

# **SESA6085 – Advanced Aerospace Engineering Management**

Lecture 15

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# Maintenance & Inspection

- An effective maintenance plan can extend the life of a system quite considerably
- But...
  - How often should such maintenance be carried out?
  - How do we keep the system in working order for longer?
  - How do we minimise the cost of such maintenance and repairs?

# Prerequisites

- We can't just tackle the problem of optimal maintenance scheduling head on
- We first need to consider a number of important definitions
  - Mean time to failure
  - Repairable systems
  - Availability
  - Expected number of failures

# Mean Time to Failure

- What is the mathematical definition of the mean time to failure?
- We can also define this as the expected failure time,  $E[T]$ , in the range  $t \in [0, \infty]$
- Mathematically this equates to:

$$\text{MTTF} = E[T] = \int_0^{\infty} t f(t) dt$$

- Or:

$$\text{MTTF} = E[T] = \int_0^{\infty} R(t) dt$$

# Repairable Systems

- We've defined a repairable system as one which is repaired upon failure
- This definition includes large and complex systems e.g. aircraft, cars, mainframes, telephone networks etc.
- The two most important performance criteria for such a system are:
  - Availability of the system
  - Mean time before failure (MTBF)
- Of these two availability is probably the most important

# Expected Number of Failures

# Expected Number of Failures, $M(T)$

- The expected number of failures of a system within a time interval  $[0, T]$  is an extremely useful quantity
  - Defines an optimal preventive maintenance schedule
  - Criterion for reliability of acceptance
    - A production lot is accepted if the number of expected failures is less than a defined limit
  - Defines warranty policies
    - If we have  $M(T)$  expected failures in the time interval  $T$ , then the expected warranty cost  $C(T)$  is

$$C(T) = cM(T)$$

# Expected Number of Failures, $M(T)$

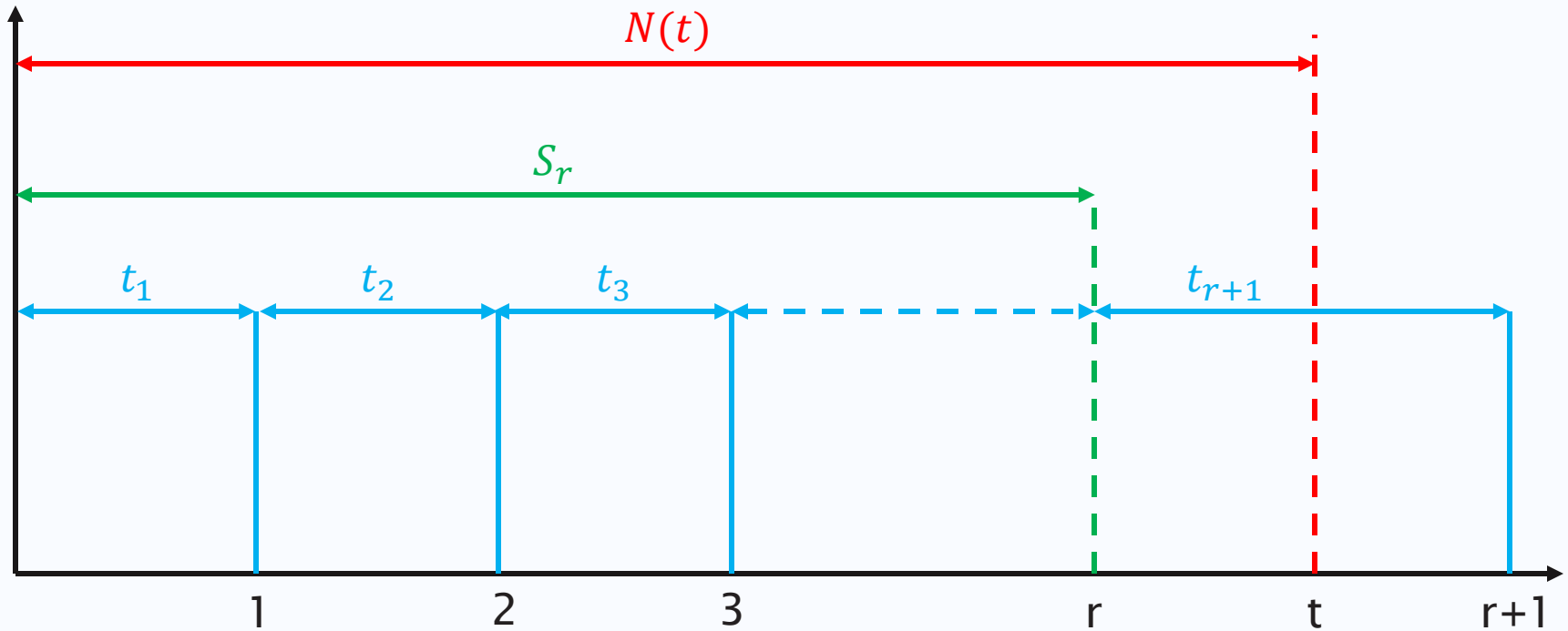
- There are two approaches to calculating  $M(T)$ 
  - *Parametric approach* – the failure-time distribution is known
  - *Nonparametric approach* – the failure-time distribution is unknown and where mean and standard deviation of failure times are known
- In the following we will focus on the parametric approach



