



reciTAL.

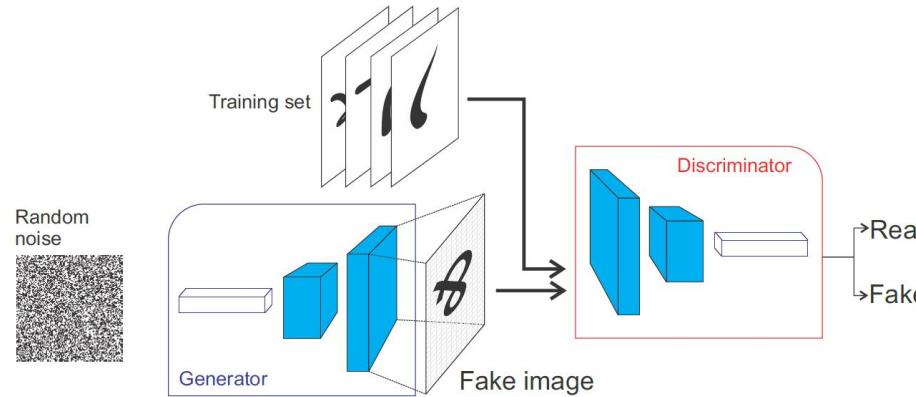


## Generative Cooperative Networks for Natural Language Generation

Sylvain Lamprier, Thomas Scialom, Antoine Chaffin, Vincent Claveau,  
Ewa Kijak, Benjamin Piwowarski, Jacopo Staiano

# Language GANs fall short

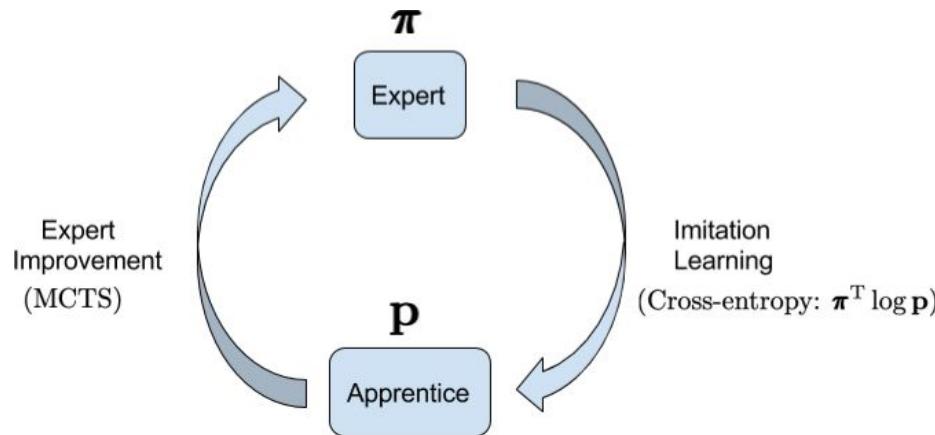
- GANs are good for approximating continuous data distributions:



- GANs for discrete data as text:
  - No backpropagation from the discriminator to the generator :
    - Reinforcement Learning with Discriminator scores as Rewards
      - Noisy, Sparse and Moving Rewards
    - Existing language GANs are known to fall short (Caccia et al, 2020)

# Cooperative Decoding

- Use of the **discriminator  $D$**  cooperatively with the generator  $p$  for sampling texts
  - In Beam Search: DAS [Scialom et. al, 2020b], Discriminative EBM [Ranzato et al., 2019]
  - In MCTS: SelfGAN [Scialom et. al, 2021]
- SelfGAN: Cooperative decoding can be useful for training via Expert Iteration

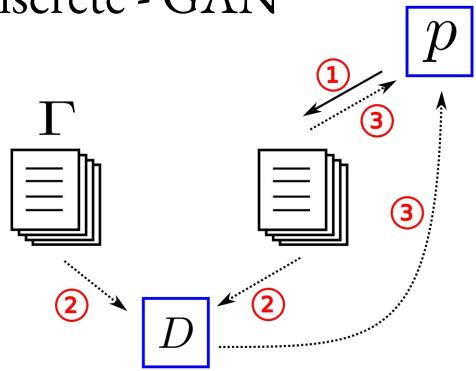


But unstable even at the optimum !  
• Can diverge or oscillate  
• Requires a LR scheduler

- We show that sampling from  $q(\tau) \propto p(\tau)D(\tau)$  can allow to ensure convergence  
(under usual assumptions and a **Reward-augmented Maximum Likelihood** process (RML) [Norouzi et al., 2016])

