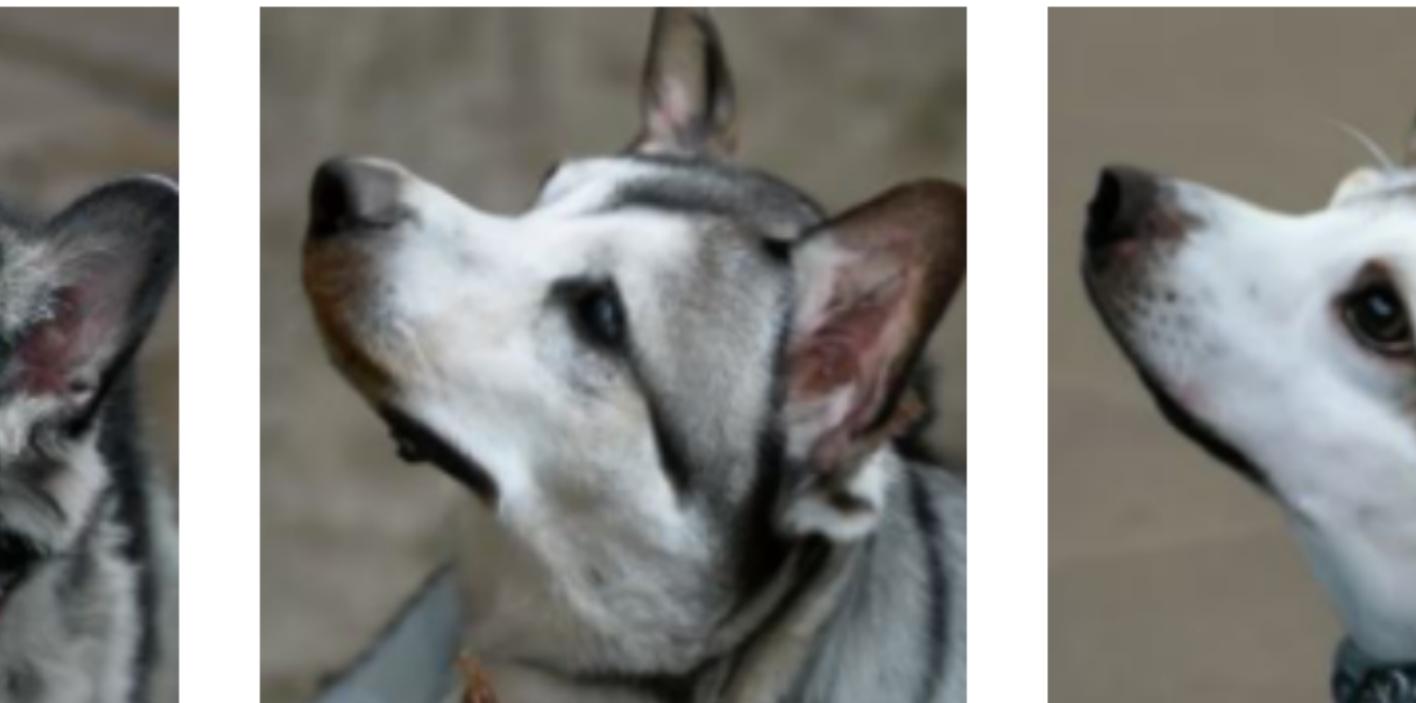


Guided dog→cat trajectory

t=0



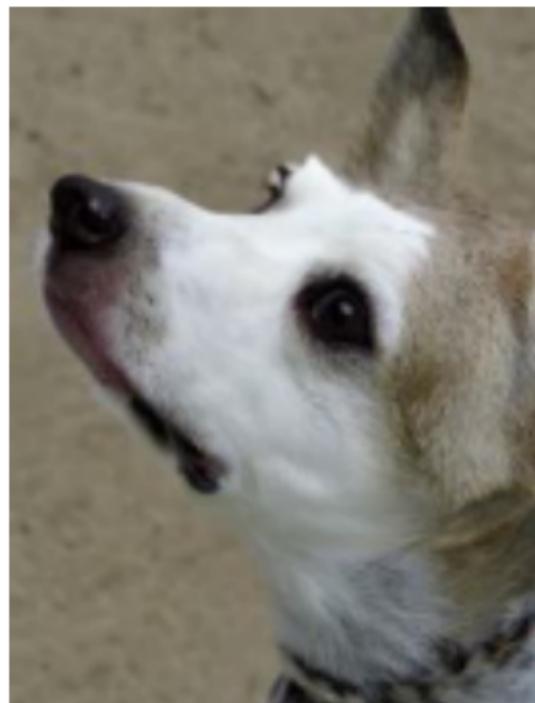
t=6



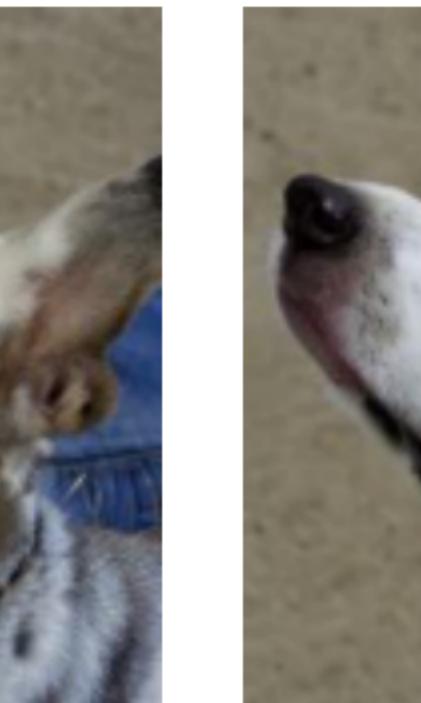
t=12



t=18



t=25



t=31



t=44

