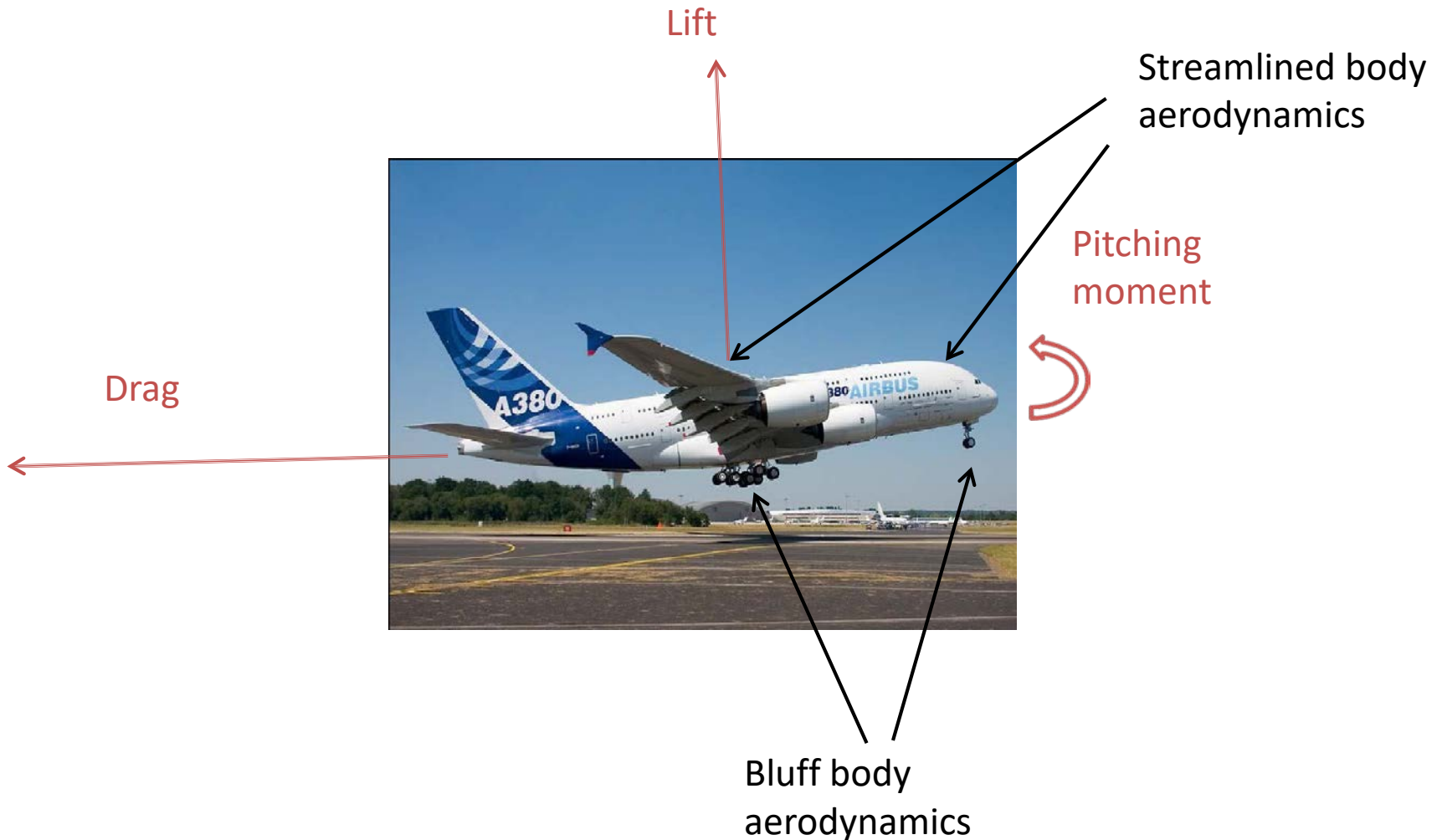


SESA3029 Aerothermodynamics

Lecture 1.2: Basic aerodynamics



Dimensionless numbers

- Mach number $M = \frac{U}{a}$
 - Ratio of velocity to speed of sound
- Reynolds number $Re = \frac{\rho UL}{\mu}$
 - Ratio of the order of magnitude of inertia to viscous terms in the governing equations
- Knudsen number $Kn = \frac{\lambda}{L}$
 - Ratio of mean free path to flow scale
 - $\lambda = 8 \times 10^{-8}$ m for air at STP
 - ($Kn < 0.01$ continuum flow, $Kn > 1$ free molecule flow)

