

# MAT 4800 Homework # 4

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## Problem #1

### Part a

Suppose we are given the following function,

$$f(x_1, x_2) = 5x_1^2 + 2x_1x_2 + x_2^2 - x_1 + 2x_2 + 3$$

on  $D = \mathbb{R}^2$ .

Here we will compute the Hessian as

$$Hf = \begin{bmatrix} 10 & 2 \\ 2 & 2 \end{bmatrix}$$

by the principal minors approach we see that,

$$\begin{aligned}\Delta_1 &= 10 > 0 \\ \Delta_2 &= 20 - 4 = 16 > 0\end{aligned}$$

thus the Hessian is Positive Definite and thus  $f(x_1, x_2)$  is convex, namely strictly convex by *Theorem 2.3.7*.

### Part b

Suppose we are given the following function,

$$f(x_1, x_2) = \frac{x_1^2}{2} + \frac{3x_2^2}{2} + \sqrt{3}x_1x_2$$

on  $D = \mathbb{R}^2$ .

$$Hf = \begin{bmatrix} 1 & \sqrt{3} \\ \sqrt{3} & 3 \end{bmatrix}$$

by the principal minors approach we see that,

$$\begin{aligned}\Delta_1 &= 1 > 0 \\ \Delta_2 &= 0\end{aligned}$$

thus the Hessian is Positive semi-definite and thus  $f(x_1, x_2)$  is convex by *Theorem 2.3.7*.

## Part e

Suppose we are given the following function,

$$f(x_1, x_2) = c_1 x_1 + \frac{c_2}{x_1} + c_3 x_2 + \frac{c_4}{x_2}$$

on  $D = \{(x_1, x_2) \in \mathbb{R}^2 : x_1 > 0, x_2 > 0\}$  where  $c_i$  is a positive number for  $i = 1, 2, 3, 4$ .

$$Hf = \begin{bmatrix} \frac{2c_2}{x_1^3} & 0 \\ 0 & \frac{2c_4}{x_2^3} \end{bmatrix}$$

by the principal minors approach we see that,

$$\begin{aligned}\Delta_1 &= \frac{2c_2}{x_1^3} > 0 \\ \Delta_2 &= \frac{4c_2 c_4}{x_1^3 x_2^3} > 0\end{aligned}$$

thus the Hessian is Positive Definite and thus  $f(x_1, x_2)$  is convex, namely strictly convex by *Theorem 2.3.7*.

## Problem #2

Suppose we have the function  $f(\vec{x})$  defined on the set,

$$D = \{\vec{x} \in \mathbb{R}^3 : x_1 > 0, x_2 > 0, x_3 > 0\}$$

by,

$$f(\vec{x}) = (x_1)^{r_1} + (x_2)^{r_2} + (x_3)^{r_3}$$

where  $r_i > 0$  for  $i = 1, 2, 3$

we compute the Hessian Matrix as,

$$Hf = \begin{bmatrix} (r_1 - 1)r_1 x_1^{r_1-2} & 0 & 0 \\ 0 & (r_2 - 1)r_2 x_2^{r_2-2} & 0 \\ 0 & 0 & (r_3 - 1)r_3 x_3^{r_3-2} \end{bmatrix}$$

such that,

$$\begin{aligned} d_1 &= (r_1 - 1)r_1 x_1^{r_1-2} \\ d_2 &= (r_2 - 1)r_2 x_2^{r_2-2} \\ d_3 &= (r_3 - 1)r_3 x_3^{r_3-2} \end{aligned}$$

### Part a

Here if we assume that  $r_i > 1$ , then note by construction that

$$\begin{aligned} d_1 &> 0 \\ d_2 &> 0 \\ d_3 &> 0 \end{aligned}$$

which means that the Hessian is **Positive Definite** and thus  $f(x_1, x_2)$  is convex, namely strictly convex by *Theorem 2.3.7*.

### Part b

Here if we instead assume that  $r_i < 1$ , then note by construction that

$$\begin{aligned} d_1 &< 0 \\ d_2 &< 0 \\ d_3 &< 0 \end{aligned}$$

which means that the Hessian is **Negative Definite** and thus  $f(x_1, x_2, x_3)$  is concave, namely strictly concave by *Theorem 2.3.7*.

