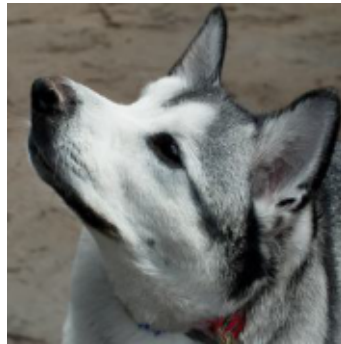


Guided dog→cat trajectory

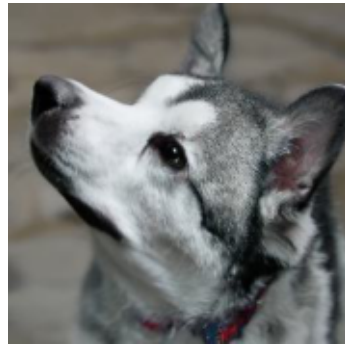
t=0



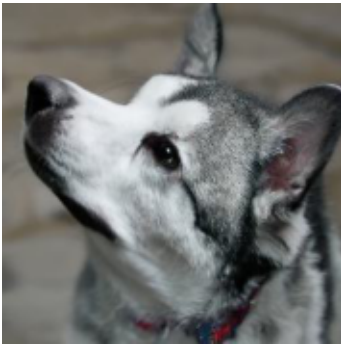
t=3



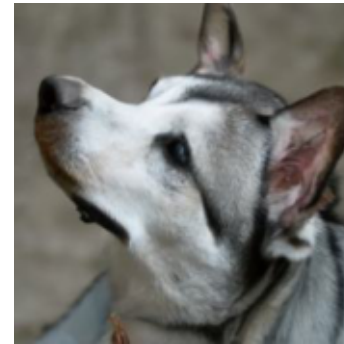
t=6



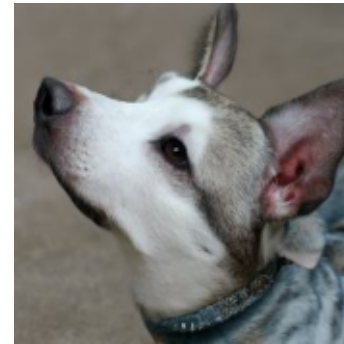
t=9



t=12



t=15



t=18



t=21