Example

- A380 in cruise at 10km
 - Mean chord= 10.4 m
 - Mach 0.85
 - $U=300 \text{ m/s}$ $\rho=0.414 \text{ kg/m}^3$ $\mu=1.45\times 10^{-5} \text{ Nsm}^{-2}$

$$\text{Re} = \frac{\rho UL}{\mu} = \frac{0.414 \times 300 \times 10.4}{1.45 \times 10^{-5}} = 8.9 \times 10^7$$

Vorticity definition

$$\boldsymbol{\omega} = \nabla \times \mathbf{u} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ u & v & w \end{vmatrix} = \frac{1}{r} \begin{vmatrix} \mathbf{e}_r & r\mathbf{e}_\theta & \mathbf{e}_z \\ \partial/\partial r & \partial/\partial \theta & \partial/\partial z \\ v_r & rv_\theta & v_z \end{vmatrix}$$

Curl
operator

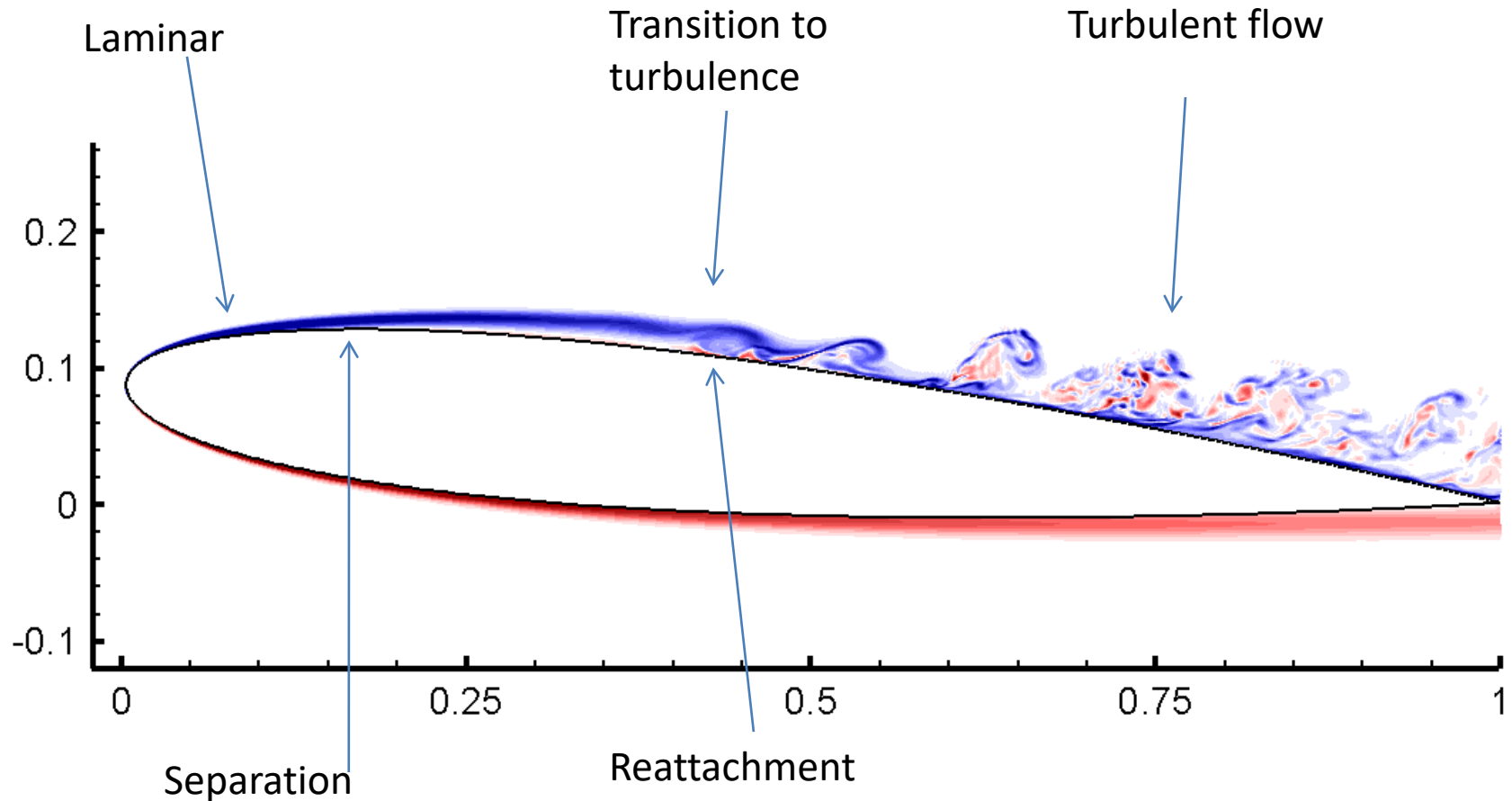
Cartesian

Cylindrical polar

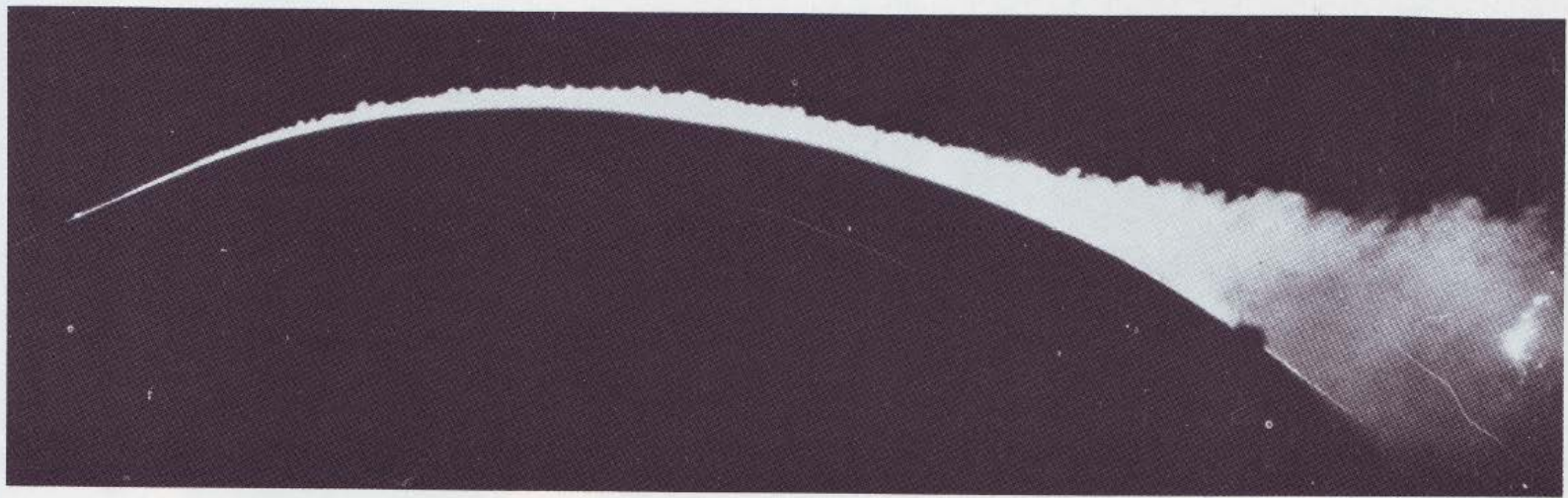
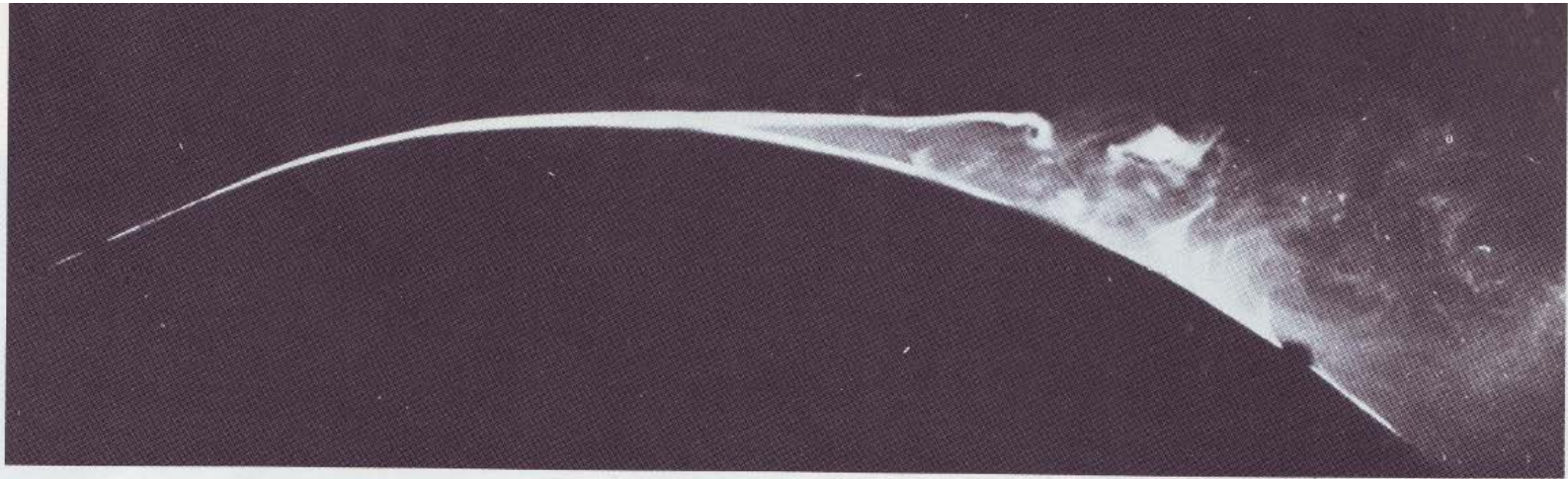
Can write out components using rules of determinants

