AIRCRAFT STRUCTURAL DESIGN SESA3026

3. Aircraft Loads

3.1 Introduction, Symmetric Manoeuvre Loads

Dr. Susmita Naskar

Email: S.Naskar@soton.ac.uk

Course Content

- ☐ Chapter 1 Aircraft structural design
- ☐ Chapter 2 Wing structural details
- ☐ Chapter 3 Aircraft loads

Part 1: Introduction, Symmetric Manoeuvre Loads

- Part 2: Tail Loads, Gust Loads
- Part 3: Total Loading on the Wing
- Part 4: Comparison of Full Load and Light Load Cases

■ ADR

- ☐ Chapter 4 Fatigue of aircraft structures
- ☐ Chapter 5 Effects of dynamic response
- ☐ Chapter 6 Static aeroelasticity
- ☐ Chapter 7 Dynamic aeroelasticity

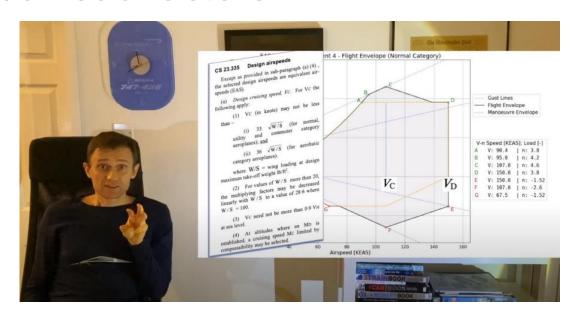
Learning Outcomes

By the end of this section, you will be able to

- Appreciate the loading actions acting on an aircraft
- https://www.southampton.ac.uk/courses/modules/sesa3026#aims_a nd_objectives
- Derive the load factor for a symmetric manoeuvre
- Illustrate the V-n diagram, explain the main features, and identify critical points of the flight envelope

