

Lecture 24 - Divergence and Curl

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- 1 Review
- 2 Vector calculus
 - Divergence
 - Curl
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1 Review

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3 Summary

- We studied the vector derivative of a scalar field: the **gradient**.
 - ▶ The gradient of the scalar field ϕ is the vector field $\nabla\phi$ given by

$$\nabla\phi = \frac{\partial\phi}{\partial\hat{\mathbf{N}}} \hat{\mathbf{N}} \quad (\text{recall: } \nabla \equiv \vec{\nabla})$$

where $\hat{\mathbf{N}}$ is the **unit normal to the surfaces** $\phi = \text{const}$ and the scalar $\frac{\partial\phi}{\partial\hat{\mathbf{N}}}$ is the directional derivative of ϕ in the $\hat{\mathbf{N}}$ direction.

- ▶ For a scalar field ϕ given in Cartesian coordinates by $\phi(x, y, z)$:

$$\nabla\phi = \frac{\partial\phi}{\partial x} \hat{\mathbf{i}} + \frac{\partial\phi}{\partial y} \hat{\mathbf{j}} + \frac{\partial\phi}{\partial z} \hat{\mathbf{k}}$$

- The **directional derivative** along $\hat{\mathbf{n}}$ at point \vec{r}_0 is the scalar field:

$$\begin{aligned} \frac{\partial\phi}{\partial\hat{\mathbf{n}}}(\vec{r}_0) &= \lim_{t \rightarrow 0} \left\{ \frac{\phi(\vec{r}_0 + t\hat{\mathbf{n}}) - \phi(\vec{r}_0)}{t} \right\} = \hat{\mathbf{n}} \cdot \nabla\phi \quad |\hat{\mathbf{n}}| = 1 \\ &= n_1 \frac{\partial\phi}{\partial x} + n_2 \frac{\partial\phi}{\partial y} + n_3 \frac{\partial\phi}{\partial z} \quad (\text{in Cartesian coordinates}) \end{aligned}$$

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→ Divergence

We have already seen how to use ∇ to compute the **gradient** ∇ . The gradient differentiates a scalar function, like $f(x, y, z)$, and produces a vector field ∇f

The same approach can be used to **introduce new “derivatives”**, that differentiate vector fields.

One such derivative is the divergence $\nabla \cdot \vec{F}$ of a vector field \vec{F} which gives a scalar derivative of a vector field.

We **define** the **divergence** to satisfy the following **two conditions**:

- ① If \vec{c} is a **constant** vector, and ϕ is a **scalar** field then

$$\nabla \cdot (\phi \vec{c}) = (\nabla \phi) \cdot \vec{c} \quad \Leftrightarrow \quad \text{div}(\phi \vec{c}) = (\text{grad } \phi) \cdot \vec{c} \quad (1)$$

- ② If \vec{F} and \vec{G} are vector fields then the divergence is linear. Hence:

$$\nabla \cdot (\vec{F} + \vec{G}) = \nabla \cdot \vec{F} + \nabla \cdot \vec{G} \quad (2)$$

Divergence in Cartesian Coordinates: definition

We can use properties (1) and (2) to **define the divergence in Cartesian coordinates**.

$$\text{Let } \vec{F}(x, y, z) = F_1(x, y, z) \hat{i} + F_2(x, y, z) \hat{j} + F_3(x, y, z) \hat{k}$$

Then **divergence of \vec{F}** , $\text{div} \vec{F} \equiv \nabla \cdot \vec{F}$, is

$$\nabla \cdot \vec{F} = \nabla \cdot (F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}) \quad \checkmark \text{ by condition (2)}$$

$$= \nabla \cdot (F_1 \hat{i}) + \nabla \cdot (F_2 \hat{j}) + \nabla \cdot (F_3 \hat{k}) \quad \checkmark \text{ by condition (1)}$$

$$= (\nabla F_1) \cdot \hat{i} + (\nabla F_2) \cdot \hat{j} + (\nabla F_3) \cdot \hat{k} \quad \checkmark \nabla F_n \equiv \text{grad } F_n \text{ is a vector}$$

$$\nabla \cdot \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \quad \text{since } \begin{cases} (\nabla F_n) \cdot \hat{i} = \partial_x F_n \\ (\nabla F_n) \cdot \hat{j} = \partial_y F_n \\ (\nabla F_n) \cdot \hat{k} = \partial_z F_n \end{cases} \quad \left(\partial_x \equiv \frac{\partial}{\partial x} \right)$$

