

## **RX Family**

R01AN2168EJ0112 Rev.1.12 Jun 30, 2019

# USB Host Human Interface Device Class Driver for USB Mini Firmware Using Firmware Integration Technology

#### Introduction

This application note describes USB Host Human Interface Device Class Driver (HHID), which utilizes Firmware Integration Technology (FIT). This module operates in combination with the USB Basic Mini Host and Peripheral Driver. It is referred to below as the USB HHID FIT module.

### **Target Device**

RX111 Group RX113 Group RX231 Group RX23W Group

When using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.

#### **Related Documents**

- 1. Universal Serial Bus Revision 2.0 specification http://www.usb.org/developers/docs/
- 2. USB Class Definitions for Human Interface Devices Version 1.1
- 3. HID Usage Tables Version 1.1 http://www.usb.org/developers/docs/
- 4. RX111 Group User's Manual: Hardware (Document number .R01UH0365)
- 5. RX113 Group User's Manual: Hardware (Document number.R01UH0448)
- 6. RX231 Group User's Manual: Hardware (Document number .R01UH0496)
- 7. RX23W Group User's Manual: Hardware (Document number .R01UH0823)
- 8. USB Basic Mini Host and Peripheral Driver (USB Mini Firmware) using Firmware Integration Technology Application Note (Document number.R01AN2166)
- · Renesas Electronics Website

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#### 1. Overview

The USB HHID FIT module, when used in combination with the USB-BASIC-F/W FIT module, operates as a USB host human interface device class driver (HHID).

This module supports the following functions.

- Data communication with a connected HID device (USB mouse, USB keyboard)
- · Issuing of HID class requests to a connected HID device
- · Supporting Interrupt OUT transfer.

#### 1.1 Please be sure to read

Please refer to the document (Document number: R01AN2166) for *USB Basic Mini Host and Peripheral Driver* (*USB Mini Firmware*) using Firmware Integration Technology Application Note when creating an application program using this driver.

This document is located in the "reference\_documents" folder within this package.

#### 1.2 Note

This driver is not guaranteed to provide USB communication operation. The customer should verify operation when utilizing it in a system and confirm the ability to connect to a variety of different types of devices.

#### 1.3 Limitations

The following limitations apply to the HHID.

- 1. The HID driver must analyze the report descriptor to determine the report format (This HID driver determines the report format from the interface protocol alone.)
- 2. This driver does not support DMA/DTC transfer.

#### 1.4 Terms and Abbreviations

Terms and abbreviations used in this document are listed below.

APL : Application program HCD : Host control driver of

HDCD : Host device class driver (device driver and USB class driver)

HHID : Host human interface device HID : Human interface device class HUBCD : Hub class sample driver

IDE : Integrated Development EnvironmentMGR : Peripheral device state manager of HCD

RSK : Renesas Starter Kits USB : Universal Serial Bus

USB-BASIC-FW : USB Basic Mini Host and Peripheral Driver

#### 1.5 USB HHID FIT

User needs to integrate this module to the project using  $r\_usb\_basic\_mini$ . User can control USB H/W by using this module API after integrating to the project.



### 2. Module Configuration

The HHID comprises the HID class driver and device drivers for mouse and keyboard.

When data is received from the connected USB device, HCD notifies the application. Conversely, when the application issues a request, HCD notifies the USB device.

Figure 2.1 shows the structure of the HHID-related modules. Table 2-1 lists the modules and an overview of each.

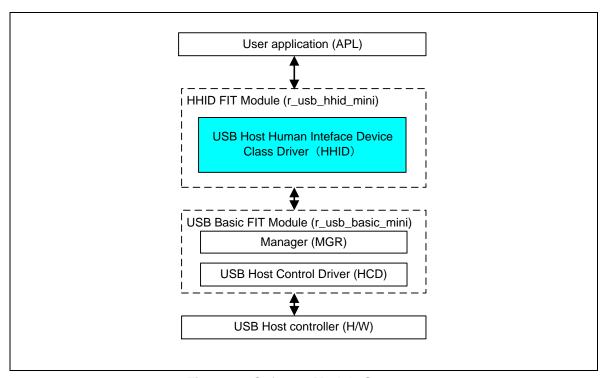


Figure 2.1 Software Module Structure

**Table 2-1 Module Function Descriptions** 

Module Name	Description			
APL	User application program.			
	Switches initiate communication with HID devices and control suspend/resume.			
	The LCD displays the information received from the HID device.			
HHID The HHID analyzes requests from HID devices.				
	Notifies APL key operation information to the HID host via the HCD.			
HCD/MGR	USB host Hardware Control Driver			

### 3. API Information

This Driver API follows the Renesas API naming standards.

