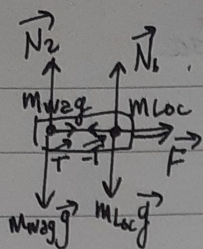


Ex. 4

Stankov 3720433



1 - Constant friction

Static friction with locom. = drive for whole system.

$$F = (m_{wag} + m_{loc})a$$

For locom. $F = \mu N_1 = \mu m_{loc} g$, hence

$$\mu m_{loc} g = (m_{wag} + m_{loc}) \cdot \frac{v_1^2 - v_0^2}{2d}$$

$$\mu g = \left(1 + \frac{m_{wag}}{m_{loc}}\right) \cdot \frac{v_1^2 - v_0^2}{2d}$$

$$m_{loc} = \frac{m_{wag}}{-1 + \frac{2\mu g d}{v_1^2 - v_0^2}}$$

$$m_{loc} = \frac{5 \cdot 10^5 \text{ kg}}{-1 + \frac{2 \cdot 0.12 \cdot 9.8 \cdot 12 \cdot 10^3}{(80/3.6)^2}} = \left[\text{units } \uparrow \text{ dropped because clear that denom. is dim-less} \right] \approx 8.9 \text{ tonm.}$$

2 - Dynamic friction

EOM: $ma = -kx$

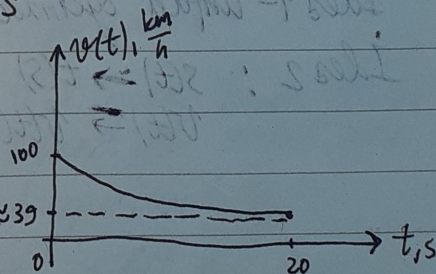
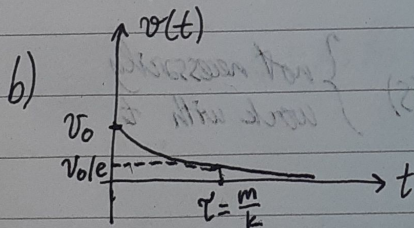
$$m\ddot{x} = -kx \rightarrow \int \frac{dx}{x} = -\frac{k}{m} \int dt$$

$$\ln x = -\frac{k}{m}t + C \quad | e^{}$$

$$x = x_0 e^{-\frac{k}{m}t}$$

a) $x_1 = x_0 e^{-\frac{k}{m}t} \rightarrow t = \left(-\frac{m}{k}\right) \ln \frac{x_1}{x_0}$

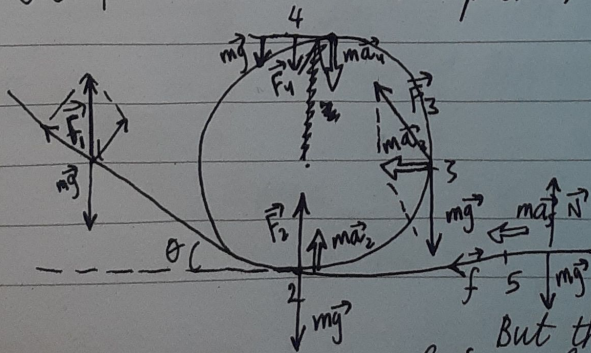
$$t = \left(\frac{-1.5 \cdot 10^3}{70}\right) \ln \frac{50}{100} \approx 14.85 \text{ s} \approx 15 \text{ s.}$$



3 - Circular motion

All points will have F dep. on v , so I write generically. Also,

$$v = \text{const} \rightarrow a_{tot} = a_c = \frac{v^2}{r} = |\vec{a}_i|, i \neq 1$$



For points 2,3,4 forces from track adjust so that \vec{ma}_i point to center.

There is friction on 1, otherwise wagon would accelerate there.

But then I considered friction to be in 5 also.

In 1: $F(t_1) = mg$, $F_{net} = 0$

In 2: $F(t_2) = ma + mg = m(g + \frac{v^2}{r})$, $F_{net} = \frac{mv^2}{r}$

In 3: $F_{(t_3)} = \sqrt{(mg)^2 + (ma)^2} = m\sqrt{g^2 + (\frac{v^2}{r})^2}$, $F_{net} = \frac{mv^2}{r}$
(see picture)

