#### **CNRS** interview

# The Fine-Grained Complexity of Evaluating Database Queries

**Nofar CARMELI** 

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- Big data requires extremely efficient algorithms
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### The Fine-Grained Complexity of Evaluating Queries

To use data: store & query

- Big data requires extremely efficient algorithms
  - Fine-grained complexity: 'polynomial' is not enough
- What is the most efficient way of answering a database query?

## My Past Work

- Query Decompositions [PODS 17, DAM 20]
- Constant delay enumeration:
  - DBs with constraints [ICDT 18, TOCS 19]
  - Unions of CQs [PODS 19, TODS 21]
  - Random order [PODS 20]
  - Ranked access [PODS 21, PODS 23]
- Repairing noisy DBs [ICDT 21]
- Representing probabilistic DBs [PODS 21]

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# **Enumeration Complexity of UCQs**

- Goal
- Overview
- Explanations
  - Easy ∪ Hard
    - Why isn't it always hard?
    - When is it easy?
  - Hard ∪ Hard
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### Goal

Which Unions of Conjunctive Queries can be answered with optimal time guarantees?

#### tutorials:

Person	Title
Alan Fekete	Making Consistency
Suresh Venkatasu	Algorithmic Fairness

#### schedule:

Title	Day
Making Consistency	Tue
Algorithmic Fairness	Wed
Regularizing Conjunct	Mon

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Conjunctive Query: Join + Project

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# Person Day Alan Fekete Tue Suresh Venkatasu... Wed

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$$Q_3 = Q_1 \cup Q_2$$

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- DelayC<sub>lin</sub>: solvable in linear preprocessing and constant delay



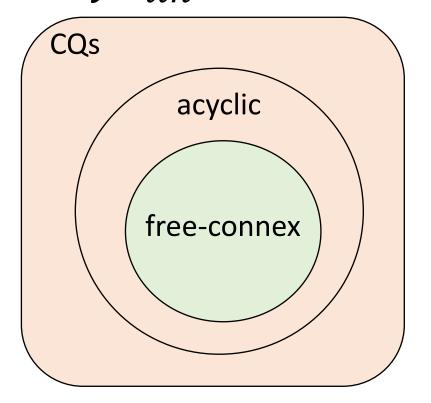
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# Starting Point

[BaganDurandGrandjean CSL'2007] [Brault-Baron 2013]

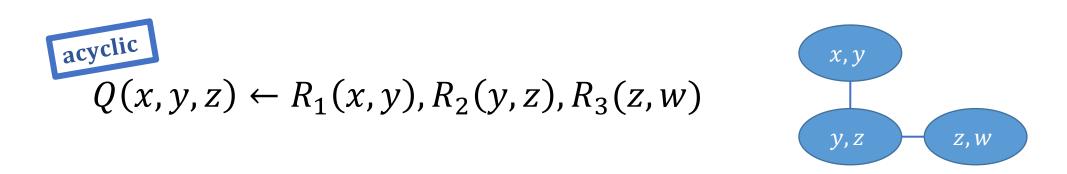
CQs:  $\in DelayC_{lin} \Leftrightarrow^* \text{free-connex}$ 



- \* Hardness results assume:
- (1) no self-joins
- (2) hardness of Boolean matrix multiplication and hyperclique

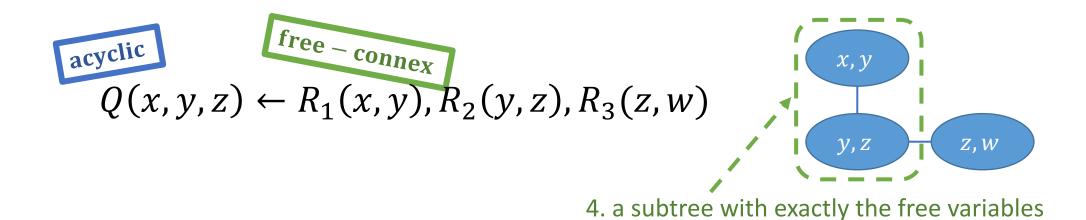
### Free-connex Definition

- 1. a node for every atom
- 2. tree
- 3. for every variable X: the nodes containing X form a subtree