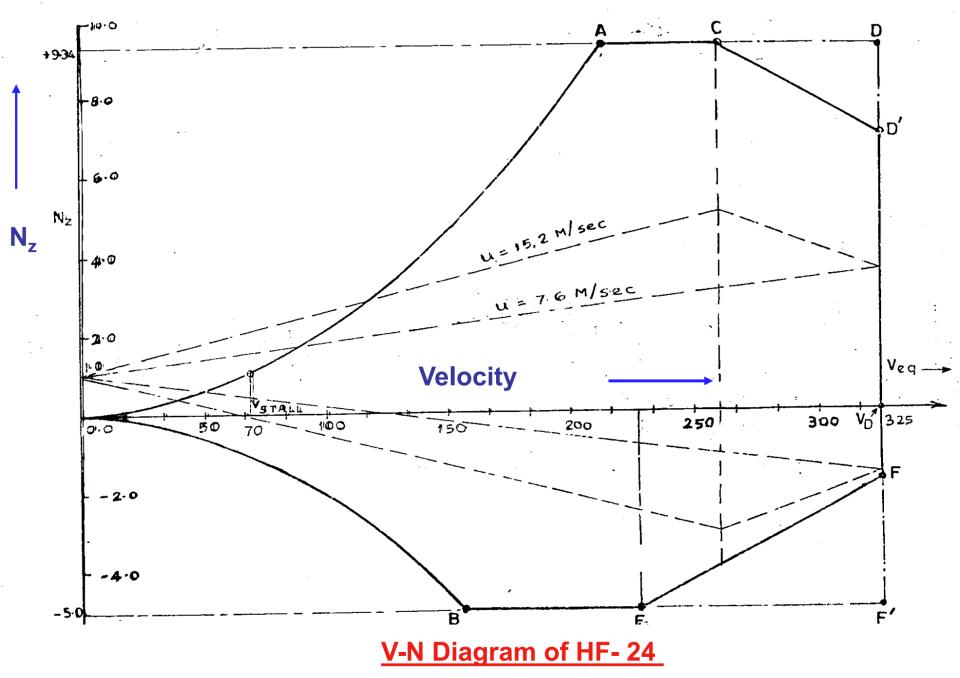
V-N Diagram

- V-N diagram definition
- a/c Load factors

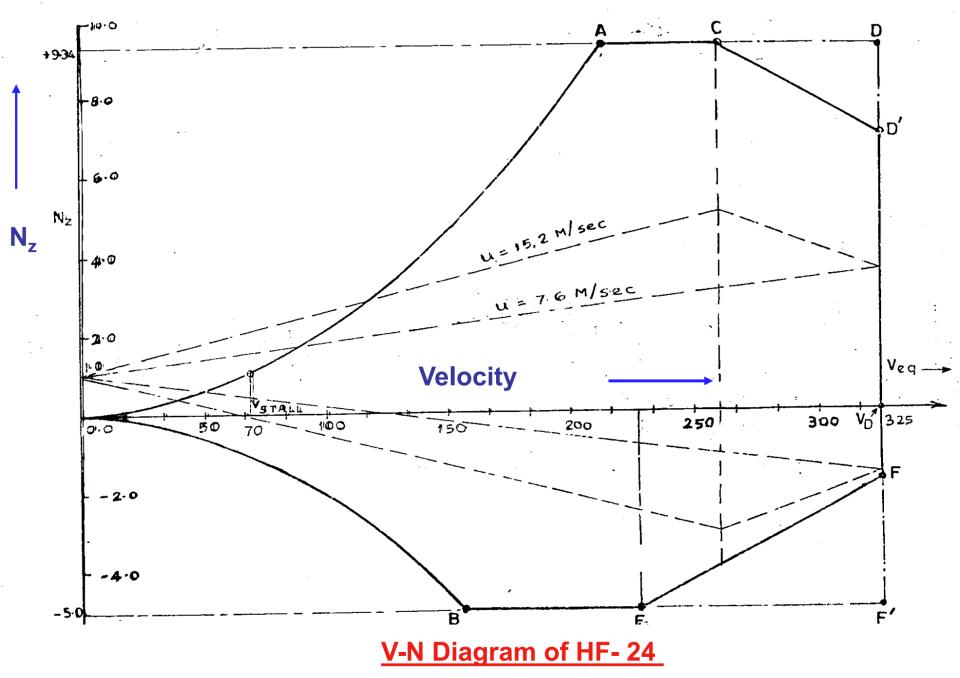


Must see: Prof. Sobester's video on V-n diagrams

https://www.youtube.com/watch?v=s-d5z-BQovY&ab_channel=AndrasSobester



V-N diagram is a graph of a/c velocity and the load factor



V-N diagram is a graph of a/c velocity and the load factor

Aircraft Load Factors

Load factor is defined as the ratio of net force acting in a direction and a/c weight.

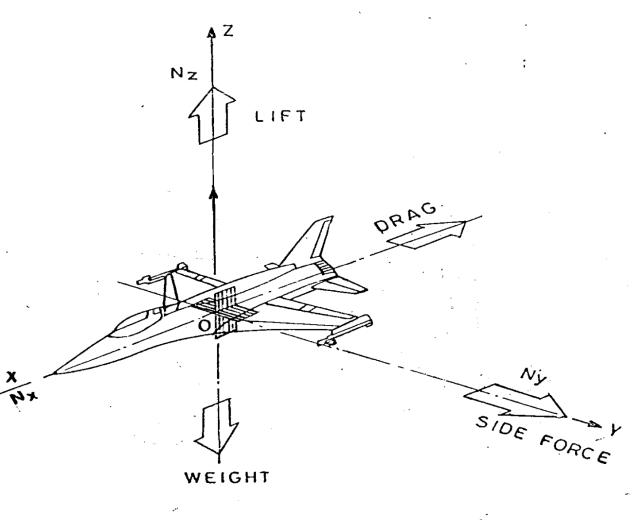
$$N = \frac{F}{W}$$
: $F = Net Force$

in a direction

There are three kinds of a/c load factors

 N_x , N_y , and N_z





Aircraft Load Factors

Load factor is defined as the ratio of net force acting in a direction and a/c weight.

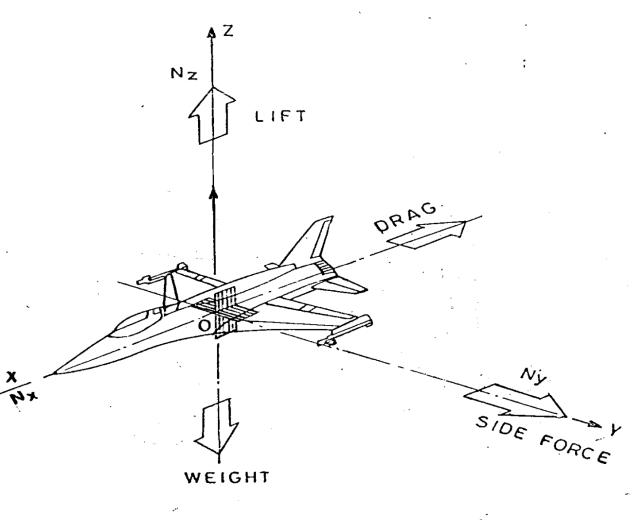
$$N = \frac{F}{W}$$
: $F = Net Force$

in a direction

There are three kinds of a/c load factors

 N_x , N_y , and N_z





Some General Points

V-N diagram is applicable only for symmetrical maneuvers in the vertical planes. Why?