# Expected Number of Failures, $M(T)$

- Before beginning lets define some of the notation used
- $N(t)$  – the number of failures in the interval  $[0, t]$
- $M(t)$  – the expected number of failures in the interval  $[0, t]$ , otherwise denoted as  $E[N(t)]$
- $t_i$  – the length of the time interval between failures  $i - 1$  and  $i$
- $S_r$  – the total time up to the  $r^{\text{th}}$  failure -  $S_r = \sum_{i=1}^r t_i$

# Expected Number of Failures, $M(T)$



# Expected Number of Failures, $M(T)$

- The probability of having a number of failures  $N(t) = r$  is the same as the probability that  $t$  lies between the  $r^{\text{th}}$  and  $(r + 1)^{\text{th}}$  failure

$$P[N(t) < r] = 1 - F_r(t)$$

- Where  $F_r(t)$  is the cumulative distribution function of  $S_r$  i.e.  
 $F_r(t) = P[S_r \leq t]$
- Hence:

$$P[N(t) > r] = F_{r+1}(t)$$

# Expected Number of Failures, $M(T)$

- From simple probability theory:

$$P[N(t) < r] + P[N(t) = r] + P[N(t) > r] = 1$$

- Therefore:

$$P[N(t) = r] = F_r(t) - F_{r+1}(t)$$

# Expected Number of Failures, $M(T)$

- Using this we can find an expression for the expected value of  $N(t)$

$$M(t) = E[N(t)] = \sum_{r=0}^{\infty} r P[N(t) = r]$$

$$M(t) = \sum_{r=0}^{\infty} r [F_r(t) - F_{r+1}(t)]$$

$$M(t) = \sum_{r=0}^{\infty} F_r(t)$$

# Expected Number of Failures, $M(T)$

- This expression for  $M(t)$  is termed the renewal function and it can also be written as

$$M(t) = F(t) + \sum_{r=1}^{\infty} F_{r+1}(t)$$

- $F_{r+1}(t)$  is the convolution of  $F_r(t)$  and  $F$  therefore

$$F_{r+1}(t) = \int_0^t F_r(t-x)f(x)dx$$

## Expected Number of Failures, $M(T)$

- Substituting this back into our expression for  $M(t)$  we get:

$$M(t) = F(t) + \sum_{r=1}^{\infty} \int_0^t F_r(t-x)f(x)dx$$

- Which equates to:

$$M(t) = F(t) + \int_0^t M(t-x)f(x)dx$$

- Which is known as the *fundamental renewal equation*

# Renewal Density Equation, $m(t)$

- Although we will not go through its derivation  $M(t)$  can be differentiated to give an expression for the renewal density,  $m(t)$

$$m(t) = f(t) + \int_0^t m(t-x)f(x)dx$$

- We can interpret this as the probability that a renewal occurs between  $[t, t + \Delta t]$