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1. a node for every atom 2. tree 3. for every variable X: the nodes containing X form a subtree

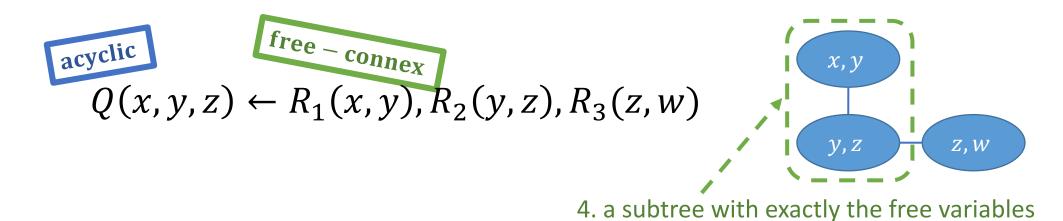


### Free-connex Definition

1. a node for every atom possibly also subsets

2. tree

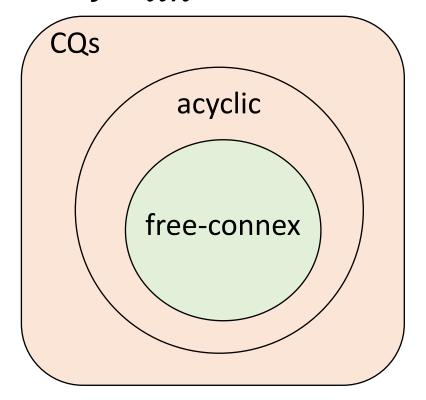
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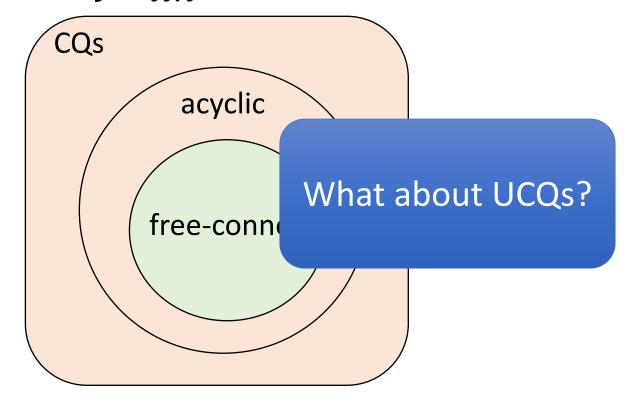


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# Cases for UCQs

All CQs are Easy
Some Easy, Some Hard
All CQs are Hard

All CQs are Easy

Some Easy, Some Hard

All CQs are Hard

All CQs are Easy

always easy

Some Easy, Some Hard

All CQs are Hard

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All CQs are Hard





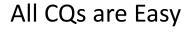
All CQs are Hard





All CQs are Hard

$$Q_1(x, y) \leftarrow R_1(x, y), R_2(y, z), R_3(z, x)$$
$$Q_2(x, y) \leftarrow R_1(x, y), R_2(y, z)$$



always easy

Some Easy, Some Hard

sometimes hard

All CQs are Hard

$$Q_1(x,y) \leftarrow R_1(x,y), R_2(y,z), R_3(z,x)$$
 non free – connex

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$$Q_1 \subseteq Q_2$$

All CQs are Easy

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$$Q_1 \subseteq Q_2 \implies Q_1 \cup Q_2 = Q_2$$





All CQs are Hard

$$Q_{1}(x,y) \leftarrow R_{1}(x,y), R_{2}(y,z), R_{3}(z,x) \text{ non free - connex}$$

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All CQs are Hard

non-redundant unions?





