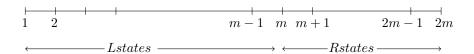
Department of Mathematics, IIT Madras MA 2040 : Probability, Statistics and Stochastic Processes $_{ m July}$ - Nov 2020

Solutions to Problem Set - 9

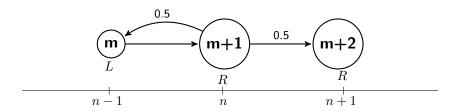
1. Note that,



We have,

$$P(X_{n+1} = R | X_n = R, X_{n-1} = L) = \frac{1}{2}.$$
 (1)

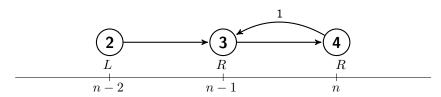
Graphically, we have



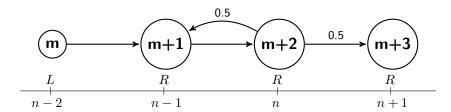
Also,

$$P(X_{n+1} = R | X_n = R, X_{n-1} = R, X_{n-2} = L) = 1.$$
(2)

For m=2

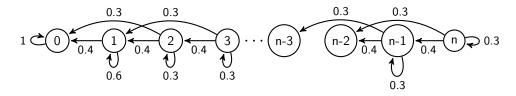


For $m=3,4,5,\cdots$



From (1) and (2) , it follows that the generated sequence of signals L and R is not a Markov chain.

2. (a) Let n be the initial distance between spider and fly. State space = $\{0, 1, 2, \dots, n\}$. Markov chain with states as distance.



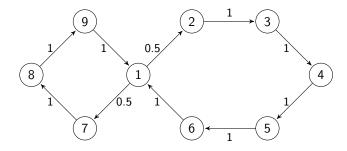
The transition probability matrix is,

$$P = R(1) = \begin{bmatrix} 0 & 1 & 2 & \cdots & n \\ 1 & 0 & 0 & \cdots & 0 \\ .4 & .6 & 0 & \cdots & 0 \\ .3 & .4 & .3 & \cdots & 0 \\ 0 & .3 & .4 & \cdots & 0 \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ n & \begin{bmatrix} 0 & 1 & 2 & \cdots & n \\ .4 & .6 & 0 & \cdots & 0 \\ .3 & .4 & .3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ 0 & 0 & 0 & \cdots & .3 \end{bmatrix}$$

Note that

 $p_{10} = P(\text{fly remains at its place and spider moves a step given the distance is one unit}) = .4$ $p_{11} = P(\text{fly moves away one unit and spider moves a unit towards fly } | \text{distance between spider}$ and fly is one unit)+ P(fly reaches the position of spider and spider reaches the position of fly | distance between spider and fly is one unit) = .3 + .3 = .6

- (b) State 0 is recurrent and all other states are transient.
- 3. This Markov chain can be represented as



All states are recurrent states and there is only one recurrent class; namely, the whole state space. Note that, this recurrent class can be partitioned into two subsets, $S_1 = \{2, 4, 6, 7, 9\}$ and $S_2 = \{1, 3, 5, 8\}$, and the state of the Markov chain jumps from S_1 to S_2 (with probability 1) in one time step. Therefore, this Markov chain's recurrent class has period 2.

4. (a) Recurrent states are 1, 2, 4, 5 and 6.

Transient state is 3.

There are two recurrent classes $A(1) = A(2) = \{1, 2\}$ and $A(4) = A(5) = A(6)\{4, 5, 6\}$. Only the second recurrent class is periodic.

- (b) The required probability = $\underbrace{0.2 \times 0.2 \times \cdots \times 0.2}_{n \text{ times}} = (0.2)^n$.
- (c) Process stays in state 3 with probability 0.2

Process leaves state 3 with probability 0.8.

Trials up to and including the trial on which process leaves state 3 is a geometric random variable with parameter 0.8.

Hence expected number of trials $=\frac{1}{0.8}=\frac{5}{4}$.

- (d) If the process goes from state 3 to state 4, then it never enters state 1. If the process goes from state 3 to 2, then it will reac state 1 with probability 1. Hence, the probability of never entering state 1 is $=\frac{3}{8}$.
- (e) Desired probability

$$= p_{34} \cdot (p_{45}p_{56}p_{64})^3 + (p_{33})^3p_{34} \cdot (p_{45}p_{56}p_{64})^2 + (p_{33})^6p_{34} \cdot (p_{45}p_{56}p_{64}) + (p_{33})^9 \cdot p_{34}$$
$$= 0.3 + (0.2)^3 \times 0.3 + (0.2)^6 \times 0.3 + (0.2)^9 \times 0.3 = 0.3024$$

The required probability may also be obtained as the $(3,4)^{th}$ element of P^{10} .

