

Guided dog→cat trajectory

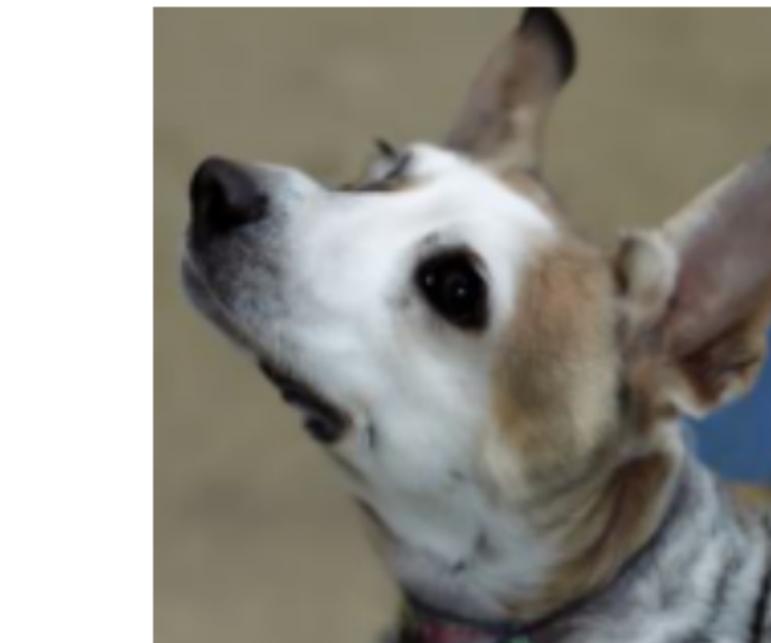
t=0



t=6



t=13



t=19



t=26



t=39



t=46

