

Unguided trajectory (full)

t=0



t=14



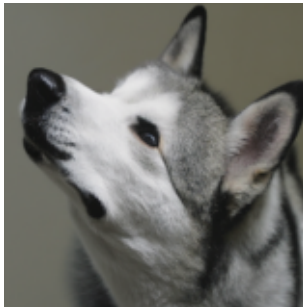
t=28



t=43



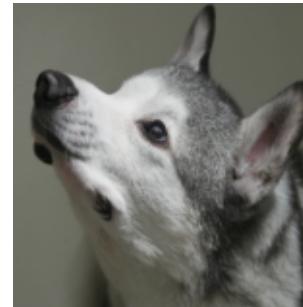
t=57



t=72



t=86



t=101

