

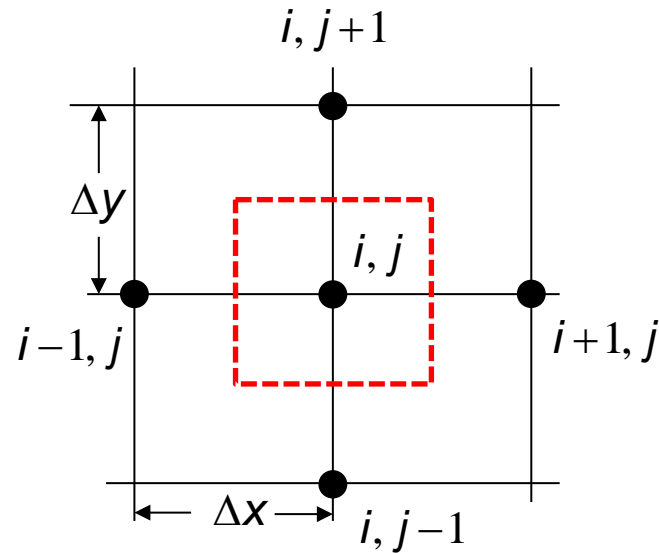
SESA3029

Aerothermodynamics

Lecture 5.7

Finite difference methods for the
heat diffusion equation in 2D,
example case

2D Discretisation



2D heat diffusion equation,
stationary, no heat source

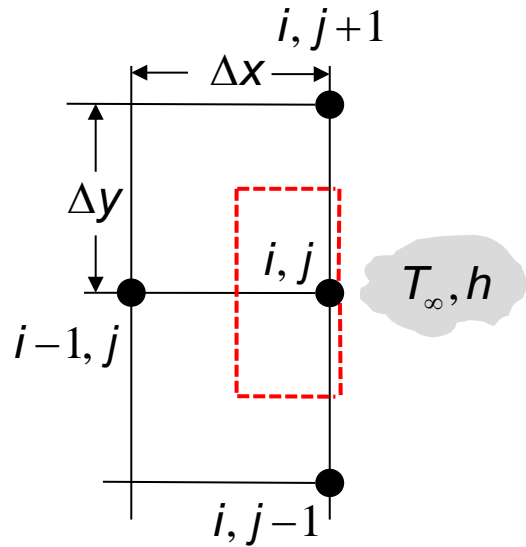
on mesh with uniform **but different**
stepsizes $\Delta x, \Delta y$

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = 0$$

$$\frac{\left. \frac{\partial T}{\partial x} \right|_{i+1/2, j} - \left. \frac{\partial T}{\partial x} \right|_{i-1/2, j}}{\Delta x} + \frac{\left. \frac{\partial T}{\partial y} \right|_{i, j+1/2} - \left. \frac{\partial T}{\partial y} \right|_{i, j-1/2}}{\Delta y} = 0$$

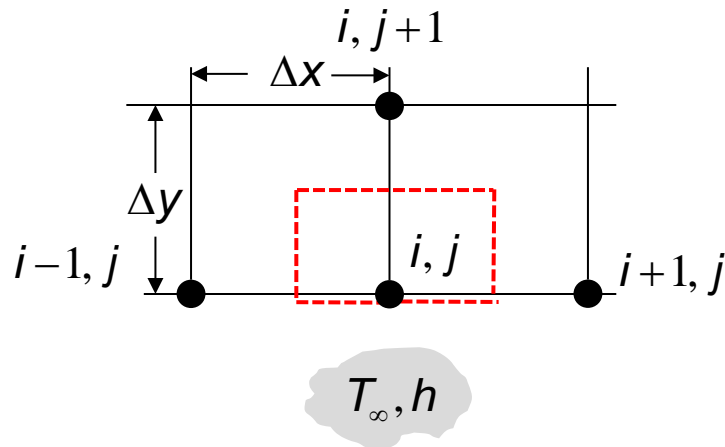
$$\frac{1}{\Delta x^2} (T_{i+1, j} - 2T_{i, j} + T_{i-1, j}) + \frac{1}{\Delta y^2} (T_{i, j+1} - 2T_{i, j} + T_{i, j-1}) = 0 \quad (5)$$

