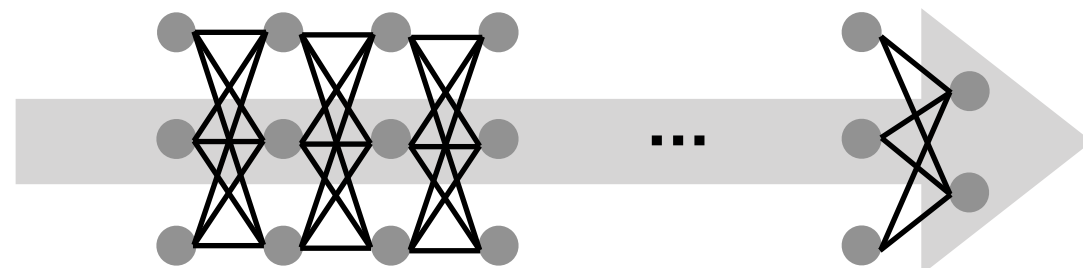
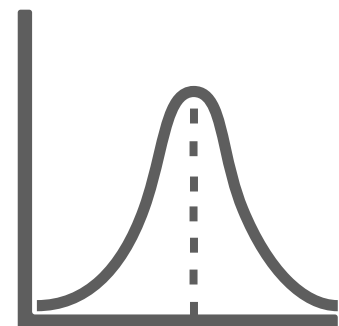


Classification Model

How does it work?