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non-redundant unions?

Claimed [ICDT 2018]: hard if contains a hard CQ





All CQs are Hard

some non-redundant unions
with a hard CQ
are easy





All CQs are Hard

\* Even for non-redundant unions

some **non-redundant** unions **with** a hard CQ

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All CQs are Easy

always easy



All CQs are Hard

\* Even for non-redundant unions

If each CQ in Q is hard and there is no body-isomorphism

 $\Rightarrow$  Q  $\notin$  Delay $C_{lin}$ 





All CQs are Hard

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UCQs containing **only hard** CQs can be **easy**!







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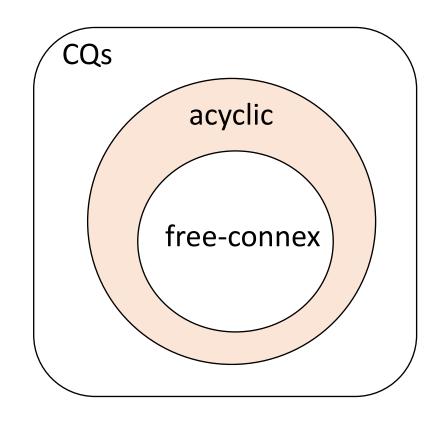
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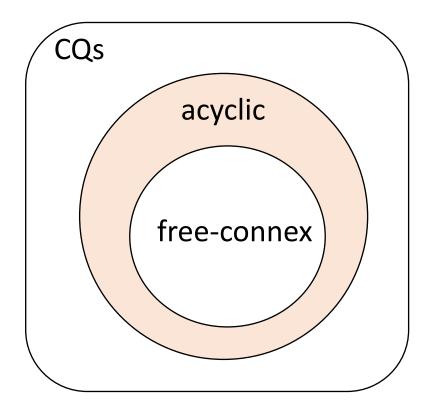


#### [BaganDurandGrandjean CSL'2007]

Assumption: Boolean  $n \times n$  matrices cannot be multiplied in time  $O(n^2)$ 

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} ? & ? \\ ? & ? \end{pmatrix}$$

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Acyclic non-free-connex:

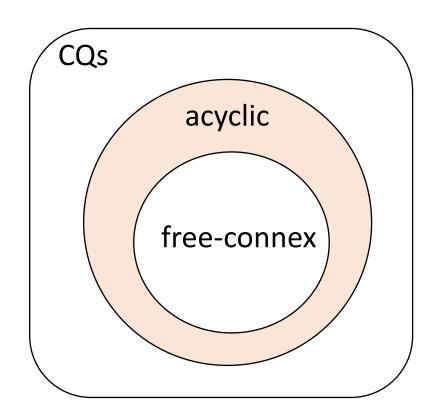
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Δ

R	С
1	1
1	2
2	2

B

1 2	R C	R
	_ 2	1
2 2	2 2	2



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Q

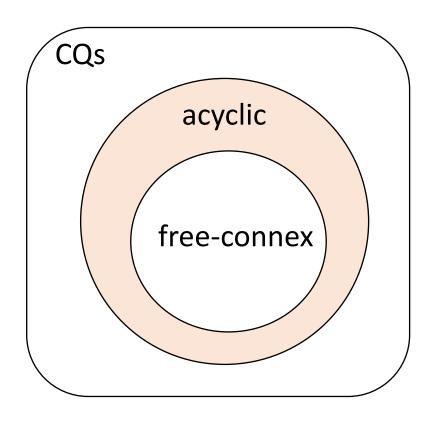
R	С
1	2
2	2

Α

R	C
1	1
1	2
2	2

В

R	С
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2	2



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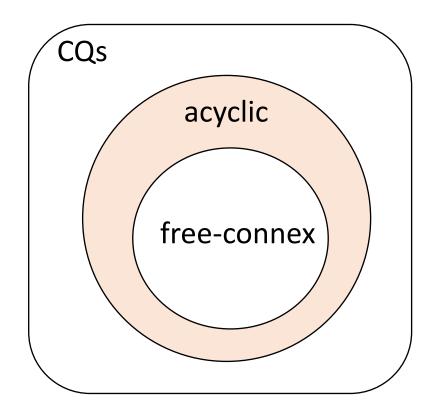
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R C 1 2