# Solving These Equations

- Both the fundamental renewal equation and the renewal density equation can be solved using Laplace transforms

$$M^*(s) = \frac{f^*(s)}{s[1 - f^*(s)]}$$

$$m^*(s) = \frac{f^*(s)}{1 - f^*(s)}$$

- Where  $f^*(s)$  denotes the Laplace transform of the failure-time PDF

# Example

- Define an expression for the number of failures of a system over the interval  $[0, t]$  described by

$$f(t) = \lambda e^{-\lambda t}$$

- Taking the Laplace transform of the PDF we obtain

$$f^*(s) = \frac{\lambda}{s + \lambda}$$

- Which upon substitution into the renewal density equation gives:

$$m^*(s) = \frac{\lambda}{s + \lambda - \lambda} = \frac{\lambda}{s}$$

# Example

- The Laplace inverse of this equation gives:

$$m(t) = \lambda$$

- Hence the expression for the number of failures in the interval  $[0, t]$  is:

$$M(t) = \int_0^t \lambda dt = \lambda t$$

- For a component with a constant failure rate of  $6 \times 10^{-6}$  per hour we will therefore expect 0.0526 failures over one year

# Calculating $M(t)$

- If we look at our general expression for  $M(t)$ ,

$$M(t) = F(t) + \int_0^t M(t-x)f(x)dx$$

- We can see that the function  $M(t)$  appears on both sides
- Of course, the equations could be solved computationally
- Researchers have investigated ways of approximating this integral

# Discrete Time Approach

- If there is no closed form solution for  $M(t)$  then a discrete time approach may be used where the number of failures at a time period  $T$  is:

$$M(t) = \sum_{i=0}^{T-1} [1 + M(T - i - 1)] \int_i^{i+1} f(t) dt$$

- Where  $M(0) = 0$

# Discrete Calculation Example

- The failure time of a system is normally distributed with mean 4 and standard deviation 1 weeks. Calculate the expected number of failures at the end of week 2

$$M(2) = [1 + M(1)] \int_0^1 f(t)dt + \dots$$
$$[1 + M(0)] \int_1^2 f(t)dt$$

- With  $f(t)$  defined by our known PDF and the integrals calculated using our CDFs

# Discrete Calculation Example

- Calculate the values of  $M(t)$  in order up to the point of interest

$T$	$M(T)$
0	0
1	0.001318
2	0.02272

- Therefore, we expect 0.0227 failures after 2 weeks

# Optimal Maintenance & Inspection



# Maintenance & Inspection

- Now we've got the basic building blocks in place let's consider our problem of defining maintenance and inspection routines
- In this case we're concerned with optimum preventive maintenance, replacements and inspection (PMRI) schedules
- The primary function of such schedules is to control the condition of the system to ensure availability

# Maintenance & Inspection

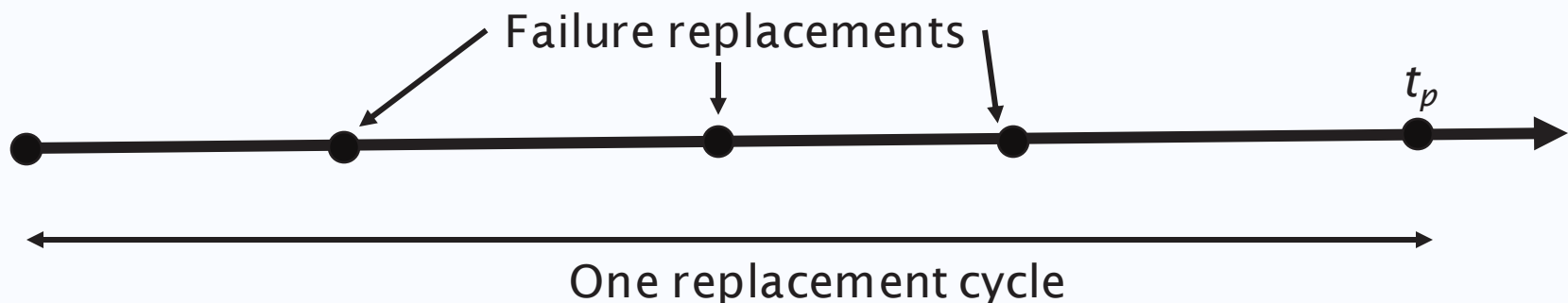
- What do we mean by optimum PRMI?
  - High frequency of PRMI reduces costs due to downtime but increases maintenance costs
  - Low frequency of PRMI reduces maintenance costs but increases costs due to downtime
- Hence there may be a sweet spot for minimum cost
- Other criteria such as availability may drive the optimal schedule

