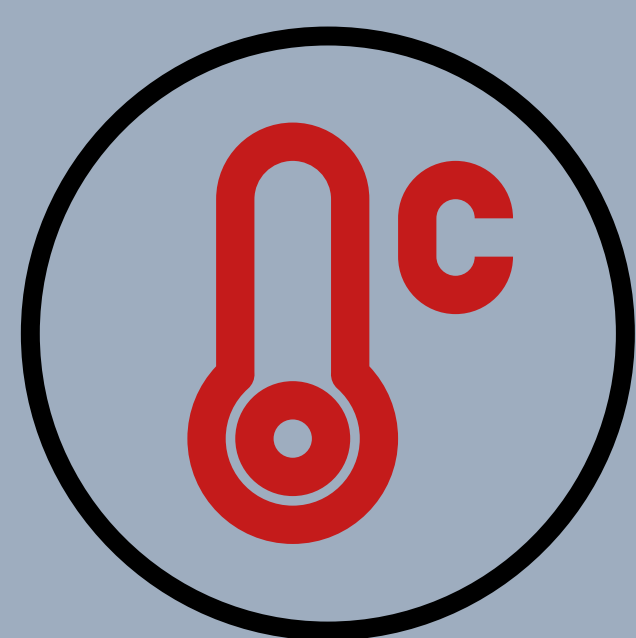
ROVER HARDWARE



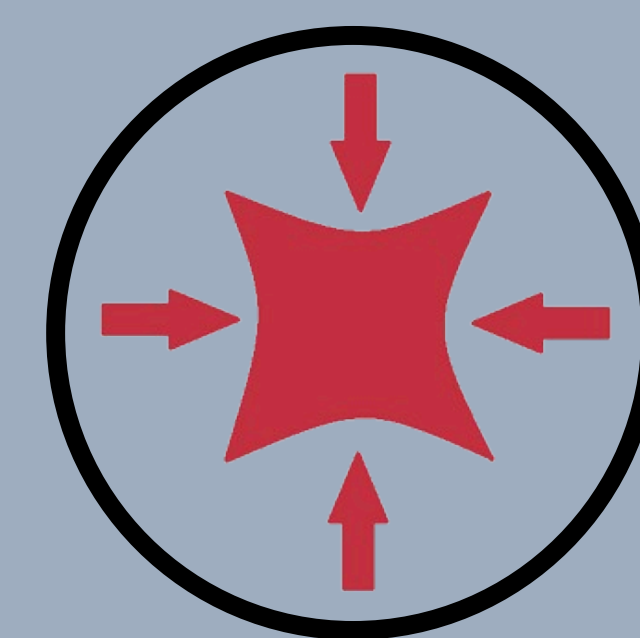
MAJOR FEATURES



Remote
Controlled



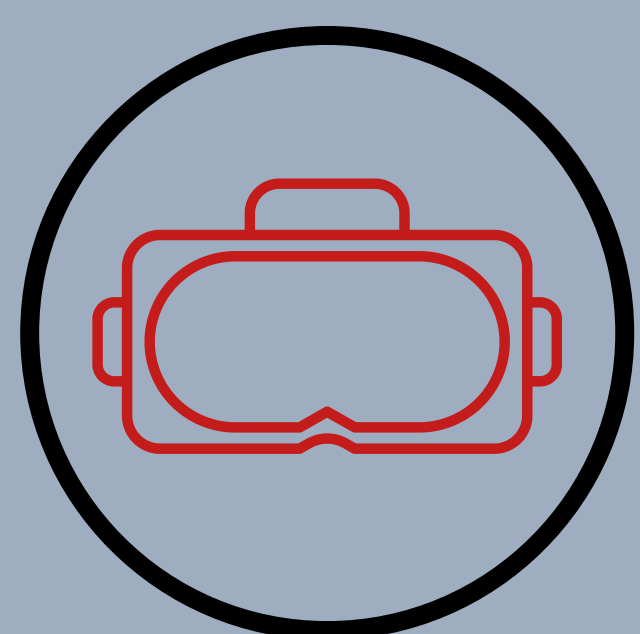
Real-Time
Temperature Data



Compact
Design



Live Video
Transmission



VR View of
Surrounding



Durable
Structure