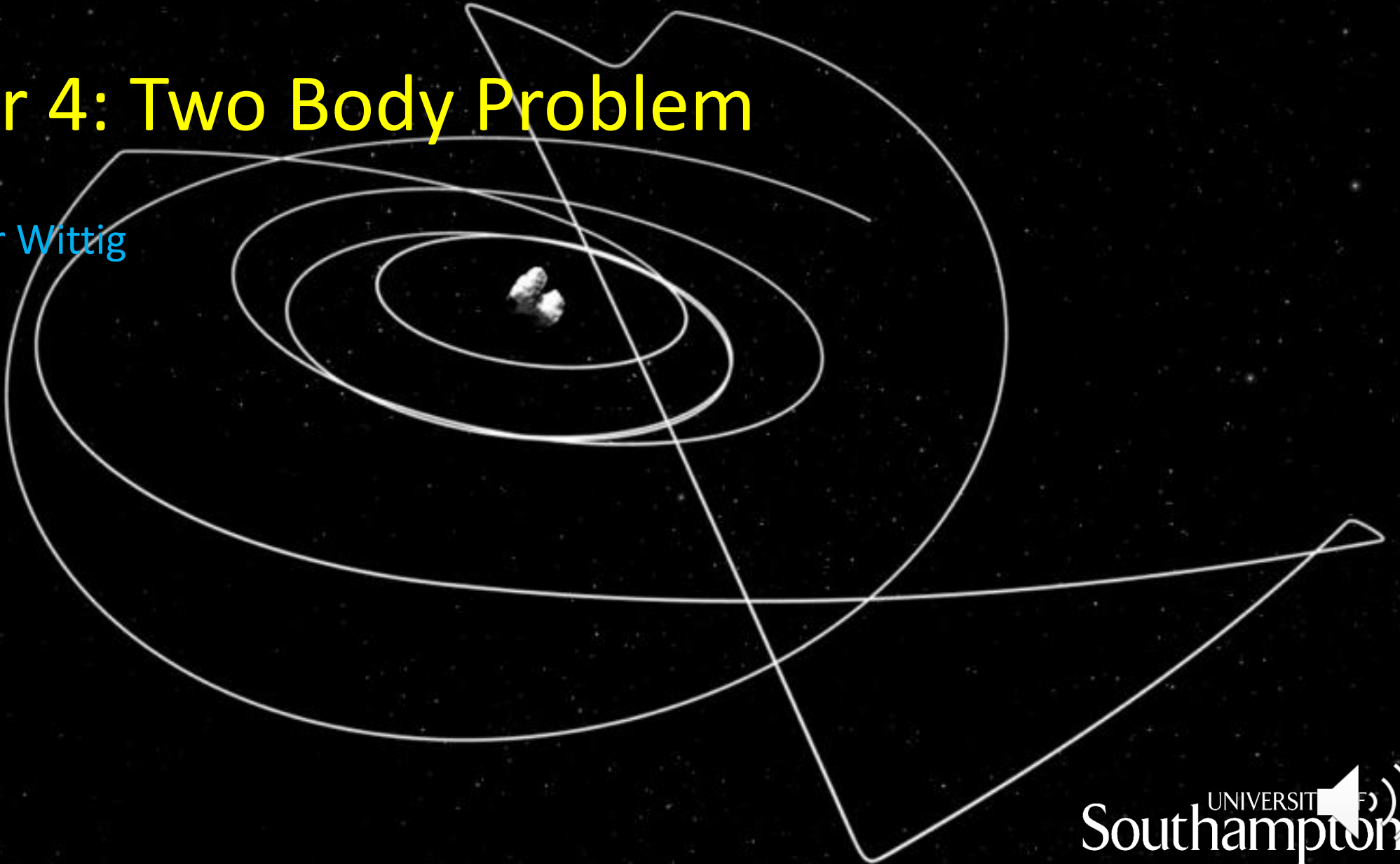


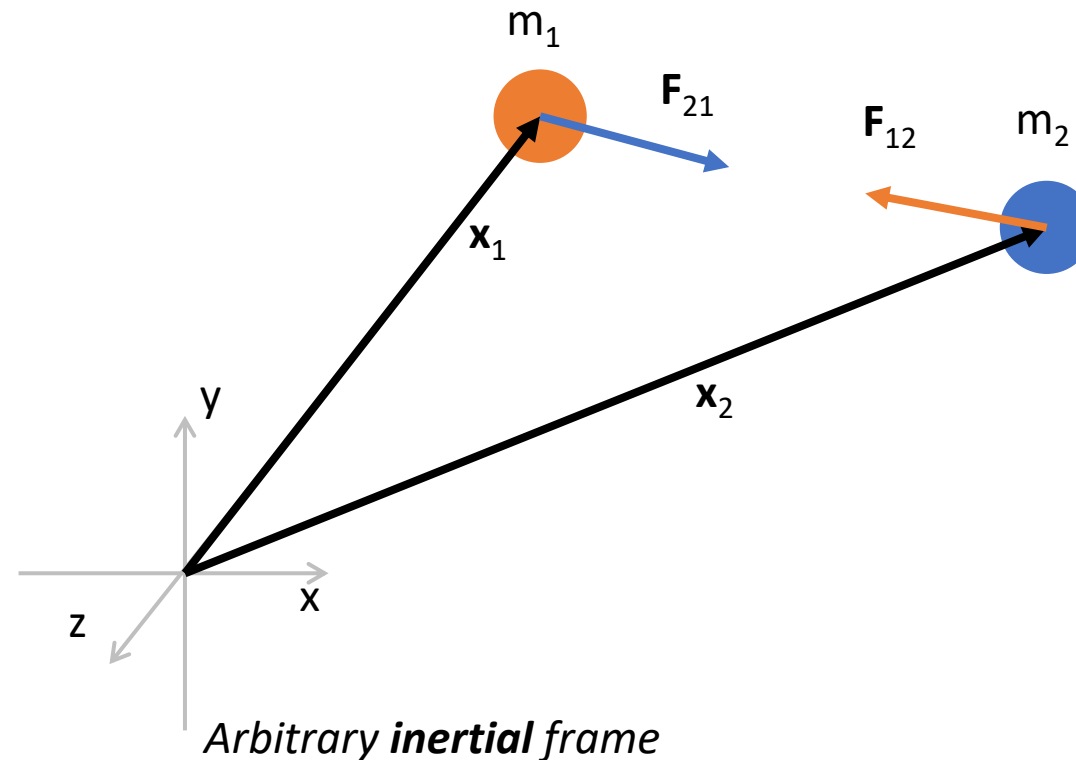
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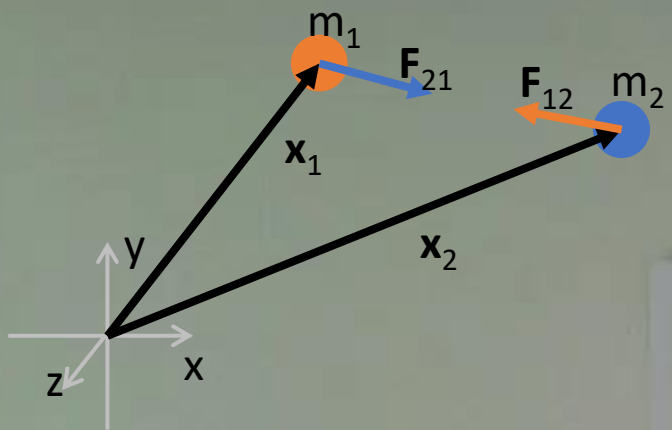
Chapter 4: Two Body Problem

Dr. Alexander Wittig



