

```

/*WAP to implement 3D Transformation.*/
/*
choice=1 , Translation, set t_x,t_y,t_z
choice=2 , Rotation about z axis (XY plane), set thitha
choice=3 , Rotation about x axis (YZ plane), set thitha
choice=4 , Rotation about y axis (XZ plane), set thitha
choice=5 , Scaling about a fixed point, set s_x,s_y,s_z,x_f,y_f,z_f
choice=6 , Reflektion about z axis (XY plane)
choice=7 , Reflection about x axis (YZ plane)
choice=8 , Reflection about y axis (XZ plane)
choice=9 , Shearing about z axis keeping z same (XY plane), set sh_x,sh_y
choice=10, Shearing about x axis keeping x same (YZ plane), set sh_y,sh_z
choice=11 , Shearing about y axis keeping y same (ZX plane), set sh_x,sh_z
*/
int choice=5;
float t_x=100,t_y=-150,t_z=-300;//Translation
float thitha=60;//Rotation thitha in degree
float s_x=2,s_y=2,s_z=2,x_f=20,y_f=-30,z_f=40 ;//Scaling
float sh_x=2,sh_y=-1,sh_z=-1.333;//Shearing
float a=400,b=-150,c=-150,d=300,e=-100,f=100,i=-50,j=100,k=120,l=-100,m=-
230,n=10;
float ac=400,bc=-150,cc=200,dc=300,ec=-100,fc=150,ic=-50,jc=100,kc=200,lc=-
100,mc=-230,nc=90;
void setup()
{
  size(1300,700,P3D);
  draw();
  jump();
  endShape();
}
void draw()
{
  translate(width/2, height/2, 0);
  rotateX(PI/2);
  rotateZ(-PI/6);
  noFill();

```

```
beginShape();  
strokeWeight(3);
```

```
stroke(0,0,255);  
vertex(a,b,c);  
vertex(d,e,f);  
vertex(i,j,k);
```

```
vertex(i,j,k);  
vertex(l,m,n);  
vertex(d,e,f);
```

```
vertex(l,m,n);  
vertex(a,b,c);  
vertex(i,j,k);
```

```
vertex(a,b,c);  
vertex(l,m,n);  
vertex(d,e,f);
```

```
endShape();
```

```
beginShape();
```

```
stroke(0,0,0);  
vertex(ac,bc,cc);  
vertex(dc,ec,fc);  
vertex(ic,jc,kc);
```

```
vertex(ic,jc,kc);  
vertex(lc,mc,nc);  
vertex(dc,ec,fc);
```

```
vertex(lc,mc,nc);  
vertex(ac,bc,cc);  
vertex(ic,jc,kc);
```

```

vertex(ac,bc,cc);
vertex(lc,mc,nc);
vertex(dc,ec,fc);

endShape();

strokeWeight(0.5);

stroke(0,255,0);
line(a,b,c,ac,bc,cc);
line(d,e,f,dc,ec,fc);
line(i,j,k,ic,jc,kc);
line(l,m,n,lc,mc,nc);
}
void jump()
{
  if (choice==1) translation();
  if (choice==2) rotation_z();
  if (choice==3) rotation_x();
  if (choice==4) rotation_y();
  if (choice==5) scaling();
  if (choice==6) reflection_z();
  if (choice==7) reflection_x();
  if (choice==8) reflection_y();
  if (choice==9) shearing_z();
  if (choice==10) shearing_x();
  if (choice==11) shearing_y();
}
void translation()//choice=1
{
  ac=a+t_x;
  bc=b+t_y;
  cc=c+t_z;

  dc=d+t_x;
  ec=e+t_y;
  fc=f+t_z;

```

```

ic=i+t_x;
jc=j+t_y;
kc=k+t_z;

lc=l+t_x;
mc=m+t_y;
nc=n+t_z;
}
void rotation_z()//choice=2
{
    thitha =thitha * 3.1415 /180;

    ac=a*cos(thitha)-b*sin(thitha);
    bc=a*sin(thitha)+b*cos(thitha);
    cc=c;

    dc=d*cos(thitha)-e*sin(thitha);
    ec=d*sin(thitha)+e*cos(thitha);
    fc=f;

    ic=i*cos(thitha)-j*sin(thitha);
    jc=i*sin(thitha)+j*cos(thitha);
    kc=kc+t_z;

    lc=l*cos(thitha)-m*sin(thitha);
    mc=l*sin(thitha)+m*cos(thitha);
    nc=n;
}
void rotation_x()//choice=3
{
    thitha =thitha * 3.1415 /180;

    ac=a;
    bc=b*cos(thitha)-c*sin(thitha);
    cc=b*sin(thitha)+c*cos(thitha);