### 3.1 Hardware Requirements

This driver requires your MCU support the following features:

USB

### 3.2 Software Requirements

This driver is dependent upon the following packages:

- r\_bsp
- r\_usb\_basic\_mini

### 3.3 Operating Confirmation Environment

Table 3-1 shows the operating confirmation environment of this driver.

Table 3-1 Operation Confirmation Environment

Item	Contents	
C compiler	Renesas Electronics C/C++ compiler for RX Family V.3.01.00	
	(The option "-lang=C99" is added to the default setting of IDE)	
	GCC for Renesas RX 4.08.04.201902	
	(The option "-std=gnu99" is added to the default setting of IDE)	
	IAR C/C++ Compiler for Renesas RX version 4.12.01	
Endian	Little Endian, Big Endian	
USB Driver Revision Number	Rev.1.12	
Using Board	Renesas Starter Kit for RX111	
	Renesas Starter Kit for RX113	
	Renesas Starter Kit for RX231	
	Renesas Solution Starter Kit for RX23W	

### 3.4 Usage of Interrupt Vector

Table 3-2 shows the interrupt vector which this driver uses.

Table 3-2 List of Usage Interrupt Vectors

Device	Contents
RX111	USBI0 Interrupt (Vector number: 36) / USBR0 Interrupt (Vector number: 90)
RX113	USB D0FIFO0 Interrupt (Vector number: 36) / USB D1FIFO0 Interrupt (Vector number: 37)
RX231	
RX23W	

### 3.5 Header Files

All API calls and their supporting interface definitions are located in r\_usb\_basic\_mini\_if.h and r\_usb\_hhid\_mini\_if.h.

### 3.6 Integer Types

This project uses ANSI C99 "Exact width integer types" in order to make the code clearer and more portable. These types are defined in *stdint.h*.



### 3.7 Compile Setting

For compile settings, refer to chapter **7**, **Configuration** (**r\_usb\_hhid\_mini\_config.h**) in this document and chapter "Configuration" in the document (Document number: R01AN2166) for *USB Basic Mini Host and Peripheral Driver* (*USB Mini Firmware*) using Firmware Integration Technology Application Note.

### 3.8 ROM / RAM Size

The follows show ROM/RAM size of this driver.

CC-RX (Optimization Level: Default)

	Checks arguments	Does not check arguments	
ROM size	18.6K bytes (Note 3)	18.4K bytes (Note 4)	
RAM size	5.3K bytes	5.3K bytes	

GCC (Optimization Level: -O2)

	Checks arguments	Does not check arguments
ROM size	21.8K bytes (Note 3)	21.6K bytes (Note 4)
RAM size	5.1K bytes	5.1K bytes

3. IAR (Optimization Level: Medium)

	Checks arguments	Does not check arguments
ROM size	15.5K bytes (Note 3)	15.3K bytes (Note 4)
RAM size	3.7K bytes	3.7K bytes

#### [Note]

- 1. ROM/RAM size for BSP and USB Basic Driver is included in the above size.
- 2. The above is the size when specifying RX V2 core option.
- 3. The ROM size of "Checks arguments" is the value when *USB\_CFG\_ENABLE* is specified to *USB\_CFG\_PARAM\_CHECKING* definition in *r\_usb\_basic\_mini\_config.h* file.
- 4. The ROM size of "Does not check arguments" is the value when *USB\_CFG\_DISABLE* is specified to *USB\_CFG\_PARAM\_CHECKING* definition in *r\_usb\_basic\_mini\_config.h* file.