## Problem #3

Suppose we are given the function,

$$f(x_1, x_2, x_3) = x_1^{-q} + x_2^{-r} + x_3^{-s}$$

defined on  $D = \{(x_1, x_2, x_3) : x_1 > 0, x_2 > 0, x_3 > 0\}$  for  $q, r, s \in \mathbb{N}$ . Here we first compute the Hessian matrix as,

$$Hf = \begin{bmatrix} -(-q-1)qx_1^{-q-2} & 0 & 0 \\ 0 & -(-r-1)rx_2^{-r-2} & 0 \\ 0 & 0 & -(-s-1)sx_3^{-s-2} \end{bmatrix}$$

such that,

$$\begin{aligned} d_1 &= -(-q-1)qx_1^{-q-2} = (q+1)qx_1^{-q-2} > 0 \\ d_2 &= -(-r-1)rx_2^{-r-2} = (r+1)rx_2^{-r-2} > 0 \\ d_3 &= -(-s-1)sx_3^{-s-2} = (s+1)sx_3^{-s-2} > 0 \end{aligned}$$

Thus the Hessian is Positive Definite and thus  $f(x_1, x_2, x_3)$  is convex, namely strictly convex by *Theorem 2.3.7*.

## Problem #4

Suppose we are given the following function,

$$f(x_1, x_2, x_3) = x_1 \ln x_1 + x_2 \ln x_2 + x_3 \ln x_3$$

on  $x_1, x_2, x_3 > 0$ . Here we compute the Hessian as,

$$Hf = \begin{bmatrix} \frac{1}{x} & 0 & 0 \\ 0 & \frac{1}{y} & 0 \\ 0 & 0 & \frac{1}{z} \end{bmatrix}$$

such that,

$$\begin{aligned} d_1 &= \frac{1}{x} > 0 \\ d_2 &= \frac{1}{y} > 0 \\ d_3 &= \frac{1}{z} > 0 \end{aligned}$$

Thus the Hessian is Positive Definite and thus  $f(x_1, x_2, x_3)$  is convex, namely strictly convex by *Theorem 2.3.7*.

## Problem #5

Suppose we are given the function,

$$f(x_1, x_2) = \sqrt{x_1 x_2}$$

with  $x_1, x_2 > 0$ . We compute the Hessian as,

$$Hf = \begin{bmatrix} -\frac{y^2}{4(xy)^{3/2}} & \frac{1}{2\sqrt{xy}} - \frac{xy}{4(xy)^{3/2}} \\ \frac{1}{2\sqrt{xy}} - \frac{xy}{4(xy)^{3/2}} & -\frac{x^2}{4(xy)^{3/2}} \end{bmatrix}$$

Note that,

$$\begin{aligned} \Delta_1 &= -\frac{y^2}{4(xy)^{3/2}} < 0 \\ \Delta_2 &= 0 \end{aligned}$$

Here we see that that the Hessian is Negative Semi-definite and thus  $f(x_1, x_2, x_3)$  is concave by *Theorem 2.3.7*.

## Problem #6

Suppose we are given the function,

$$f(x) = x + \frac{1}{x}$$

for  $x > 0$ . We first compute the derivative,

$$f'(x) = 1 - \frac{1}{x^2}$$

setting equal to 0, we get

$$0 = 1 - \frac{1}{x^2}$$

yields  $x^* = 1$  which is the critical point.

## Part a

By computing the second derivative we get

$$f''(x) = \frac{2}{x^3}$$

plugging in  $x^*$  to get,

$$f''(1) = \frac{2}{1^3} = 2 > 0$$

Thus see that  $x^* = 1$  is a strict minimizer of  $f(x)$ .