```

```

dc=d;
ec=e*cos(thitha)-f*sin(thitha);
fc=f*sin(thitha)+f*cos(thitha);

ic=i;
jc=j*cos(thitha)-k*sin(thitha);
kc=j*sin(thitha)+k*cos(thitha);

lc=l;
mc=m*cos(thitha)-n*sin(thitha);
nc=m*sin(thitha)+n*cos(thitha);

}
void rotation_y()//choice=4
{
thitha =thitha * 3.1415 /180;

ac=c*sin(thitha)+a*cos(thitha);
bc=b;
cc=c*cos(thitha)-a*sin(thitha);

dc=f*sin(thitha)+d*cos(thitha);
ec=e;
fc=f*cos(thitha)-d*sin(thitha);

ic=k*sin(thitha)+i*cos(thitha);
jc=j;
kc=k*cos(thitha)-i*sin(thitha);

lc=n*sin(thitha)+l*cos(thitha);
mc=m;
nc=n*cos(thitha)-l*sin(thitha);
}
void scaling()//choice=5
{
ac=a*s_x+(1-s_x)*x_f;
bc=b*s_y+(1-s_y)*y_f;

```

cc=c*s_z+(1-s_z)*z_f;

dc=d*s_x+(1-s_x)*x_f;

ec=e*s_y+(1-s_y)*y_f;

fc=f*s_z+(1-s_z)*z_f;

ic=i*s_x+(1-s_x)*x_f;

jc=j*s_y+(1-s_y)*y_f;

kc=k*s_z+(1-s_z)*z_f;

lc=l*s_x+(1-s_x)*x_f;

mc=m*s_y+(1-s_y)*y_f;

nc=n*s_z+(1-s_z)*z_f;

}

void reflection_z()//choice=6

{

ac=a;

bc=b;

cc=-c;

dc=d;

ec=e;

fc=-f;

ic=i;

jc=j;

kc=-k;

lc=l;

mc=m;

nc=-n;

}

void reflection_x()//choice=7

{

ac=-a;

bc=b;

cc=c;

```
dc=-d;
ec=e;
fc=f;

ic=-i;
jc=j;
kc=k;

lc=-l;
mc=m;
nc=n;
}
void reflection_y()//choice=8
{
ac=a;
bc=-b;
cc=c;

dc=d;
ec=-e;
fc=f;

ic=i;
jc=-j;
kc=k;

lc=l;
mc=-m;
nc=n;
}
void shearing_z()//choice=9
{
ac=a+sh_x*c;
bc=b+sh_y*c;
cc=c;
```

```
dc=d+sh_x*f;  
ec=e+sh_y*f;  
fc=f;
```

```
ic=i+sh_x*k;  
jc=j+sh_y*k;  
kc=k;
```

```
lc=l+sh_x*n;  
mc=m+sh_y*n;  
nc=n;
```

```
}
```

```
void shearing_x()//choice=10
```

```
{
```

```
ac=a;  
bc=b+sh_y*a;  
cc=c+sh_z*a;
```

```
dc=d;  
ec=e+sh_y*d;  
fc=f+sh_z*d;
```

```
ic=i;  
jc=j+sh_y*i;  
kc=k+sh_z*i;
```

```
lc=l;  
mc=m+sh_y*l;  
nc=n+sh_z*l;
```

```
}
```

```
void shearing_y()//choice=11
```

```
{
```

```
ac=a+sh_x*b;  
bc=b;  
cc=c+sh_z*b;
```

```
dc=d+sh_x*e;
```



```
ec=e;  
fc=f+sh_z*e;
```

```
ic=i+sh_x*j;  
jc=j;  
kc=k+sh_z*j;
```

```
lc=l+sh_x*m;  
mc=m;  
nc=n+sh_x*m;  
}
```