### 3.9 Argument

For the structure used in the argument of API function, refer to chapter "**Structures**" in the document (Document number: R01AN2166) for *USB Basic Mini Host and Peripheral Driver (USB Mini Firmware) using Firmware Integration Technology Application Note*.

### 3.10 Adding the FIT Module to Your Project

This module must be added to each project in which it is used. Renesas recommends the method using the Smart Configurator described in (1) or (3) below. However, the Smart Configurator only supports some RX devices. Please use the methods of (2) or (4) for RX devices that are not supported by the Smart Configurator.

- (1) Adding the FIT module to your project using "Smart Configurator" on e<sup>2</sup> studio

  By using the Smart Configurator in e<sup>2</sup> studio, the FIT module is automatically added to your project. Refer to "Renesas e<sup>2</sup> studio Smart Configurator User Guide (R20AN0451)" for details.
- (2) Adding the FIT module to your project using the FIT Configurator in e<sup>2</sup> studio

  By using the FIT Configurator in e<sup>2</sup> studio, the FIT module is automatically added to your project. Refer to "Adding Firmware Integration Technology Modules to Projects (R01AN1723)" for details.



- (3) Adding the FIT module to your project using the Smart Configurator in CS+

  By using the Smart Configurator Standalone version in CS+, the FIT module is automatically added to your project. Refer to "Renesas e² studio Smart Configurator User Guide (R20AN0451)" for details.
- (4) Adding the FIT module to your project on CS+ In CS+, please manually add the FIT module to your project. Refer to "Adding Firmware Integration Technology Modules to CS+ Projects (R01AN1826)" for details.

### 4. Target Peripheral List (TPL)

For the structure used in the argument of API function, refer to chapter " **How to Set the Target Peripheral List** (**TPL**)" in the document (Document number: R01AN2166) for *USB Basic Mini Host and Peripheral Driver (USB Mini Firmware) using Firmware Integration Technology Application Note*.

### 5. Human Interface Device Class (HID)

#### 5.1 Basic Functions

This driver complies with the HID class specification. The main functions of this driver are as follows.

- (1) HID device access
- (2) Class request notifications to the HID device
- (3) Data communication with the HID device

### 5.2 Class Requests (Host to Device Requests)

This driver supports the following class requests.

For the class request processing, refer to chapter "USB Class Requests" in the document (Document number: R01AN2166) for USB Basic Mini Host and Peripheral Driver (USB Mini Firmware) using Firmware Integration Technology Application Note.

Table 5-1 HID Class Requests

Symbol	Request	Code	Description
а	USB_GET_REPORT	0x01	Receives a report from the HID device
b	USB_SET_REPORT	0x09	Sends a report to the HID device
С	USB_GET_IDLE	0x02	Receives a duration (time) from the HID device
d	USB_SET_IDLE	0x0A	Sends a duration (time) to the HID device
е	USB_GET_PROTOCOL	0x03	Reads a protocol from the HID device
f	USB_SET_PROTOCOL	0x0B	Sends a protocol to the HID device
	USB_GET_REPORT_DESCRIPT OR	Standard	Transmits report descriptor
	USB_GET_HID_DESCRIPTOR	Standard	Transmits an HID descriptor

The class request data formats supported in this driver are described below.

#### a). GetReport Request Format

Table 5-2 shows the GetReport request format.

Receives a report from the device in a control transfer.

**Table 5-2 GetReport Format** 

bmRequestType	e bRequest	wValue	wIndex	wLength	Data
0xA1	GET_REPORT	ReportType & ReportID	Interface	ReportLength	Report
	(0x01)	Reportio			

#### b). SetReport Request Format

Table 5-3 shows the SetReport request format.

Sends report data to the device in a control transfer.

**Table 5-3 SetReport Format** 

bmRequestType	bRequest	wValue	windex	wLength	Data
0x21	SET_REPORT (0x09)	ReportType & ReportID	Interface	ReportLength	Report



#### c). GetIdle Request Format

Table 5-4 shows the GetIdle request format.

