Trig cheat (say: odd trig function hence integrates to zero)

$$egin{aligned} \int_0^{2\pi} \sin^{2m+1}x\cos^nx\,dx &= 0 \qquad n,m\in\mathbb{Z} \ \int_0^{2\pi} \sin^mx\cos^{2n+1}x\,dx &= 0 \qquad n,m\in\mathbb{Z} \end{aligned}$$

ODEs

euler type linear homogeneous ODEs

So these are actually quite cool (and common), as you'll see in a bit this is a homogeneous Euler type:

$$x^2rac{d^2y}{dx^2}+bxrac{dy}{dx}+cy=0$$

The case where k is real and has 2 solutions

$$x^2rac{d^2y}{dx^2}+bxrac{dy}{dx}+cy=0 \ k_{1,2}=rac{-(b-1)\pm\sqrt{(b-1)^2-4c}}{2}=rac{(1-b)\pm\sqrt{(b-1)^2-4c}}{2} \ y=Ax^{k_1}+Bx^{k_2}$$

The case where k is complex or duplicate

$$x^2rac{d^2y}{dx^2}+bxrac{dy}{dx}+cy=0$$
 $rac{d^2y}{dt^2}+(b-1)rac{dy}{dt}+cy=0$ $t=\ln x$

 ${f s}$ then sub ${f t}$ back in to get the equation in terms of ${m x}$ and ${m y}$.

Fourier stuff

Fourier series

$$f(x) = rac{1}{2}a_0 + \sum_{n=1}^{\infty} \left[a_n \cos\left(rac{n\pi}{L}x
ight) + b_n \sin\left(rac{n\pi}{L}x
ight)
ight]$$

f(x) = f(x+2L) = a periodic function (it repeats perfectly every 2L) $a_0 = a$ offset constant (offsets the function from an average of 0) $a_n, b_n =$ the nth constant related to \cos and \sin respectively

e constants a_n, b_n usually end up being defined as a function of n which when solved allows you to calculate the constants a_1, a_2, a_3 ... where the more constants calculated the closer the approximation of the original periodic

nding the constants

$$egin{align} a_m &= rac{1}{L} \int_{R_2}^{R_1} f(x) \cos\left(rac{n\pi}{L}x
ight) \cdot dx \ \ b_m &= rac{1}{L} \int_{R_2}^{R_1} f(x) \sin\left(rac{n\pi}{L}x
ight) \cdot dx \ \ a_0 &= rac{1}{L} \int_{R_2}^{R_1} f(x) \cdot dx \ \end{align}$$

 b_m = often expands to a function defining the *n*th *b* constant in terms of *m* f(x) = f(x + 2L) = a periodic function (it repeats perfectly every 2L)

 $R_1,R_2=$ a region the functions defined over, often this is just $R_1=L$ and $R_2=-L$

Complex fourier series

$$f(x) = \sum_{n=-\infty}^{\infty} c_n e^{\frac{j\pi nx}{L}} \qquad c_n = \begin{cases} \frac{1}{2}(a_n - jb_n) & n > 0 \\ \frac{1}{2}a_0 & n = 0 \\ \frac{1}{2}(a_{-n} + jb_{-n}) & n < 0 \end{cases}$$

$$= \frac{1}{2}a_0 + \sum_{n=1}^{\infty} c_n e^{\frac{jn\pi x}{L}} + \sum_{n=-\infty}^{-1} c_{(n)} e^{\frac{jn\pi x}{L}}$$

$$= \frac{1}{2}a_0 + \sum_{n=1}^{\infty} \left[c_n e^{\frac{jn\pi x}{L}} + c_{(-n)} e^{-\frac{jn\pi x}{L}} \right]$$

$$c_n = \frac{1}{2L} \int_{-L}^{L} f(x) e^{-j\frac{jn\pi x}{L}} \cdot dx$$

$$a_0 = \frac{1}{L} \int_{-L}^{L} f(x) \cdot dx$$

$$\begin{cases} where \\ f(x) = \text{some function} \\ j = \sqrt{1} \\ c_n = \text{the thic constant} \end{cases}$$
When dealing with this type of problem, the following identity is very frequently used:
$$\sin(A) = \frac{1}{2j} (e^{jA} - e^{-jA})$$

