

CS221: Algorithms and Data Structures

Lecture #4

Sorting Things Out

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Today's Outline

- Categorizing/Comparing Sorting Algorithms
 - PQSorts as examples
- MergeSort
- QuickSort
- More Comparisons
- Complexity of Sorting

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Categorizing Sorting Algorithms

- Computational complexity
 - Average case behaviour: Why do we care?
 - Worst/best case behaviour: Why do we care? How often do we re-sort sorted, reverse sorted, or “almost” sorted (k swaps from sorted where $k \ll n$) lists?
- Stability: What happens to elements with identical keys?
- Memory Usage: How much *extra* memory is used?

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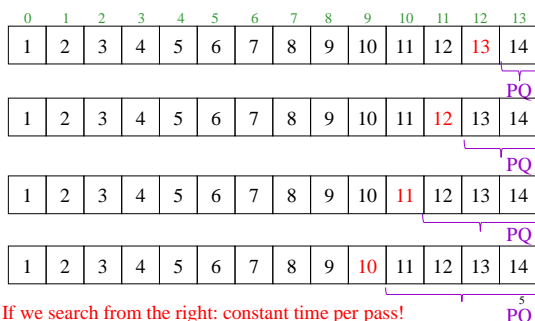
Comparing our “PQSort” Algorithms

- Computational complexity
 - Selection Sort: *Always* makes n passes with a “triangular” shape. Best/worst/average case $\Theta(n^2)$
 - Insertion Sort: *Always* makes n passes, but if we’re lucky and search for the maximum from the right, only constant work is needed on each pass. Best case $\Theta(n)$; worst/average case: $\Theta(n^2)$
 - Heap Sort: *Always* makes n passes needing $O(\lg n)$ on each pass. Best/worst/average case: $\Theta(n \lg n)$.

Note: best cases assume *distinct* elements.
With identical elements, Heap Sort can get $\Theta(n)$ performance.

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Insertion Sort Best Case



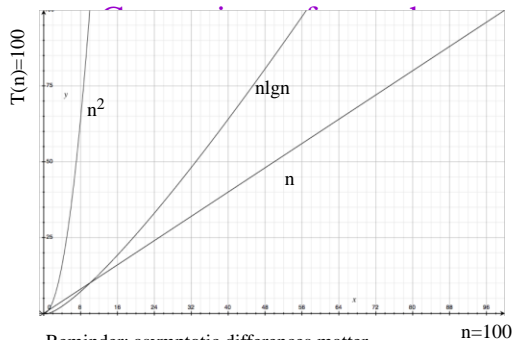
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Comparing our “PQSort” Algorithms

- Stability
 - Selection: Easily made stable (when building from the left, prefer the left-most of identical “biggest” keys).
 - Insertion: Easily made stable (when building from the left, find the rightmost slot for a new element).
 - Heap: Unstable ☹
- Memory use: All three are essentially “in-place” algorithms with small $O(1)$ extra space requirements.
- Cache access: Not detailed in 221, but... algorithms that don’t “jump around” tend to perform better in modern memory systems. Which of these “jumps around”?

But note: there’s a trick to make *any* sort stable.

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Reminder: asymptotic differences matter, but a factor of $\lg n$ doesn't matter as much as a factor of n .⁷

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MergeSort

Mergesort belongs to a class of algorithms known as “divide and conquer” algorithms (your recursion sense should be tingling here...).

The problem space is continually split in half, recursively applying the algorithm to each half until the base case is reached.

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MergeSort Algorithm

1. If the array has 0 or 1 elements, it's sorted. Else...
2. Split the array into two halves
3. Sort each half recursively (i.e., using mergesort)
4. Merge the sorted halves to produce one sorted result:
 1. Consider the two halves to be queues.
 2. Repeatedly compare the fronts of the queues. Whichever is smaller (or, if one is empty, whichever is left), dequeue it and insert it into the result.

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MergeSort Performance Analysis

1. If the array has 0 or 1 elements, it's sorted. Else... $T(1) = 1$
2. Split the array into two halves
3. Sort each half recursively (i.e., using mergesort) $2 * T(n/2)$
4. Merge the sorted halves to produce one sorted result: n
 1. Consider the two halves to be queues.
 2. Repeatedly compare the fronts of the queues. Whichever is smaller (or, if one is empty, whichever is left), dequeue it and insert it into the result.

