

Unguided trajectory (full)

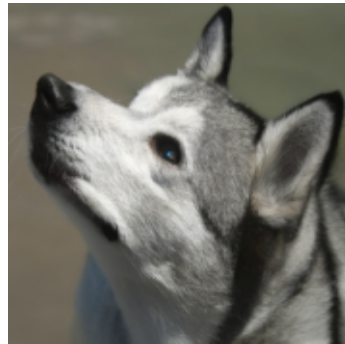
t=0



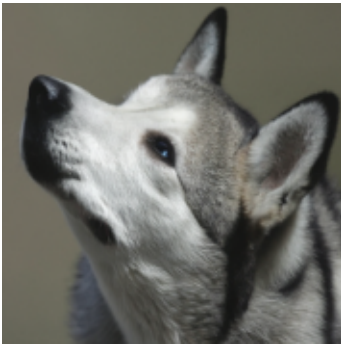
t=14



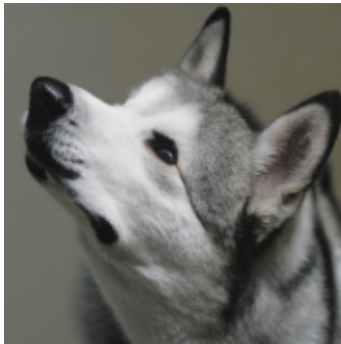
t=28



t=43



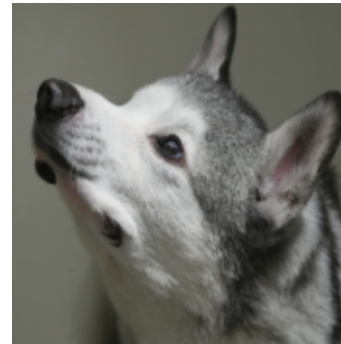
t=57



t=72



t=86



t=101