$$\cos(A) = \frac{1}{2} (e^{jA} + e^{-jA})$$

Fourier transform

Fourier Transform: $F(\omega)\equiv \mathcal{F}[f(t)]=rac{1}{\sqrt{2\pi}}\int_{-\infty}^{\infty}f(t)e^{-j\omega t}\cdot dt$ Inverse Transform: $f(t)=rac{1}{\sqrt{2\pi}}\int_{-\infty}^{\infty}F(\omega)e^{j\omega t}\cdot d\omega$ where: f(t)= some input function of t $F(\omega)=$ the fourier transform of f(t) f(t)= f(t)=

Laplace stuff

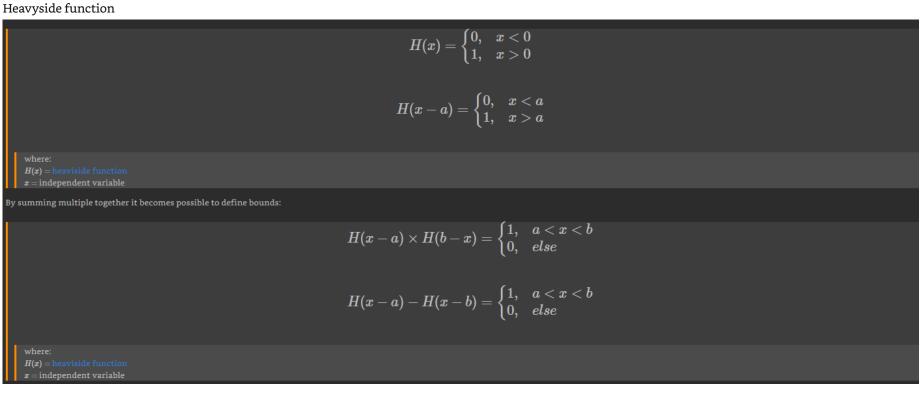
Laplace transform

```
where: \mathcal{L}[...] = \text{Laplace transform function} f(x) = \int_0^\infty f(x) e^{-sx} \cdot dx f(x) = \text{Laplace transform of } f(x) f(x) = \text{Laplace transform of } f(x) f(x) = \text{Laplace transform of } f(x) f(x) = \text{Laplace transform function} f(x) = \text{Laplace transform function}
```

 $Laplace\ transform\ known\ results$

f(t)	$\mathcal{L}[f(t)] \equiv ilde{f}(s)$
A	$\frac{A}{s}$, $\operatorname{Re}(s) > 0$
e^{at}	$\frac{1}{s-a}$, $\operatorname{Re}(s) > a$
$t^n, \qquad n=1,2\dots$	$\frac{n!}{s^{n+1}} , \qquad \text{Re}(s) > 0$
$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$, $\operatorname{Re}(s) > 0$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2} , \qquad \text{Re}(s) > 0$
$\sinh \omega t$	$\frac{\omega}{s^2 - \omega^2}$, $\operatorname{Re}(s) > \omega $
$\cosh \omega t$	$\frac{s}{s^2 - \omega^2}$, $\operatorname{Re}(s) > \omega $
$t^n f(t)$	$(-1)^n \frac{d^n \tilde{f}}{ds^n}$
$rac{df}{dt}$	$s\tilde{f}(s)-f(0)$
$rac{d^2f}{dt^2}$	$s^2\tilde{f}(s) - sf(0) - \frac{df}{dt}(0)$
H(t-a)	$\frac{e^{-as}}{s}$
$\delta(t-a)$	e^{-as}
$e^{-at}f(t)$	$ ilde{f}(s+a)$
f(t-a)H(t-a)	$e^{-as} ilde{f}(s)$