# Cost Minimisation

Constant Interval Replacement

# Cost Minimisation - CIRP

- The simplest preventive replacement policy is where a component is replaced after a constant interval
  - Constant Interval Replacement Policy (CIRP)
- This approach has two actions:
  1. A component is replaced on failure
  2. A component is replaced at a predetermined interval regardless of age



# Cost Minimisation - CIRP

- In order to optimise this function we need some sort of objective
- As we're interested in minimising cost lets use the total replacement cost per unit time

$$c(t_p) = \frac{\text{Total expected cost } [0, t_p]}{\text{Length of the interval}}$$

- The total cost consists of:
  - The cost of preventative replacement
  - The expected cost of failure replacements

# Cost Minimisation - CIRP

- During the interval  $[0, t_p]$  we therefore have
  - A single preventative replacement of cost,  $c_p$
  - $M(t_p)$  failure replacements of cost,  $c_f$  each
  - We already know our expected interval length is  $t_p$
- Hence:

$$c(t_p) = \frac{c_p + c_f M(t_p)}{t_p}$$

# CIRP Example

- A bearing in a rotating shaft wears out according to a normal distribution with a mean of  $1 \times 10^6$  cycles and standard deviation of  $1 \times 10^5$  cycles
- The cost of preventative replacement is \$50
- The cost of failure replacement \$100
- Assuming discrete time intervals of  $1 \times 10^5$  cycles determine the optimum replacement interval
- How do we proceed?

# CIRP Example

- First define a list of discrete intervals
- Next use the PDF to calculate  $M(t_p)$  at each interval
- Use the costs along with  $M(t_p)$  and  $t_p$  to calculate the cost per interval