С
2
2



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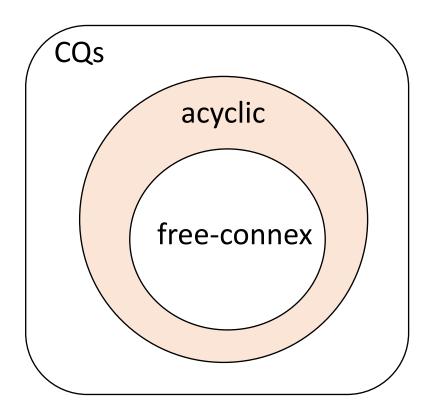
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Q		
R	С	
1	2	
2	2	

A		
R	С	
1	1	
1	2	
2	2	

R	С
1	2
2	2



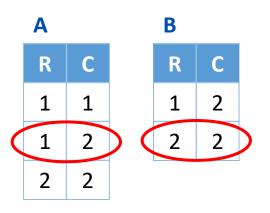
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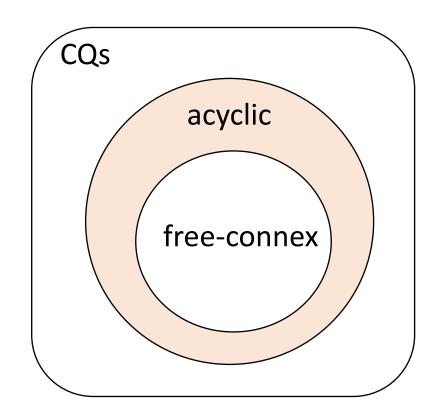
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	Q		
	R	С	
(	1	2	
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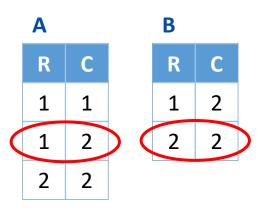
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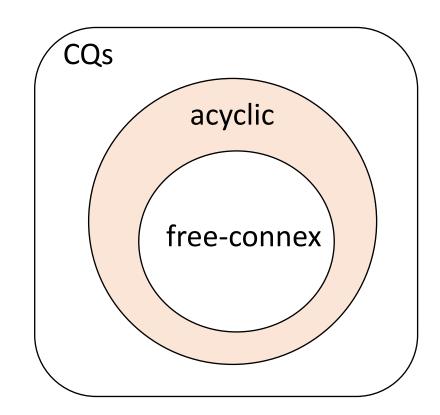
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Q(x,z)	$\leftarrow R_1$	(x, y)	$R_2$	(v, z)	z
$Q(\lambda, \Delta)$	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	$(\lambda, y)$	, 1\2\	( <i>y</i> , ∠	5 J

Q		
R	С	
1	2	
2	2	





$$Q_1(x, z, w) \leftarrow R_1(x, y), R_2(y, z), R_3(z, w)$$

$$\underbrace{R_1(x, y), R_2(y, z), R_3(z, w)}_{\text{not free connex}}$$

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$R_1$		$R_2$	
1	1	1	2
1	2	2	2
2	2		

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$Q_1$		
1	2	Ţ
2	2	T

$R_1$		$R_2$		$R_3$	
1	1	1	2	2	Τ
1	2	2	2		
2	2				

$$Q_1(x,z,w) \leftarrow R_1(x,y), R_2(y,z), R_3(z,w)$$

$$\cup$$

$$Q_2(x',y',z') \leftarrow R_1(x',y'), R_2(y',z')$$

$Q_1$		
1	2	Τ
2	2	1

$R_1$		$R_2$		$R_3$	
1	1	1	2	2	Τ
1	2	2	2		
2	2				

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$Q_1$		
1	2	Τ
2	2	Τ
$Q_2$		
1	1	2
1	2	2
2	2	2