Acquires the intarval time of the report notification (interrupt transfer). Idle rate is indicated in 4 ms units.

#### **Table 5-4 GetIdle Format**

bmRequestType	bRequest	wValue	wIndex	wLength	Data
0xA1	GET_IDLE	0(Zero) & ReportID	Interface	1(one)	Idle rate
	(0x02)				

### d). SetIdle Request Format

Table 5-5 shows the SetIdle request format.

Sets the interval time of the report notification (interrupt transfer). Duration time is indicated in 4 ms units.

#### **Table 5-5 SetIdle Format**

bmRequestType	bRequest	wValue	wIndex	wLength	Data
0x21	SET_IDLE (0x0A)	Duration & ReportID	Interface	0(zero)	Not applicable

### e). GetProtocol Request Format

Table 5-6 shows the GetProtocol request format.

Acquires current protocol (boot protocol or report protocol) settings.

#### **Table 5-6 GetProtocol Format**

bmRequestType	bRequest	wValue	wIndex	wLength	Data
0xA1	GET_PROTOCOL	0(Zero)	Interface	1(one)	0(BootProtocol) /
	(0x03)				1(ReportProtocol)

### f). SetProtocol Request Format

Table 5-7 shows the SetProtocol request format. Sets protocol (boot protocol or report protocol).

### **Table 5-7 SetProtocol Format**

bmRequestType	bRequest	wValue	wIndex	wLength	Data
0x21	SET_PROTOCOL	0(BootProtocol) /	Interface	0(zero)	Not applicable
	(0x03)	1(ReportProtocol)			



### 5.3 HID-Report Format

### 5.3.1 Receive Report Format

Table 5-8 shows the receive report format used for notifications from the HID device. Reports are received in interrupt IN transfers or class request GetReport.

**Table 5-8 Receive Report Format** 

Offset	Keyboard Mode	Mouse Mode
Data length	8 Bytes	3 Bytes
0 (Top Byte)	Modifier keys	b0: Button 1
		b1: Button 2
		b2-7: Reserved
+1	Reserved	X displacement
+2	Keycode 1	Y displacement
+3	Keycode 2	-
+4	Keycode 3	-
+5	Keycode 4	-
+6	Keycode 5	-
+7	Keycode 6	-

### 5.3.2 Transmit Report Format

Table 5-9 shows the format of the transmit report sent to the HID device. Reports are sent in the class request SetReport.

**Table 5-9 Transmit Report Format** 

Offset	Keyboard	Mouse
Data length	1 Byte	Not supported
0 (Top Byte)	b0: LED 0 (NumLock)	-
	b1: LED 1(CapsLock)	
	b2: LED 2(ScrollLock)	
	b3: LED 3(Compose)	
	b4: LED 4(Kana)	
+1 ~ +16	-	-

#### 5.3.3 Note

The report format used by HID devices for data communication is based on the report descriptor. This HID driver does not acquire or analyze the report descriptor; rather, the report format is determined by the interface protocol code.

### 6. API Functions

The following is Host Human Interface Device Class specific API function.

API	Desription
R_USB_HhidGetType()	Obtains type information for the HID device.
R_USB_HhidGetMxps()	Obtains the max packet size for the HID device.

### Note:

Refer to chapter "API" in the document (Document number: R01AN2166) for *USB Basic Mini Host and Peripheral Driver (USB Mini Firmware) using Firmware Integration Technology Application Note* when using the other API.

### 6.1 R\_USB\_HhidGetType

### Obtains type information for the HID device.

#### **Format**

usb\_err\_t R\_USB\_HhidGetType(uint8\_t \*p\_type)

### **Arguments**

p\_drive Pointer to the area to store the type information

#### **Return Value**

USB\_SUCCESS Successfully completed

USB\_ERR\_PARA Parameter error USB\_ERR\_NG Other error

### **Description**

This API obtains type information (mouse, keyboard, etc.) for the connected HID device. The type information is set to the area indicated by the argument ( $p_type$ ). For the type information to be set, see Table 6-1.