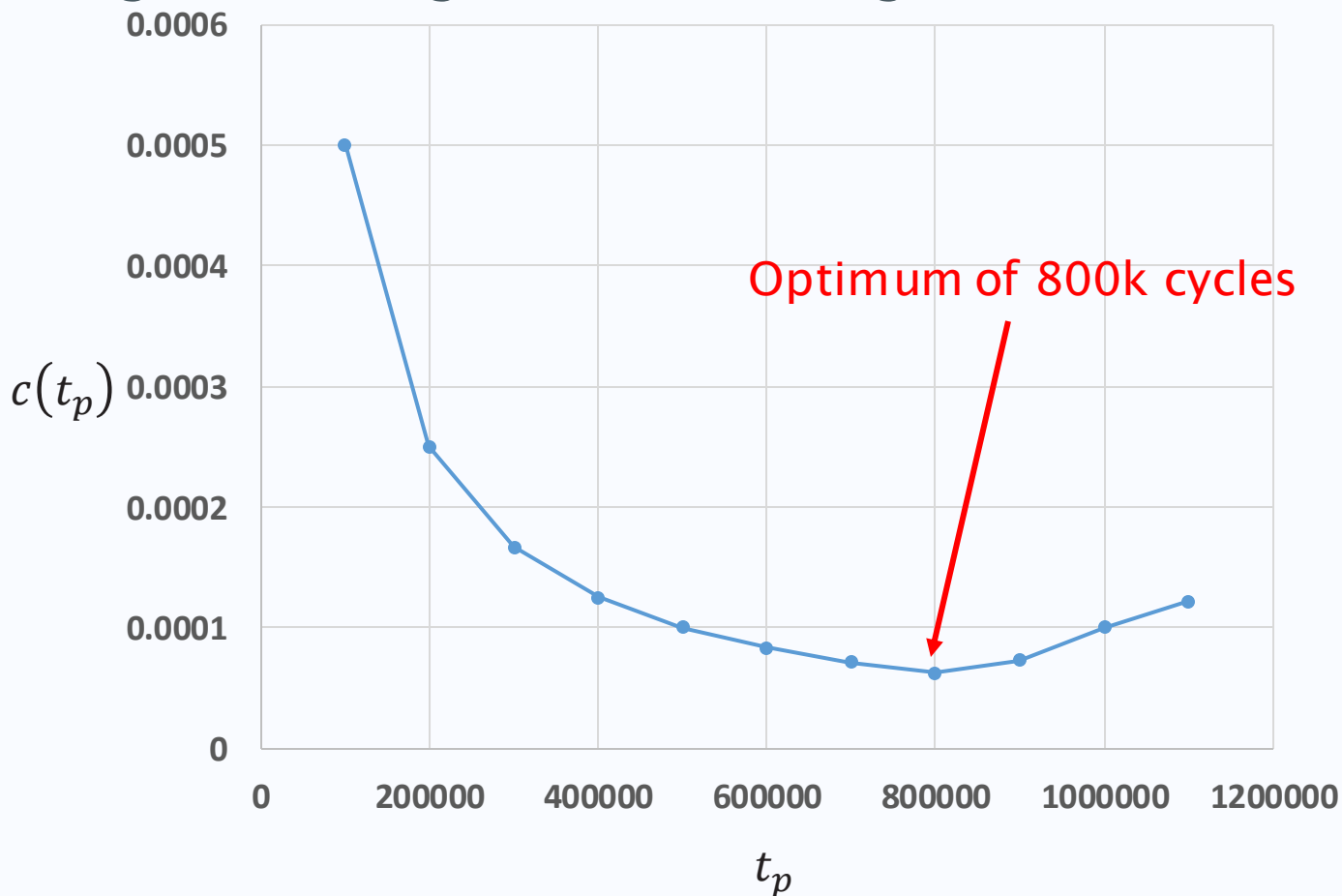
# CIRP Example

- Doing so for the first 11 intervals gives

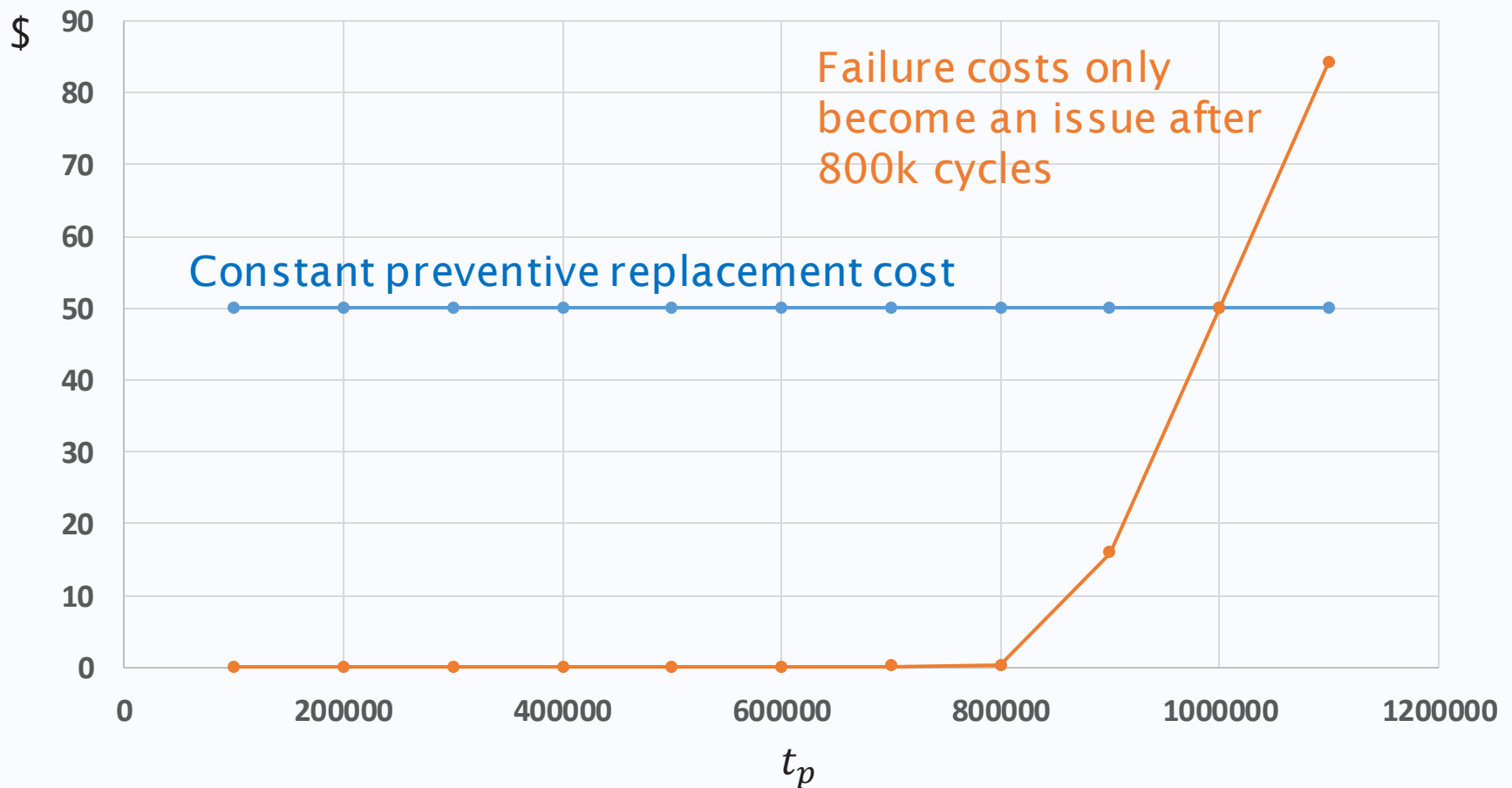
$t_p$	$M(t_p)$	$c(t_p)$
100,000	0	0.000500
200,000	0	0.000250
300,000	0	0.000166
400,000	0	0.000125
500,000	0	0.000100
600,000	0	0.000083
700,000	0.00140	0.000072
800,000	0.00275	0.000065
900,000	0.15875	0.000073
1,000,000	0.50005	0.0001
1,100,000	0.84135	0.000121

# CIRP Example

- Plotting this result gives the following...



# CIRP Example



# Cost Minimisation

Replacement at Predetermined Age

# Replacement at Predetermined Age

- CIRP may result in preventative replacements being performed shortly after failure replacements
- Replacement at predetermined age is a slightly different preventative policy
- Under this policy:
  - Components are replaced on failure
  - Components are replaced after a set age,  $t_{pa}$
  - Or whichever comes first

# Replacement at Predetermined Age

- As before we need to select the length of time,  $t_{pa}$ , in order to minimise the cost of the preventative maintenance
- As before we therefore need some form of objective function to minimise
- Again, we'll use a cost per unit time

$$c(t_{pa}) = \frac{\text{Total expected replacement cost per cycle}}{\text{Expected length of cycle}}$$

