

## Lecture 12 - Laplace transform properties and solution methods

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- 2 Laplace Transform Properties
  - Properties
  - Examples and methods
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## 1 Review

## 2 Laplace Transform Properties

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# Review

- Definition of Laplace Transform (LT):

$$\mathcal{L}[f(x)] = \tilde{f}(\overset{\text{frequency}}{s}) = \int_0^{\infty} f(x) e^{-sx} dx.$$

- First shift theorem:

$$\mathcal{L}[e^{-ax} f(x)] = \tilde{f}(s+a)$$

- Laplace Transform of Derivatives:

$$\mathcal{L}\left[\frac{df}{dx}\right] = s\tilde{f}(s) - f(0)$$

$$\mathcal{L}\left[\frac{d^2f}{dx^2}\right] = s^2\tilde{f}(s) - sf(0) - f'(0)$$

- List of known basic examples (you need to know them by heart!):

not all on formula sheet

$$\mathcal{L}[e^{ax}] = \frac{1}{s-a}$$

$$\mathcal{L}[\sin(ax)] = \frac{a}{s^2 + a^2},$$

$$\mathcal{L}[\cos(ax)] = \frac{s}{s^2 + a^2}$$

$$\mathcal{L}[1] = \frac{1}{s} \quad [\text{Today's lecture}]$$

$$\mathcal{L}[x] = \frac{1}{s^2} \quad [\text{Today's lecture}]$$

$$\mathcal{L}[x^n] = \frac{n!}{s^{n+1}} \quad [\text{Today's lecture}]$$

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## → Laplace Transform Properties: Linearity

The Laplace transform is linear:

if  $\mathcal{L}[f_{1,2}(x)] = \tilde{f}_{1,2}(s)$  and  $\mu_{1,2}$  are constants then

$$\mathcal{L}[\mu_1 f_1(x) + \mu_2 f_2(x)] = \mu_1 \tilde{f}_1(s) + \mu_2 \tilde{f}_2(s).$$

# LT Properties: Products or derivatives

The Laplace transform of  $x f(x)$  is related to the derivative of the LT as

$$\mathcal{L}[x f(x)] = -\frac{d\tilde{f}}{ds}$$

**Proof:** differentiating the definition of the Laplace transform:

$$\begin{aligned}
 \mathcal{L}[f(x)] &= \int_0^{\infty} dx e^{-sx} f(x) \\
 x \frac{d}{ds} \quad \left( \frac{d\tilde{f}}{ds} \right) &= \frac{d}{ds} \int_0^{\infty} f(x) e^{-sx} dx \\
 &= \int_0^{\infty} f(x) \left( \frac{d}{ds} e^{-sx} \right) dx \quad \text{can do this since } s \text{ and } x \text{ are independent.} \\
 &= - \int_0^{\infty} x f(x) e^{-sx} dx \quad \text{just differentiation with respect to } s \\
 \frac{d\mathcal{L}[f(x)]}{ds} &= \frac{d\tilde{f}}{ds} = -\mathcal{L}[x f(x)]. \quad \text{rearrange terms of Lap trans}
 \end{aligned}$$

## Example

As an example we can use the result

$$\mathcal{L}[1] = \int_0^{\infty} 1 e^{-sx} dx = \left[ -\frac{1}{s} e^{-sx} \right]_0^{\infty} = \frac{1}{s}$$

to compute

$$\mathcal{L}[x] = \mathcal{L}[1 \times x] = -\frac{d}{ds} \mathcal{L}[1] = \frac{1}{s^2}$$

and by induction

$$\mathcal{L}[x^2] = \frac{2}{s^3} \dots$$

$$\mathcal{L}[x^n] = \frac{n!}{s^{n+1}}$$

This is proved by repeating above

∴ using linearity and any polynomial can be found

assuming  $x > 0$

this identity

$$\therefore -\frac{d}{ds} \frac{1}{s} = \frac{1}{s^2}$$



We often have functions depending on parameters or constants, such as  $\sin(ax)$ . A useful trick is to note that

$$\mathcal{L} \left[ \frac{\partial f}{\partial a} \right] = \frac{\partial \tilde{f}}{\partial a} \quad [\leftarrow \mathcal{L}[f(x)] = \tilde{f}(s)]$$