2D Boundary conditions



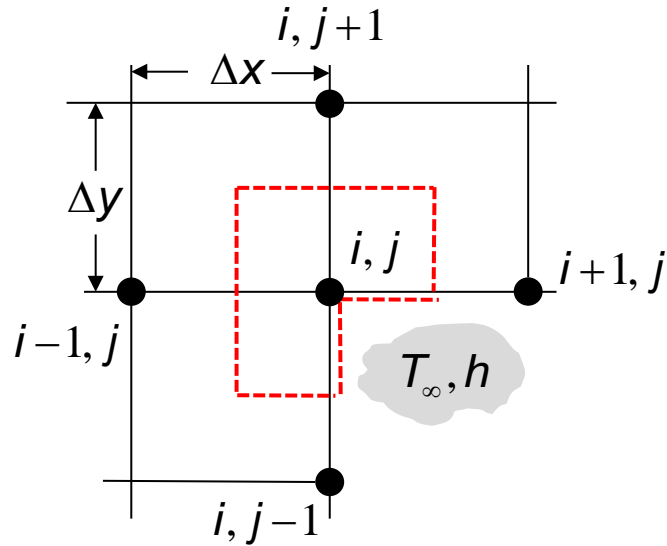
Node at a plane surface with convection

$$\frac{2}{\Delta x^2} T_{i-1,j} + \frac{1}{\Delta y^2} (T_{i,j+1} + T_{i,j-1}) - 2T_{i,j} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{h}{k\Delta x} \right) = -\frac{2h}{k\Delta x} T_{\infty} \quad (6)$$



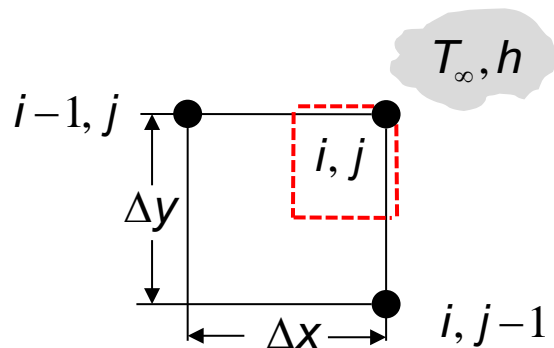
$$\frac{1}{\Delta x^2} (T_{i+1,j} + T_{i-1,j}) + \frac{2}{\Delta y^2} T_{i,j+1} - 2T_{i,j} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{h}{k\Delta y} \right) = -\frac{2h}{k\Delta y} T_{\infty} \quad (7)$$

Node at an internal corner



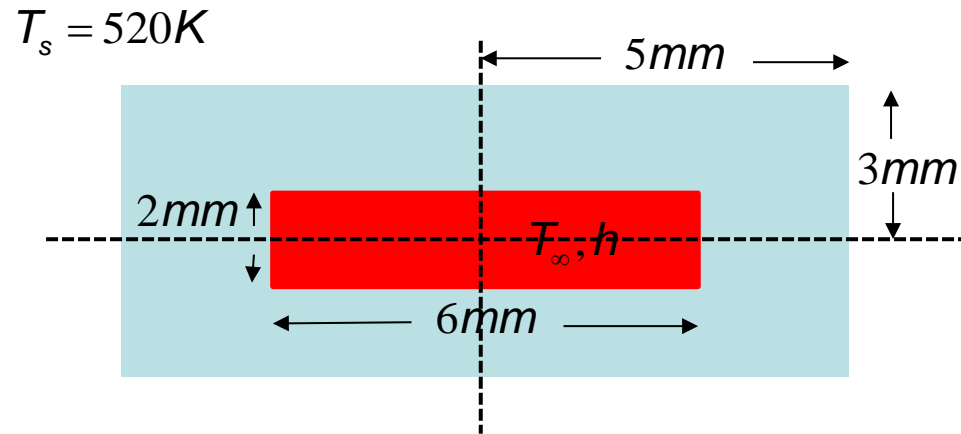
$$\begin{aligned}
 & \frac{1}{\Delta x^2} (T_{i+1,j} + 2T_{i-1,j}) + \frac{1}{\Delta y^2} (2T_{i,j+1} + T_{i,j-1}) \\
 & - T_{i,j} \left(3 \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} \right) + \frac{h}{k} \left(\frac{1}{\Delta x} + \frac{1}{\Delta y} \right) \right) \\
 & = -\frac{h}{k} \left(\frac{1}{\Delta x} + \frac{1}{\Delta y} \right) T_{\infty}
 \end{aligned} \tag{8}$$