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MergeSort Performance Analysis

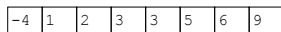
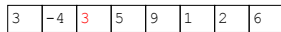
$$\begin{aligned}
 T(1) &= 1 \\
 T(n) &= 2T(n/2) + n \\
 &= 4T(n/4) + 2(n/2) + n \\
 &= 8T(n/8) + 4(n/4) + 2(n/2) + n \\
 &= 8T(n/8) + n + n + n = 8T(n/8) + 3n \\
 &= 2^i T(n/2^i) + in.
 \end{aligned}$$

Let $i = \lg n$

$$T(n) = nT(1) + n \lg n = n + n \lg n \in \Theta(n \lg n)$$

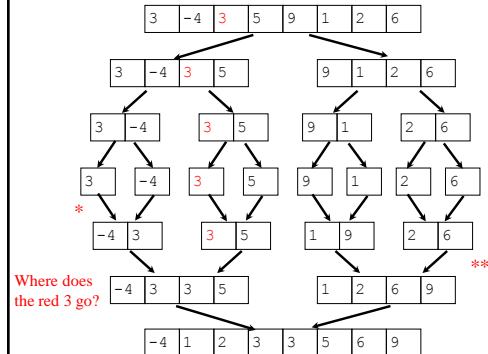
We ignored floors/ceilings. To prove performance formally, we'd use this as a guess and prove it with floors/ceilings by induction.¹²

Try it on this array!



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Try it on this array!



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Mergesort (by Jon Bentley):

```
void msort(int x[], int lo, int hi, int tmp[]) {
    if (lo >= hi) return;
    int mid = (lo+hi)/2;
    msort(x, lo, mid, tmp);
    msort(x, mid+1, hi, tmp);
    merge(x, lo, mid, hi, tmp);
}

void mergesort(int x[], int n) {
    int *tmp = new int[n];
    msort(x, 0, n-1, tmp);
    delete[] tmp;
}
```

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Merge (by Jon Bentley):

```
void merge(int x[], int lo, int mid, int hi,
           int tmp[])
{
    int a = lo, b = mid+1;
    for( int k = lo; k <= hi; k++ )
    {
        if( a <= mid && (b > hi || x[a] < x[b]) )
            tmp[k] = x[a++];
        else tmp[k] = x[b++];
    }
    for( int k = lo; k <= hi; k++ )
        x[k] = tmp[k];
}
```

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Elegant in one sense... but not how I'd write it

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QuickSort

In practice, one of the fastest sorting algorithms is QuickSort, developed in 1961 by C.A.R. Hoare.

Comparison-based: examines elements by comparing them to other elements

Divide-and-conquer: divides into “halves” (that may be very unequal) and recursively sorts

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QuickSort algorithm

- Pick a pivot
- Reorder the list such that all elements $<$ pivot are on the left, while all elements \geq pivot are on the right
- Recursively sort each side

Are we missing a base case?

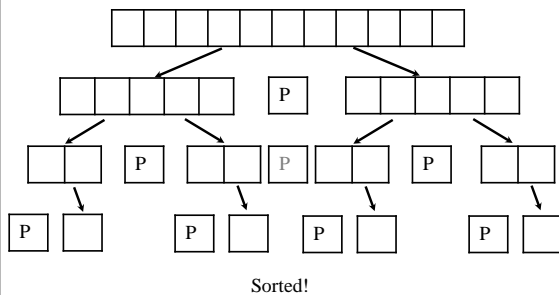
Partitioning

- The act of splitting up an array according to the pivot is called partitioning
- Consider the following:

$\underbrace{-4 \quad 1 \quad -3 \quad 2}_{\text{left partition}} \quad \underbrace{3}_{\text{pivot}} \quad \underbrace{5 \quad 4 \quad 7}_{\text{right partition}}$

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QuickSort Visually



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QuickSort (by Jon Bentley):

```

void qsort(int x[], int lo, int hi)
{
    int i, p;
    if (lo >= hi) return;
    p = lo;
    for (i = lo + 1; i <= hi; i++)
        if (x[i] < x[lo]) swap(x[++p], x[i]);
    swap(x[lo], x[p]);
    qsort(x, lo, p - 1);
    qsort(x, p + 1, hi);
}

void quicksort(int x[], int n) {
    qsort(x, 0, n - 1);
}
    
```

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Elegant in one sense... but not how I'd write it

QuickSort Example (using intuitive algorithm, not Bentley's)
(Pick first element as pivot, "scoot" elements to left/right.)

2 -4 6 1 5 -3 3 7

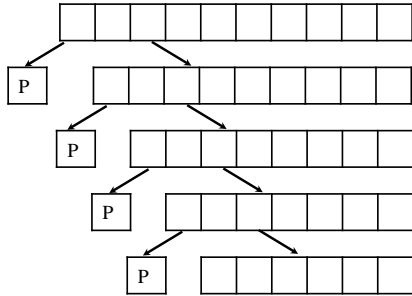
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QuickSort: Complexity

- Recall that Quicksort is comparison based
 - Thus, the operations are comparisons
- In our partitioning task, we compared each element to the pivot
 - Thus, the total number of comparisons is N
 - As with MergeSort, if one of the partitions is about half (or *any* constant fraction of) the size of the array, complexity is $\Theta(n \lg n)$.
- In the worst case, however, we end up with a partition with a 1 and $n-1$ split

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QuickSort Visually: Worst case



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QuickSort: Worst Case

- In the overall worst-case, this happens at every step...
 - Thus we have N comparisons in the first step
 - $N-1$ comparisons in the second step
 - $N-2$ comparisons in the third step
 - ...
- $$n + (n-1) + \dots + 2 + 1 = \frac{n(n+1)}{2} = \frac{n^2}{2} + \frac{n}{2}$$
- ...or approximately n^2

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QuickSort: Average Case (Intuition)

- Clearly pivot choice is important
 - It has a direct impact on the performance of the sort
 - Hence, QuickSort is fragile, or at least “attackable”
- So how do we pick a good pivot?