**Proof:** As the integrals in the definition do not depend on the parameter  $a$  at all, the partial derivative commutes with the integrals:

$$\mathcal{L} \left[ \frac{\partial f}{\partial a} \right] = \int_0^{\infty} \frac{\partial f}{\partial a} e^{-sx} dx = \frac{\partial}{\partial a} \int_0^{\infty} f(x) e^{-sx} dx = \frac{\partial}{\partial a} \tilde{f}.$$

*a is independent*

# LT Properties: An odd corollary

For integral equations, or strange inversion problems, the following is useful:

$$\mathcal{L} \left[ \int_0^x f(z) dz \right] = \frac{1}{s} \mathcal{L} [f(x)].$$

**Proof:** This requires an unusual integration by parts step. Start from

$$\mathcal{L} [f(x)] = \int_0^\infty \overbrace{e^{-sx}}^u \overbrace{f(x)dx}^{dv} \quad \longleftarrow \quad dv = f(x)dx \Rightarrow v = \int_0^x f(z) dz$$

Now perform the unusual integration by parts:

$$\begin{aligned} & \left( \checkmark \int_A^B u dv = [uv]_A^B - \int_A^B v du \right) \\ &= \left[ \overbrace{e^{-sx}}^u \overbrace{\int_0^x f(z) dz}^v \right]_0^\infty - \int_0^\infty \left[ \overbrace{(-s e^{-sx})}^{du} \overbrace{\int_0^x f(z) dz}^v \right] dx \\ &= 0 + s \mathcal{L} \left[ \int_0^x f(z) dz \right]. \end{aligned}$$

At the **lower bound** ( $x = 0$ ) the integral vanishes, and at the **upper bound** we assume that the **integral of  $f$  is bounded**, and so the **decaying exponential kills this term too**.

# LT Properties: Examples and methods

With LT properties we bagged we can **solve ODEs indirectly**. For example:

**BVP:**  $y'' + 2y' + 5y = 2 + 5x$ ;  $y(0) = 0$ ,  $y'(0) = 3$ . *since are known!*

Taking Laplace transform of the ODE & (considerable) rearrangement:

$$\mathcal{L}[y''] + 2\mathcal{L}[y'] + 5\mathcal{L}[y] = 2\mathcal{L}[1] + 5\mathcal{L}[x]$$

$$\begin{cases} \mathcal{L}[y''(x)] = s^2 \tilde{y}(s) - s y(0) - y'(0) \\ \mathcal{L}[y'(x)] = s \tilde{y}(s) - y(0) \end{cases}$$

$$\Leftrightarrow \tilde{y}(s^2 + 2s + 5) = 3 + \frac{2}{s} + \frac{5}{s^2} \Rightarrow \tilde{y}(s) = \frac{1}{s^2} + \frac{2}{(s+1)^2 + 4}$$

*intermittent step*  
*sub and simplification*  
*Arrange to partial fractions to simplify using  $y = \frac{As+B}{s^2+2s+5}$*

To invert  $\tilde{y}(s)$  and get  $y(x)$ , we use **known results** & the **first shift theorem**:  $\frac{As+B}{s^2+2s+5}$

$$\tilde{y}(s) = \frac{1}{s^2} + \frac{2}{(s+1)^2 + 2^2} = \mathcal{L}[x] + \mathcal{L}[e^{-x} \sin(2x)]$$

$$\Rightarrow y(x) = x + e^{-x} \sin(2x)$$

*inverse linearity*  
*identity used*

$$\begin{cases} \mathcal{L}[x] = \frac{1}{s^2} \\ \mathcal{L}[\sin(ax)] = \frac{a}{s^2 + a^2} \\ \mathcal{L}[e^{-\beta x} f(x)] = \tilde{f}(s+\beta) \end{cases}$$