## Problem #7

Plotting the  $f(x) = x + \frac{1}{x}$  we get,

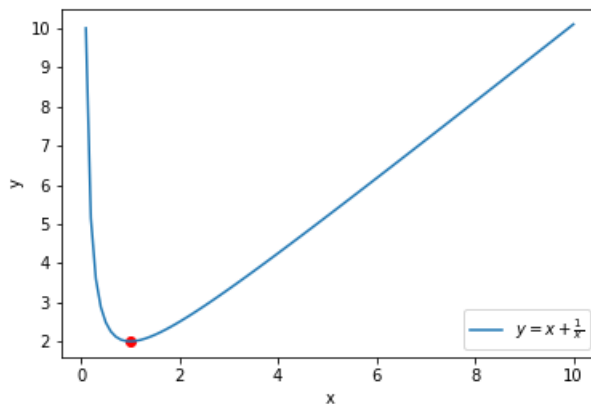


Figure 1: Graph of  $f(x) = x + \frac{1}{x}$

## Problem #8

Suppose we are given,

$$g(x_1, x_2) = 2x_1^2 + x_2^2 + \frac{1}{2x_1^2 + x_2^2}$$

let  $y(x_1, x_2)$  be defined as,

$$y(x_1, x_2) = 2x_1^2 + x_2^2$$

we then rewrite  $g$  as,

$$g(x_1, x_2) = y(x_1, x_2) + \frac{1}{y(x_1, x_2)}$$

note that from (a) the above equation has a global minimum at  $y(x_1, x_2) = 1$ , thus we find the critical points of  $g$  lie on  $2x_1^2 + x_2^2 = 1$  which are the minimizers of  $g(x_1, x_2)$ , where  $g(x_1, x_2) = 2$ .

## Problem #9

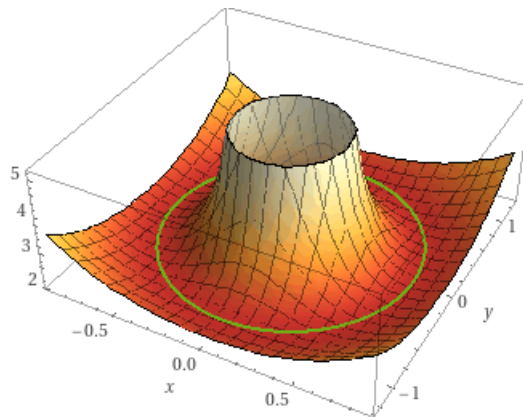


Figure 2: graph of  $g(x_1, x_2)$

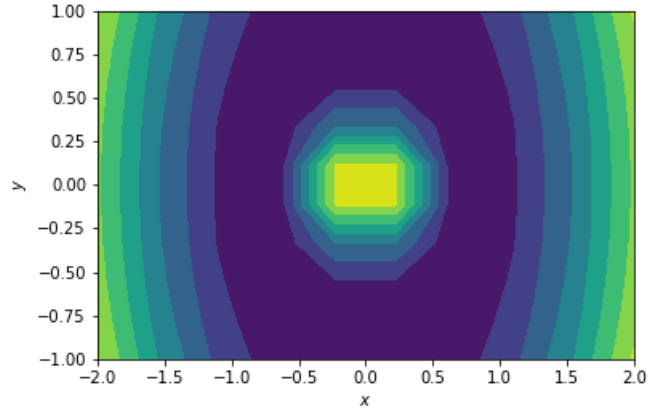


Figure 3: contour of  $g(x_1, x_2)$

## Problem #10

Suppose we are given,

$$h(x_1, x_2, x_3) = e^{x_1 - x_2 + x_3} + e^{-x_1 + x_2 - x_3}$$

here we let  $j(x_1, x_2)$  be defined as,

$$j(x_1, x_2, x_3) = x_1 - x_2 + x_3$$

then we rewrite  $h$  as,

$$h(x_1, x_2, x_3) = e^{j(x_1, x_2, x_3)} + e^{-j(x_1, x_2, x_3)}$$

next let  $t = e^{j(x_1, x_2, x_3)}$  to get,

$$h(x_1, x_2, x_3) = t + \frac{1}{t}$$

then we see that from (a) we see that the minimizers occur at  $t^* = 1$ , thus we see,

$$e^{j(x_1, x_2, x_3)=1}$$



which implies that,

$$x_1 - x_2 + x_3 = 0$$

of which the plane defined above is the minimizers of  $h$ , with  $h(x_1, x_2, x_3) = 2$ .