Lecture #13: Trees **Summary**

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13. Trees

10.5 Trees

- Definitions: circuit-free, tree, trivial tree, forest
- Characterizing trees: terminal vertex (leaf), internal vertex

10.6 Rooted Trees

- Definitions: rooted tree, root, level, height, child, parent, sibling, ancestor, descendant
- Definitions: binary tree, full binary tree, subtree
- Binary tree traversal: breadth-first-search (BFD), depth-first-search (DFS)

10.7 Spanning Trees and Shortest Paths

- Definitions: spanning tree, weighted graph, minimum spanning tree (MST)
- Kruskal's algorithm, Prim's algorithm
- Dijkstra's shortest path algorithm (non-examinable)

10.5 Trees

Definition: Tree

A graph is said to be circuit-free iff it has no circuits.

A graph is called a **tree** ifd it is circuit-free and connected.

A **trivial tree** is a graph that consists of a single vertex.

A graph is called a **forest** iff it is circuit-free and not connected.

Definitions: Terminal vertex (leaf) and internal vertex

Let *T* be a tree. If *T* has only one or two vertices, then each is called a **terminal vertex** (or **leaf**). If *T* has at least three vertices, then a vertex of degree 1 in *T* is called a **terminal vertex** (or **leaf**), and a vertex of degree greater than 1 in *T* is called an **internal vertex**.

10.5 Trees

Lemma 10.5.1

Any non-trivial tree has at least one vertex of degree 1.

Theorem 10.5.2

Any tree with n vertices (n > 0) has n - 1 edges.

Lemma 10.5.3

If G is any connected graph, C is any circuit in G, and one of the edges of C is removed from G, then the graph that remains is still connected.

Theorem 10.5.4

If G is a connected graph with n vertices and n-1 edges, then G is a tree.

10.6 Rooted Trees

Definitions: Rooted Tree, Level, Height

A **rooted tree** is a tree in which there is one vertex that is distinguished from the others and is called the **root**.

The **level** of a vertex is the number of edges along the unique path between it and the root.

The **height** of a rooted tree is the maximum level of any vertex of the tree.

Definitions: Child, Parent, Sibling, Ancestor, Descendant

Given the root or any internal vertex v of a rooted tree, the **children** of v are all those vertices that are adjacent to v and are one level farther away from the root than v.

If w is a child of v, then v is called the **parent** of w, and two distinct vertices that are both children of the same parent are called **siblings**.

Given two distinct vertices v and w, if v lies on the unique path between w and the root, then v is an **ancestor** of w, and w is a **descendant** of v.

10.6 Rooted Trees

Definitions: Binary Tree, Full Binary Tree

A **binary tree** is a rooted tree in which every parent has at most two children. Each child is designated either a **left child** or a **right child** (but not both), and every parent has at most one left child and one right child.

A **full binary tree** is a binary tree in which each parent has exactly two children.

Definitions: Left Subtree, Right Subtree

Given any parent v in a binary tree T, if v has a left child, then the **left subtree** of v is the binary tree whose root is the left child of v, whose vertices consist of the left child of v and all its descendants, and whose edges consist of all those edges of T that connect the vertices of the left subtree.

The **right subtree** of *v* is defined analogously.

10.6 Rooted Trees

Theorem 10.6.1: Full Binary Tree Theorem

If T is a full binary tree with k internal vertices, then T has a total of 2k + 1 vertices and has k + 1 terminal vertices (leaves).

Theorem 10.6.2

For non-negative integers h, if T is any binary tree with height h and t terminal vertices (leaves), then

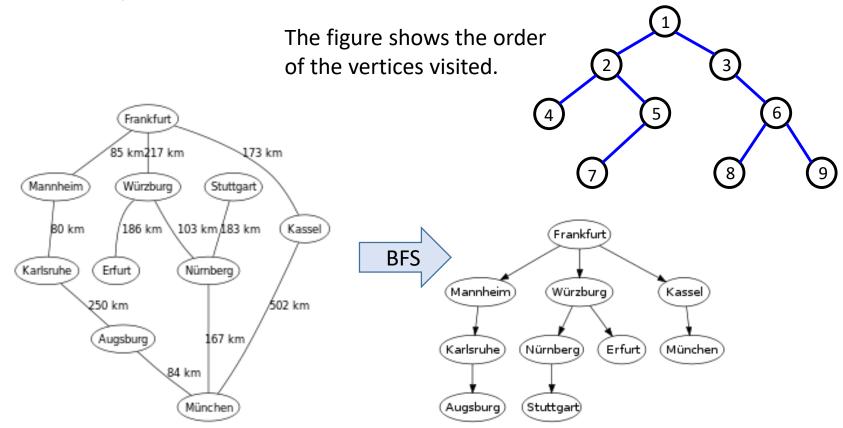
$$t \leq 2^h$$

Equivalently,

$$\log_2 t \le h$$

Breadth-First Search

In breadth-first search (by E.F. Moore), it starts at the root and visits its adjacent vertices, and then moves to the next level.