*identity used + first shift theorem*

1st shift theorem  $[a = 2, \beta = 1]$

We used:  $\mathcal{L}[\sin(ax)] = \frac{a}{s^2 + a^2} = \tilde{f}(s)$  &  $\frac{a}{(s+\beta)^2 + a^2} = \tilde{f}(s+\beta) = \mathcal{L}[e^{-\beta x} \sin(ax)]$

# LT Properties: systematic approach using Partial fractions

There is a systematic approach to solve ODEs using LT in such a way that we can invert the LT of the ODE  $\tilde{y}(s)$  to get the solution  $y(t)$  of the original BVP.

- Step 1: If possible, rearrange  $\tilde{y}(s)$  in the partial fractions form:

$$\begin{aligned}\tilde{y}(s) &= \frac{\text{Numerator (a Rational Polynomial)}}{(s+a_1)(s+a_2)^2 \cdots (s+a_n)^n [(s+c)^2+b^2] [(s+\alpha)^2+\beta^2]} \\ &= \frac{C_1}{s+a_1} + \frac{C_2}{(s+a_2)^2} + \cdots + \frac{C_n n!}{(s+a_n)^n} + \frac{K_1 b}{(s+c)^2+b^2} + \frac{K_2 s}{(s+\alpha)^2+\beta^2}\end{aligned}$$

- Step 2: use known results & 1st shift theorem to invert  $\tilde{y}(s)$  & get  $y(x)$ :

$$\tilde{y}(s) \sim \underbrace{\frac{1}{s+a}}_{\rightarrow \mathcal{L}[e^{-ax}]} + \underbrace{\frac{1}{(s+a)^2}}_{\rightarrow \mathcal{L}[x e^{-ax}]} + \underbrace{\frac{n!}{(s+a)^n}}_{\rightarrow \mathcal{L}[x^{n-1} e^{-ax}]} + \underbrace{\frac{b}{(s+c)^2+b^2}}_{\rightarrow \mathcal{L}[e^{-cx} \sin(bx)]} + \underbrace{\frac{s}{(s+\alpha)^2+\beta^2}}_{\rightarrow \mathcal{L}[e^{-\alpha x} \cos(\beta x)]}.$$

We can always write the denominator of a rational polynomial as a product of (powers of) linear and (irreducible) quadratic terms by finding its (real) roots. For example,

$$s^2 + 2\alpha s + C^2 = s^2 + 2\alpha s + \alpha^2 + (C^2 - \alpha^2) = (s + \alpha)^2 + \underbrace{(C^2 - \alpha^2)}_{\beta^2} \equiv (s + \alpha)^2 + \beta^2$$

# LT Properties: Partial fractions examples

$$\text{BVP: } y'' + 3y' + 2y = x + e^{-x}; \quad y(0) = 0, \quad y'(0) = 0.$$

Taking the Laplace Transform of the ODE gives

$$\mathcal{L}[y'' + 3y' + 2y] = \mathcal{L}[x + e^{-x}] \quad \checkmark \text{ Linearity: } \mathcal{L}[\alpha f(x) + \beta g(x)] = \alpha \mathcal{L}[f(x)] + \beta \mathcal{L}[g(x)]$$

$$\mathcal{L}[y''] + 3\mathcal{L}[y'] + 2\mathcal{L}[y] = \mathcal{L}[x] + \mathcal{L}[e^{-x}] \quad \checkmark \begin{cases} \mathcal{L}[y''(x)] = s^2 \tilde{y}(s) - s y(0) - y'(0) \\ \mathcal{L}[y'(x)] = s \tilde{y}(s) - y(0) \end{cases}$$

$$\Leftrightarrow \tilde{y}(s^2 + 3s + 2) = \frac{1}{s^2} + \frac{1}{s+1} \quad \Leftrightarrow \tilde{y}(s+2)(s+1) = \frac{1}{s^2} + \frac{1}{s+1}.$$

$$\nearrow \text{Quadratic equation: } a s^2 + b s + c = 0 \Rightarrow s = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

