Robotic and AI

<u>Task 3</u>

Install Package Robot arm on ROS
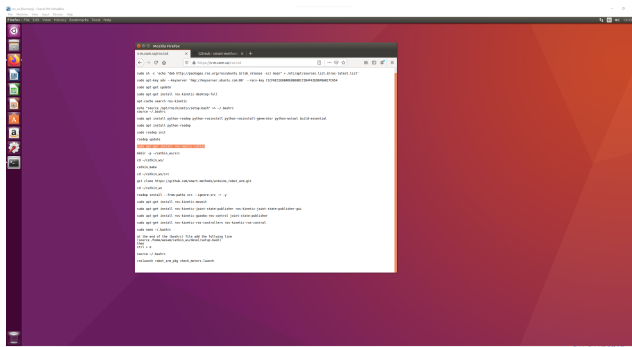
Download ROS
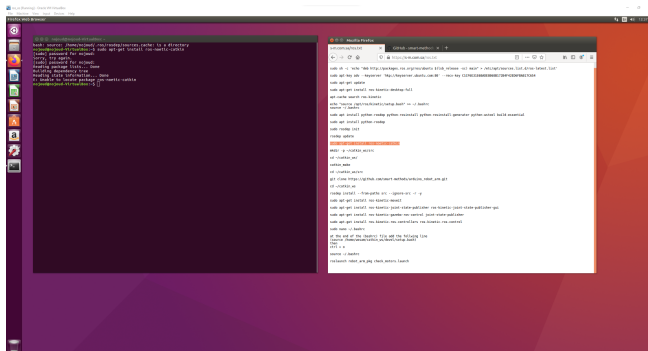
Open Linux

Open file code of package robot arm
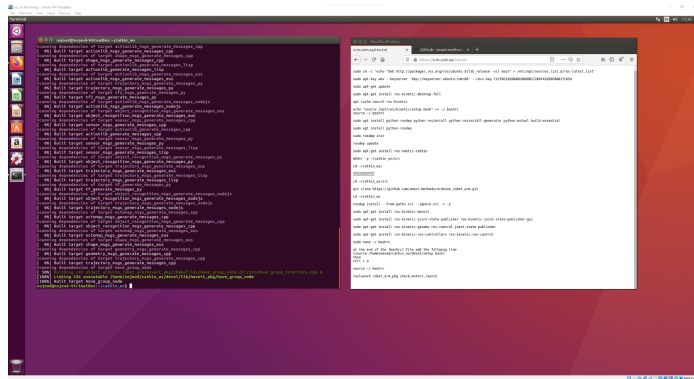
https://s-m.com.sa/ros.txt

Cope code from sudo apt-get install ros-noetic-catkin

And prest code antle last to Terminal

The when finish all code so open Rivz with joint-state-publisher-gui