

Base Julios GOD

Contents

1 Data structures	2	3.2 Modular inverse	15
1.1 Segment tree	2	3.3 Linear Sieve	15
1.2 Segment tree - Range update, point query	2	3.4 Factorials	16
1.3 Segment tree - Lazy propagation	2	3.5 Prime factorization	16
1.4 Segment tree - Persistence	3	3.6 Divisors	16
1.5 Fenwick tree	3	3.7 Identities	16
1.6 DSU	3	4 Strings	16
1.7 SQRT decomposition	4	4.1 Rolling Hash	16
1.8 Trie	4	4.2 LCP using hashing + bs	17
1.9 Trie XOR	5	5 Geometry	17
1.10 Map custom hash	5	5.1 Convex Hull	17
1.11 Ordered set	5	6 Techniques	18
1.12 Merge Sort Tree	5	6.1 MO's algorithm	18
1.13 Wavelet Tree	6	6.2 Parallel binary search	18
1.14 Monotonic stack	6	6.3 Split objects into light and heavy	19
1.15 Matrix operations	7	6.4 Meet in the middle	19
1.16 Heavy Light Decomposition	7	6.5 Dijkstra on ST	20
1.17 Convex Hull Trick	7	6.6 Venice set	21
1.18 Dynamic Convex Hull Trick	8	7 Basic techniques	21
2 Graphs	8	7.1 Difference array	21
2.1 Euler tour	8	7.2 Prefix Sum 2D	21
2.2 Find bridges	8	7.3 Random number generator	21
2.3 Dijkstra	9	7.4 Coordinate compression	21
2.4 Binary Lifting LCA	9	7.5 Digit DP	22
2.5 Centroid decomposition	10	7.6 Intersection $[L1, R1]$ and $[L2, R2]$	22
2.6 Edmonds karp	10		
2.7 Dinics	11		
2.8 Bipartite check	12		
2.9 Has cycle?	12		
2.10 Kuhn - matching	12		
2.11 Hopcroft Karp - matching	12		
2.12 Min cost - max flow	13		
2.13 2sat	14		
3 Math	15		
3.1 Bincpow	15		

1 Data structures

1.1 Segment tree

```

1 #define M ((l + r) >> 1)
2 #define op(x, y) (x + y)
3 int st[4*N], values[N];
4 void build(int l, int r, int i) {
5     if(l == r) {
6         st[i] = values[l];
7         return;
8     }
9     build(l, M, 2*i+1);
10    build(M+1, r, 2*i+2);
11    st[i] = op(st[2*i+1], st[2*i+2]); // #!
12 }
13 // Point update - range query
14 void update(int l, int r, int idx, int x, int i) {
15     if(l == r) {
16         st[i] += x;
17         return;
18     }
19     if(idx <= M) update(l, M, idx, x, 2*i+1);
20     else update(M+1, r, idx, x, 2*i+2);
21     st[i] = op(st[2*i+1], st[2*i+2]);
22 }
23 int query(int l, int r, int a, int b, int i) {
24     if(a > r || b < l) return 0; // change for min/max
25     if(a <= l && r <= b) return st[i];
26     return op(query(l, M, a, b, 2*i+1), query(M+1, r, a, b, 2*i+2));
27 }
28 // l = 0, r = n-1, i = 0

```

1.2 Segment tree - Range update, point query

```

1 // Range update - point query
2 // same as classic segment tree, but comment this line #!
3 void update(int l, int r, int a, int b, int x, int i) {
4     if (a > r || b < l) return;
5     if (a <= l && r <= b) {
6         st[i] += x;
7         return;
8     }

```

```

9     update(l, M, a, b, x, 2*i+1);
10    update(M+1, r, a, b, x, 2*i+2);
11 }
12 int query(int l, int r, int idx, int i) {
13     if(idx > r || idx < l) return 0; // change for min/max
14     if(idx <= l && r <= idx) return st[i];
15     return op(op(query(l, M, idx, 2*i+1), query(M+1, r, idx, 2*i+2)), st
16               [i]);

