Carr Madan Method:

Theory:

Framework: $S_t = S_0 e^{rt + X_t}$ where $(X_t)_t$ is Lévy such that :

- $\int_{|x|>1} e^x \nu(dx) < +\infty$: requirement on a bound for exponential of large jumps ;
- $\Psi_X(-i) = 0$: we are under the risk-neutral measure \mathbb{Q} .

We know that : $price_{CALL}(t) = \mathbb{E}^{\mathbb{Q}}\left[e^{-r(T-t)}(S_T - K)^+|F_t\right]$ (Fund. Thm of Asset Pricing).

Idea: we want to compute the price using the characteristic function (1998, Carr & Madan Formula).

A) Let's define : $k = log(K/S_0)$, so that, at t = 0 :

$$c(k) = \mathbb{E}^{\mathbb{Q}} \left[e^{-rT} \left(S_0 e^{rT + X_T} - S_0 e^k \right)^+ | F_t \right] = S_0 \mathbb{E}^{\mathbb{Q}} \left[e^{-rT} \left(e^{rT + X_T} - e^k \right)^+ | F_t \right]$$

NB: for the moment we can take $S_0 = 1$ and multiply at the end.

- **B)** Limits of c(k):
 - $\lim_{k\to+\infty}c(k)=0$;
 - $\lim_{k\to-\infty} c(k) = 1$: not integrable!

So we define a new function that is integrable : $z(k) = c(k) - (1 - e^{k-rT})^+$. Nothing stochastic in the subtracted term so that we can compute the price once we know z(k). And :

- $\lim_{k\to+\infty} \zeta(k) = 0$;
- $\lim_{k\to-\infty} Z(k) = 0$: integrable!
- **C)** Now we apply the **Fourier Transform** to z.
 - First we notice that : $z(k) = c(k) (1 e^{k-rT}) = e^{-rT} \int_{-\infty}^{+\infty} (e^{rT+x} e^k) (1_{k \le x + rT} 1_{k \le rT}) \rho_T(dx)$;
 - Then we compute the FT using the previous formula :

$$g_T(v) = F(z)(v) = e^{-rT} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} e^{ivk} (e^{rT+x} - e^k) (1_{k \le x + rT} - 1_{k \le rT}) \rho_T(dx) dk$$

and after a lot of computations (cf page 6) we get the Carr-Madan Formula:

$$g_T(v) = \frac{e^{ivrT}}{iv(iv+1)} \left[\Phi_{X_T}(v-i) - 1 \right].$$

1

D) Finally we can collect z(k) by inverting the formula : $z(k) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} e^{-ikv} g_T(v) dv$ and finally :

$$c(k) = z(k) + (1 - e^{k - rT})^{+}$$

Remark: Carr-Madan is a very general framework that can be applied to other models: just compute $g_T(v)$ analytically (1), invert the formula by IFT (by approximation since we cannot compute this formula analytically) (2), and finally retrieve the price of the EU Call Option c(k) (3). It's very fast and with nice precision. It's great to calibrate to the market, because calibration requires a lot of iterations, but on (simple) plain vanilla objects.

Code:

```
% Parameters :
Strike = [80 90 100 110];
S0 = 102;
T = 1;
r = 0.01 / 100;
params = [0.5 \ 3 \ 0.6 \ 20 \ 30];
% sigma = params(1);
% lambda = params(2);
% p = params(3);
% lambdap = params(4);
% lambdam = params(5);
params_MERTON = [0.5, 3, -0.01, 0.4];
% sigma = params_MERTON(1);
% lambda = params MERTON(2);
% muJ = params_MERTON(3);
% sigmaJ = params MERTON(4);
% WARNING: be sure to take the same 'sigma' and 'lambda' to be able to
% compare the results.
```

0) Truncation of the integral for the Inverse Fourier Transform:

$$z_T(k) = IFT(g_T)(k) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} e^{-ivk} g_T(v) dv = \frac{1}{\pi} \int_0^{+\infty} e^{-ivk} g_T(v) dv \text{ (since it must be real)}$$

$$\mathbf{Truncation} : z_T(k) \approx \frac{1}{\pi} \int_0^{A(N-1)/N} e^{-ivk} g_T(v) dv$$