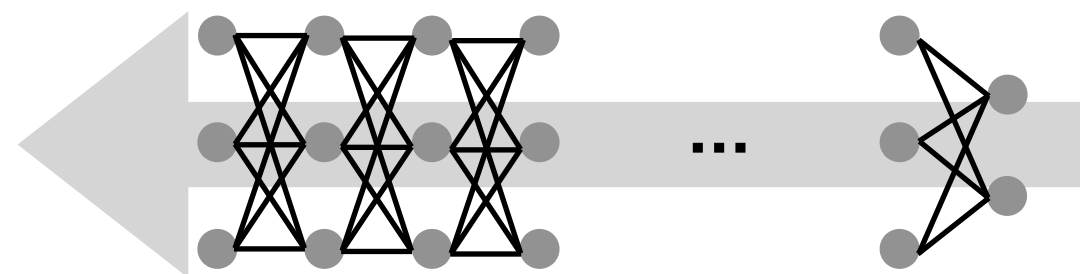
Forward path



Penguin: 0.01

Iteration

**Difference
measurement
(Loss)**

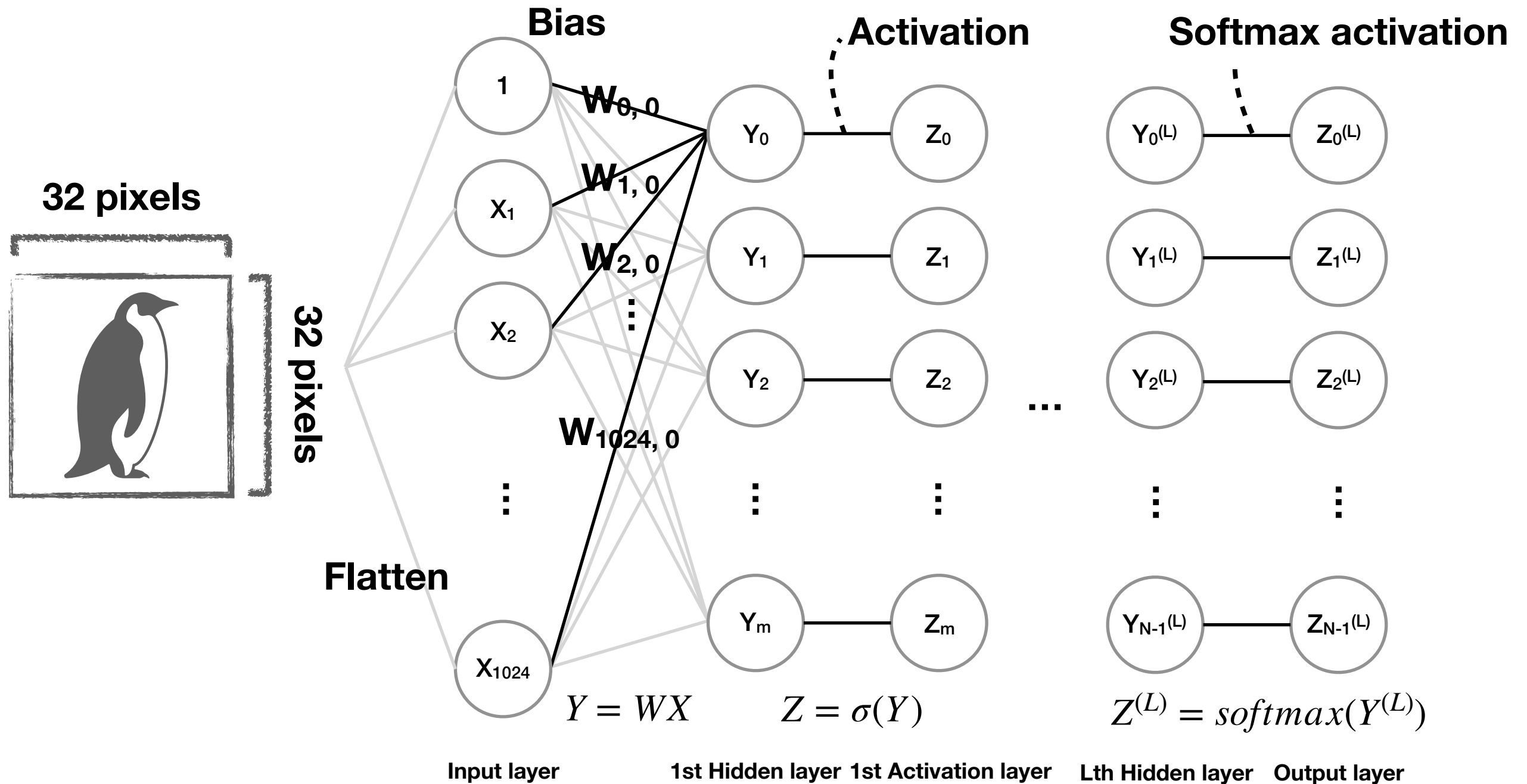


**Backward path
(Gradient back-propagation)**

$\nabla_{\theta} L$

Penguin: 1.0

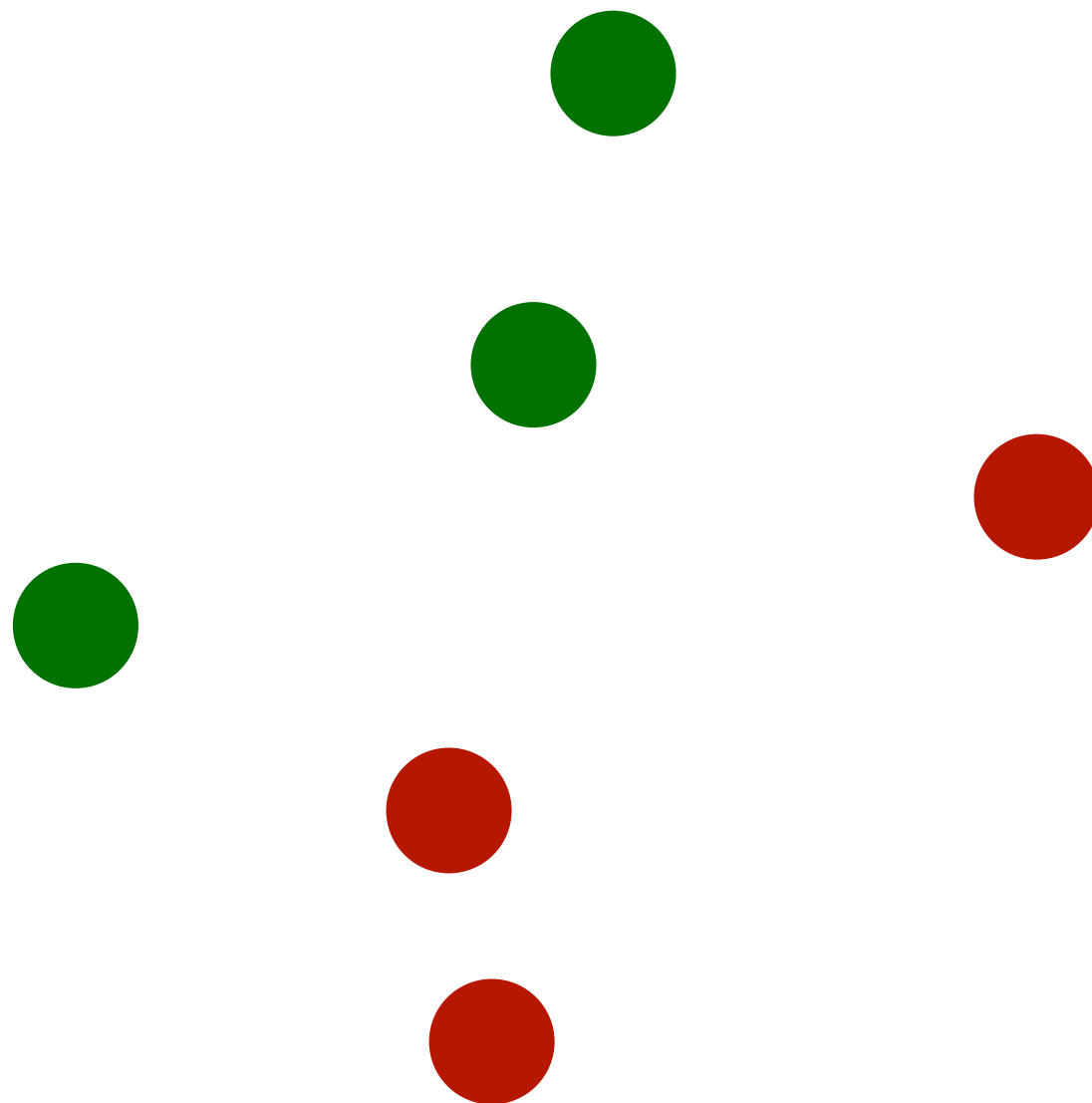
Forward path



**Densely connected
(fully connected)**

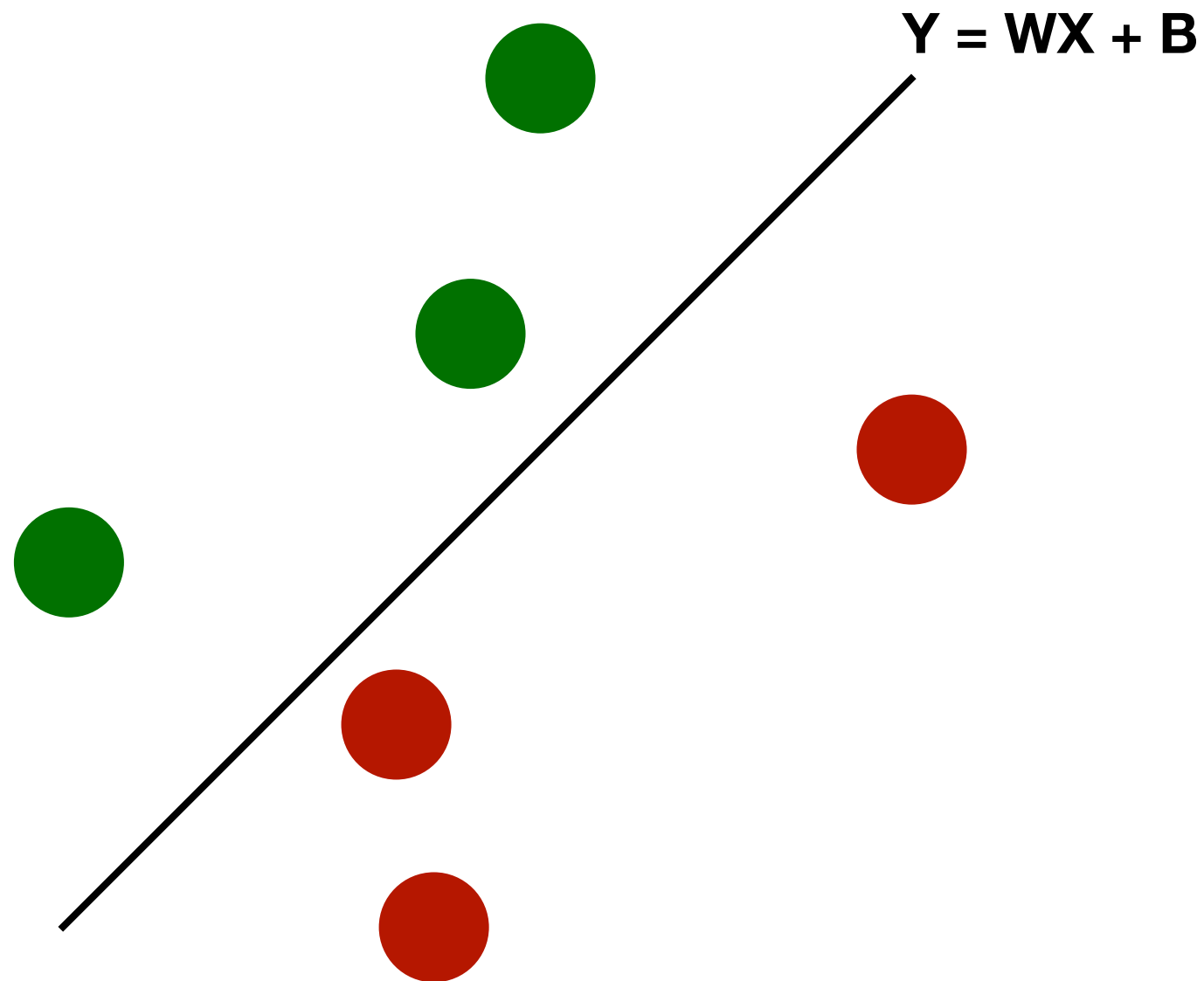
Forward path

- Why do we need an activation after a weight layer?



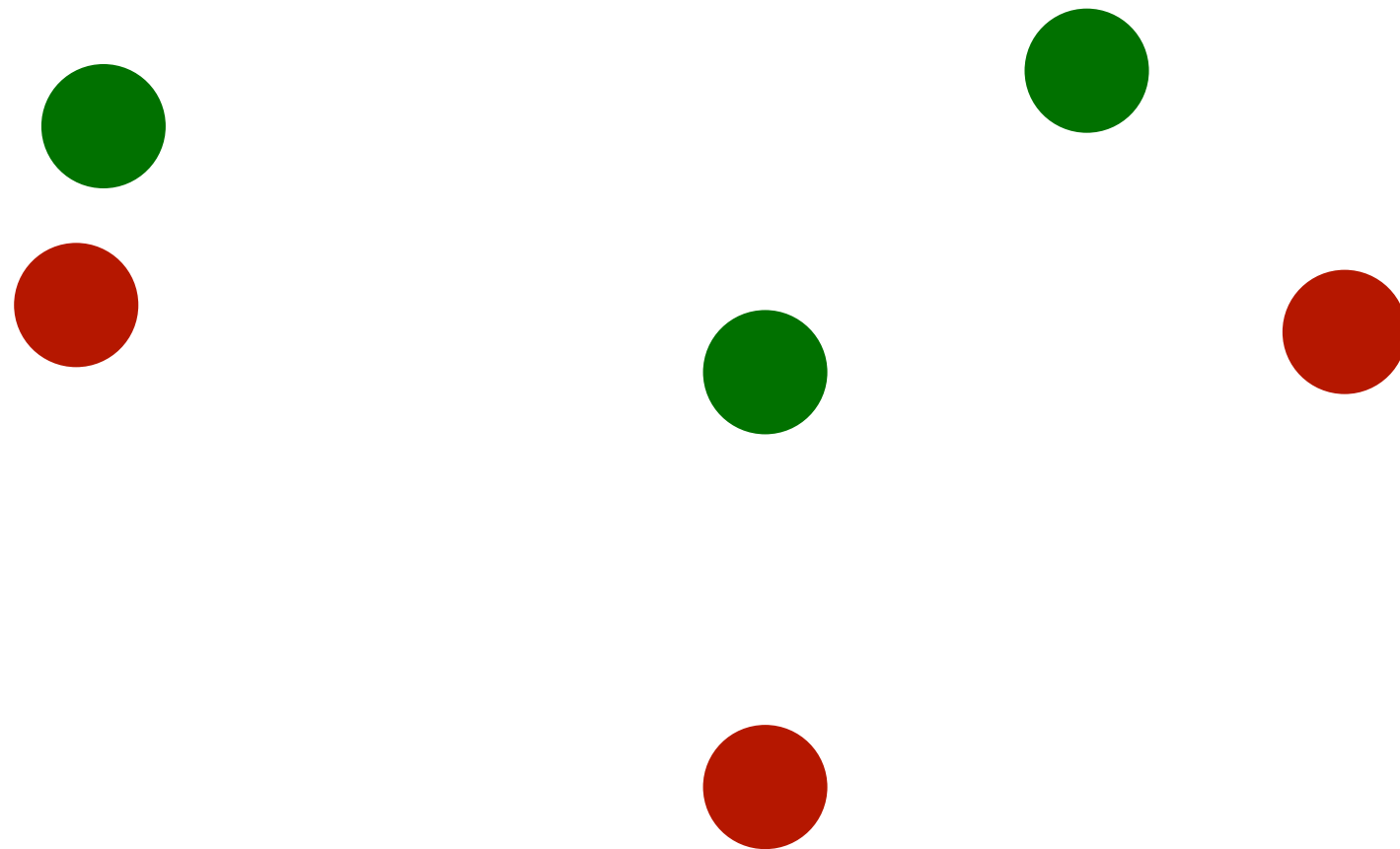
Forward path

- Why do we need an activation after a weight layer?