$$\mathcal{L}\left[rac{d^nf}{dx^n}
ight] = s^n ilde{f}(s) - \sum_{k=0}^{n-1} s^{n-(k+1)}f^k(0)$$



dirac function

$$\int_{-\infty}^{\infty} \delta(x-a)K\cdot dx = K$$
 $\int_{-\infty}^{\infty} \delta(x-a)f(x)\cdot dx = f(a)$ $\int_{B}^{A} \delta(x-a)K\cdot dx = 0 \quad ext{if } a > A ext{ or } a < B$ $\delta(x-a)pprox egin{cases} 0, & x
eq a \ \infty = rac{1}{dx}, & x = a \end{cases}$

Vector calculus

cross product

$$\vec{c} = \vec{a} \times \vec{b}$$

$$= \begin{vmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$\vec{k}$$

line integral of vector field

$$ec{r}(t) = v_x(t)i + v_y(t)j + v_z(t)k \qquad t_0 \leq t \leq t_1 \ x: ec{r}(t) = v_x(t) \qquad y: ec{r}(t) = v_y(t) \qquad x: ec{r}(t) = v_z(t) \ ec{F}(x,y,z) = f_x(x,y,z)i + f_y(x,y,z)j + f_z(x,y,z)k \qquad
ightarrow \ ec{F}(r(t)) = f_x(v_x,v_y,v_z)i + f_y(v_x,v_y,v_z)j + f_z(v_x,v_y,v_z)k \ = f_x(t) + f_y(t) + f_z(t) \ ec{f}(t) = \int_{t_0}^{t_1} \left[ec{F}(r(t)) \cdot rac{dec{r}}{dt}
ight] dt \ = \int_{t_0}^{t_1} \left[f_x(t) rac{dv_x(t)}{dt} + f_y(t) rac{dv_y(t)}{dt} + f_y(t) rac{dv_y(t)}{dt}
ight] dt$$

Del, nabla operator (put it on scalars)

$$egin{align} (n)D: &
abla = \sum_{i=1}^n ec{e}_i rac{\delta}{\delta x_i} \ &
abla f = \sum_{i=1}^n ec{e}_i rac{\delta f}{\delta x_i} \ & \ 3D: &
abla f = \left(rac{\delta f}{\delta x}, rac{\delta f}{\delta y}, rac{\delta f}{\delta z}
ight) = ec{e}_x rac{\delta}{\delta x} + ec{e}_y rac{\delta}{\delta y} + ec{e}_z rac{\delta}{\delta z} \ & \ \ \end{array}$$

divergance operator:

$$\mathrm{div}\,F=
abla\cdot F$$
 $3D\colon \mathrm{div}\,F=rac{\delta F_x}{\delta x}+rac{\delta F_y}{\delta y}+rac{\delta F_z}{\delta z}$

Curl:

$$2D: \; ec{\omega} =
abla imes ec{V} = \left(rac{\delta V_y}{\delta x} - rac{\delta V_x}{\delta y}
ight) \hat{e}_z \ 3D: \; ec{\omega} =
abla imes ec{F} = \left(rac{\delta F_z}{\delta y} - rac{\delta F_y}{\delta z}
ight) \hat{e}_x - \left(rac{\delta F_z}{\delta x} - rac{\delta F_x}{\delta z}
ight) \hat{e}_y + \left(rac{\delta F_y}{\delta x} - rac{\delta F_x}{\delta y}
ight) \hat{e}_z = \det \left(egin{matrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ rac{\delta}{\delta x} & rac{\delta}{\delta y} & rac{\delta}{\delta z} \\ F_x & F_y & F_z \end{matrix}
ight)$$

Normal of a plane (Just use del)