Aim: derive the full motion of two gravitating masses from first principles!





- Forces and accelerations:

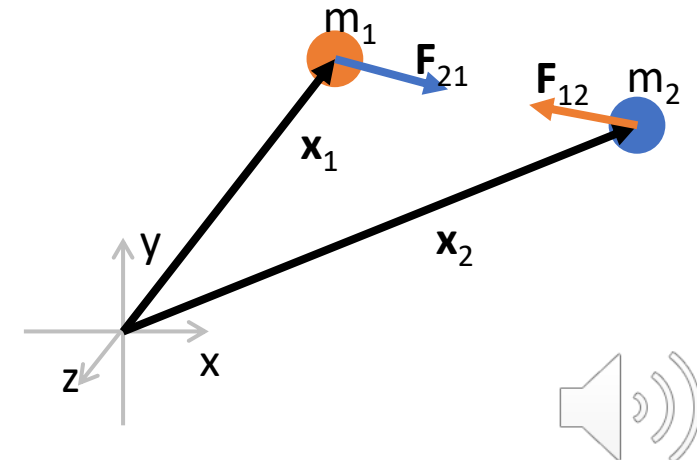
$$\vec{F}_{21} = \frac{Gm_1m_2}{|\vec{x}_2 - \vec{x}_1|^3}(\vec{x}_2 - \vec{x}_1)$$