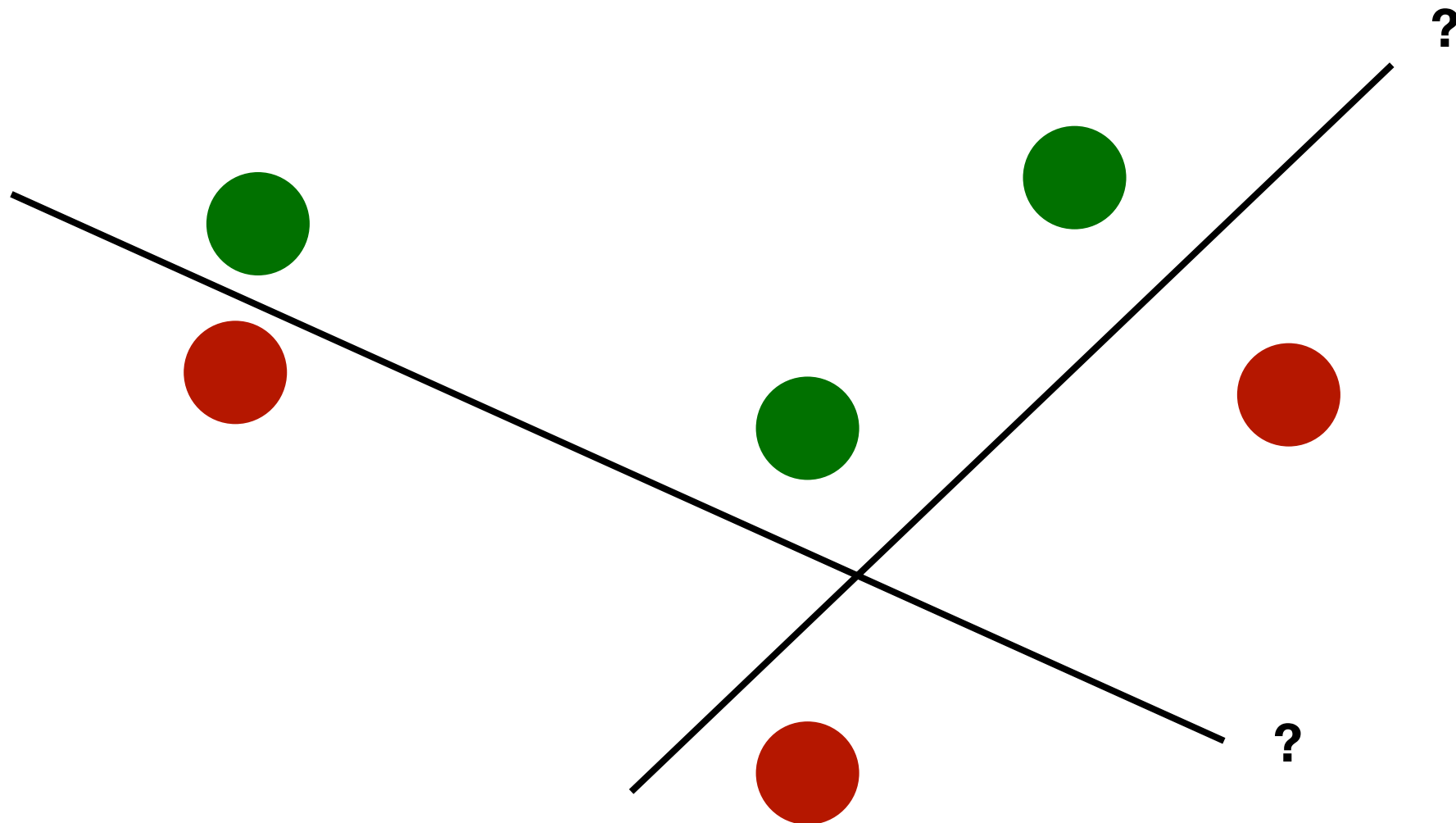
Forward path

- Why do we need an activation after a weight layer?



Forward path

- Why do we need an activation after a weight layer?



Forward path

- Why do we need an activation after a weight layer?

Without any activation function, it's impossible to express higher degree function than linear function

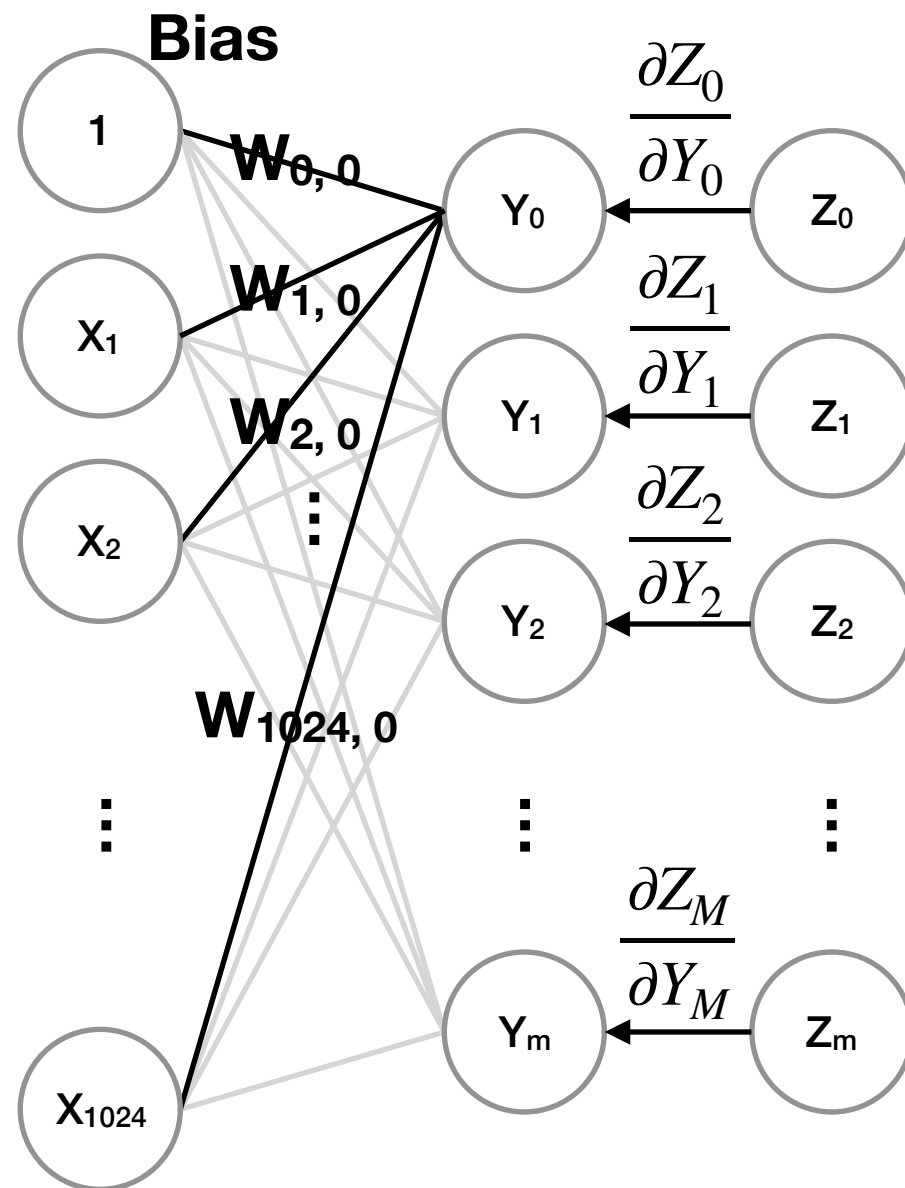
$$\begin{aligned}Y_1 &= WX_1 + B \\Y_2 &= W(WX_1 + B) + B = WX_1 + B\end{aligned}$$

$$\begin{aligned}Y_1 &= WX_1 + B \\Z_1 &= f(Y_1) \\Y_2 &= WZ_1 + B\end{aligned}$$

where $f(.)$ is non-linear activation function

Thus we add an activation function after a weight layer.