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QuickSort: Average Case (Intuition)

- Let's assume that pivot choice is random
 - Half the time the pivot will be from the centre half of the array
- Thus at worst the split will be $n/4$ and $3n/4$

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QuickSort: Average Case (Intuition)

- We can apply this to the notion of a good split
 - Every “good” split: 2 partitions of size $n/4$ and $3n/4$
 - Or divides N by $4/3$
 - Hence, we make up to $\log_{4/3}(N)$ splits
- Expected # of partitions is at most $2 * \log_{4/3}(N)$
 - $O(\lg N)$
- Given N comparisons at each partitioning step, we have $\Theta(N \lg N)$

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Quicksort Complexity: How does it compare?

N	Insertion Sort	Quicksort
10,000	4.1777 sec	0.05 sec
20,000	20.52 sec	0.11 sec
300,000	4666 sec (1.25 hrs)	2.15 sec

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How Do Quick, Merge, Heap, Insertion, and Selection Sort Compare?

Complexity

- Best case: Insert < Quick, Merge, Heap < Select
- Average case: Quick, Merge, Heap < Insert, Select
- Worst case: Merge, Heap < Quick, Insert, Select
- Usually on “real” data: Quick < Merge < Heap < I/S *(not asymptotic)*
- On very short lists: quadratic sorts may have an advantage (so, some quick/merge implementations “bottom out” to these as base cases)

Some details depend on implementation!
(E.g., an initial check whether the last elt of the left sublist is less than first of the right can make merge's best case ³²linear.)

How Do Quick, Merge, Heap, Insertion, and Selection Sort Compare?

Stability

- Easily Made Stable: Insert, Select, Merge (prefer the “left” of the two sorted sublists on ties)
- Unstable: Heap
- Challenging to Make Stable: Quick
- Memory use:
 - Insert, Select, Heap < Quick < Merge

How much stack space does recursive QuickSort use?
In the worst case? Could we make it better?

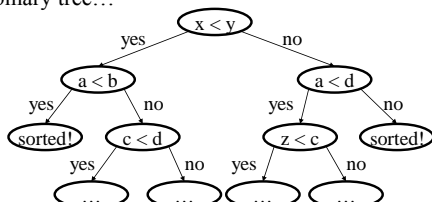
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Complexity of Sorting Using Comparisons as a Problem

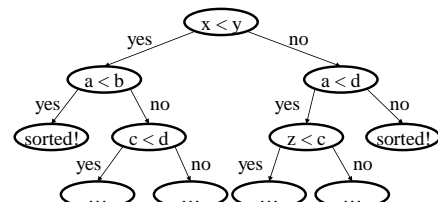
Each comparison is a “choice point” in the algorithm. You can do one thing if the comparison is true and another if false. So, the whole algorithm is like a binary tree...



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Complexity of Sorting Using Comparisons as a Problem

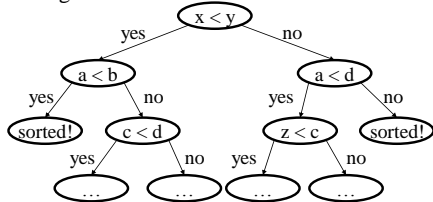
The algorithm spits out a (possibly different) sorted list at each leaf. What's the maximum number of leaves?



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Complexity of Sorting Using Comparisons as a Problem

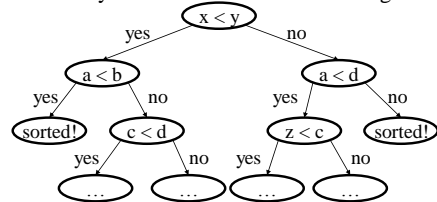
There are $n!$ possible permutations of a sorted list (i.e., input orders for a given set of input elements). How deep must the tree be to distinguish those input orderings?



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Complexity of Sorting Using Comparisons as a Problem

If the tree is *not* at least $\lg(n!)$ deep, then there's some pair of orderings I could feed the algorithm which the algorithm does not distinguish. So, it must not successfully sort one of those two orderings.



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Complexity of Sorting Using Comparisons as a Problem

QED: The complexity of sorting using comparisons is $\Omega(n \lg n)$ in the worst case, *regardless of algorithm!*

In general, we can *lower-bound* but not *upper-bound* the complexity of problems.

(Why not? Because I can give as crappy an algorithm as I please to solve any problem.)

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To Do

- Read: Epp Section 9.5 and KW Section 10.1, 10.4, and 10.7-10.10

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