Because N_z has the highest numerical value and in symmetrical maneuvers in vertical plane N_x & N_v remain constant.

V-N diagram is drawn only for N₂. Why?

Because the numerical values of N_x , N_y are small and can't lead to structural damage to a/c if they are too high.

Some General Points

V-N diagram is applicable only for symmetrical maneuvers in the vertical planes. Why?

Because N_z has the highest numerical value and in symmetrical maneuvers in vertical plane N_x & N_v remain constant.

V-N diagram is drawn only for N₂. Why?

Because the numerical values of N_x , N_y are small and can't lead to structural damage to a/c if they are too high.

It can be seen that $N_z \propto V^2$ and (AOA) How?

$$\mathbf{N} = \frac{\mathbf{L}}{\mathbf{W}}$$

$$L=1/2\rho_{\infty}v^{2}_{\infty}SC_{L}$$

$$L=1/2\rho_{\infty}v^{2}_{\infty}S(AOA)a_{0}$$

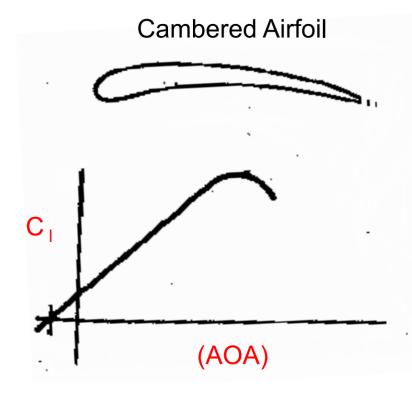
where

$$\rho_{\infty}$$
 =density of air C_1 = Lift Coefficient

 a_0 = Lift curve slope

Thus N_z and N_z

: Lift



$$\mathbf{N} = \frac{\mathbf{L}}{\mathbf{W}}$$

$$L=1/2\rho_{\infty}v^{2}_{\infty}SC_{L}$$

$$L=1/2\rho_{\infty}v^{2}_{\infty}S(AOA)a_{0}$$

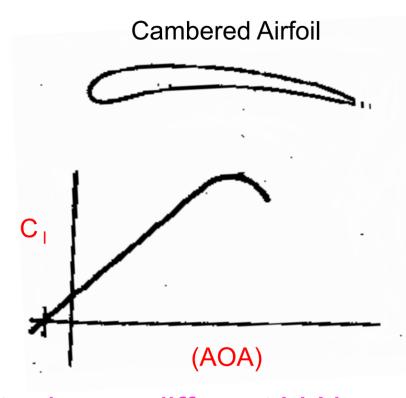
where

$$\rho_{\infty}$$
 =density of air C_1 = Lift Coefficient

a₀ = Lift curve slope

Thus N_z α ρ V^2 and N_z α (AOA)

: Lift



But this would imply that we need to draw a different V-N diagram for every possible altitude.

So how do we eliminate this problem?

Equivalent Airspeed is used in calculations instead of True airspeed as found by Pitot-Static tube

- The velocity (True Airspeed [TAS]) indicated by the Airspeed Indicator is proportional to dynamic pressure
- Taking into account the errors in calibrated instruments we get the calibrated airspeed [CAS].
- And after taking into considerations the compressibility effects we get Equivalent airspeed [EAS] (so it is that speed at which the a/c would be flying at sea level under same conditions of pressure and temp.)
- By using this <u>equivalent speed</u> the variable 'ρ' can be eliminated

• So
$$N_z$$
 α AOA α V_{eq}^2 ONLY

Aircraft Loads



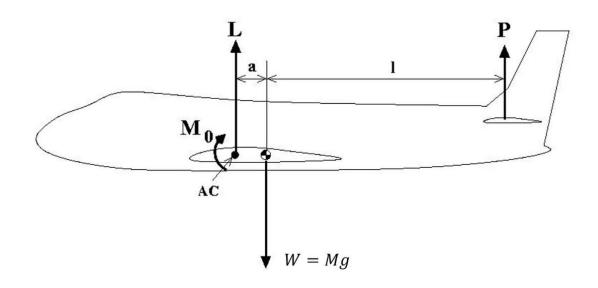
Each of these loading types are covered by various regulations

- This course: symmetric loads due to
- ✓ Manoeuvres
- ✓ gusts

- Aerodynamic forces
- Self-weight
- Manoeuvres
- Taxiing
- Towing
- Crash landing