(f) P(process was in state 4 after the first trial | process is in state 4 after 10 trials)

 $=\frac{P(\text{in state 4 after 10 trials} \mid \text{in state 4 after first trial})P(\text{in state 4 after first trial})}{P(\text{in state 4 after 10 trials})}$ $=\frac{(p_{45}p_{56}p_{64})^3 \cdot p_{34}}{0.3024} = \frac{1 \times 0.3}{0.3024} = 0.992$

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5. (a) Transition probability matrix is given by

$$P = R(1) = \begin{bmatrix} .4 & .6 & 0 \\ .3 & .5 & .2 \\ 0 & .2 & .8 \end{bmatrix}$$

The steady-state probabilities π_i satisfy

$$\pi_j = \sum_{k=1}^m \pi_k p_{kj}, \quad j = 1, 2, 3$$

From this we obtain, $\pi_1 = .2, \pi_2 = .4, \pi_3 = .4$ Alternatively for large n, (say n = 100)

$$P^{100} = \begin{bmatrix} .2 & .4 & 4 \\ .2 & .4 & .4 \\ 2 & .4 & .4 \end{bmatrix}$$

, by using Python or Matlab.

which imply $r_{11}(100) = r_{21}(100) = r_{31}(100) = .2$

$$r_{12}(100) = r_{22}(100) = r_{32}(100) = .4$$

$$r_{31}(100) = r_{32}(100) = r_{33}(100) = .4$$

that is the nth step probabilities does not depends on initial state. In other words the probability of going to state 1 from state 1, state 2, and state 3 is same and is equal to .2. Probability is .4 for the system to be in state 2 after reaching steady state.

(b) Desired probability = P(transition from state 1 to 2| chain is in state 1) P(in state 1) + P(transition from state 2 to 3| chain is in state 2) P(in state 2)

$$= .6 \times .2 + .2 \times .4 = .2$$

- (c) P(first change of state is a birth)
 - = P(first change of state is a birth| chain is in state 1)P(chain in state 1)+P(first change of state is a birth| chain is in state 2)P(chain in state 2)+P(first change of state is a birth| chain is in state 3)P(chain in state 3)

$$= 1 \times .2 + \frac{.2}{.2+.3} \times .4 + 0 \times .4 = .36$$

- (d) P(Process was in state 2 | first transition is a birth)
 - $= \frac{P(\text{Process was in state 2 and first transition is a birth})}{P(\text{first transition is a birth})}$
 - $= \frac{P(\text{first transition is a birth} \text{Process was in state 2})}{P(\text{first transition is birth})} \times P(\text{Process was in state 2})$

$$=\frac{.2\times.4}{.2}$$
 (using 5(b))
= .4

(e) Similar to part 5(d),

P(Process was in state 2 | first change of state is birth)

 $= \frac{P(\text{first change of state is birth} - \text{process was in state 2})}{P(\text{First change of state is birth})} \times P(\text{Process was in state 2})$

$$=\frac{.2/(.2+.3)\times.4}{.36}=\frac{.16}{.36}=\frac{4}{9}.$$

- (f) P(first observed transition is a birth | first observed transition resulted in change of state)
 - $= \frac{P(\text{first observed transition is a birth and it resulted in change of state})}{P(\text{first observed transition resulted in change of state})}$

$$= \frac{p_{12}\pi_1 + p_{23}\pi_3}{p_{12}\pi_1 + (p_{23} + p_{21})\pi_2 + p_{32}\pi_3}$$
$$= \frac{.6 \times .2 + .2 \times .4}{.6 \times .2 + .5 \times .4 + .2 \times .4} = 0.5$$

- (g) P(first transition leads to state 2/mid first observed transition resulted in change of state)
 - = $\frac{P(\text{first transition leads to state 2 and it also resulted in change of state})$

P(first observed transition resulted in change of state)

$$= \frac{p_{12}\pi_1 + p_{32}\pi_3}{p_{12}\pi_1 + (p_{23} + p_{21})\pi_2 + p_{32}\pi_3}$$
$$= \frac{.6 \times .2 + .2 \times .4}{.6 \times .2 + .5 \times .4 + .2 \times .4} = 0.5$$