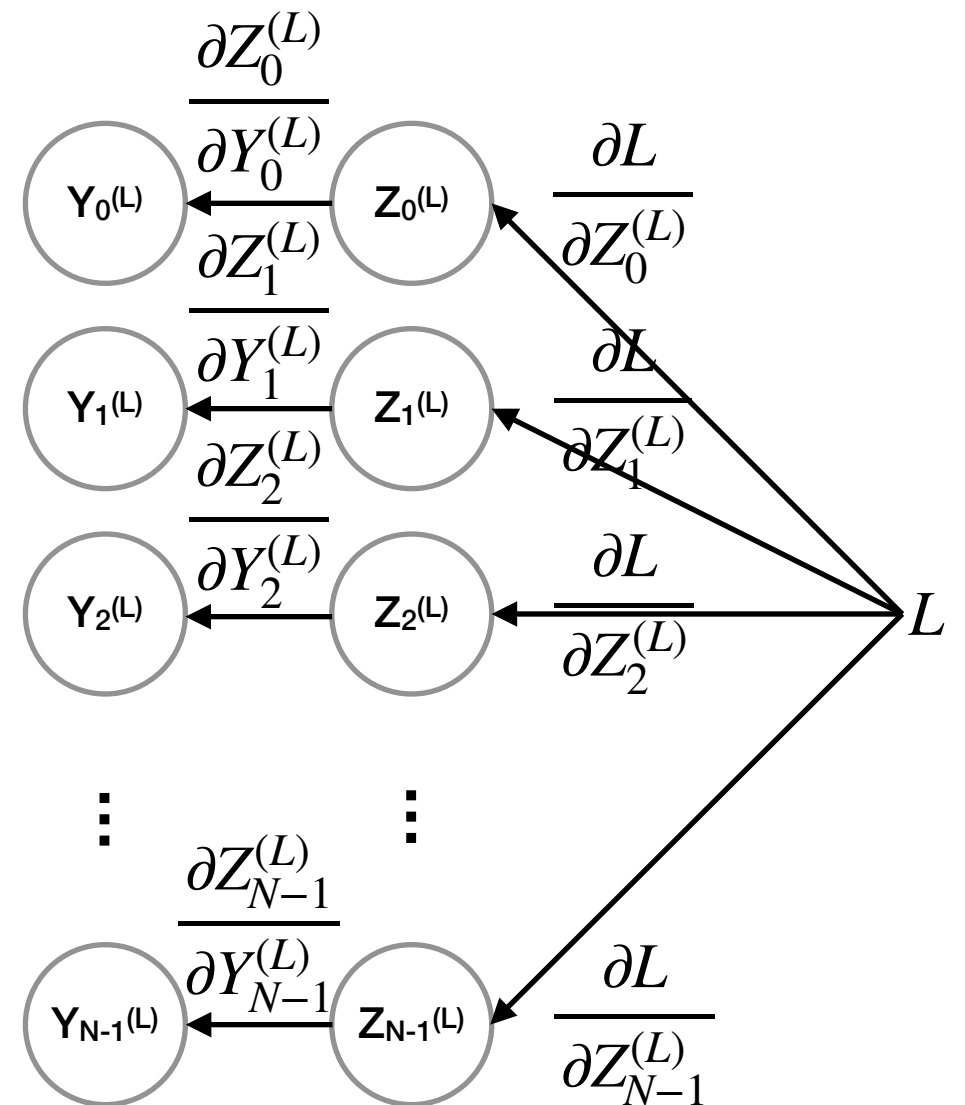
Backward path



$$\frac{\partial L}{\partial w_{0,0}} = \frac{\partial L}{\partial y_0} \frac{\partial y_0}{\partial w_{0,0}}$$

$$w_{0,0} = w_{0,0} - \rho \frac{\partial L}{\partial w_{0,0}}$$

...

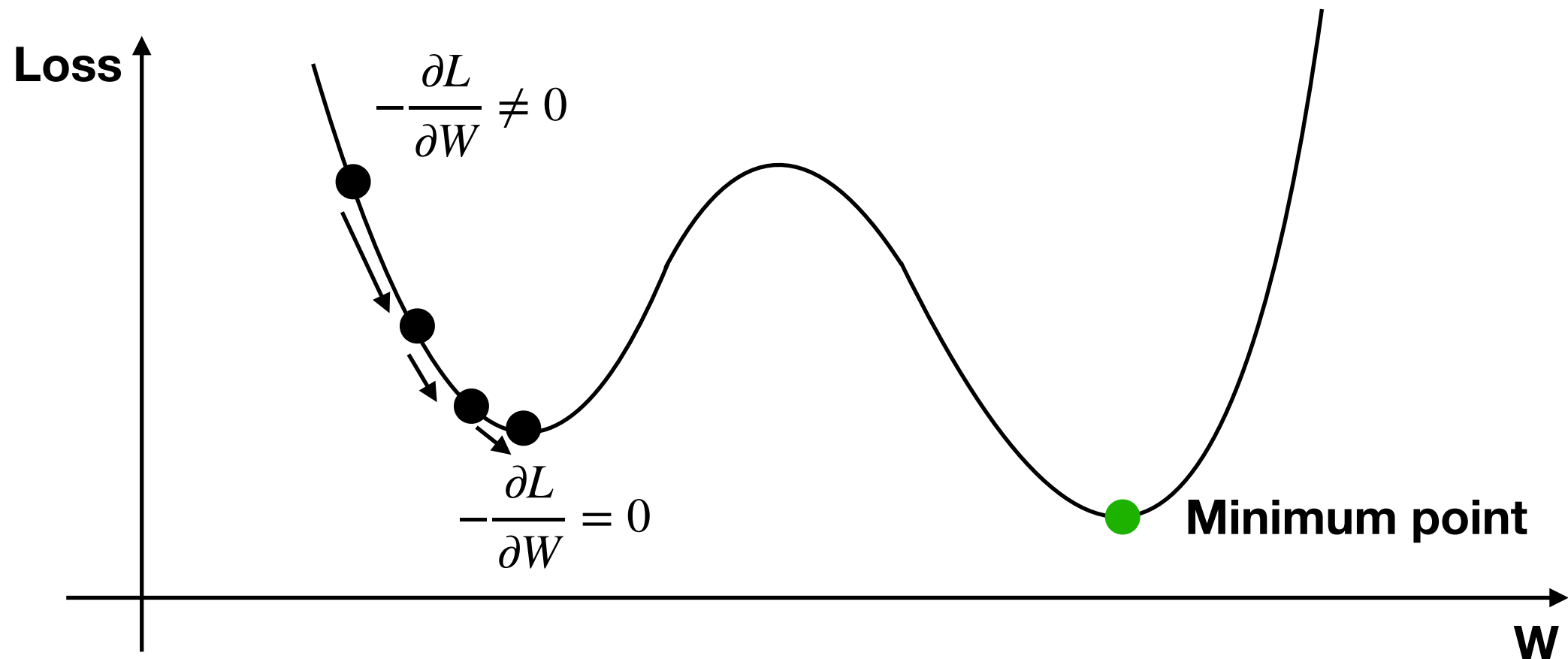


$$L = - \sum_{k=0}^{N-1} t_k \log Z_k = - \log Z_i$$

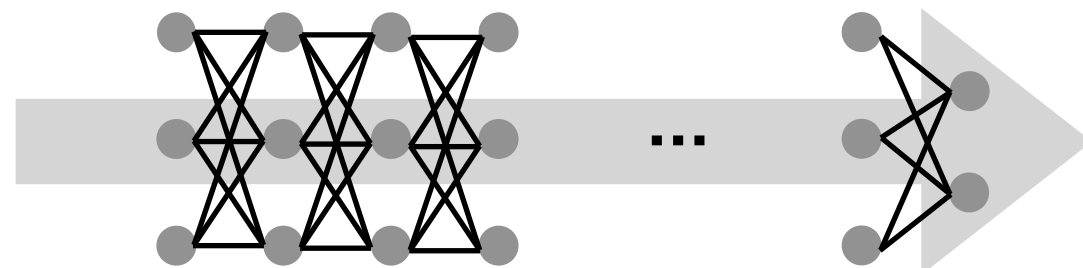
Cross-entropy loss

Backward path

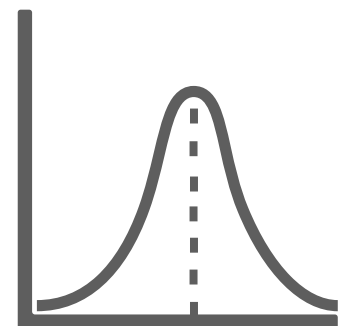
- Gradient back-propagation changes weights to have lower loss in a way loss decreases most fast.
- However this does not guarantee the loss converges to its minimum value



How does it work?