The required partial fraction is (Exercise: check at home using next slide!)

$$\tilde{y}(s) = \frac{1 + s + s^2}{s^2(s+1)^2(s+2)} = -\frac{3}{4} \underbrace{\frac{1}{s}}_{\mathcal{L}[1]} + \frac{3}{4} \underbrace{\frac{1}{s+2}}_{\mathcal{L}[e^{-2x}]} + \frac{1}{2} \underbrace{\frac{1}{s^2}}_{\mathcal{L}[x]} + \underbrace{\frac{1}{(s+1)^2}}_{\mathcal{L}[x e^{-x}]}.$$

Inverting this LT  $\tilde{y}(s)$  we get the solution  $y(x)$  of the BVP:

$$y(x) = -\frac{3}{4} + \frac{3}{4} e^{-2x} + \frac{1}{2} x + x e^{-x}.$$

# LT Properties: be best friends with Partial Fractions !

To actually do the partial fractions we write out the most general possibility:

$$\frac{1 + s + s^2}{s^2(s+1)^2(s+2)} = \frac{as+b}{s^2} + \frac{cs+d}{(s+1)^2} + \frac{f}{(s+2)}.$$

Multiply both sides by the denominator:

$$1 + s + s^2 = (as+b)(s+1)^2(s+2) + (cs+d)s^2(s+2) + fs^2(s+1)^2.$$

You then have two routes. One is to expand both sides and match terms in powers of  $s$ . The other is to note that this must hold for all  $s$  and pick particular values of  $s$  to find constraints. For large problems the second approach is faster.

There are three obvious choices: the roots  $s = -2, 0, 1$ :

$$\begin{array}{lll} s = -2 : & 3 = 4f & \Rightarrow f = 3/4, \\ s = 0 : & 1 = 2b & \Rightarrow b = 1/2, \\ s = -1 : & 1 = d - c & \Rightarrow d = c + 1. \end{array}$$

At this point we have no more “easy” values to choose, so try say  $s = 1$  and  $s = 2$  to get

$$\begin{array}{ll} 3 = 12(a+b) + 3(c+d) + 4f & = 12a + 6c + 12 \\ 7 = 36(2a+b) + 16(2c+d) + 36f & = 72a + 48c + 61, \end{array}$$

which imply that  $a = -3/4$  and  $c = 0$ , giving  $d = 1$ .

A final property - a negative result - is that

$$\mathcal{L}[f(x) \times g(x)] \neq \mathcal{L}[f(x)] \times \mathcal{L}[g(x)].$$

This should be clear from earlier results; e.g.

$$\mathcal{L}[x] = \frac{1}{s^2}, \quad \mathcal{L}[x^2] = \frac{2}{s^3} \neq \mathcal{L}[x] \times \mathcal{L}[x].$$

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- We derived many **key properties of Laplace Transforms**:

$$\mathcal{L} [\mu_1 f_1(x) + \mu_2 f_2(x)] = \mu_1 \tilde{f}_1(s) + \mu_2 \tilde{f}_2(s).$$

$$\mathcal{L} [x f(x)] = -\frac{d\tilde{f}}{ds}$$

$$\mathcal{L} \left[ \frac{\partial f}{\partial a} \right] = \frac{\partial \tilde{f}}{\partial a}$$

$$\mathcal{L} \left[ \int_0^x f(u) du \right] = \frac{1}{s} \mathcal{L} [f(x)].$$

- The **use of partial fractions** is often essential in inverting Laplace Transforms  $\tilde{f}(s) = \mathcal{L} [f(x)]$  to get  $f(x)$ .
- Practice is really useful  
... actually it is fundamental no matter how good you are!