

Lab 1: Sensors

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1. The numbers and letters simply help you identify individual holes in the breadboard.
2. The plus sign indicates voltage and the minus sign indicates ground.
3. The rows are connected horizontally but not across the bridge in the middle and they are connected vertically on the plus and minus sign strips or the voltage and ground strips.
4. Jumper wires are simply to connect holes on the breadboard.

Lab1ButtonLed.py source code

```
#!/usr/bin/env python3
import RPi.GPIO as GPIO
import time

BtnPin = 11
Gpin   = 13
Rpin   = 12

def setup():
    print("setup method called")
    GPIO.setmode(GPIO.BOARD)      # Numbers GPIOs by physical location
    GPIO.setup(Gpin, GPIO.OUT)    # Set Green Led Pin mode to output
    GPIO.setup(Rpin, GPIO.OUT)    # Set Red Led Pin mode to output
    GPIO.setup(BtnPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)
    # Set BtnPin's mode is input, and pull up to high level(3.3V)
```

```

GPIO.add_event_detect(BtnPin, GPIO.BOTH, callback=detect, bouncetime=200)

def Led(x):
    print("button pressed")
    print(x)
    if (x==0):
        GPIO.output(Rpin,0)
        GPIO.output(Gpin,0)
    while True:
        if not GPIO.input(BtnPin):
            GPIO.output(Rpin, 1)
            time.sleep(3)
            GPIO.output(Rpin, 0)
            GPIO.output(Gpin,0)
            time.sleep(1)
        else:
            break

def detect(chn):
    print("detect method called")
    Led(GPIO.input(BtnPin))

def loop():
    print("loop method called")
    while True:
        pass

def destroy():
    print("destroy method called")
    GPIO.output(Gpin, GPIO.HIGH)      # Green led off
    GPIO.output(Rpin, GPIO.HIGH)      # Red led off
    GPIO.cleanup()                   # Release resource

if __name__ == '__main__':          # Program start from here
    setup()
    try:
        loop()
    except KeyboardInterrupt:      # When 'Ctrl+C' is pressed, the child program
executed.
        destroy()

```

Lab1Led.py source code

```

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import RPi.GPIO as GPIO

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import time

BtnPin = 11
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def setup():
    print("setup method called")
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    GPIO.setup(BtnPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)
# Set BtnPin's mode is input, and pull up to high level(3.3V)

def loop():
    print("loop method called")
    while True:
        print("printing loop")
        GPIO.output(Rpin,1)
        time.sleep(3)
        GPIO.output(Gpin,0)
        GPIO.output(Rpin,0)
        time.sleep(1)

def destroy():
    print("destroy method called")
    GPIO.output(Gpin, GPIO.HIGH)   # Green led off
    GPIO.output(Rpin, GPIO.HIGH)   # Red led off
    GPIO.cleanup()                 # Release resource

if __name__ == '__main__':        # Program start from here
    setup()
    try:
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