# Replacement at Predetermined Age

- As noted previously we have two modes of operation
  1. The component reaches  $t_{pa}$  and is replaced
  2. The component fails before  $t_{pa}$  and is replaced
- The numerator in our above equation includes:
  - The cost of preventative replacement  $\times$  the probability of survival to  $t_{pa}$
  - The cost of failure replacement  $\times$  the probability of failure before  $t_{pa}$
  - Note that the expected number of failures is not present because we restart our cycle from the time of a failure

# Replacement at Predetermined Age

- The numerator is therefore:

$$c_p R(t_{pa}) + c_f [1 - R(t_{pa})]$$

- The denominator is defined from:
  - Length of a preventive cycle times the probability of that cycle
  - Expected length of a failure cycle times the probability of a failure cycle



# Replacement at Predetermined Age

- This gives us the following denominator

$$t_{pa}R(t_{pa}) + [1 - R(t_{pa})] \int_{-\infty}^{t_{pa}} tf(t)dt$$

- And finally, an expression for the cost per unit time

$$c(t_{pa}) = \frac{c_p R(t_{pa}) + c_f [1 - R(t_{pa})]}{t_{pa} R(t_{pa}) + [1 - R(t_{pa})] \int_{-\infty}^{t_{pa}} tf(t)dt}$$

