

Maxwell Austin Feinberg

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EDUCATION **University of Illinois Urbana-Champaign, Champaign, IL**
B.S. Aerospace Engineering, Minor in Computer Science, May 2018

- James Scholar
- Member of Tau Beta Pi
- GPA: 3.98, Dean's List

Selected course work:

- CS 440 Artificial Intelligence
- CS 543 Computer Vision
- ECE 470 Introduction to Robotics
- ECE 489 Robot Dynamics and Control

Deerfield High School, Deerfield, IL

- GPA: 3.99, Salutatorian 2/431

EXPERIENCE **Nasa Ames Intelligent Robotics Group**
Intelligent Robotics Intern June 2016 - August 2016

- Designed and performed reliability tests for the propulsion and perching arm subsystems of Astrobee, the freeflying astronaut assistant robot for the International Space Station (ISS)
- Developed a bootloader for the dsPIC33EP512MC806 microcontroller by Microchip for the perching arm subsystem of Astrobee
- Utilized the Robot Operating System (ROS) and Gazebo to increase the functionality of the simulator for Astrobee

Danaher Sensors and Controls
Mechanical Engineering Intern May 2015 - August 2015

- Developed software for an embedded encoder monitoring system that employed cloud computing for data analysis
- Designed and performed thermal and battery tests for the prototype encoder system
- Tested the viability of a mesh network of encoder systems
- Designed tools and fixtures utilized for manufacturing encoders

Evanston Hospital
Surgical Research Intern June 2013 - August 2013

- Assisted two undergraduate students with their surgery related research projects
- One of the studies examined the safety of a gastric bypass after a sleeve gastropasty
- The other study compared various laparoscopic vessel sealing energy devices

Northshore University Health Systems
Informatics Research Intern June 2012 - August 2012

- Created a mobile application designed to aid doctors with Deep Vein Thrombosis(DVT) prophylaxis utilizing the Caprini DVT Score system
- The application is available on the Apple app market under the name Caprini DVT

ADDITIONAL
EXPERIENCE

Anheuser-Busch Inbev Hack the World

Baxter Research Robot Hack

September 17-18, 2016

- Utilized the Baxter Research Robot to carry out beverage preparation and to analyze the health of grain samples
- Utilized vision feedback to improve the Robot's grasping capabilities
- Utilized multithreading to control both of the robot's arms simultaneously

American Institute of Aeronautics and Astronautics

Technical Director

May 2016 - Present

- Managed 6 Technical Projects with a total team encompassing more than 50 people
- Projects Include: a 3D Printed UAV, JetCat Jet Engine Research, Engineering Open House Projects, Autonomous Hexrotor Design, an FPV System, and a Rocket Simulator

Hexrotor Project

August 2015 - May 2016

- Managed a team of 8 people while they developed an autonomous hexrotor from scratch
- Designed the structure of the hex rotor using a novel, minimalist design to minimize weight and allow for modularity
- Designed software for the hexrotor utilizing the open source ArduPilot project as a base

Junior Board President

August 2015 - May 2016

- Managed a team of 6 people that organized social, educational, and professional events for the aerospace engineering department students
- Taught monthly seminars on how to program using Python and MATLAB for students that lacked coding experience

Bretl Research Group

Undergraduate Research

September 2015 - Present

- Integrated IMU data into visual simultaneous localization and mapping (SLAM) algorithms to improve performance
- Currently implementing a stereo RGBD camera system to localize thin elastic rods in order to test an advanced physics model of the rod

GRANTS AWARDED	University NASA Aeronautics Scholarship	Fall 2015 and Fall 2016
PUBLICATIONS	<p>B. Abar, M. Feinberg, R. Tanaka, MD, PhD, M. Ujiki, MD, FACS, <i>Conversion to Gastric Bypass Is Technically Feasible After Endoscopic Gastroplasty</i>, Society of American Gastrointestinal and Endoscopic Surgeons (SAGES) , Los Angeles, CA, 2014.</p> <p>D. Meiselman, Mr, R. Tanaka, MD, PhD, M. Zapf, C. Karras, B. Abar, M. Feinberg, J. Zhao, MD, M. Ujiki, MD, <i>Evaluation of Vessel Sealing Performance of Ultrasonic Devices in a Porcine Model</i>, Society of American Gastrointestinal and Endoscopic Surgeons (SAGES) , Los Angeles, CA, 2014.</p>	
PROGRAMMING LANGUAGES	Proficient: C++, Java, python, MATLAB, L ^A T _E X Familiar: C, C#, x86 Assembly, Javascript, Bash, Mathematica	
SOFTWARE PACKAGES	Operating Systems Proficient: Ubuntu, Debian, Windows 10 Familiar: Arch Linux CAD Proficient: Autodesk Inventor, AutoCAD, Pro/Engineer, CREO, NX9/10 Familiar: Solidworks FEA Familiar: Abaqus Software Frameworks Proficient: ROS, OpenCV, Tesseract, PySerial Familiar: Microchip IDE and Packages, FTDI Packages, PCL Additional Software Proficient: Simulink	
REFERENCES	<p>Ikemefuna Agbanusi, Visiting Assistant Professor, Colgate University, (315)228-7951, iagbanusi@colgate.edu</p> <p>Michael McIntyre, GNC Engineer, NASA (650)279-7182, michael.j.mcintyre@nasa.gov</p> <p>Jonathan Barlow, Astrobee Integration and Test Lead, NASA, (801)830-5183, jonathan.s.barlow@nasa.gov</p> <p>In-Won Park, Robotics Engineer, NASA (408)455-2051, in.w.park@nasa.gov</p>	