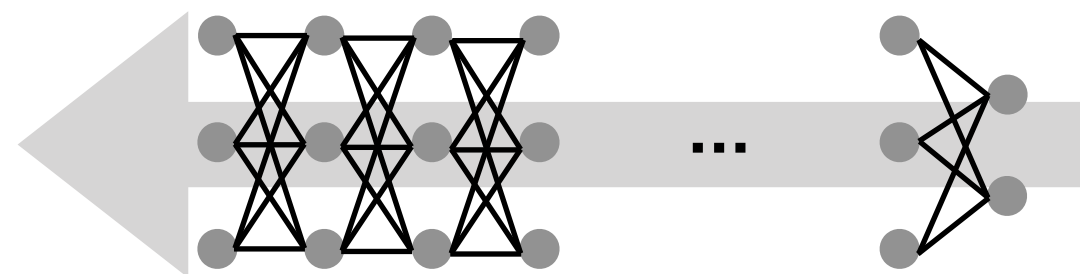
Forward path



Penguin: 0.01

Iteration

**Difference
measurement
(Loss)**



**Backward path
(Gradient back-propagation)**

$\nabla_{\theta} L$

Penguin: 1.0

Practice

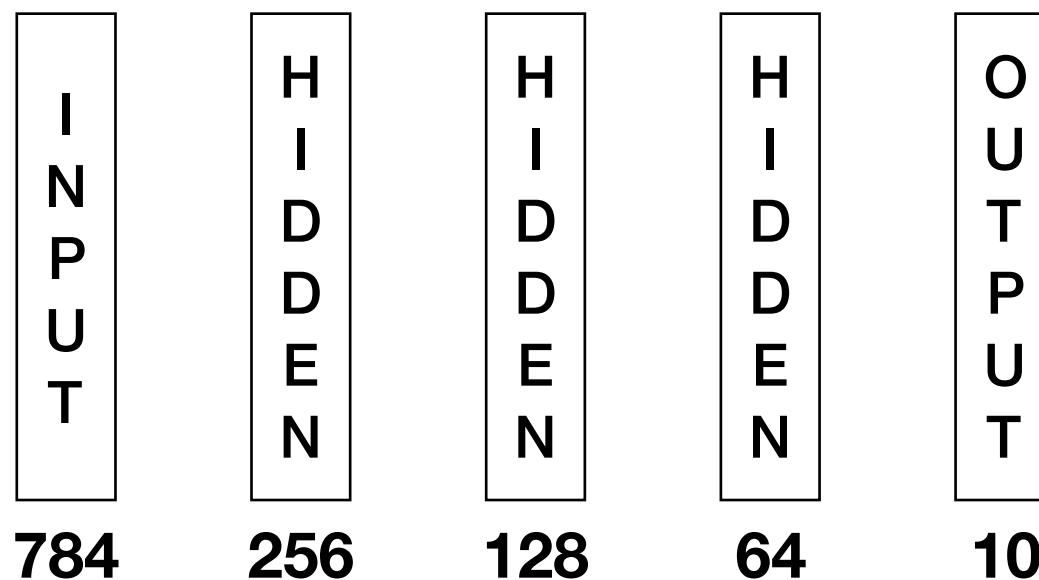
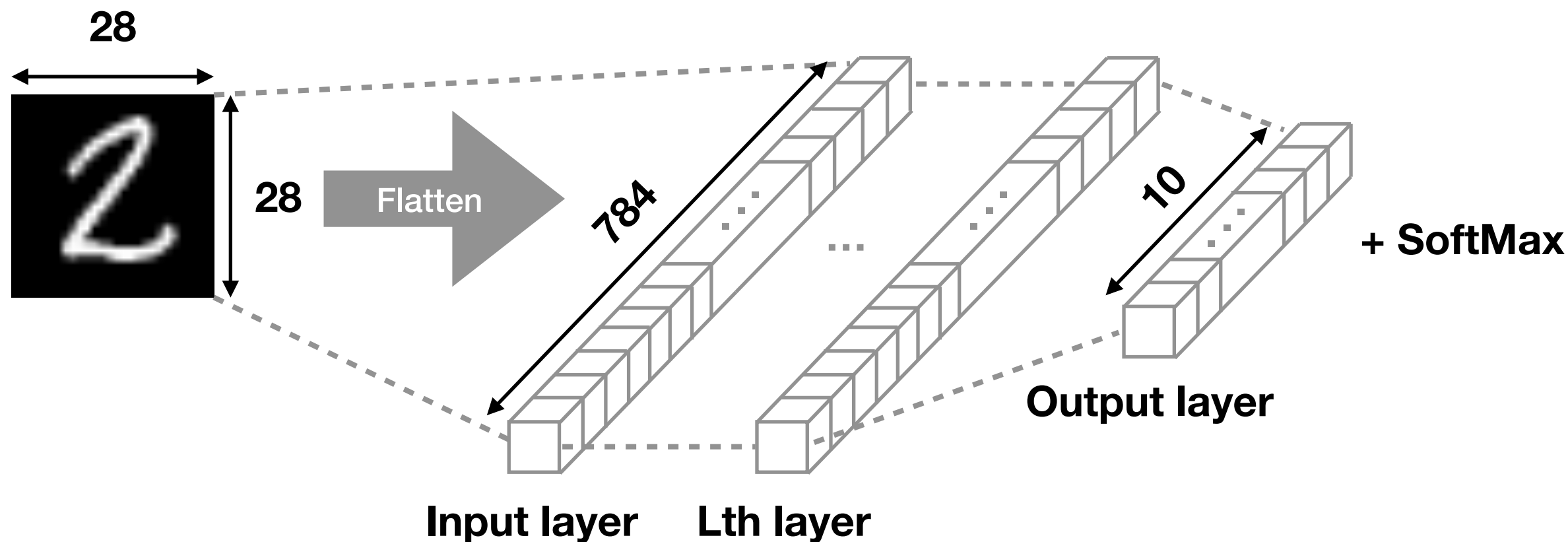
MNIST database



Training set: 60,000 images and labels
Test set: 10,000 images and labels

The MNIST database (Modified National Institute of Standards and Technology database) is a large database of handwritten digits that is commonly used for training various image processing systems.

Model architecture



Code snippet

```
import torch.nn as nn
import torch.nn.functional as F
```

```
class CNN(nn.Module):
    def __init__(self):
        super(CNN, self).__init__()
        self.conv1 = nn.Conv2d(in_channels=1, out_channels=64, kernel_size=3, stride=2, padding=1)
        self.conv2 = nn.Conv2d(in_channels=64, out_channels=128, kernel_size=3, stride=2, padding=1)
        self.conv3 = nn.Conv2d(in_channels=128, out_channels=256, kernel_size=3, stride=2, padding=1)
        self.fc = nn.Linear(in_features=4 * 4 * 256, out_features=10)

    def forward(self, x):
        x = F.relu(self.conv1(x))
        x = F.relu(self.conv2(x))
        x = F.relu(self.conv3(x))
        x = x.view(x.shape[0], -1)
        x = self.fc(x)
        return x
```

```
class MLP(nn.Module):
    def __init__(self):
        super(MLP, self).__init__()
        self.linear1 = nn.Linear(in_features=28 * 28, out_features=256)
        self.linear2 = nn.Linear(in_features=256, out_features=128)
        self.linear3 = nn.Linear(in_features=128, out_features=64)
        self.linear4 = nn.Linear(in_features=64, out_features=10)

    def forward(self, x):
        x = F.relu(self.linear1(x))
        x = F.relu(self.linear2(x))
        x = F.relu(self.linear3(x))
        x = self.linear4(x)
        return x
```

