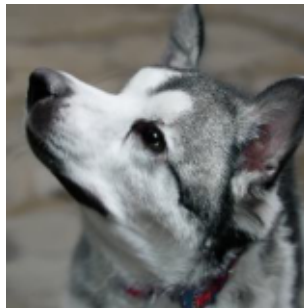


Guided dog→cat trajectory

t=0



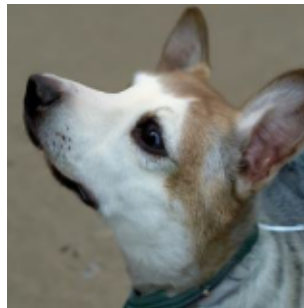
t=6



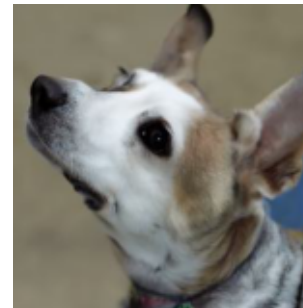
t=13



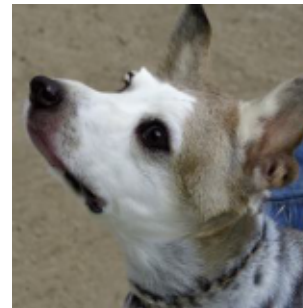
t=19



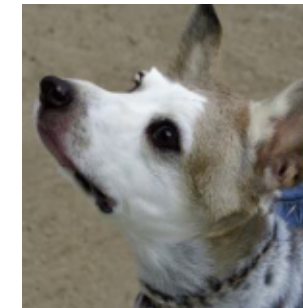
t=26



t=32



t=39



t=46