The boundary layer

(low-speed flow over an airfoil with a laminar separation bubble)



Contours of vorticity show rotational flow region; $Re=50,000$ in this example



156. Comparison of laminar and turbulent boundary layers. The laminar boundary layer in the upper photograph separates from the crest of a convex surface (cf. figure 38), whereas the turbulent layer in the second

photograph remains attached; similar behavior is shown below for a sharp corner. (Cf. figures 55-58 for a sphere.) Titanium tetrachloride is painted on the forepart of the model in a wind tunnel. *Head 1982*

Potential flow

If a flow is irrotational ($\omega = \text{curl } \mathbf{u} = 0$) we can always write $\mathbf{u} = \nabla \phi$

with velocity components $u = \frac{\partial \phi}{\partial x} \quad v = \frac{\partial \phi}{\partial y}$

where ϕ is a scalar known as the velocity potential

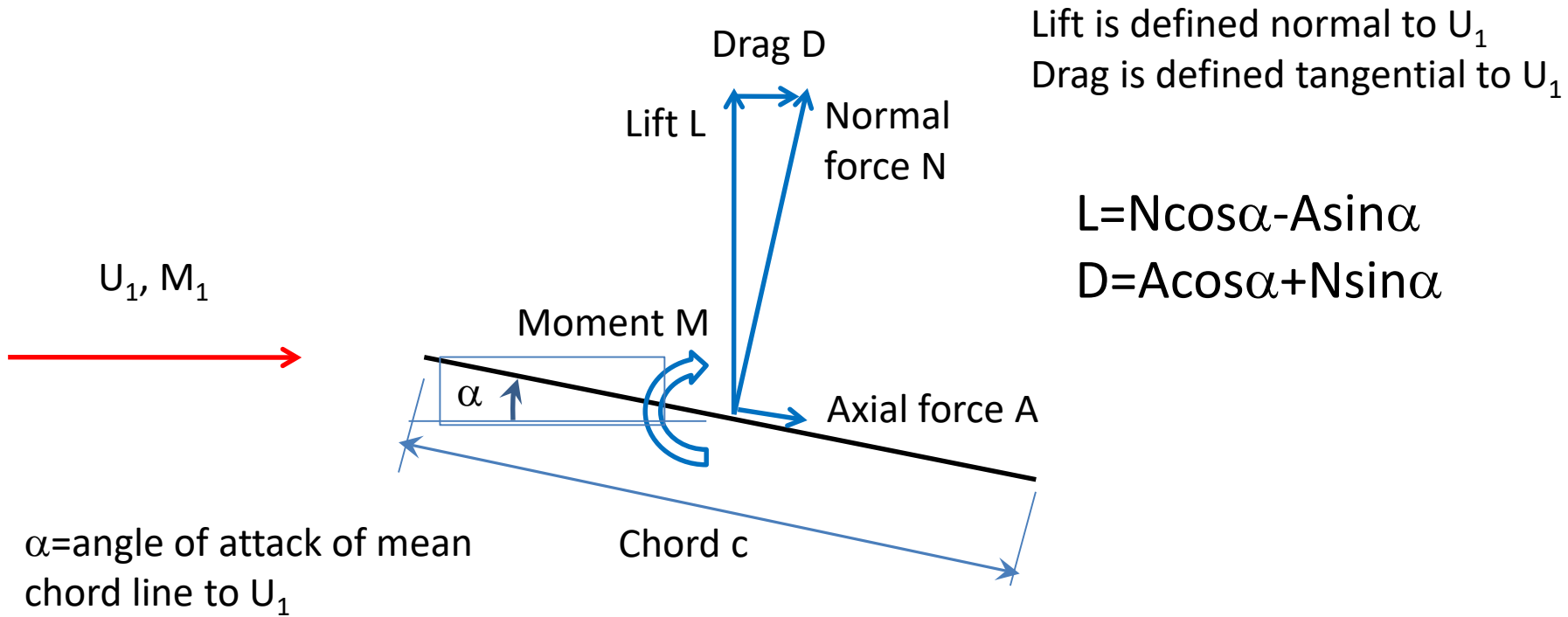
- this works because of the vector identity $\nabla \times (\nabla \phi) = 0$

Circulation:
$$\Gamma = - \oint_{\text{closed circuit}} \mathbf{u} \cdot d\mathbf{s} = - \iint_{\text{surface}} \omega \cdot d\mathbf{S}$$

Circular cylinder with circulation
(Kutta-Joukowski theorem):

$$L = \rho U_{\infty} \Gamma$$

Aerodynamic forces



Force and moment coefficients

- Wing-based (L=lift, D=drag, M=pitching moment, S=wing planform area)