For a full code, please visit

<https://github.com/NoelShin/Deep-Learning-Bootcamp-with-PyTorch>

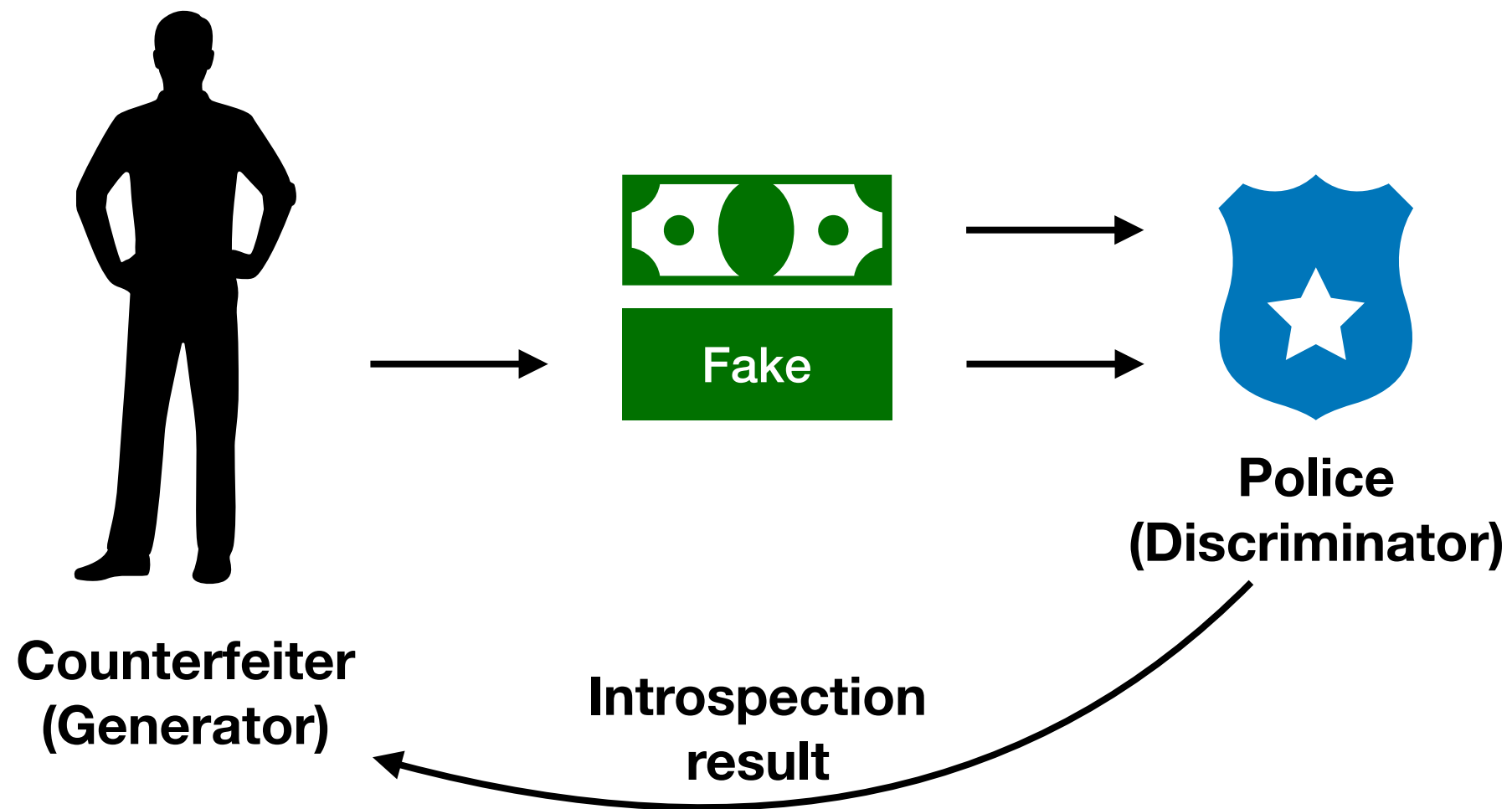
Generative Model

Various generative models

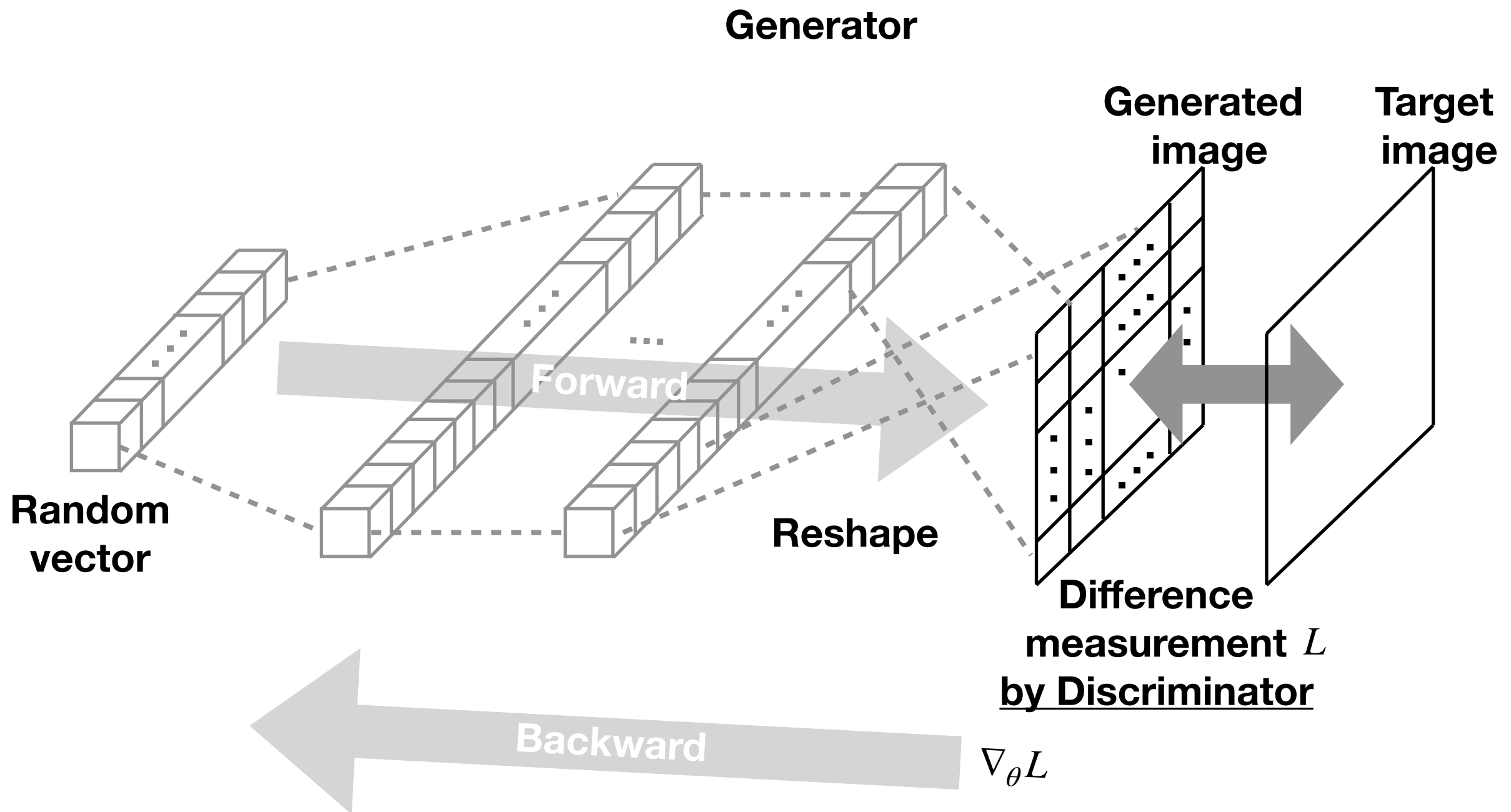
- Hidden Markov Model (HMM)
- Restricted Boltzmann Machine (RBM)
- Variational Auto-Encoder (VAE)
- Recurrent Neural Network (RNN)
- **Generative Adversarial Network (GAN)**

GAN

What is GAN?

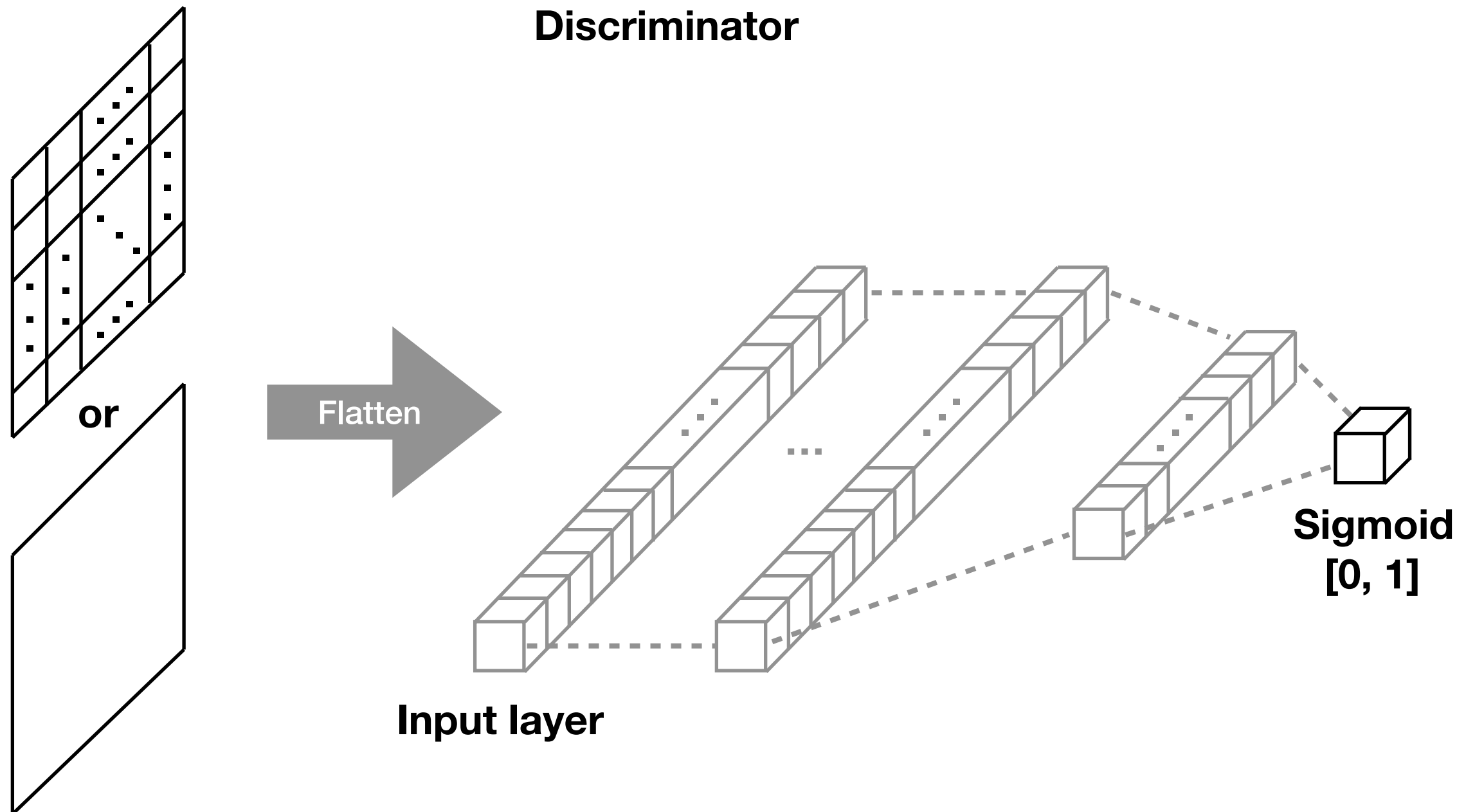


How does GAN work?



E.g. image generation model

How does GAN work?



Practice

MNIST database



Training set: 60,000 images and labels
Test set: 10,000 images and labels

The MNIST database (Modified National Institute of Standards and Technology database) is a large database of handwritten digits that is commonly used for training various image processing systems.

