

Unguided trajectory (full)

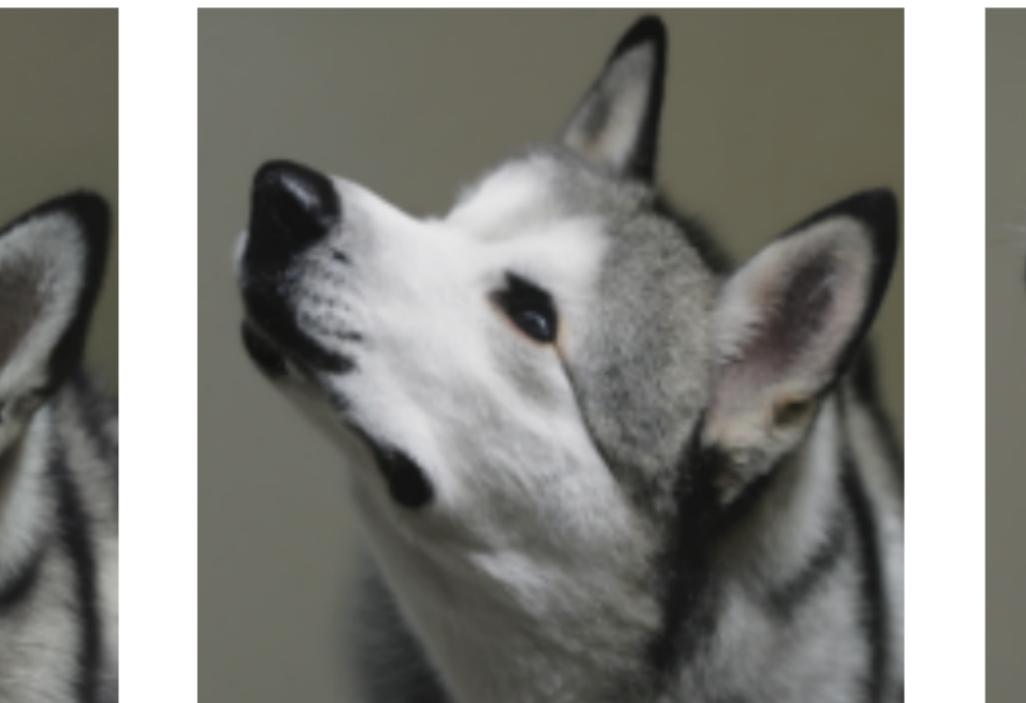
t=0



t=14



t=28



t=43



t=57



t=86



t=101

