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## AE 4631 - HW 4 workspace

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clc
clear
close all

## Q1

```
Test a = 6.796620707e6; i = 51.6439; e = 2.404e-4; RAAN = 86.8571; w = 1.8404; t = 15000;
t_arr = linspace(0,t,15001); pos_arr = [];
for j = t_arr[lat, lon, h] = oe2ecef(a,e,i,RAAN,w,j); pos_arr = [pos_arr; lat, lon];
GroundTrack(pos_arr(:,1), pos_arr(:,2)) title('ISS Ground Track - Noe Lepez')
% Part a - Planet Lab's FLOCK 2P-6
a = 6.864718799e6; i = 97.3262; e = 8.8380e-4; RAAN = 218.6861;
w = 216.6629; t = 17000;
t_arr = linspace(0,t,t+1);
pos_arr = [];
for j = t_arr
    [lat, lon, h] = oe2ecef(a,e,i,RAAN,w,j);
    pos_arr = [pos_arr ; lat, lon, h];
end
% Create the ground track
GroundTrack(pos_arr(:,1), pos_arr(:,2))
title('FLOCK 2P-6 Ground track - Noe Lepez')
Gx = qcf;
Gx.Position(3:4) = Gx.Position(3:4)*2;
Ax = qca;
saveas(figure(1), "q1_a.png")
% Create the 3D ground track
Plot3D_Earth(pos_arr(:,1), pos_arr(:,2), pos_arr(:,3), 2)
```

```
title('FLOCK 2P-6 3D Ground track- Noe Lepez')
Gx = qcf;
Gx.Position(3:4) = Gx.Position(3:4)*2;
Ax = qca;
saveas(figure(2), "q1_a_3d.png")
% Part b - Molniya 2-9 Communication Satellite
% Clear the previous figure and vars
clc
clear
close all
a = 2.323698972e7; i = 64.0370; e = 0.680478; RAAN = 343.6936;
w = 288.0884; t = 86400;
t_arr = linspace(0,t,t+1);
pos_arr = [];
for j = t arr
    [lat, lon, h] = oe2ecef(a,e,i,RAAN,w,j);
   pos_arr = [pos_arr ; lat, lon, h];
end
% Create the ground track
GroundTrack(pos_arr(:,1), pos_arr(:,2))
title('Molniya 2-9 Communication Satellite Ground track - Noe Lepez')
Gx = qcf;
Gx.Position(3:4) = Gx.Position(3:4)*2;
Ax = qca;
saveas(figure(1), "q1_b.png")
% Create the 3D ground track
Plot3D_Earth(pos_arr(:,1), pos_arr(:,2), pos_arr(:,3), 2)
title('Molniya 2-9 Communication Satellite 3D Ground track - Noe Lepez')
% Gx = gcf;
% Gx.Position(3:4) = Gx.Position(3:4)*2;
% Ax = qca;
saveas(figure(2), "q1_b_3d.png")
Q2
```

Clear the previous figure and vars

```
clc
clear
close all
% Part a
phi_GS = deg2rad(48.096);
lamb_GS = deg2rad(-119.781);
r_GS_ecef = 6371E3*[cos(lamb_GS)*cos(phi_GS);
```

```
sin(lamb_GS)*cos(phi_GS);
                    sin(phi GS)];
% Part b
% Test
% a = 6.796620707e6; i = 51.6439; e = 2.404e-4; RAAN = 86.8571; w = 1.8404;
% t = 65000;
% t_arr = linspace(0,t,t+1);
% pos_arr = [];
% for j = t_arr
     [lat, lon, h] = oe2ecef(a,e,i,RAAN,w,j);
왕
     pos_arr = [pos_arr ; j, lat, lon, h];
응
% end
% test_out = GSVisibilityCheck(pos_arr);
% test out(1,:)
% Planet Lab's FLOCK 2P-6
a = 6.864718799e6; i = 97.3262; e = 8.8380e-4; RAAN = 218.6861;
w = 216.6629; t = 40000;
t_arr = linspace(0,t,t+1);
pos_arr = [];
for j = t_arr
    [lat, lon, h] = oe2ecef(a,e,i,RAAN,w,j);
    pos_arr = [pos_arr ; j, lat, lon, h];
end
vis = GSVisibilityCheck(pos arr);
vis(1,:)
Q3
Part a
[azi, elev] = GSsatLOS(vis(1,:));
% Part b
% Test
% a = 6.796620707e6; i = 51.6439; e = 2.404e-4; RAAN = 86.8571; w = 1.8404;
% t = 65000;
% t_arr = linspace(0,t,t+1);
% pos_arr = [];
% for j = t_arr
```

```
[lat, lon, h] = oe2ecef(a,e,i,RAAN,w,j);
      pos_arr = [pos_arr ; j, lat, lon, h];
% end
응
% test_out = GSVisibilityCheck(pos_arr);
c = 1;
theta = [];
rho = [];
elev_arr = [];
azi_arr = [];
while c<=length(vis)</pre>
    [azi, elev] = GSsatLOS(vis(c,:));
    elev_arr = [elev_arr;elev];
    azi arr = [azi arr;azi];
    % Transfrom azimuth and elevation into theta and rho
    theta = [theta;azi*(pi/180)];
    rho = [rho; 1-(elev/90)];
    c = c+1;
end
% Plot theta and rho
figure(6)
polarplot(theta, rho, 'r.')
hold on
rlim([0 1])
ax = gca;
ax.ThetaZeroLocation = 'top';
ax.ThetaDir = 'clockwise';
ax.RTickLabel = {};
title("Noe Lepez - 14 Feb. 2022")
saveas(figure(6), "Q3b.png")
```

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