$$\vec{F}_{21} = m_1\vec{a}_1 = m_1\ddot{\vec{x}}_1$$

$$\vec{F}_{12} = \frac{Gm_1m_2}{|\vec{x}_1 - \vec{x}_2|^3}(\vec{x}_1 - \vec{x}_2)$$

$$\vec{F}_{12} = m_2\vec{a}_2 = m_2\ddot{\vec{x}}_2$$

Note: $\vec{F}_{21} = -\vec{F}_{12}$ (actio = reactio)



- Forces and accelerations:

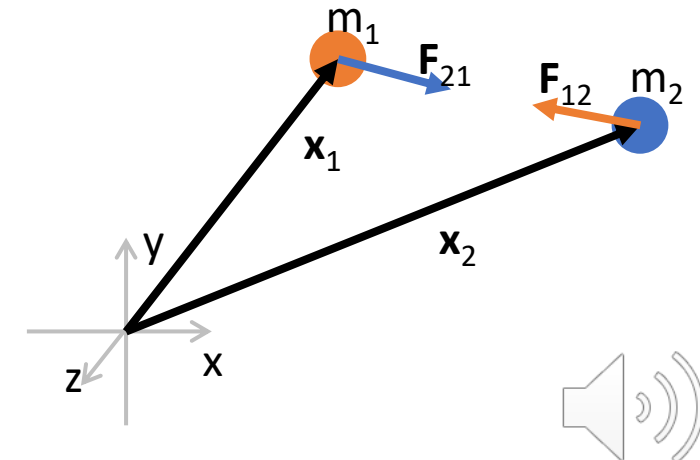
$$\vec{F}_{21} = \frac{Gm_1m_2}{|\vec{x}_2 - \vec{x}_1|^3}(\vec{x}_2 - \vec{x}_1)$$

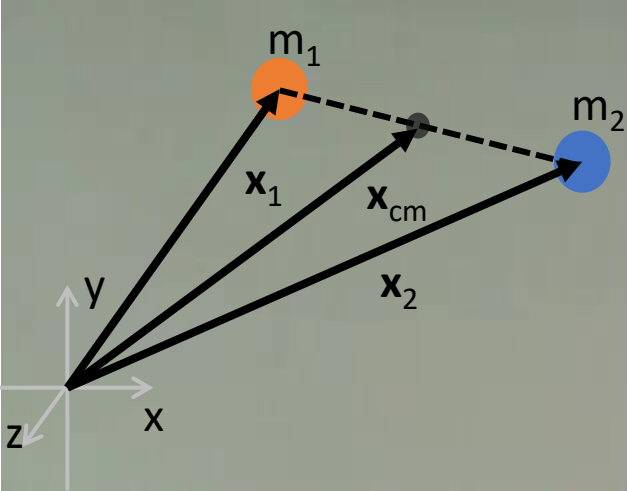
$$\vec{F}_{21} = m_1\vec{a}_1 = m_1\ddot{\vec{x}}_1$$

$$\vec{F}_{12} = \frac{Gm_1m_2}{|\vec{x}_1 - \vec{x}_2|^3}(\vec{x}_1 - \vec{x}_2)$$

$$\vec{F}_{12} = m_2\vec{a}_2 = m_2\ddot{\vec{x}}_2$$

12 degrees of freedom!





$$\vec{F}_{21} = m_1 \vec{a}_1 = m_1 \ddot{\vec{x}}_1$$

$$\vec{F}_{21} = \frac{G m_1 m_2}{|\vec{x}_2 - \vec{x}_1|^3} (\vec{x}_2 - \vec{x}_1)$$