- Our optimum is therefore the value of predetermined age which gives us the lowest cost per cycle

# Predetermined Age Example

- Previously in the CIRP example we considered a shaft with failure-time described by a normal distribution with a mean of  $1 \times 10^6$  cycles and standard deviation of  $1 \times 10^5$  cycles
- The cost of preventative replacement is \$50
- The cost of failure replacement \$100
- For CIRP we saw an optimum  $t_p$  of 800,000 cycles
- What is the predetermined age,  $t_{pa}$ , for this case?
- How to proceed?

# Predetermined Age Example

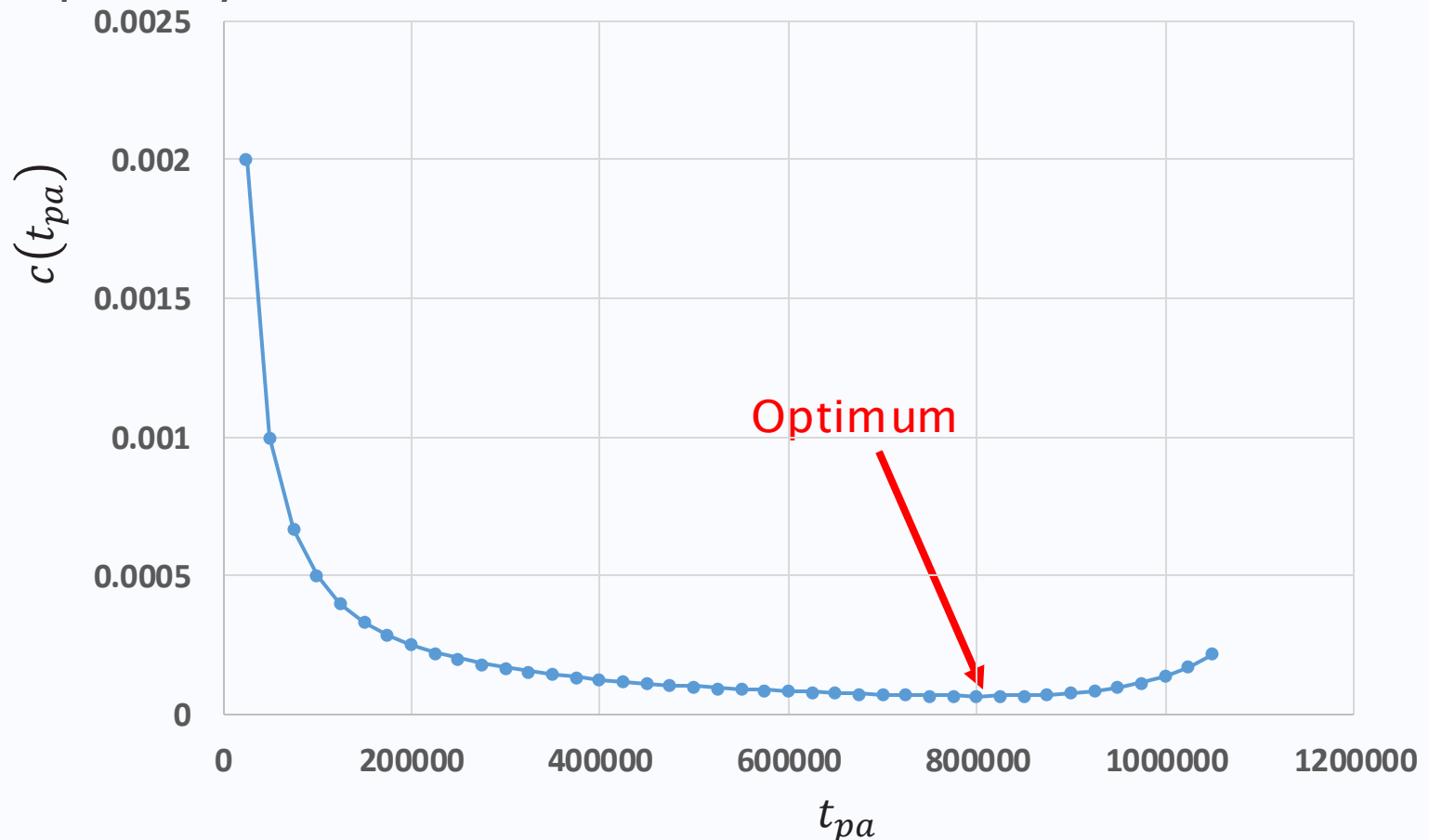
- Define a range of  $t_{pa}$  to consider
- Calculate  $R(t_{pa})$ ,  $F(t_{pa})$ ,  $f(t_{pa})$  and  $\int_{-\infty}^{t_{pa}} tf(t)dt$
- Calculate the numerator and denominator
- Finally calculate  $c(t_{pa})$
- Select the value of  $t_{pa}$  which gives the minimum
- How can we calculate  $\int_{-\infty}^{t_{pa}} tf(t)dt$ ?
  - Matlab or Python can be used but a very simple trapezoidal approach will suffice