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$Q_1$		
1	2	Τ
2	2	Τ
$Q_2$		
1	1	2
1	2	2
2	2	2

 $O(n^3)$  solutions: The computation does not contradict the assumption

$R_1$	
1	1
1	2
2	2



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$Q_1$		
1	2	Τ
2	2	Τ
$Q_2$		
1	1	2
1	2	2
2	2	2

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				ı		
$R_1$		$R_2$			$R_3$	
1	1	1	2		2	<b>T</b>
1	2	2	2			
2	2			•		

The hardness results do not hold within a union

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$$free - connex Q_2(x',y',z') \leftarrow R_1(x',y'), R_2(y',z')$$

$$\in DelayC_{lin}$$

$$Q_{1}(x,z,w) \leftarrow R_{1}(x,y), R_{2}(y,z), R_{3}(z,w)$$

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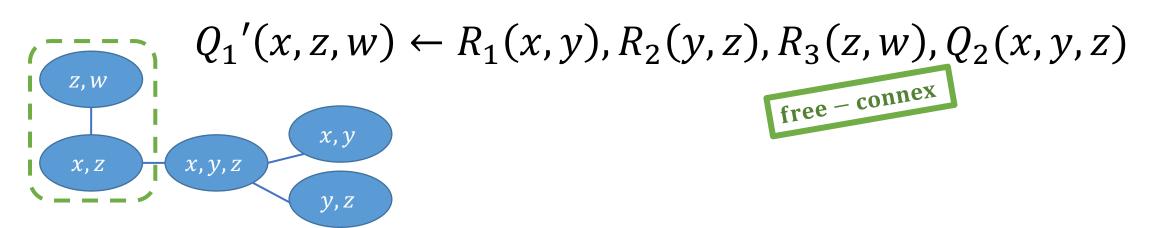
$$\in \text{Delay}_{\text{Lin}}$$

$$\begin{array}{c} \text{hard part} \\ \text{non free - connex} \ Q_1(x,z,w) \leftarrow R_1(x,y), R_2(y,z), R_3(z,w) \\ \text{Body-homomorphism} / \\ \text{free - connex} \ Q_2(x',y',z') \leftarrow R_1(x',y'), R_2(y',z') \end{array}$$

$$\begin{array}{c} \text{hard part} \\ \text{non free - connex} \ Q_1(x,z,w) \leftarrow R_1(x,y), R_2(y,z), R_3(z,w) \\ \text{Body-homomorphism} \\ Q_2(x',y',z') \leftarrow R_1(x',y'), R_2(y',z') \end{array}$$

$$Q_1'(x,z,w) \leftarrow R_1(x,y), R_2(y,z), R_3(z,w), Q_2(x,y,z)$$

$$\begin{array}{c} \text{hard part} \\ \text{non free - connex} \ Q_1(x,z,w) \leftarrow R_1(x,y), R_2(y,z), R_3(z,w) \\ \text{Body-homomorphism} \\ Q_2(x',y',z') \leftarrow R_1(x',y'), R_2(y',z') \end{array}$$



## **Enumeration Complexity of UCQs**

- Goal
- Overview
- Explanations
  - Easy ∪ Hard
    - Why isn't it always hard?
    - When is it easy?
  - Hard ∪ Hard
    - Sometimes it is easy

## Hard ∪ Hard = Easy

• Example: CQs with isomorphic bodies.

$$Q_1(x, z, w, u) \leftarrow R_1(x, y), R_2(y, z), R_3(z, w), R_4(w, u)$$
  
$$Q_2(x, y, z, u) \leftarrow R_1(x, y), R_2(y, z), R_3(z, w), R_4(w, u)$$

## Hard ∪ Hard = Easy

• Example: CQs with isomorphic bodies.