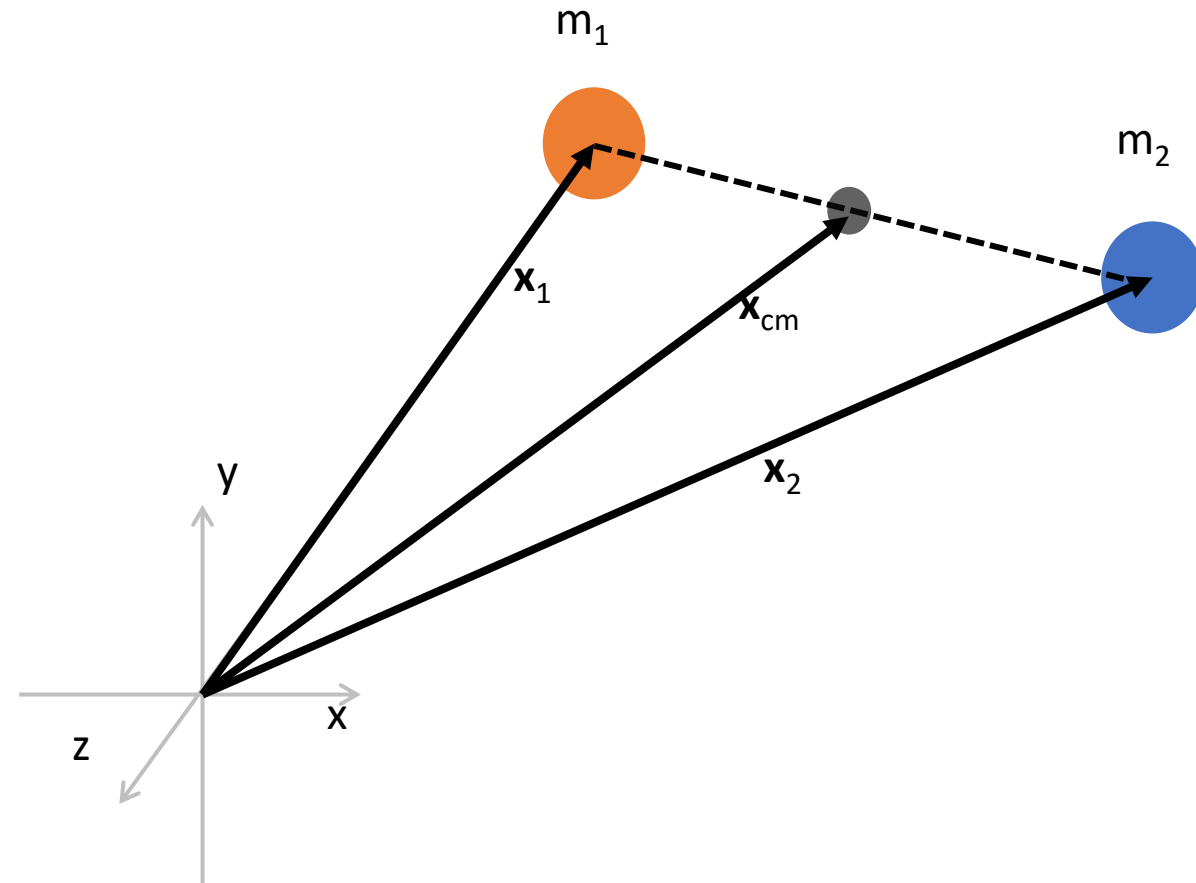
$$\vec{F}_{12} = m_2 \vec{a}_2 = m_2 \ddot{\vec{x}}_2$$