Plane equation:
$$0 = F(x,y,z) = f_x(x) + f_y(y) + f_z(z) + C$$

Normal equation: $\vec{n} = \nabla F$

Laplacian operator

scalar case:
$$\nabla^2 f \equiv \nabla \cdot (\nabla f) \equiv \text{div:}(\text{grad} f) = \frac{\delta^2}{\delta x^2} f + \frac{\delta^2}{\delta y^2} f + \frac{\delta^2}{\delta z^2} f$$
vector case:
$$\nabla^2 \vec{f} = \hat{i} \nabla^2 (\vec{f} \cdot \hat{i}) + \hat{j} \nabla^2 (\vec{f} \cdot \hat{j}) + \hat{k} \nabla^2 (\vec{f} \cdot \hat{k}) = \left(\nabla^2 f_{\hat{i}}, \nabla^2 f_{\hat{j}}, \nabla^2 f_{\hat{k}} \right)$$

$$\nabla^2 = \frac{\delta^2}{\delta x^2} + \frac{\delta^2}{\delta y^2} + \frac{\delta^2}{\delta z^2}$$

Vector identities

$$\nabla \times (\nabla f) = 0 \Leftrightarrow \text{curl of grad of a scalar vanishes}$$

③
$$\nabla \times (g\vec{F}) = g(\nabla \times \vec{F}) + \nabla g \times \vec{F}$$
 ← Linearity of curl

5
$$\nabla \cdot (\nabla \times \vec{F}) = 0 \Leftrightarrow \text{div of curl of a vector vanishes}$$

Conservative field

$$ec{F} = -
abla \phi(x,y,z)$$

in (continuous across domain)

representing terrain height then the terrain represents the potent in, since irrelevant of path the difference in height between two p imple it is the case that:

$$ec{F} = -
abla \phi(x,y,z) = -
abla (\phi(x,y,z) + C)$$

d \emph{A}, \emph{B} then the potential difference is the same regardless of path.

$$\int_A^B ec{F} \cdot dec{s} = \phi(A) - \phi(B)$$

l is not conservative:

conservative field: $\nabla imes \vec{F} = 0$

non-conservative field: $\nabla \times \vec{F} \neq 0$

Surface normal:

$$ec{r}(s,t) = f_x(s,t)\,\hat{i} + f_y(s,t)\,\hat{j} + f_z(s,t)\,\hat{k}$$
 $rac{\delta ec{r}}{\delta s} \cdot rac{\delta ec{r}}{\delta t} = 0$ $rac{\delta ec{r}}{\delta s} imes rac{\delta ec{r}}{\delta t} = ec{n}$

Surface integral:

$$dA = \left| rac{\delta ec{r}}{\delta s} imes rac{\delta ec{r}}{\delta t}
ight| ds \ dt \ = a \ ds \ dt \ A = \int dA = \int \int \left| rac{\delta ec{r}}{\delta s} imes rac{\delta ec{r}}{\delta t}
ight| ds \ dt \ = \int \int a \ ds \ dt$$

Flux integral:

$$\int\int_{S}ec{F}\cdot dec{S} = \int\int_{S}\left[ec{F}(ec{r}(s,t))\cdot\left(rac{\deltaec{r}}{\delta s} imesrac{\deltaec{r}}{\delta t}
ight)
ight]ds\,dt$$

Volume integrals:

$$\int\!\!\int\!\!\int_V f\,dV = \int\!\!\int\!\!\int_V f(x,y,z)\,dx\,dz\,dy \ = \int\!\!\int\!\!\int_V f(s,t,u)\,J\,ds\,dt\,du \ J = rac{\delta(x,y,z)}{\delta(s,t,u)} = egin{bmatrix} rac{\delta x}{\delta s} & rac{\delta x}{\delta t} & rac{\delta x}{\delta u} \ rac{\delta y}{\delta s} & rac{\delta y}{\delta t} & rac{\delta y}{\delta u} \ rac{\delta z}{\delta s} & rac{\delta z}{\delta t} & rac{\delta z}{\delta u} \ \end{pmatrix}$$

Divergance theorem:

Stokes theorem:

$$\iint_S (
abla imes ec{F}) \cdot dec{S} = \oint_{C=\delta S} ec{F} \cdot dec{r}$$