In 4: $F_{(t_4)} = ma - mg = m(\frac{v^2}{r} - g)$, $F_{net} = \frac{mv^2}{r}$

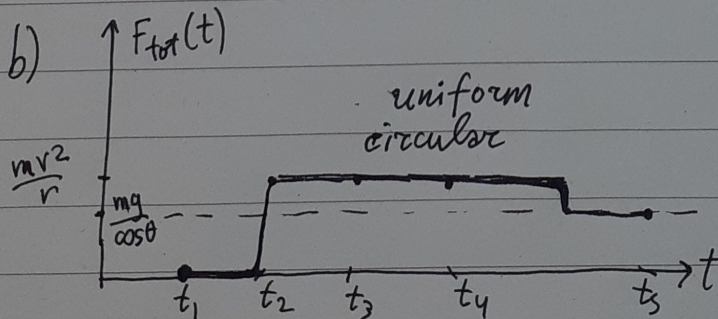
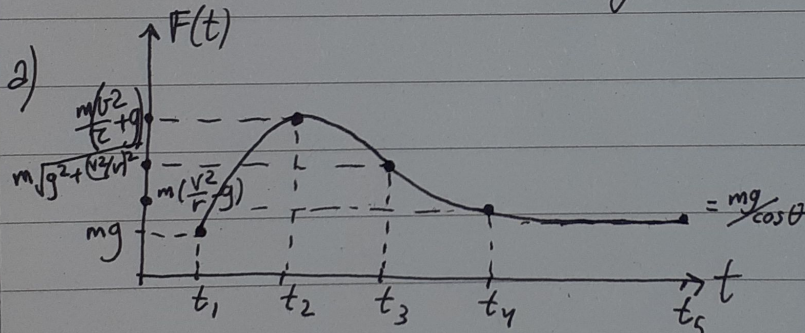
In 5: $F(t_5) = \sqrt{N^2 + f^2} = \sqrt{\mu^2 + 1} mg$ (because I consider "track force" = all friction + normal impact)
(see picture)

μ can be found from 1:

$mg \sin \theta = \mu mg \cos \theta \rightarrow \mu = \tan \theta$, so

$F(t_5) = \sqrt{1 + \tan^2 \theta} mg = \frac{mg}{\cos \theta}$, $F_{net} = \frac{mg}{\cos \theta}$.

Hence $F_2 > F_3 > F_1$, and F_4/F_5 can relate differently to them, because θ and v can vary. Below is ~~approx~~ some possibility for F_4, F_5



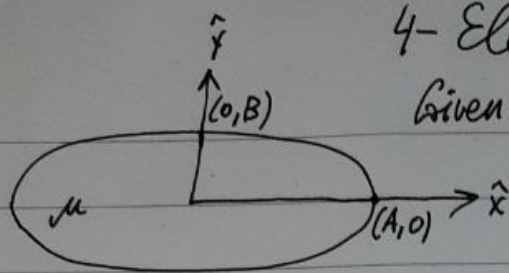
(if consider $F_5 = 0$ - must admit there is no friction in 5, and there is in 1 \rightarrow track differs in positions 1 and 5. I assumed it is same)

c) $a_{max} = 6g = \frac{v_{max}^2}{r} \rightarrow v_{max} = \sqrt{6gr} \approx \sqrt{6 \cdot 9.8 \cdot 30} \text{ m.s}^{-1} = 42 \text{ m.s}^{-1}$

d) $a_{min} = g$ (when $F_4 = 0$, barely touching) $\rightarrow v_{min} = \sqrt{gr} \approx 17 \text{ m.s}^{-1}$

4- Elliptical Paths

Given $v = \text{const}$



a) Point A has smallest rad. of curvature $\rightarrow a_{\max} = \frac{v^2}{r_{\min}}$ is in A.

Point B ... largest ... \rightarrow

$a_{\min} = \frac{v^2}{r_{\max}}$ is in B.

b) Curvature for a curve $(x(t), y(t))$ can be found

$$K = \frac{|x'y'' - y'x''|}{(x'^2 + y'^2)^{3/2}}, \quad R = K^{-1}, \quad [K] = m^{-1}, \quad [R] = m.$$

(deriving this is great exercise, but it is pure math, and I will derive for elliptic case)

Ellipse parametrization

$$x = A \cos t \rightarrow \dot{x} = -A \sin t \rightarrow \ddot{x} = -A \cos t$$

$$y = B \sin t \rightarrow \dot{y} = B \cos t \rightarrow \ddot{y} = -B \sin t$$

$$\text{Then } K = \frac{-A \sin t (-B \sin t) - B \cos t (-A \cos t)}{(A^2 \sin^2 t + B^2 \cos^2 t)^{3/2}} = \frac{AB}{(A^2 \sin^2 t + B^2 \cos^2 t)^{3/2}}$$

$$\text{In point } (A, 0) \quad t=0 \rightarrow K = \frac{AB}{B^3} = \frac{A}{B^2} \rightarrow R = \frac{B^2}{A}.$$

The accel. is max at A, assume it is also the max. possible from all others at A: μg (from Frict. max). Then

$$v_{\max} = \sqrt{\mu g \frac{B^2}{A}}$$

Note: I can reason that $v = \sqrt{a R_{\text{cur}}}$ can be bigger in other points even when $a < \mu g$, but $R_{\text{cur}} > \frac{B^2}{A}$ (for example at B $R_{\text{cur}} = \frac{A^2}{B} > \frac{B^2}{A}$), but then task says v is same everywhere, so v_A will be bigger than $\sqrt{\mu g \frac{B^2}{A}}$, which is impossible!