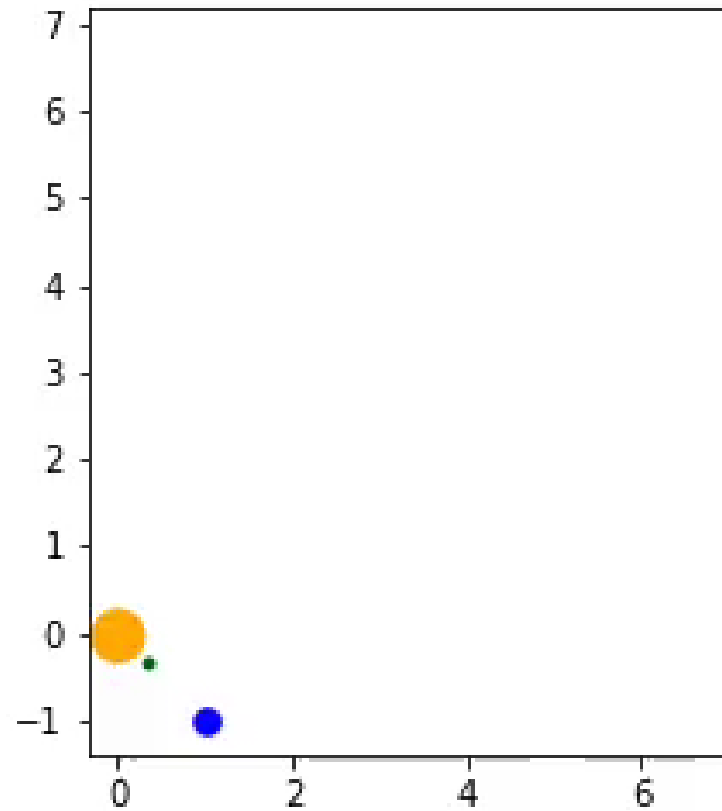
$$\vec{F}_{12} = \frac{G m_2 m_1}{|\vec{x}_1 - \vec{x}_2|^3} (\vec{x}_1 - \vec{x}_2)$$

$$|\vec{F}_{21}| = \frac{G m_1 m_2}{|\vec{x}_2 - \vec{x}_1|^3} |\vec{x}_2 - \vec{x}_1| = \frac{G m_1 m_2}{|\vec{x}_2 - \vec{x}_1|^2}$$

$$\vec{x}_{cm} = \frac{m_1 \vec{x}_1 + m_2 \vec{x}_2}{m_1 + m_2}$$

- 6 degrees of freedom
- Moves uniformly at constant velocity
- Coordinate frame attached at CM is inertial!





$$\dot{\vec{x}}_{cm} = \frac{m_1 \dot{\vec{x}}_1 + m_2 \dot{\vec{x}}_2}{m_1 + m_2}$$

$$\ddot{\vec{x}}_{cm} = \frac{m_1 \ddot{\vec{x}}_1 + m_2 \ddot{\vec{x}}_2}{m_1 + m_2} = \frac{\vec{F}_{21} + \vec{F}_{12}}{m_1 + m_2} = \vec{0}$$

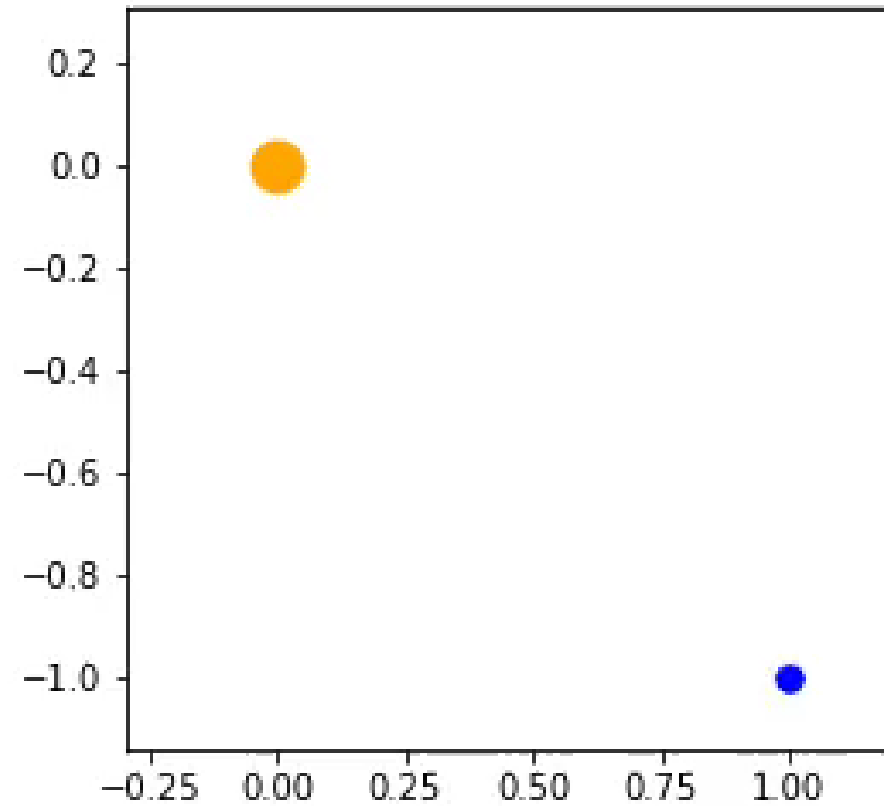
- Equation of motion exactly like central force problem with sum of masses:

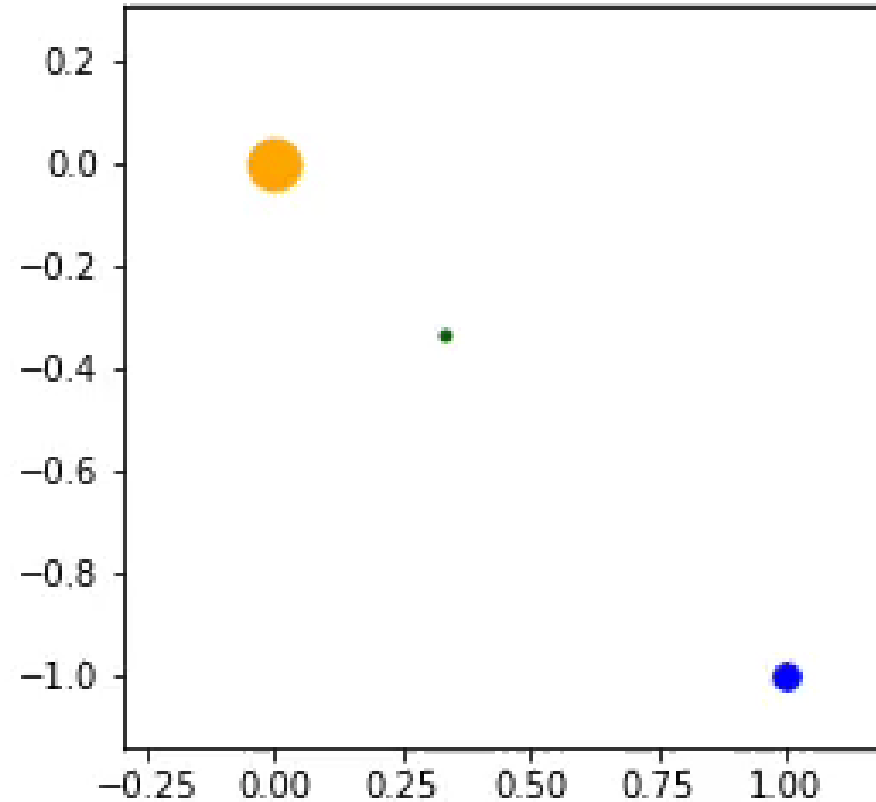
$$\vec{d} = \vec{x}_2 - \vec{x}_1$$

$$\ddot{\vec{d}} = -\frac{G(m_1 + m_2)}{|\vec{d}|^3} \vec{d} = -\frac{\mu}{|\vec{d}|^3} \vec{d}$$

- Solution of relative motion is a conic section (ellipse, parabola, hyperbola)
- BUT: fixing one body is then not an inertial frame!







Center of mass is moving along ellipse because frame not inertial!
Requires fictitious forces generating motion of CM!



- Center of mass: moves uniformly
- Relative distance: moves on ellipse
- Convert back from x_{cm} and d to x_1 and x_2 :

$$\vec{x}_1 = \vec{x}_{cm} - \frac{m_2}{m_1 + m_2} \vec{d}$$

$$\vec{x}_2 = \vec{x}_{cm} + \frac{m_1}{m_1 + m_2} \vec{d}$$



Observations:

- Both bodies on ellipses around barycenter
- Heavy mass moves closer to barycenter than light mass

If $m_1 \gg m_2$:

- $\mu \approx Gm_1$
- $\vec{x}_{cm} \approx \vec{x}_1$

$$\vec{x}_1 = \vec{x}_{cm} - \frac{m_2}{m_1 + m_2} \vec{d}$$

$$\vec{x}_2 = \vec{x}_{cm} + \frac{m_1}{m_1 + m_2} \vec{d}$$

$$\mu = G(m_1 + m_2)$$

Restricted Two-Body Problem



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