10.6 Rooted Trees

Depth-First Search

There are three types of depth-first traversal:

Pre-order

- Print the data of the root (or current vertex)
- Traverse the left subtree by recursively calling the pre-order function
- Traverse the right subtree by recursively calling the pre-order function

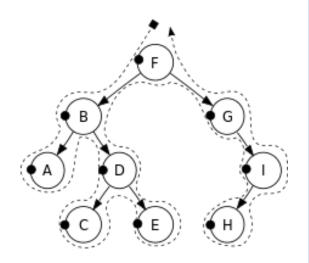
In-order

- Traverse the left subtree by recursively calling the in-order function
- Print the data of the root (or current vertex)
- Traverse the right subtree by recursively calling the in-order function

Post-order

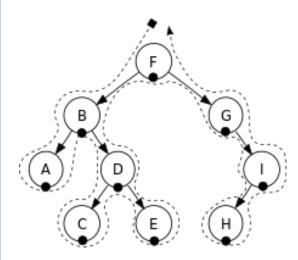
- Traverse the left subtree by recursively calling the post-order function
- Traverse the right subtree by recursively calling the post-order function
- Print the data of the root (or current vertex)

Depth-First Search



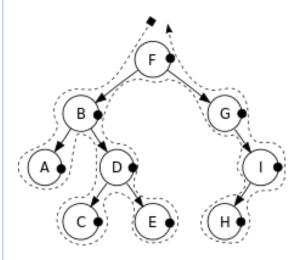
Pre-order:

F, B, A, D, C, E, G, I, H



In-order:

A, B, C, D, E, F, G, H, I



Post-order:

A, C, E, D, B, H, I, G, F

10.7 Spanning Trees and Shortest Paths

Definition: Spanning Tree

A **spanning tree** for a graph *G* is a subgraph of *G* that contains every vertex of *G* and is a tree.

Proposition 10.7.1

- 1. Every connected graph has a spanning tree.
- 2. Any two spanning trees for a graph have the same number of edges.

Definitions: Weighted Graph, Minimum Spanning Tree

A **weighted graph** is a graph for which each edge has an associated positive real number **weight**. The sum of the weights of all the edges is the **total weight** of the graph.

A **minimum spanning tree** for a connected weighted graph is a spanning tree that has the least possible total weight compared to all other spanning trees for the graph.

If G is a weighted graph and e is an edge of G, then w(e) denotes the weight of e and w(G) denotes the total weight of G.

Algorithm 10.7.1 Kruskal

Input: G [a connected weighted graph with n vertices]

Algorithm:

- 1. Initialize T to have all the vertices of G and no edges.
- 2. Let E be the set of all edges of G, and let m = 0.
- 3. While (m < n 1)
 - 3a. Find an edge e in E of least weight.
 - 3b. Delete e from E.
 - 3c. If addition of e to the edge set of T does not produce a circuit, then add e to the edge set of T and set m = m + 1

End while

Output: T [T is a minimum spanning tree for G]

Algorithm 10.7.2 Prim

Input: G [a connected weighted graph with n vertices]

Algorithm:

- 1. Pick a vertex v of G and let T be the graph with this vertex only.
- 2. Let V be the set of all vertices of G except v.
- 3. For i = 1 to n 1
 - 3a. Find an edge *e* of *G* such that (1) *e* connects *T* to one of the vertices in *V*, and (2) *e* has the least weight of all edges connecting *T* to a vertex in *V*. Let *w* be the endpoint of *e* that is in *V*.
 - 3b. Add *e* and *w* to the edge and vertex sets of *T*, and delete *w* from *V*.

Output: T [T is a minimum spanning tree for G]

To skip for this semester.

Algorithm 10.7.3 Dijkstra

Inputs:

- G [a connected simple graph with positive weight for every edge]
- \blacksquare ∞ [a number greater than the sum of the weights of all the edges in G]
- w(u, v) [the weight of edge $\{u, v\}$]
- a [the source vertex]
- Z [the destination vertex]

Algorithm:

- Initialize T to be the graph with vertex a and no edges.
 Let V(T) be the set of vertices of T, and let E(T) be the set of edges of T.
- 2. $L(a) \leftarrow 0$, and for all vertices u in G except a, $L(u) \leftarrow \infty$. [The number L(u) is called the label of u.]
- 3. Initialize $v \leftarrow a$ and $F \leftarrow \{a\}$. [The symbol v is used to denote the vertex most recently added to T.]

To skip for this semester.

Algorithm 10.7.3 Dijkstra (continued...)

Let Adj(x) denote the set of vertices adjacent to vertex x.

- 4. While $(z \notin V(T))$
 - a. $F \leftarrow (F \{v\}) \cup \{\text{vertices} \in \text{Adj}(v) \text{ and } \notin V(T)\}$ [The set F is the set of fringe vertices.]
 - b. For each vertex $u \in Adj(v)$ and $\notin V(T)$, if L(v) + w(v, u) < L(u) then $L(u) \leftarrow L(v) + w(v, u)$ $D(u) \leftarrow v$

[The notation D(u) is introduced to keep track of which vertex in T gave rise to the smaller value.]

c. Find a vertex x in F with the smallest label. Add vertex x to V(T), and add edge $\{D(x), x\}$ to E(T). $v \leftarrow x$

Output: L(z) [this is the length of the shortest path from a to z.]

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