↙ Divergence of a vector field is thus a scalar field

Examples of calculating the Divergence

$$\operatorname{div} \vec{F} \equiv \nabla \cdot \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

Example: Let $\vec{F} = y^2 z \hat{i} + xz \hat{j} - y^2 \hat{k}$. Then

$$\begin{aligned}\nabla \cdot \vec{F} &= \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \\ &= \frac{\partial(y^2 z)}{\partial x} + \frac{\partial(xz)}{\partial y} + \frac{\partial(-y^2)}{\partial z} \\ &= 0 + 0 + 0 = 0\end{aligned}$$

So, for $\vec{F} = y^2 z \hat{i} + xz \hat{j} - y^2 \hat{k}$ one has $\nabla \cdot \vec{F} = 0$.

This example shows that:

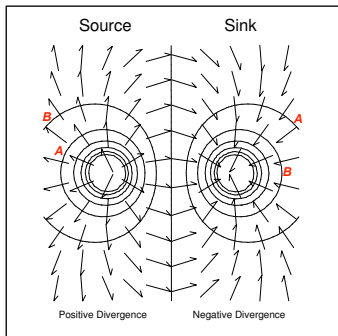
$\operatorname{div} \vec{F} = 0$ does not imply that \vec{F} is constant.

A field with zero divergence is called solenoidal.

Properties of the divergence: Geometric interpretation

The **divergence of a field** is associated with the:

{ **sources** of vector field: **expansion (divergence)** of the vector flow
sinks of vector field: **contraction (convergence)** of the vector flow



A **source** is a region in space from which field lines tangent to \vec{F} flow outward (e.g., the neighbourhood of a positive charge or a “source” of water). In such a region the **divergence is positive** (field lines diverge/expand).

A **sink** is a region of space where the field lines converge (e.g., the neighbourhood of a negative charge or a “hole” into which water disappears). In such a region the **divergence is negative** (field lines converge/contract).

If the **divergence vanishes** there is **no overall change** in the **volume** of the **surface orthogonal to the field lines** (see $A \rightarrow B$ in Fig.) as we move along the flow (or, in 2D, area of the curves orthogonal to the field lines).

→ Curl

A further derivative is the **curl of a vector field** \vec{F} : $\text{curl } \vec{F} \equiv \nabla \times \vec{F}$, which gives a **vector derivative of a vector field**.

We **define** the **curl** to satisfy the following **two conditions**:

- ① If \vec{c} is a **constant** vector, and ϕ is a scalar field then

$$\nabla \times (\phi \vec{c}) = (\nabla \phi) \times \vec{c} \quad \Leftrightarrow \quad \text{curl } (\phi \vec{c}) = (\text{grad } \phi) \times \vec{c} \quad (1)$$

- ② If \vec{F} and \vec{G} are vector fields then the divergence is linear:

$$\nabla \times (\vec{F} + \vec{G}) = \nabla \times \vec{F} + \nabla \times \vec{G} \quad (2)$$

Curl in Cartesian Coordinates: definition

We can use properties (1) and (2) to **define the curl in Cartesian coordinates**.

Let $\vec{F}(x, y, z) = F_1(x, y, z) \hat{i} + F_2(x, y, z) \hat{j} + F_3(x, y, z) \hat{k}$

Then curl of \vec{F} , $\text{curl } \vec{F} \equiv \nabla \times \vec{F}$, is:

$$\begin{aligned} \nabla \times \vec{F} &= \nabla \times (F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}) \quad \swarrow \text{by condition (2)} \\ &= \nabla \times (F_1 \hat{i}) + \nabla \times (F_2 \hat{j}) + \nabla \times (F_3 \hat{k}) \quad \swarrow \text{by condition (1)} \\ &= (\nabla F_1) \times \hat{i} + (\nabla F_2) \times \hat{j} + (\nabla F_3) \times \hat{k} \quad \swarrow \text{def. cross prod: Lecture 21} \\ &= \left(-\frac{\partial F_1}{\partial y} \hat{k} + \frac{\partial F_1}{\partial z} \hat{j} \right) + \left(\frac{\partial F_2}{\partial x} \hat{k} - \frac{\partial F_2}{\partial z} \hat{i} \right) + \left(-\frac{\partial F_3}{\partial x} \hat{j} + \frac{\partial F_3}{\partial y} \hat{i} \right) \end{aligned}$$

$$\nabla \times \vec{F} = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} - \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) \hat{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}$$