Trapezoidal quadrature formula : $z_T(k) \approx \frac{1}{\pi} \sum_{j=0}^{N-1} w_j \eta e^{-ij\eta k} g_T(\eta j)$ where $\eta = A/N, w_0 = w_{N-1} = 0.5$ and $\forall j \notin \{0, N-1\}, w_j = 1$.

```
Npow = 16; 
 N = 2^Npow; % Nb of terms in the trapezoidal quadrature formula (sum). 
 A = 1000; % Truncation of the integral : from 0 to A(N-1)/N.
```

The computations with the **log-strike grid** $\forall l \in \{0, 1, ..., N-1\}, k_l = -\lambda N/2 + \lambda l, \lambda = 2\pi/(N\eta)$ give :

$$z_T(k_l) \approx \frac{1}{\pi} IFFT_{PROBABILISTS}(\{w_j \eta e^{ij\pi} g_T(\eta j)\}_{j=0}^{N-1} = \frac{1}{\pi} FFT_{MATLAB}(\{w_j \eta e^{ij\pi} g_T(\eta j)\}_{j=0}^{N-1}.$$

Nodes of the quadrature formula:

- $\left[0, A \frac{N-1}{N}\right] = [0, A \eta]$ is divided into N-1 trapezoids : $([0, \eta], [\eta, 2\eta], ..., [(N-2)\eta, (N-1)\eta])$;
- *N*nodes $(0\eta, 1\eta, ..., (N-1)\eta)$ put into the vector v in MATLAB (cf below).

```
eta = A / N;  % Cut [0, A - eta] in N-1 trapezoids of length eta. v = [0 : eta : A * (N - 1) / N]; % eta = v_j - v_{j-1} (j in [0, N-1]). v(1) = 1e-22; % To avoid division by 0.
```

Log-strike grid:

• $\forall l \in \{0, ..., N-1\}, k_l = -\lambda \frac{N}{2} + \lambda l \text{ with } : \lambda = \frac{2\pi}{Nn}.$

```
lambda = 2 * pi / (N * eta); % Step-size in log-strike grid.
k = -lambda * N / 2 + lambda * (0:N-1); % Log-strike grid.
```

- 1) Compute $g_T(v) = \frac{e^{ivrT}}{iv(iv+1)} \left[\Phi_{X_T}(v-i) 1 \right]$ analytically :
 - We need $\Psi_{X}(u)$: cf Kou_Merton.pdf
- **1.1)** Characteristic exponent for B&S : $\Psi_X(u) = -\frac{\sigma^2 i u}{2} \frac{\sigma^2 u^2}{2}$.

```
function PSI_BS = CharExp_BS(u, params)
    sigma = params(1);
    PSI_BS = 1i * (-sigma^(2) / 2) .* u - (sigma^(2) * u.^(2)) / 2;
end
```

1.2) Characteristic exponent for Kou : $\Psi_X(u) = -\frac{\sigma^2 u^2}{2} + ibu + iu\lambda \left(\frac{p}{\lambda_+ - iu} - \frac{1-p}{\lambda_- + iu}\right)$.

```
function PSI_KOU = CharExp_KOU(u, params)
    sigma = params(1);
    lambda = params(2);
    p = params(3);
    lambdap = params(4);
    lambdam = params(5);
    % 1) (Kou) Characteristic exponent X-hat :
    V = @(u) - sigma^2 * u.^2 / 2 + 1i * u * lambda .*...
        (p ./ (lambdap - 1i * u) - (1 - p) ./ (lambdam + 1i * u)); % cf PDF.
```

```
% 2) Risk-Neutral Drift (of X) :
    drift_rn = -V(-1i);
    % 3) Characteristic exponent X :
    PSI_KOU = drift_rn * 1i * u + V(u);
    % Therefore we are under the RN measure.
end
```

1.3) Characteristic exponent for Merton : $\Psi_X(u) = -\frac{\sigma^2 u^2}{2} + ibu + \lambda \left(e^{-\delta^2 u^2/2 + i\mu u} - 1\right)$.

```
function PSI_MERTON = CharExp_MERTON(u, params)
    sigma = params(1);
    lambda = params(2);
    mu = params(3);
    delta = params(4);
% 1) (Merton) Characteristic exponent X-hat :
    V = @(u) - sigma^2 * u.^2 / 2 + lambda *...
        (exp(-delta^2 * u.^2 / 2 + 1i * mu * u) - 1); % cf PDF.
% 2) Risk-Neutral Drift (of X) :
    drift_rn = -V(-1i);
% 3) Characteristic exponent X :
    PSI_MERTON = drift_rn * 1i * u + V(u);
% Therefore we are under the RN measure.
end
```