Code snippet

```
import torch.nn as nn
```

```
class Generator(nn.Module):
```

```
    def __init__(self):
```

```
        super(Generator, self).__init__()
```

```
        model = [nn.Linear(in_features=100, out_features=128), nn.ReLU(inplace=True)]
```

```
        model += [nn.Linear(in_features=128, out_features=256), nn.ReLU(inplace=True)]
```

```
        model += [nn.Linear(in_features=256, out_features=28 * 28), nn.Sigmoid()]
```

```
        self.model = nn.Sequential(*model)
```

```
# "The generator nets used a mixture of rectifier linear activations and sigmoid activations, while the  
# discriminator net used maxout activations." – Generative Adversarial Networks
```

```
    def forward(self, x):
```

```
        return self.model(x)
```

```
class Discriminator(nn.Module):
```

```
    def __init__(self):
```

```
        super(Discriminator, self).__init__()
```

```
        model = [Maxout(28 * 28, 256, dropout=False, k=5)]
```

```
        model += [Maxout(256, 128, dropout=True, k=5)]
```

```
        model += [nn.Linear(128, 1), nn.Sigmoid()]
```

```
        self.model = nn.Sequential(*model)
```

```
    def forward(self, x):
```

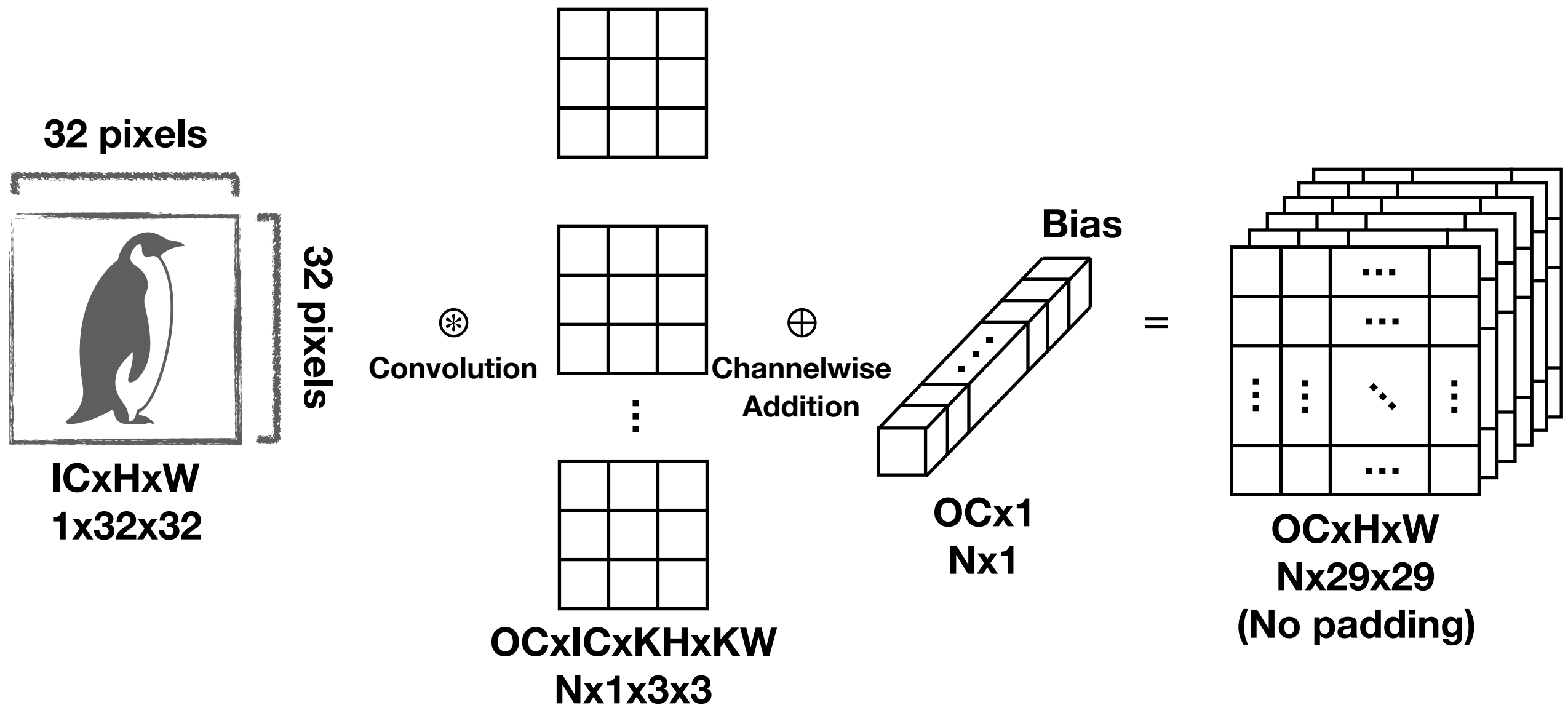
```
        return self.model(x)
```

For a full code, please visit

<https://github.com/NoelShin/Deep-Learning-Bootcamp-with-PyTorch>

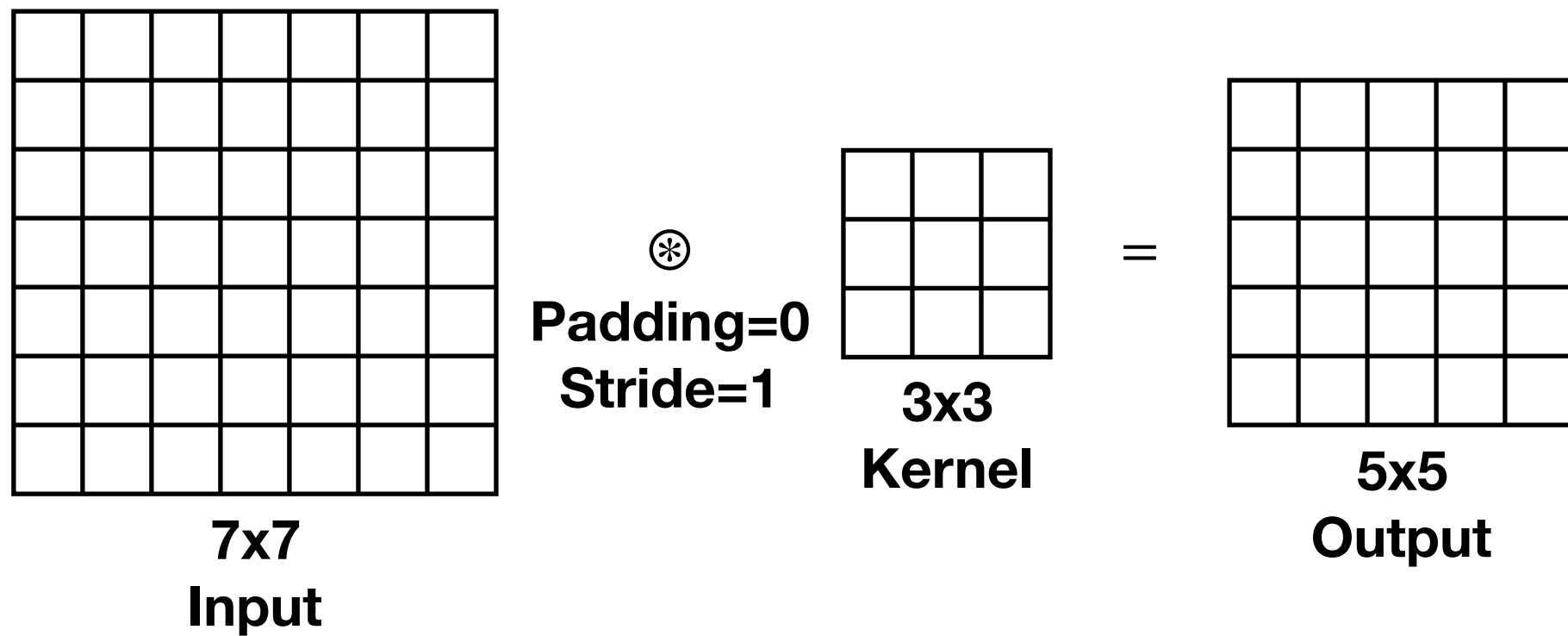
Appendix

Convolution



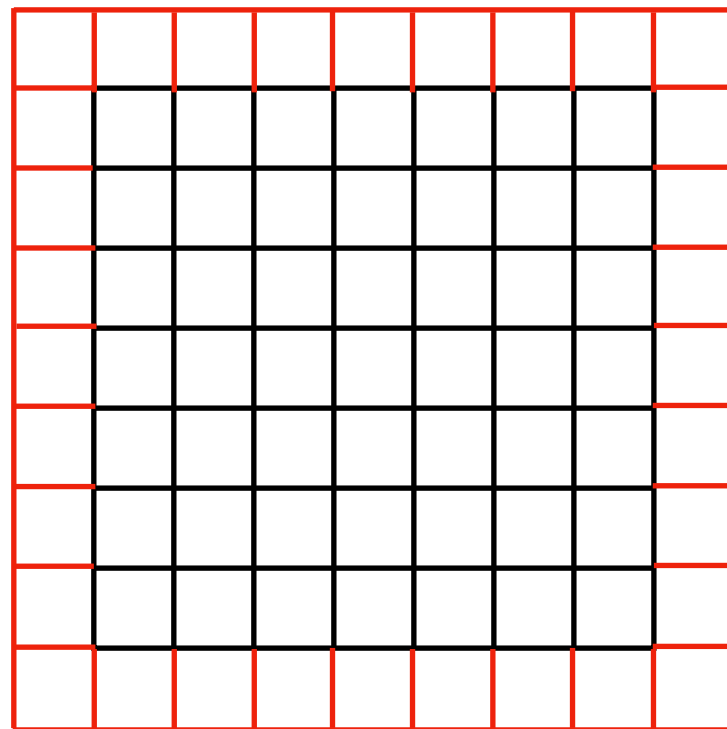
H: Height
 W: Width
 OC: Output Channel
 IC: Input Channel
 KH: Kernel Height
 KW: Kernel Width