$$Q_{1}(x, z, w, u) \leftarrow R_{1}(x, y), R_{2}(y, z), R_{3}(z, w), R_{4}(w, u)$$

$$Q_{2}(x, y, z, u) \leftarrow R_{1}(x, y), R_{2}(y, z), R_{3}(z, w), R_{4}(w, u)$$
hard part

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hard part

	Step	Output	Side Effect
1	Solve ${Q_2}^\prime$	$\subseteq Q_2$	Find $R_1 \bowtie R_2$
2	Solve $Q_1^+$	$Q_1$	Find $R_3 \bowtie R_4$
3	Solve $Q_2^+$	$Q_2$	

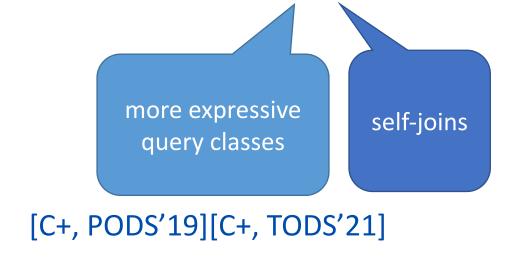
## **Enumeration Complexity of UCQs**

- Goal
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  - Easy ∪ Hard
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  - Hard ∪ Hard
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## Research Project

To use data: store & query

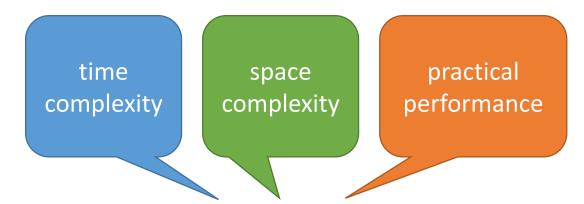
- Big data requires extremely efficient algorithms
  - Fine-grained complexity: 'polynomial' is not enough
- What is the most efficient way of answering a database query?

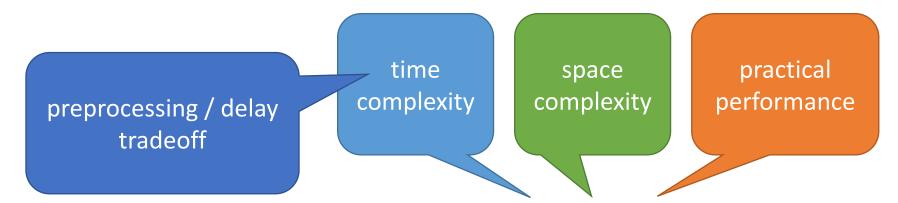


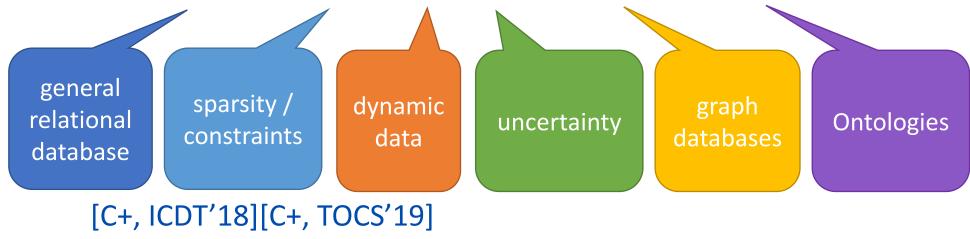
What is the most efficient way of answering a database query?

enumeration vs. direct access

[C+, PODS'20] [C+, PODS'21]







## Integration

	IRIF	LaBRI	LIRMM
Example common interests	Graph DBs	DBs with constraints	Ontologies
	Uncertain data	Ontologies	Dynamic data
Natural collaborators	Cristina Sirangelo	Diego Figueira	David Carral
	Amélie Gheerbrant	Meghyn Bienvenu	Federico Ulliana

# Thank you.