• Now we can compute the characteristic function :

```
CharFunc_BS = @(u) \exp(T * CharExp_BS(u, params));

CharFunc_KOU = @(u) \exp(T * CharExp_KOU(u, params));

CharFunc_MERTON = @(u) \exp(T * CharExp_MERTON(u, params_MERTON));
```

• Now we can implement the Carr-Madan Formula :

2) Numerical inversion of the $z_T(k)$ formula by IFT :

```
% Trapezoïdal quadrature formula :
w = ones(1, N);
w(1) = 0.5;
w(end) = 0.5;

% Argument inside FFT_MATLAB (or IFFT_PROBABILISTS) :
x_BS = w .* eta .* Z_k_BS .* exp(1i * pi * (0:N-1));
```

```
x_KOU = w .* eta .* Z_k_KOU .* exp(1i * pi * (0:N-1));
x_MERTON = w .* eta .* Z_k_MERTON .* exp(1i * pi * (0:N-1));
% FFT formula for z_T(k_l):
z_k_BS = real(fft(x_BS) / pi);
z_k_KOU = real(fft(x_KOU) / pi);
z_k_MERTON = real(fft(x_MERTON) / pi);
```

Warning: we use fft() funtion because MATLAB's FFT is implemented with a "-" in the exponential, whereas probabilists use the IFT with a "-" in the exponential. So here we perform FFT in Matlab's POV, but it corresponds to the IFT in mathematician's POV.

Warning: We know theoretically that the price should be a real number, but due to numerical approximation we must use the real() function to cap the imaginary part to, indeed, zero.

3) Retrieve the call option price starting from $z_T(k)$:

$$c(k) = z_T(k) + (1 - e^{k - rT})^+$$

```
C_BS = S0 * (z_k_BS + max(1 - exp(k - r * T), 0)); % Option prices array. 
C_KOU = S0 * (z_k_KOU + max(1 - exp(k - r * T), 0)); 
C_MERTON = S0 * (z_k_MERTON + max(1 - exp(k - r * T), 0));
```

We can **process the output** by retrieving the real strikes K, removing very small strikes and very large strikes :

```
% Get strikes from log-strikes:
K = S0 * exp(k);

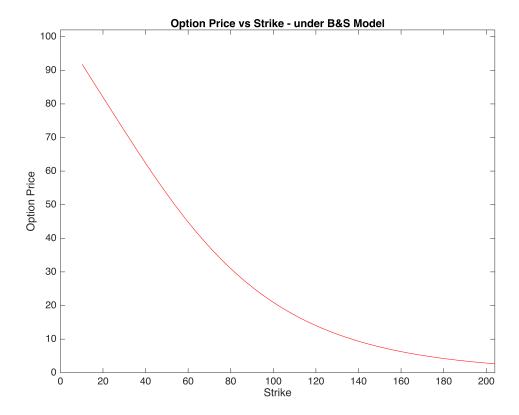
% Filter strikes:
index = find(K > 0.1 * S0 & K < 3 * S0);
K = K(index);

% Filter prices:
C_BS = C_BS(index);
C_KOU = C_KOU(index);
C_MERTON = C_MERTON(index);</pre>
```

Finally we can **plot** everything:

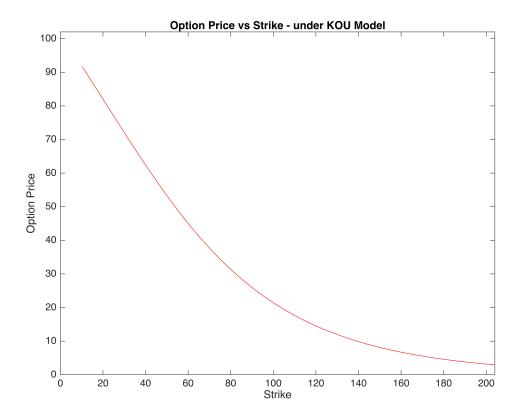
B&S model:

```
figure
plot(K, C_BS, 'r');
hold on
axis([0 2*S0 0 S0]);
title('Option Price vs Strike - under B&S Model');
ylabel('Option Price');
xlabel('Strike');
```