Node at an external corner with convection



$$\begin{aligned}
 & \frac{1}{\Delta x^2} T_{i-1,j} + \frac{1}{\Delta y^2} T_{i,j-1} \\
 & - T_{i,j} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{h}{k} \left(\frac{1}{\Delta x} + \frac{1}{\Delta y} \right) \right) \\
 & = -\frac{h}{k} \left(\frac{1}{\Delta x} + \frac{1}{\Delta y} \right) T_{\infty}
 \end{aligned} \tag{9}$$

2D heat diffusion example



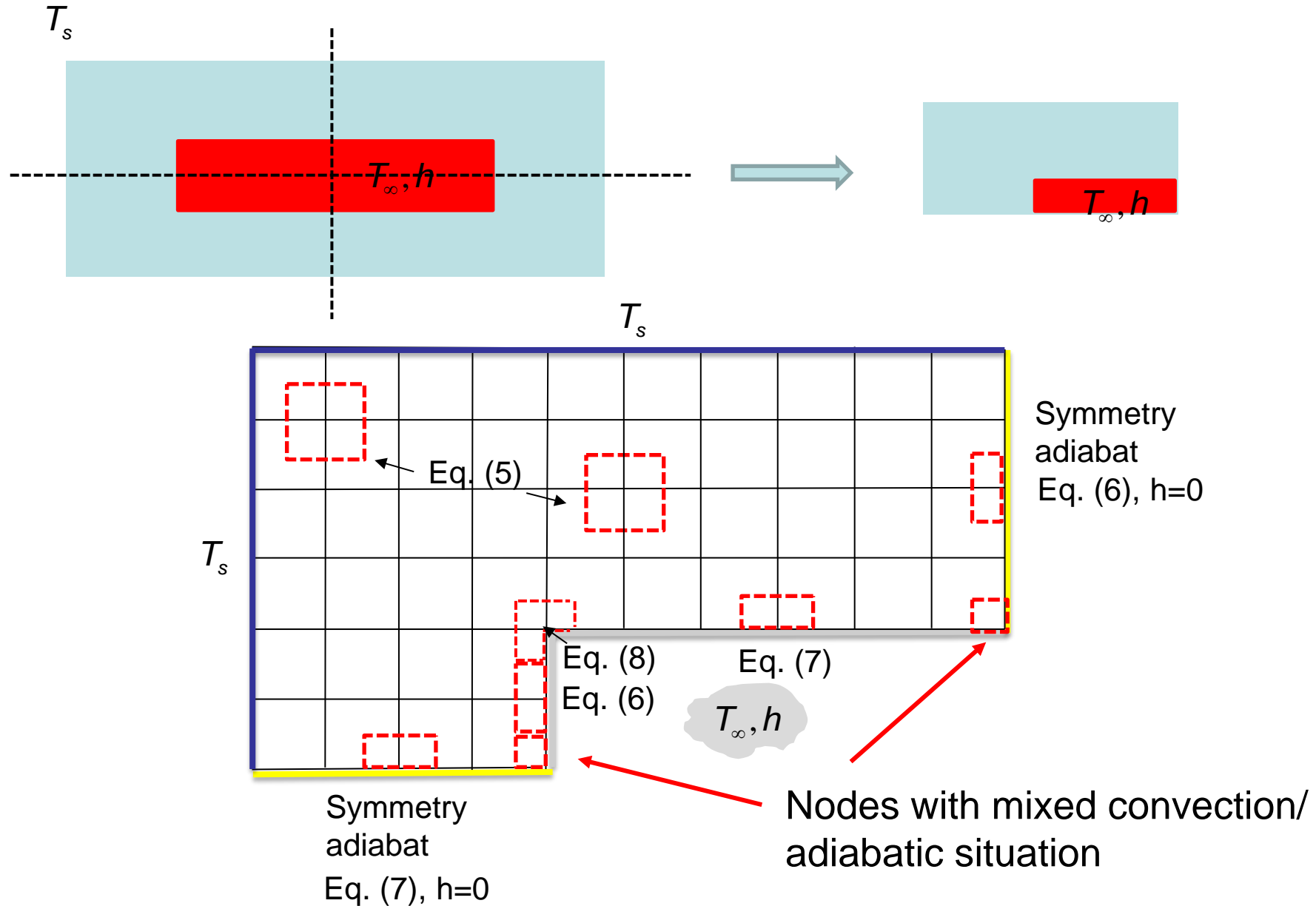
A rectangular glass channel ($k = 2 \text{ W/(mK)}$) with 2mm wall thickness is exposed to an outside constant temperature $T_s = 520K$.