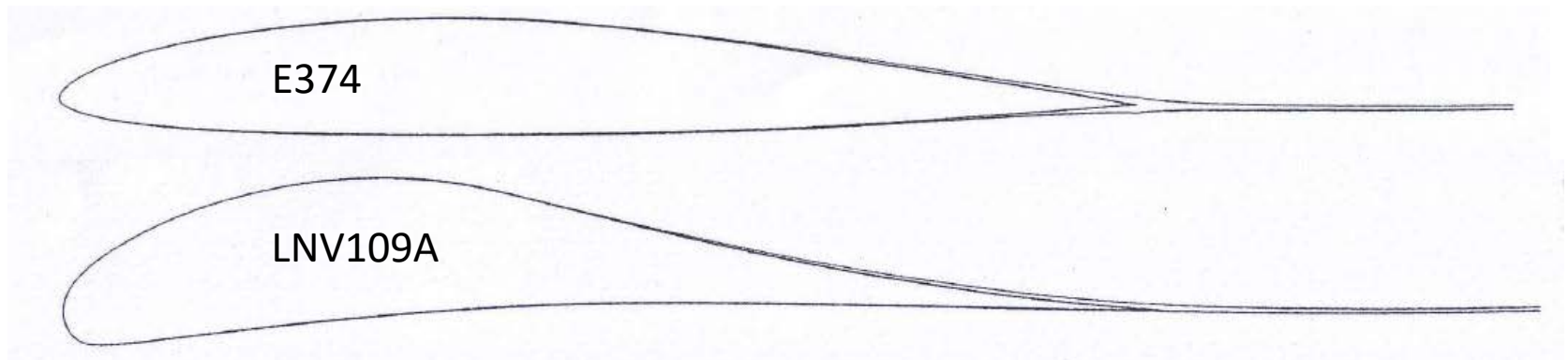
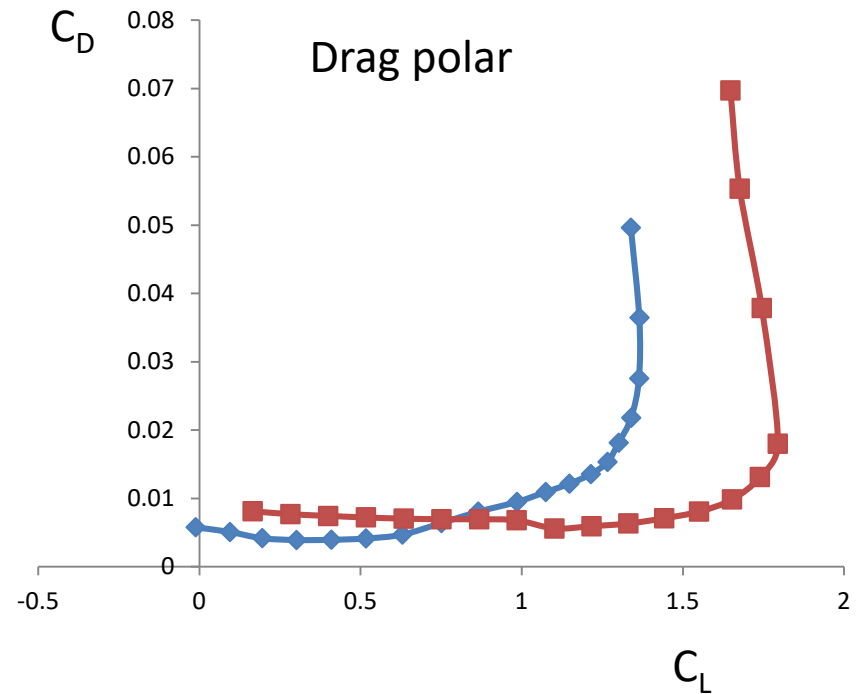
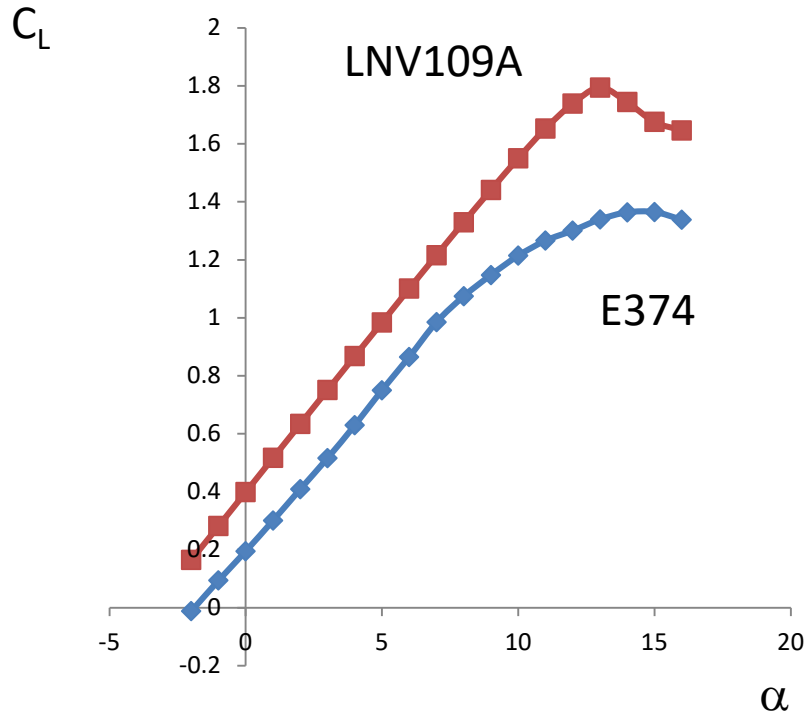
$$C_L = \frac{L}{\frac{1}{2} \rho_{\infty} U_{\infty}^2 S} \quad C_D = \frac{D}{\frac{1}{2} \rho_{\infty} U_{\infty}^2 S} \quad C_M = \frac{M}{\frac{1}{2} \rho_{\infty} U_{\infty}^2 S c}$$