The Load Factor

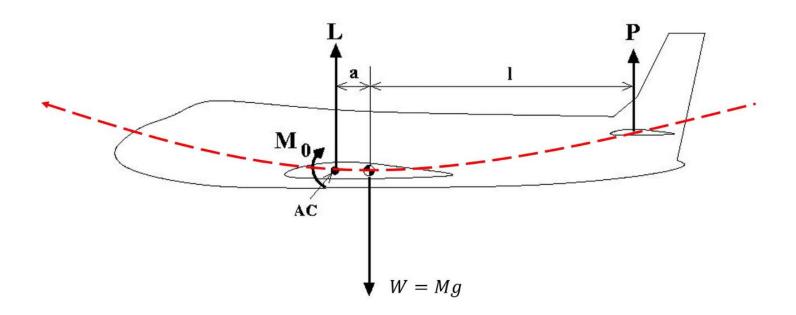


Equilibrium vertical direction:

$$L + P = Mg$$

= nW

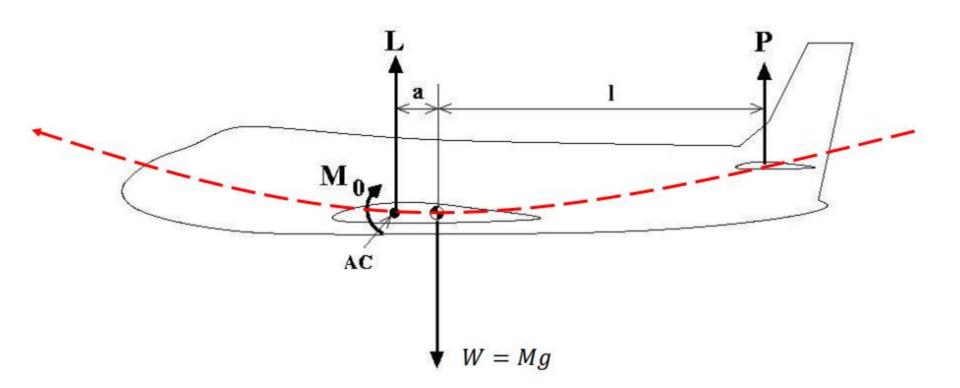
The Load Factor



Equilibrium vertical direction:

$$L + P = Mg + \underline{Ma_i} = Mg\left(1 + \frac{a_j}{g}\right) = nW$$

The Load Factor



Equilibrium vertical direction:

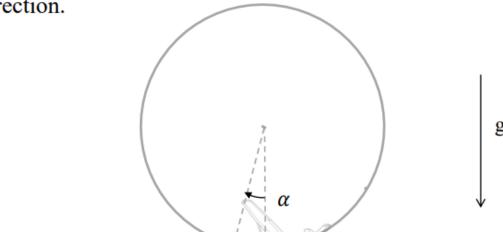
$$L + P = Mg + \underline{Ma_i} = Mg \left(1 + \frac{a_j}{g} \right) = nW$$

Load factor: n

Maximum Load Factor

Example in a circular loop

Derive the analytical formulation that relates the load factor, n, to the aircraft angular position, α , when performing the loop sketched below. Then, indicate the point in which n is maximum and minimum. The gravity field acts in the downward direction.



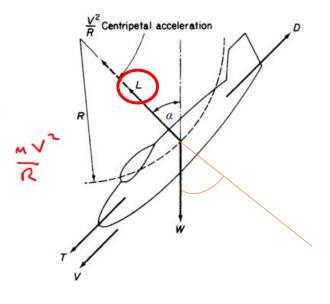
Consider the sketch shown on the right

1. Write equilibrium of forces in radial direction

2. Load factor

$$\frac{L}{W} = \frac{V^2}{gR}$$

$$n = \omega_S x + \frac{V}{gR}$$



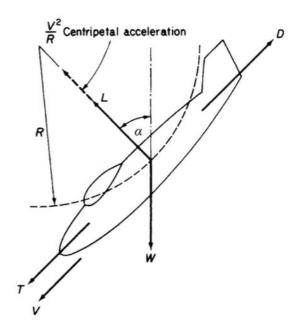
Consider the sketch shown on the right

1. Write equilibrium of forces in radial direction

$$L = W \cos \alpha + M \frac{V^2}{R}$$

2. Load factor

$$n = \frac{L}{W} = \frac{W}{W}\cos\alpha + \frac{M}{W}\frac{V^2}{R} = \cos\alpha + \frac{V^2}{gR}$$

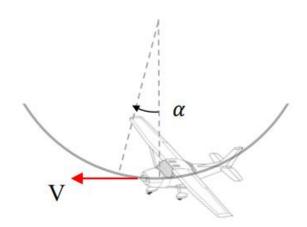


- Note n varies during the manoeuvre.
- The **max value** occurs when the aircraft is at the lowest point of the loop, $\alpha = 0^{\circ}$.
- The min value occurs when the aircraft is at the highest point, α = 180°; in this case, the
 pilot is upside down and the centrifugal acceleration directed upward acts in the opposite
 direction to the gravity field.

