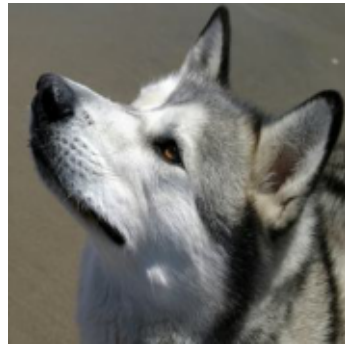
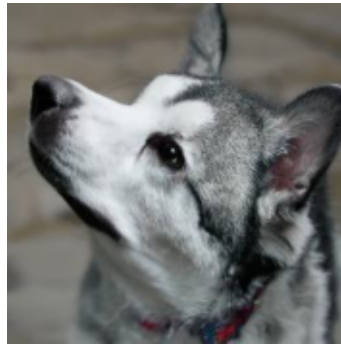


# Guided dog→cat trajectory

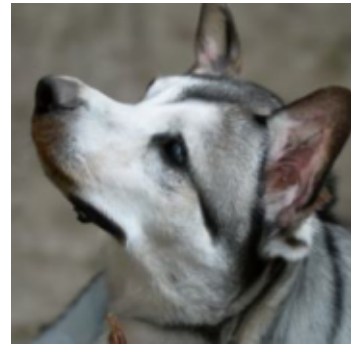
t=0



t=6



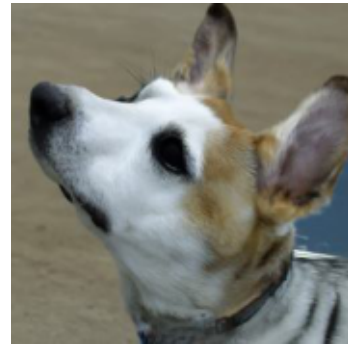
t=12



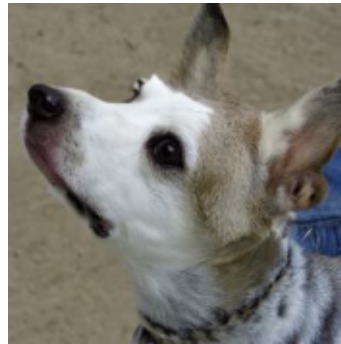
t=18



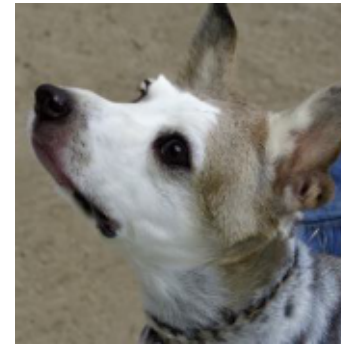
t=25



t=31



t=37



t=44