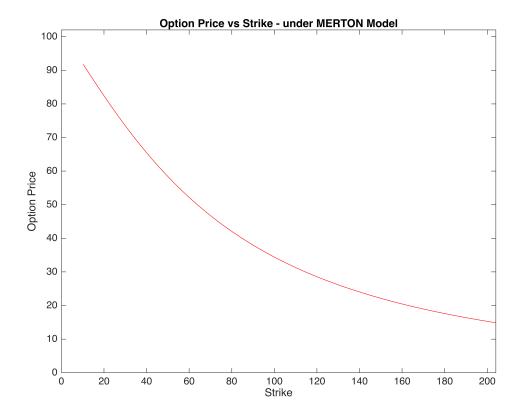
• KOU model:

```
figure
plot(K, C_KOU, 'r');
hold on
axis([0 2*S0 0 S0]);
title('Option Price vs Strike - under KOU Model');
ylabel('Option Price');
xlabel('Strike');
```



• MERTON model:

```
figure
plot(K, C_MERTON, 'r');
hold on
axis([0 2*S0 0 S0]);
title('Option Price vs Strike - under MERTON Model');
ylabel('Option Price');
xlabel('Strike');
```



And we can interpolate to get the prices for a very specific set of strikes:

```
Price_BS = interp1(K, C_BS, Strike, 'spline')
Price_BS = 1 \times 4
            25.5337
                      20.9583
  30.9938
                                17.1626
Price_KOU = interp1(K, C_KOU, Strike, 'spline')
Price KOU = 1 \times 4
            25.9582
                                17.6532
  31.3565
                      21.4253
Price_MERTON = interp1(K, C_MERTON, Strike, 'spline')
Price\_MERTON = 1 \times 4
   42.0723
            37.9854
                      34.4234
                                31.3088
```

Calibration to the market prices :

Obviously, if there is a **closed formula** there is no problem : we calibrate using the formula : e.g when we inverse the B&S formula to find the volatility σ . But in the general Lévy framework, we don't have a closed formula. So Carr-Madan algorithm is a great choice to perform the calibration of the model based on the market prices : it is fast and accurate.

A) Calibration of the Kou Model:

Let's use CM algorithm to find the best parameters 'params' which represent $(\sigma, \lambda, p, \lambda_+, \lambda_-)$ that best fits market prices, under Kou Model.

1) The data:

```
Maturity = 4/12; % Maturity of 4 months
                 200 % Prices, Strikes
Data = [25.30
        10.00
                 225
        18.20
                 210
        41.85
                 180
        15.20
                 215
        7.85
                230
        12.36
                 220
        46.05
                 175
        70.70
                 150
        50.85
                 170
        60.40
                 160
        29.40
                 195];
Data1 = [Data(:,2), Maturity * ones(size(Data(:,2))), Data(:,1)];
% Data1 is in the form : [Strike, Time to Maturity, Market Price].
Maturity = 4/252; % Maturity of 4 (trading) days
Data = [0.24]
                230
        9.25
                210
        2.26
                220
        0.76
                225
        19.03
                 200
        5.20
                215
        14.00
                 205
                235];
        0.10
Data = [Data(:,2), Maturity * ones(size(Data(:,2))), Data(:,1)];
% Data is in the form : [Strike, Time to Maturity, Market Price].
Data = [Data1; Data]; % We merge the two datasets (with two different
% maturities).
```

2) Optimisation:

• We want to compute the parameters 'params' which represent $(\sigma, \lambda, p, \lambda_+, \lambda_-)$ and which minimize the distance between market prices and prices computed by the Kou model. The function that computes the model prices under Kou is 'fun.m': it does so via CM algorithm.

```
% Parameters :
r = 0.02; spot = 218.75;

% Optimisation :
x0 = [0.5, 5, 0.8, 15, 15]; % Initial guess
LB = [0.1, 0, 0, 1,1]; % Lower bound
UB = [0.8, 20, 1, 50, 50]; % Upper bound

tic
```

```
[params, error] = lsqnonlin(@(params) ...
   fun(params, spot, Data(:,1), r, Data(:,2), Data(:,3)), ...
   x0, LB, UB)
```

Local minimum possible.

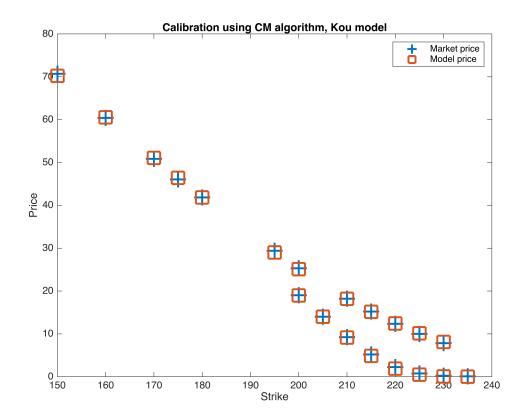
lsqnonlin stopped because the final change in the sum of squares relative to its initial value is less than the value of the function tolerance. <stopping criteria details> params = 1×5 0.2115 0.6554 0.0000 50.0000 6.7451 error = 1.0934

```
toc
```

Elapsed time is 3.228849 seconds.