Symmetric Manoeuvre Loads

A Circular Manoeuvre at Constant Rate of Pitch

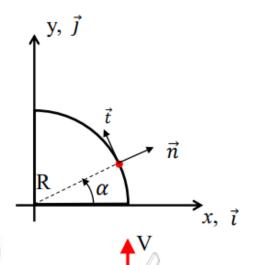
An aircraft travelling at a constant EAS, V = 435 km/h, performs the symmetric manoeuvre sketched below. If the curved part of the path is an arc of a circle, covered with a constant rate of pitch, $\dot{\alpha} = 7$ deg/s, calculate the load factor, n. Assume the aircraft is at its lowest position.



1. Kinematic analysis

acceleration:

 $\vec{p} = R(\cos\alpha \cdot \vec{\imath} + \sin\alpha \cdot \vec{\imath})$

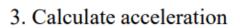


2. Use problem data

- velocity:
- · acceleration:

$$\overline{a} = R\left(-\dot{x}\sin x \,\dot{\iota} + \dot{x}\cos x \,\dot{j}\right)$$

$$\overline{a} = R\left(-\dot{x}\sin x - \dot{x}^2\cos x\right)\dot{\iota}$$



Load factor

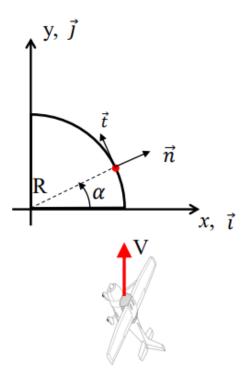
$$n = 1 + \frac{a}{g}$$
 $n = \omega_S K + \sqrt{2}$
 gR

$$n = 1 + \frac{\sqrt{2}}{gR}$$

$$n = 1 + R \times \frac{1}{9}$$

$$V = 435 \text{ hm/h} = 120.83 \text{ m/s}$$

 $K = 7 \text{ deg/s} = 0.12217 \text{ m/s}$
 $N = 1 + 120.83.0.12217$
 9.81



1. Kinematic analysis

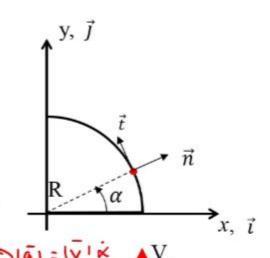
position:

$$\vec{p} = R(\cos\alpha \cdot \vec{\imath} + \sin\alpha \cdot \vec{\jmath})$$

· velocity:

x=x(+)

- · acceleration:



- 2. Use problem data
 - velocity:
 - · acceleration:



- 3. Calculate acceleration

4. Load factor

1. Kinematic analysis

• position:
$$\vec{p} = R(\cos \alpha \cdot \vec{i} + \sin \alpha \cdot \vec{j})$$

• acceleration:
$$\vec{a} = R \vec{\alpha} \cdot \vec{t} - R \dot{\alpha}^2 \cdot \vec{n}$$

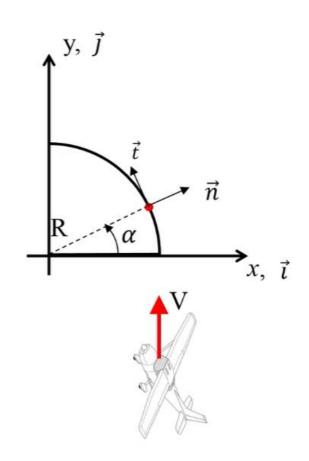
2. Use problem data

•
$$\dot{\alpha} = \text{const.}$$
 $\Rightarrow a = |\vec{\alpha}| = |R\dot{\alpha}^2|$

• velocity:
$$V = R\dot{\alpha}$$

3. Calculate acceleration
$$a = R\dot{\alpha}^2 = ... = V\dot{\alpha} = 14.8m/s^2$$

4. Load factor
$$n = \left(1 + \frac{a}{g}\right) = 2.5$$



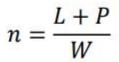
Maximum Load Factor

Load factor

$$L + P = nW$$

n = 1: level and straight flight

n = 0: zero-g (parabolic flight)





Maximum value of *n* just before stall

$$n_{MAX} = \frac{0.5\rho V^2 S C_L^{MAX}}{W}$$

determined by total aircraft lift coefficient, C_L^{MAX}