The channel is water cooled at constant temperature $T_\infty = 300K$ with a constant convective heat transfer coefficient $h = 150 \text{ W/(m}^2\text{K)}$.

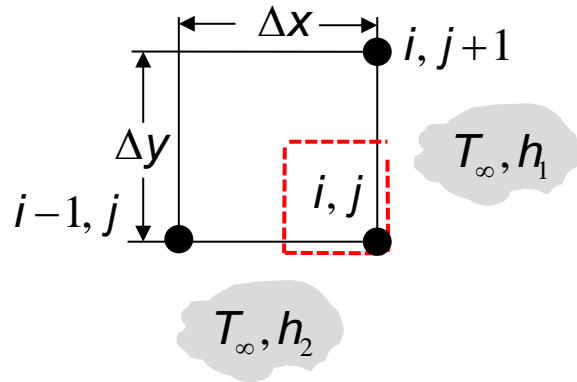
Approximate the temperature field in the walls and study the convergence of the predicted values at selected channel locations.

See also Bergman et al., page 251ff / Incropera et al. page 231ff (different values)

Domain and boundary conditions



Node at an external corner with mixed convection



$$\begin{aligned} & \frac{1}{\Delta x^2} T_{i-1,j} + \frac{1}{\Delta y^2} T_{i,j+1} \\ & - T_{i,j} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{1}{k} \left(\frac{h_1}{\Delta x} + \frac{h_2}{\Delta y} \right) \right) \\ & = -\frac{1}{k} \left(\frac{h_1}{\Delta x} + \frac{h_2}{\Delta y} \right) T_{\infty} \end{aligned}$$

Lower left: $h_1 = h, \quad h_2 = 0$

$$\frac{1}{\Delta x^2} T_{i-1,j} + \frac{1}{\Delta y^2} T_{i,j+1} - T_{i,j} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{h}{k\Delta x} \right) = -\frac{h}{k\Delta x} T_{\infty}$$

Upper right : $h_1 = 0, \quad h_2 = h$

$$\frac{1}{\Delta x^2} T_{i-1,j} + \frac{1}{\Delta y^2} T_{i,j+1} - T_{i,j} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{h}{k\Delta y} \right) = -\frac{h}{k\Delta y} T_{\infty}$$

Matrix organization

$$\begin{array}{c} \text{---} \rightarrow \end{array} \begin{matrix} j \cdot l + i \\ \uparrow \\ (j-1) \cdot l + i \end{matrix} \begin{pmatrix} 1 & 0 & & \dots & & \dots & & 0 \\ & \ddots & & & & & & \\ \dots & 0 & \frac{1}{\Delta y^2} & 0 \dots 0 & \frac{1}{\Delta x^2} & -2 \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} \right) & \frac{1}{\Delta x^2} & 0 \dots 0 & \frac{1}{\Delta y^2} & 0 & \dots \\ & & & \ddots & & & & & & & \\ 0 & & \dots & & \dots & & \dots & & 0 & 1 \end{pmatrix} \begin{pmatrix} T_{0,0} \\ T_{1,0} \\ \vdots \\ T_{i,j-1} \\ \vdots \\ T_{i-1,j} \\ T_{i,j} \\ T_{i+1,j} \\ \vdots \\ T_{i,j+1} \\ \vdots \\ T_{l,j} \end{pmatrix} = \begin{pmatrix} T_s \\ \vdots \\ 0 \\ \vdots \\ T_s \end{pmatrix}$$

Define an index function to transform the 2D solution into a 1D vector:

```
def index(i,j,Nx):
    return j*Nx+i
```

Matrix assembly:

```
A[index(i,j,Nx),index(i,j,Nx)]=-2.0*(dx2i+dy2i)
A[index(i,j,Nx),index(i+1,j,Nx)]=dx2i
A[index(i,j,Nx),index(i-1,j,Nx)]=dx2i
A[index(i,j,Nx),index(i,j+1,Nx)]=dy2i
A[index(i,j,Nx),index(i,j-1,Nx)]=dy2i
C[index(i,j,Nx)]=0.0
```

```
dx2i = 1.0/(dx*dx)
dy2i = 1.0/(dy*dy)
```