### Table 6-1 Type Information

Type Information	Description
USB_HID_KEYBOARD	Keyboard
USB_HID_MOUSE	Mouse
USB_HID_OTHER	HID device other than keyboard and mouse

#### Note

- 1. If USB\_NULL is assigned to the argument (p\_type), then USB\_ERR\_PARA will be the return value.
- 2. This function can be called when the USB device is in the configured state. When the API is called in any other state, *USB\_ERR\_NG* is returned.

### **Example**

#### 6.2 R\_USB\_HhidGetMxps

#### Obtains the max packet size of the HID device.

#### **Format**

```
usb_err_t
                  R_USB_HhidGetMxps(uint16_t *p_mxps, uint8_t dir)
```

#### **Arguments**

p\_mxps Pointer to the area to store the max packe size

Transfer direction dir

#### **Return Value**

```
USB SUCCESS
                Successfully completed
USB ERR PARA Parameter error
USB_ERR_NG
                Other error
```

#### **Description**

This API obtains max packet size for the connected HID device. The max packet size is set to the area indicated by the 1st argument  $(p\_mxps)$ .

Set the direction (USB\_IN / USB\_OUT) of the max packet size which the user want to obtain to the 2nd argument.

#### Note

- 1. If USB\_NULL is assigned to the argument (p\_mxps), then USB\_ERR\_PARA will be the return value.
- This function returns USB\_ERR\_PARA when the connected HID device does not support the transfer direction set the 2nd argument (dir).
- This function can be called when the USB device is in the configured state. When the API is called in any other state, USB\_ERR\_NG is returned.

#### **Example**

```
void usb_application( void )
  uint16_t mxps;
  usb ctrl t ctrl;
  while (1)
    switch (R_USB_GetEvent(&ctrl))
       case USB_STS_CONFIGURED:
         R_USB_HhidGetMxps(&mxps, USB_IN);
       break;
    }
  }
}
```

### 7. Configuration (r\_usb\_hhid\_mini\_config.h)

Please set the following according to your system.

#### Note:

Be sure to set *r\_usb\_basic\_mini\_config.h* file as well. For *r\_usb\_basic\_mini\_config.h* file, refer to chapter "**Configuration**" in the document (Document number: R01AN2166) for *USB Basic Mini Host and Peripheral Driver (USB Mini Firmware) using Firmware Integration Technology Application Note.* 

#### 1. Setting pipe to be used

Set the pipe number (PIPE6 to PIPE9) to use for Interrupt IN transfer and Interrupt OUT. Do not set the same pipe number.

#define	USB_CFG_HHID_INT_IN	Pipe number (USB_PIPE6 to USB_PIPE9)
#define	USB CFG HHID INT OUT	Pipe number (USB_PIPE6 to USB_PIPE9)



### 8. Creating an Application

Refer to the chapter "Creating an Application Program" in the document (Document number: R01AN2166) for USB Basic Mini Host and Peripheral Driver (USB Mini Firmware) using Firmware Integration Technology Application Note.

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### **Revision Record**

### Description

		Description	
Rev.	Date	Page	Summary
1.00	Dec 1, 2014	_	First edition issued
1.01	Jun 1, 2015	_	RX231 is added in the target device.
1.02	Dec 28, 2015	_	Upgrading of this USB driver by upgrading of "USB Basic Mini Firmware (R01AN2166)".
1.10	Nov 30, 2018	_	Supporting Smart Configurator.
			<ol><li>The following chapter is added.</li></ol>
			(1). 7. Configuration (r_usb_hhid_mini_config.h)
			<ol><li>The following chapters are changed.</li></ol>
			(1). 3. API Information
			(2). 5. Human Interface Device Class (HID)
			(3). 6. API Functions
			(4). 8. Creating an Application
			4. The following chapters are deleted.
			"How to Register Class Driver", "System Resources", "Task ID and Priority Setting".
1.11	May 31, 2019	_	Support GCC compiler and IAR compiler.
1.12	Jun 30, 2019	_	RX23W is added in the target device.

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The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

#### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
 In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

#### 3. Prohibition of Access to Reserved Addresses

completed.

Access to reserved addresses is prohibited.

 The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

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