Convolution



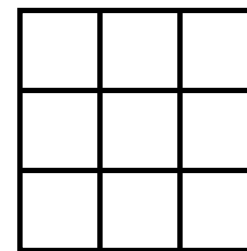
$$o = i - k + 1$$

Convolution



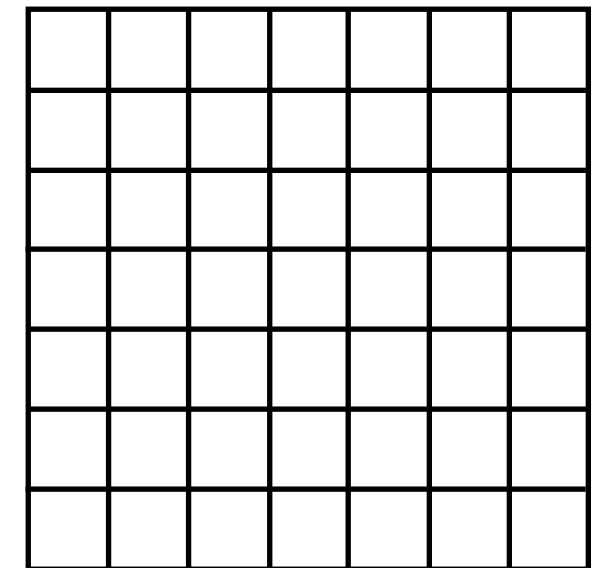
$(7 + 2 \times p) \times (7 + 2 \times p)$
Input

\otimes
Padding=1
Stride=1



3x3
Kernel

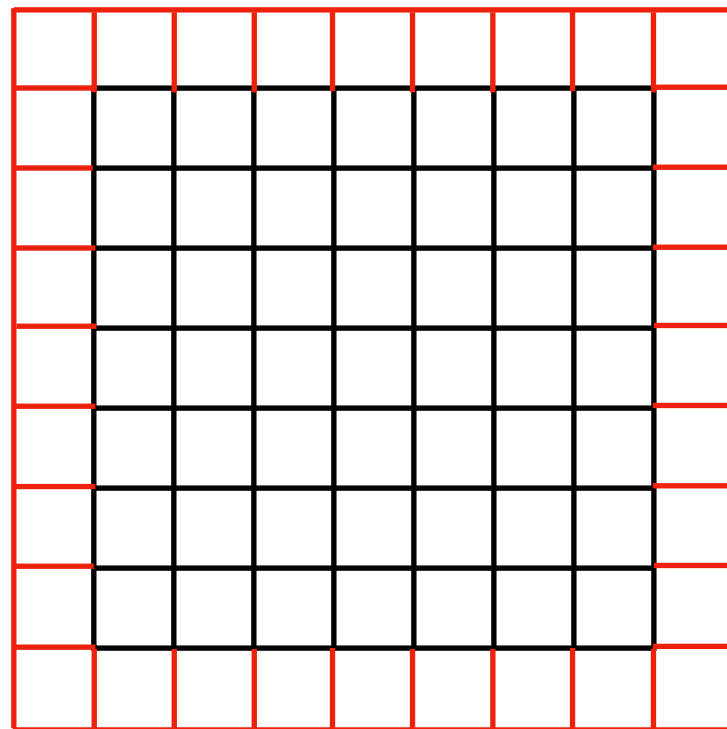
=



7x7
Output

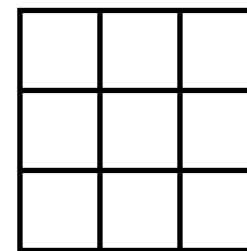
$$o = i - k + 2p + 1$$

Convolution



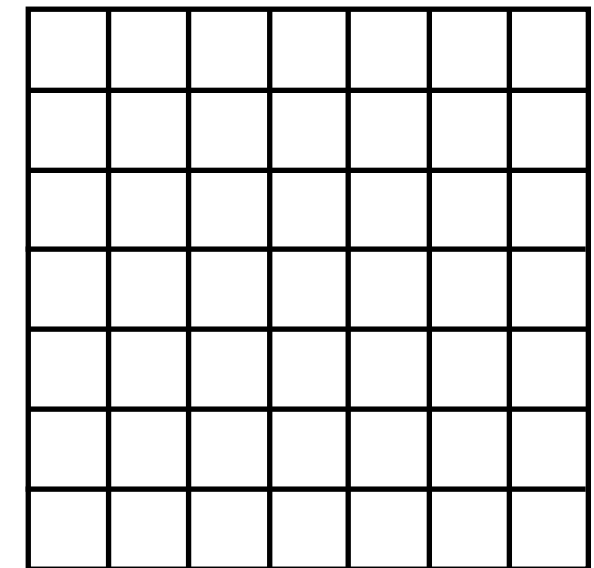
$(7 + 2 \times p) \times (7 + 2 \times p)$
Input

\otimes
Padding=1
Stride=2



3x3
Kernel

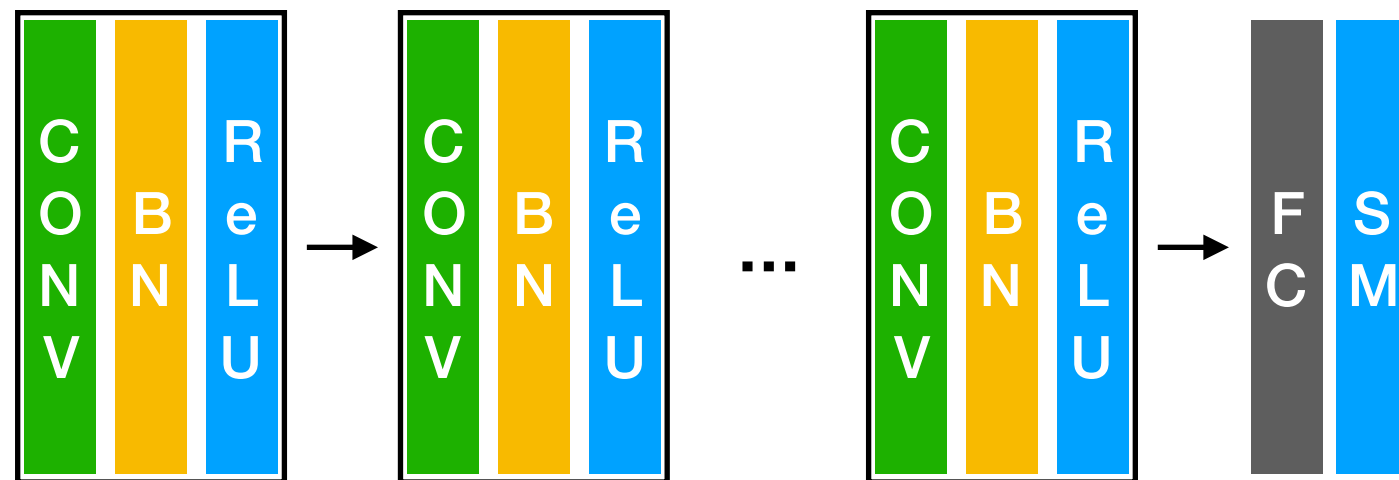
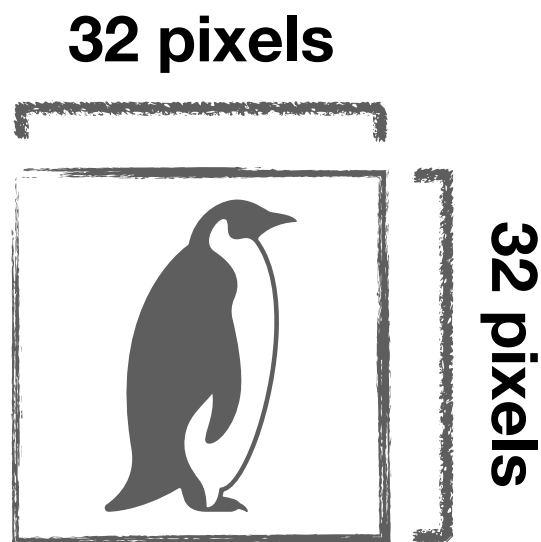
=



4x4
Output

$$o = \left\lfloor \frac{i - k + 2p}{s} \right\rfloor + 1$$

Convolutional neural network



BN: Batch Normalization
CONV: CONVolution
FC: Fully Connected layer
ReLU: Rectified Linear Unit
SM: SoftMax activation layer