# GAN vs RML-GAN

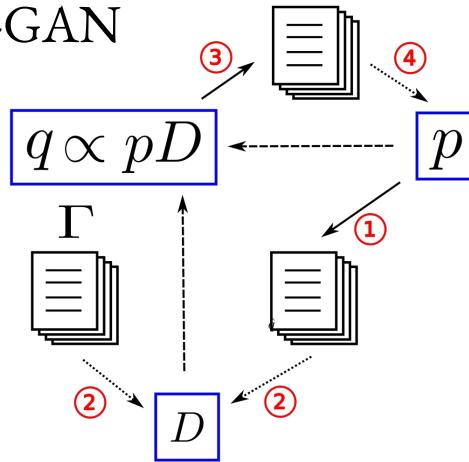
## Discrete - GAN



- ① Sample M documents from generator  $p$   
 $y^i \sim p_\theta(y^i)$
- ② Train the discriminator  $D_t$
- ③ Train  $p$  with rewards from discriminator  $D$  on generated samples (policy gradient)

$$\theta \leftarrow \theta + \epsilon \frac{1}{M} \sum_{i=1}^M D_t(y^i) \nabla_\theta \log p_\theta(y^i)$$

## RML-GAN

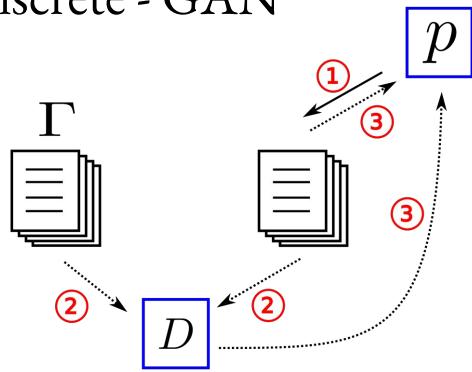


- ① Sample documents from generator  $p$
- ② Train the discriminator  $D$
- ③ Generate M samples from  $q \propto pD$   
 $y^i \sim q(y^i)$
- ④ Train  $p$  using samples from  $q$

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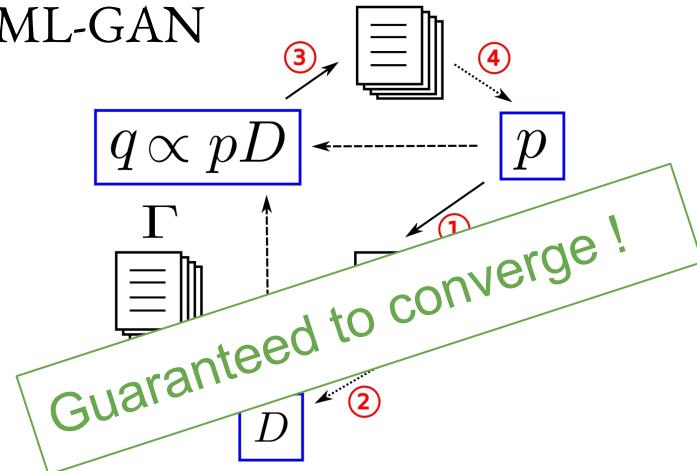
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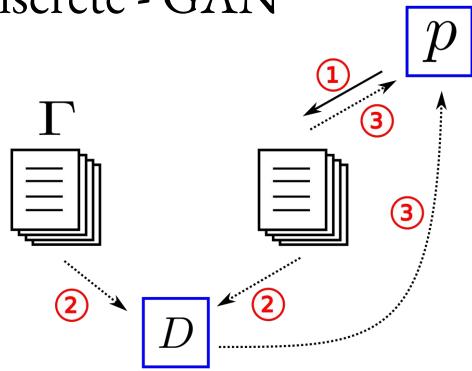