\nwarrow Curl of a vector field is thus a vector field

Examples of calculating the Curl

Let \vec{F} be a vector field with components

$$\vec{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$$

Then

$$\text{curl } \vec{F} \equiv \nabla \times \vec{F} = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} - \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) \hat{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}$$

This may be **formally written using a determinant** as:

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} \quad (1)$$

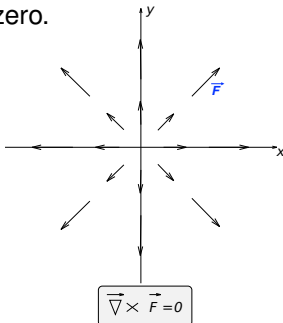
Example: Let $\vec{F} = x y^2 \hat{i} + e^z \hat{j} + y e^z \sin x \hat{k}$. Using (1) yields

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy^2 & e^z & y \sin x e^z \end{vmatrix} = e^z (\sin x - 1) \hat{i} - (y \cos x e^z) \hat{j} - 2xy \hat{k}$$

- $\nabla \times (g \vec{F}) = g(\nabla \times \vec{F}) + \nabla g \times \vec{F}$, where g is a scalar function and \vec{F} a vector field. Note that (1) in slide 9 is a special case of this identity when $\vec{F} \equiv \vec{c} = \text{constant vector} \Rightarrow \nabla \times \vec{F} = 0$
- $\nabla \times (\nabla f) = 0 \Leftrightarrow$ **curl** of **grad** of a **scalar vanishes**
- The curl of a **centrally symmetric** field \vec{F} is **zero**:

$$\vec{F} = f(r)\vec{r} \implies \nabla \times \vec{F} = 0.$$

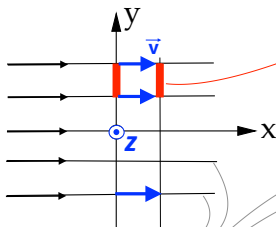
This result is in line with the **interpretation of the curl as a measure of the rotation of a vector field**. Since a centrally symmetric field does not “rotate” its curl must be zero.



- If $\vec{F} \equiv \vec{v}$ is **fluid velocity** then $\vec{\omega} = \nabla \times \vec{F}$ is **vorticity**

Irrotational flow: $\nabla \times \vec{v} = 0$

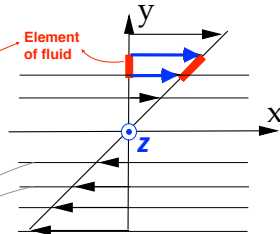
(No vorticity: elements of fluid do not spin)



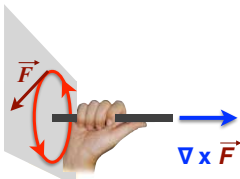
Streamlines: field lines
tangent to fluid velocity \vec{v}

Rotational flow: $\nabla \times \vec{v} \neq 0$

(fluid with vorticity: elements of fluid 'spin')



- Direction of $\nabla \times \vec{F}$** given by **right hand rule (version 2)**:



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- Divergence

$$\operatorname{div} \vec{F} \equiv \nabla \cdot \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

- Curl

$$\operatorname{curl} \vec{F} \equiv \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

- Differential operators: (\checkmark recall: $\nabla \equiv \vec{\nabla}$)

$\operatorname{grad} \equiv \nabla$	\longleftarrow acts on a <u>scalar</u> field & produces a <u>vector</u> field
$\operatorname{div} \equiv \nabla \cdot$	\longleftarrow acts on a <u>vector</u> field & produces a <u>scalar</u> field
$\operatorname{curl} \equiv \nabla \times$	\longleftarrow acts on a <u>vector</u> field & produces a <u>vector</u> field