- Section-based (c=chord)

$$C_L = \frac{L}{\frac{1}{2} \rho_{\infty} U_{\infty}^2 c} \quad C_D = \frac{D}{\frac{1}{2} \rho_{\infty} U_{\infty}^2 c} \quad C_M = \frac{M}{\frac{1}{2} \rho_{\infty} U_{\infty}^2 c^2}$$

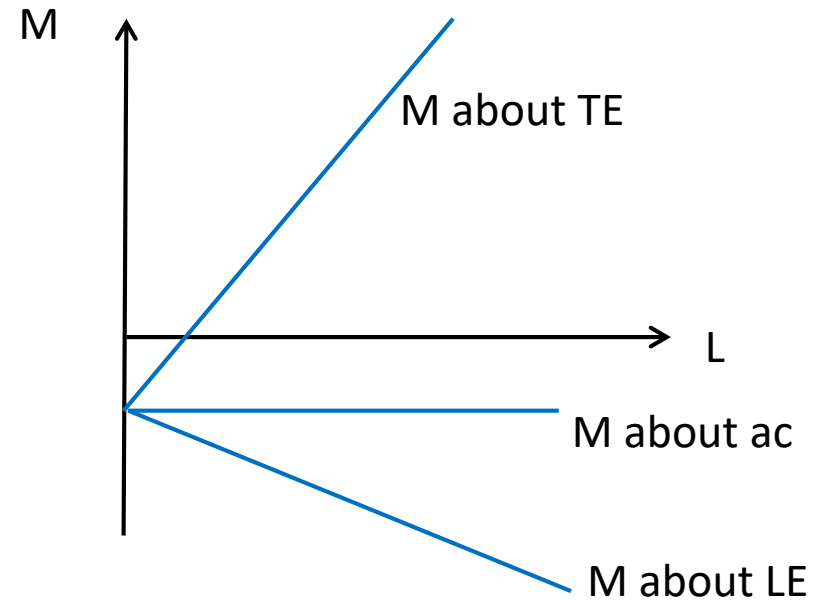
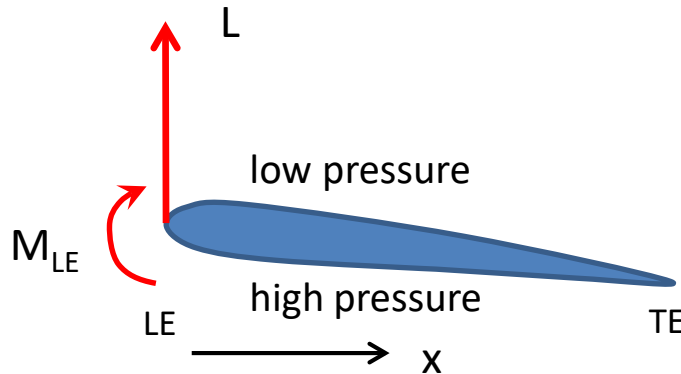
- Forces and moments come from the integrated effects of pressure and surface shear stress

Airfoil performance ($Re=3 \times 10^6$ XFOIL results)



Moments, centre of pressure (cp) and aerodynamic centre (ac)

We can represent forces and moments about any point e.g. leading edge (LE)



About any x $M_x = M_{LE} + xL$

let $\bar{x} = x / c$

$$C_{M,x} = C_{M,LE} + \bar{x}C_L \quad \Rightarrow \quad \bar{x}_{cp} = -\frac{C_{M,LE}}{C_L} \quad \text{(point where lift acts with no moment)}$$

$$\frac{dC_{M,x}}{dC_L} = \frac{dC_{M,LE}}{dC_L} + \bar{x} \quad \Rightarrow \quad \bar{x}_{ac} = -\frac{dC_{M,LE}}{dC_L} \quad \text{(point where } C_M \text{ is independent of } C_L\text{)}$$

Results from thin aerofoil theory

- Incompressible inviscid flow around a 2D thin aerofoil
- Kutta condition (zero loading at trailing edge)
- Kutta-Joukowski theorem $L = \rho U_{\infty} \Gamma$

$$\frac{dC_L}{d\alpha} = 2\pi \qquad \bar{x}_{ac} = \frac{1}{4}$$