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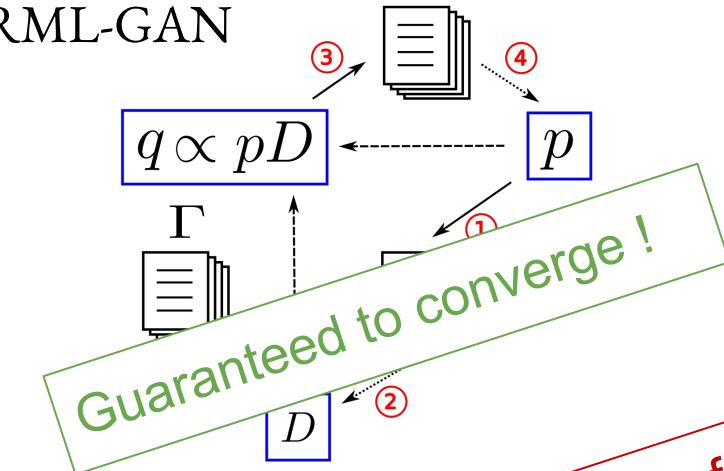
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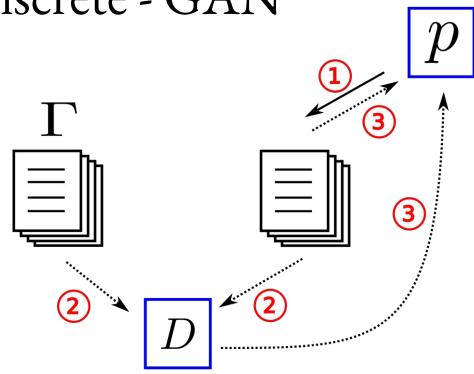
**But we do not know sampling from  $q$ !**

$q \propto pD$

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# GAN vs GCN

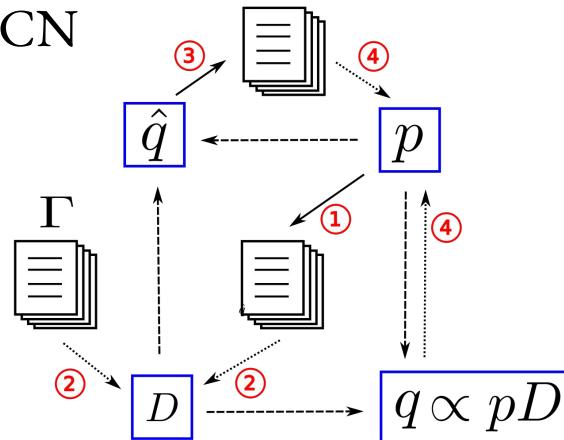
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## GCN

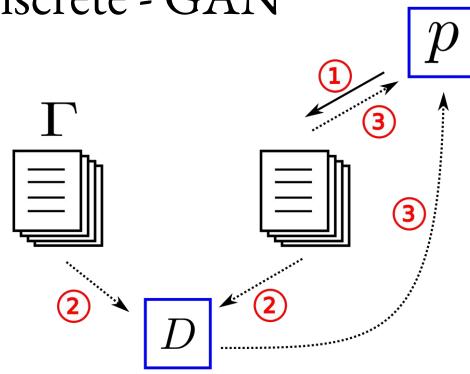


- ① Sample documents from generator  $p$
- ② Train the discriminator  $D$
- ③ Generate M samples from  $\hat{q}$   
 $y^i \sim \hat{q}(y^i)$
- ④ Train  $p$  using weighted importance sampling

$$\theta \leftarrow \theta + \epsilon \frac{1}{\sum_{i=1}^M w^i} \sum_{i=1}^M w^i \nabla_\theta \log p_\theta(y^i) \quad \text{with: } w^i = \frac{q(y^i)}{\hat{q}(y^i)}$$

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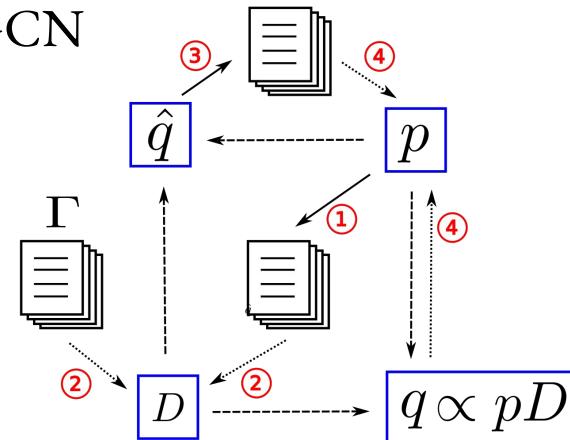
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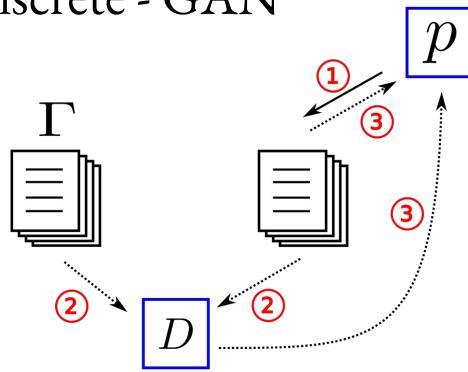
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→ With  $\hat{q} = p_\theta$ , we have:  $\theta \leftarrow \theta + \epsilon \frac{1}{Z_t} \sum_{i=1}^M D_t(y^i) \nabla_\theta \log p_\theta(y^i)$ , where  $Z_t = \sum_{i=1}^M p_\theta(y^i) D_t(y^i)$