3) Plot:

```
figure
plot(Data(:,1), Data(:,3), '+', 'markersize', 16, 'linewidth', 5);
hold on
% Compute and plot the calibrated prices (so with the calibrated sigma):
Price = fun(params, spot, Data(:,1), r, Data(:,2), 0);
plot(Data(:,1), Price, 's', 'markersize', 16, 'linewidth', 5);
legend('Market price', 'Model price')
xlabel("Strike")
ylabel("Price")
title("Calibration using CM algorithm, Kou model")
```



B) Calibration of the Merton model:

1) The data:

same as before.

2) Optimisation:

Local minimum possible.

lsqnonlin stopped because the final change in the sum of squares relative to its initial value is less than the value of the function tolerance.

```
<stopping criteria details>
params = 1x4
```

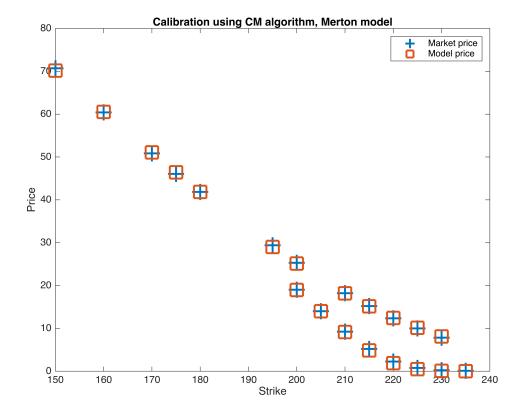
```
0.2140 0.2933 -0.2579 0.1471 error = 1.1214
```

```
toc
```

Elapsed time is 2.320401 seconds.

3) Plot:

```
figure
plot(Data(:,1), Data(:,3), '+', 'markersize', 16, 'linewidth', 5);
hold on
% Compute and plot the calibrated prices (so with the calibrated sigma):
Price = fun_MERTON(params, spot, Data(:,1), r, Data(:,2), 0);
plot(Data(:,1), Price, 's', 'markersize', 16, 'linewidth', 5);
legend('Market price', 'Model price')
xlabel("Strike")
ylabel("Price")
title("Calibration using CM algorithm, Merton model")
```



C) Calibration of the B&S model:

1) The data:

same as before.

2) Optimisation:

• Warning: look only at the first parameter in 'params', since it is the only one for B&S model. The others are for models such as Kou or Merton (cf before).

Local minimum possible.

lsqnonlin stopped because the final change in the sum of squares relative to its initial value is less than the value of the function tolerance.

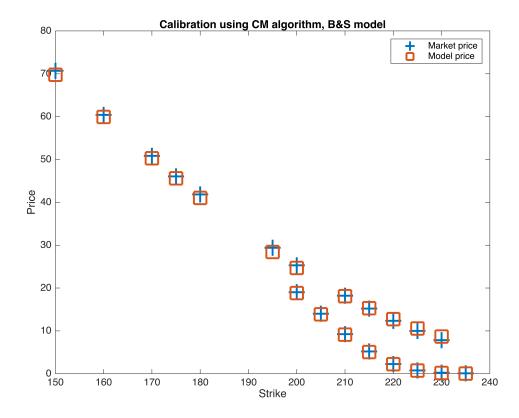
```
<stopping criteria details>
params = 1x5
    0.2517    5.0000    0.8000    15.0000    15.0000
error = 4.8569
```

```
toc
```

Elapsed time is 0.416198 seconds.

3) Plot:

```
figure
plot(Data(:,1), Data(:,3), '+', 'markersize', 16, 'linewidth', 5);
hold on
% Compute and plot the calibrated prices (so with the calibrated sigma):
Price = fun_CM_BS(params, spot, Data(:,1), r, Data(:,2), 0);
plot(Data(:,1), Price, 's', 'markersize', 16, 'linewidth', 5);
legend('Market price', 'Model price')
xlabel("Strike")
ylabel("Price")
title("Calibration using CM algorithm, B&S model")
```



We can see that the B&S calibration is the worst between the three calibrations we performed. It seems normal since it only has one parameter (sigma).