# Predetermined Age Example

$t_{pa}$	$f(t_{pa})$	$F(t_{pa})$	$R(t_{pa})$	$c(t_{pa})$
0	7.69e-28	7.62e-24	1.0	
100,000	1.03e-23	1.12e-19	1.0	0.0005
200,000	5.05e-20	6.22e-16	1.0	0.00025
300,000	9.13e-17	1.28e-12	1.0	0.000167
400,000	6.08e-14	9.87e-10	1.0	0.000125
500,000	1.49e-11	2.87e-7	1.0	0.0001
600,000	1.34e-9	3.17e-5	0.99997	8.33E-05
700,000	4.43e-8	0.00135	0.99865	7.16E-05
800,000	5.40e-7	0.02275	0.97725	6.54E-05
900,000	2.42e-6	0.15866	0.84135	7.45E-05
1,000,000	3.99e-6	0.5	0.5	0.000115
1,100,000	2.42e-6	0.84134	0.15866	0.000203

# Predetermined Age Example

- Graphically...



# Downtime Minimisation

# Downtime Minimisation

- There are many situations where availability is much more important than the cost of repair or maintenance
  - In such cases the consequences of any downtime may exceed any measurable cost
- In these cases, it's more appropriate to minimise the total downtime experienced by the system
- In such cases the equations to be minimised take a very similar form to those for cost minimisation
  - We consider time to replace instead of cost to replace

# CIRP Downtime Minimisation

- The total downtime is due to...
  - Downtime due to failure
  - Downtime due to preventive replacement

$$D_{CIRP}(t_p) = \frac{M(t_p)T_f + T_p}{T_p + t_p}$$

$T_f$  - time to perform a replacement after failure

$T_p$  - time to perform a preventive replacement

$M(t_p)$  - Expected number of failures in the interval,  $[0, t_p]$

- The goal is to find an interval,  $t_p$ , which minimises this function



# Predetermined Age Downtime Minimisation

- As before this policy involves:
  - Replacement when a component fails
  - Replacement when a component reaches its planned replacement age

$$D_{ARP}(t_{pa}) = \frac{T_p R(t_{pa}) + T_f [1 - R(t_{pa})]}{(t_{pa} + T_p) R(t_{pa}) + \left[ \int_{-\infty}^{t_{pa}} t f(t) dt + T_f \right] [1 - R(t_{pa})]}$$

# Other Approaches



# Other Approaches & Models

- There are of course numerous other models for preventative repair and maintenance
- Minimal number of spares
- Minimal repair models:
  - Assume that the system is no longer as good as new after a repair
- Systems subject to shocks:
  - Apply to systems which are subject to shocks causing cumulative damage



# Other Approaches & Models

- Group maintenance
  - Considers the maintenance of a group of similar machines at once
  - This may be more economical than considering each machine separately
- Periodic inspection
  - Reliability can be improved further by coupling preventative maintenance with periodic inspection
- Condition monitoring or condition-based maintenance
  - Replacement when an indicator says failure is imminent