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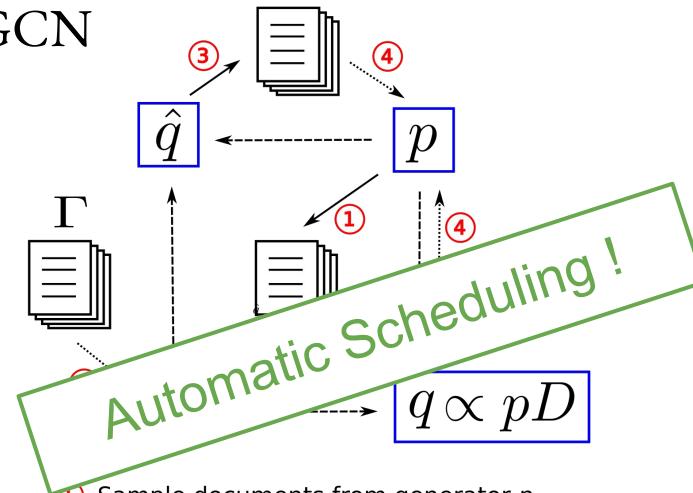
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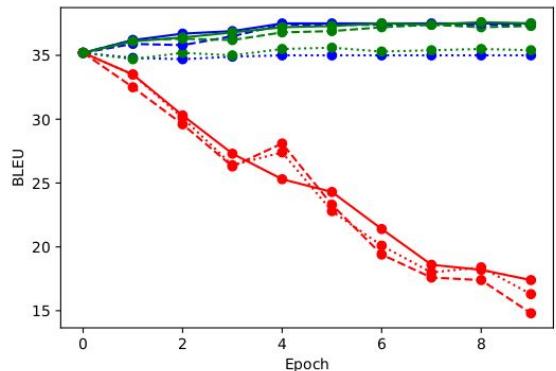
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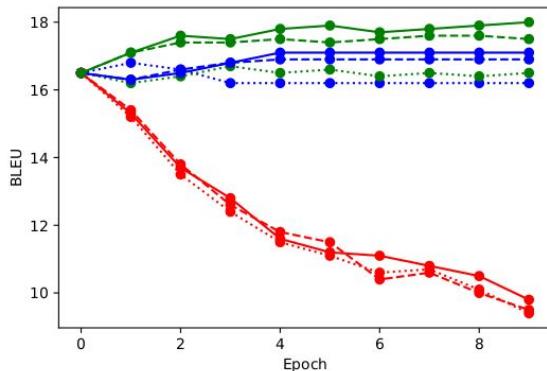
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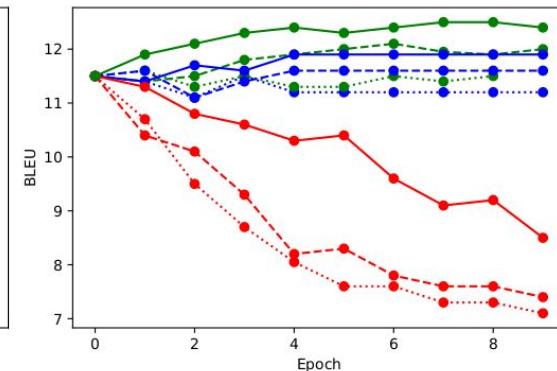
Unconditional NLG



Question Generation



Summarization



Legend:

- GAN $\hat{q}=p$  (blue dotted)
- GAN $\hat{q}=P$  (red dotted)
- GCN $\hat{q}=p$  (green dotted)
- GAN $\hat{q}=\text{scheduler}$  (blue solid)
- GAN $\hat{q}=\text{Nucleus}$  (red solid)
- GCN $\hat{q}=\text{Nucleus}$  (green solid)
- GAN $\hat{q}=MCTS$  (blue dashed)
- GAN $\hat{q}=\text{MCTS}$  (red dashed)
- GCN $\hat{q}=MCTS$  (green dashed)

- No scheduler required
- Sampling closer to  $q$  allows to still improve results (state-of-the-art) !
  - Use of Monte-Carlo Tree Search guided by  $p_\theta(y)D(y)$

Thank you for your attention !  
Please check the paper for more details

