

AE 4610 – Project proposal

Team member: Noe Lepez Da Silva Duarte

Project Idea: For this project, I plan on using Webots to create a line following robot, which will go around obstacles placed on the track. The robot shall therefore also have the ability to follow walls. I would like for the robot to have the ability to follow any set of lines at any angles to each other, however, my main goal will be to make the robot follow lines at no less than 90 degrees from each other.