```

1.3 Segment tree - Lazy propagation

```

1 #define M ((l + r) >> 1)
2 #define op(x, y) (x + y)
3 ll st[4*N], lazy[4*N], arr[N];
4 void build(int l, int r, int i) {
5     lazy[i] = 0;
6     if (l == r) {st[i] = arr[l]; return;}
7     build(l, M, 2*i+1);
8     build(M+1, r, 2*i+2);
9     st[i] = op(st[2*i+1], st[2*i+2]);
10 }
11 void push(int l, int r, int i) {
12     if (!lazy[i]) return;
13     st[i] += (r-l+1) * lazy[i]; // change for min/max
14     if (l != r) {
15         lazy[2*i+1] += lazy[i];
16         lazy[2*i+2] += lazy[i];
17     }
18     lazy[i] = 0; // change for multiplication
19 }
20 void update(int l, int r, int a, int b, ll x, int i) {
21     push(l, r, i);
22     if (a > r || b < l) return;
23     if (a <= l && r <= b) {
24         lazy[i] += x;
25         push(l, r, i);
26         return;
27     }
28     update(l, M, a, b, x, 2*i+1);
29     update(M+1, r, a, b, x, 2*i+2);
30     st[i] = op(st[2*i+1], st[2*i+2]);
31 }

```

```

32 ll query(int l, int r, int a, int b, int i) {
33     if (a > r || b < l) return 0;    // change for min/max
34     push(l, r, i);
35     if (a <= l && r <= b) return st[i];
36     return op(query(l, M, a, b, 2*i+1), query(M+1, r, a, b, 2*i+2));
37 } // i=0, l=0, r=n-1, x=value, a,b=range query

```

1.4 Segment tree - Persistence

```

1 #define M ((l + r) >> 1)
2 struct Node{
3     Node *left, *right;
4     ll val;
5     Node(ll x) : left(NULL), right(NULL), val(x) {}    // Add value
6     Node(Node *l, Node *r) : left(l), right(r), val(0) {}    // Update
7         values
8         if(l) val += l->val;
9         if(r) val += r->val;
10    }
11    Node(Node *root) : left(root->left), right(root->right), val(root->
12        val) {}    // Make copy
13};
14Node *build(int l, int r, vector<int> &values) {
15    if(l == r) return new Node(values[l]);
16    return new Node(build(l, M, values), build(M+1, r, values));
17}
18Node *update(Node *node, int l, int r, int idx, ll k) {
19    if(l == r) return new Node(k);
20    if(idx <= M) return new Node(update(node->left, l, M, idx, k), node
21        ->right);
22    return new Node(node->left, update(node->right, M+1, r, idx, k));
23}
24ll query(Node *node, int l, int r, int a, int b) {
25    if(a > r || b < l) return 0;
26    if(a <= l && r <= b) return node->val;
27    return query(node->left, l, M, a, b) + query(node->right, M+1, r, a,
28        b);
29}
30Node *roots[N];
31// 0 based indexing
32// roots[copy++] = build(0, n-1);
33// roots[copy++] = new Node(roots[--idx]);
34// roots[--copy] = update(roots[--copy], 0, n-1, --idx, x);

```

```

31 // query(roots[--copy], 0, n-1, --a, --b)

```

1.5 Fenwick tree

```

1 struct FT{
2     int n;
3     vector<int> ft;
4     FT(int _n) : n(_n), ft(_n+1) {}
5     void add(int idx, int k) {
6         for(; idx<=n; idx+=idx&-idx)
7             ft[idx] += k;
8     }
9     int query(int idx) {
10        int sum = 0;
11        for(; idx>0; idx-=idx&-idx)
12            sum += ft[idx];
13        return sum;
14    }
15    int query(int l, int r) {
16        return query(r) - query(l-1);
17    }
18    int lower_bound(int k) { // LOG = log2(n) + 1
19        int sum = 0, idx = 0;
20        for(int i=LOG-1; i>=0; i--) {
21            if(idx + (1 << i) <= n && sum + ft[idx + (1 << i)] < k) {
22                sum += ft[idx + (1 << i)];
23                idx += 1 << i;
24            }
25        }
26        return idx + 1;
27    }
28}; // 1-based indexing

```

1.6 DSU

```

1 struct DSU{
2     int n;
3     vector<int> parent, rank;
4     DSU(int _n) : n(_n), parent(_n), rank(_n) {
5         for(int i=0; i<n; i++) {
6             parent[i] = i;
7             rank[i] = 0;
8         }
9     }

```

```

10 int find_set(int v) {
11     if (v == parent[v]) return v;
12     return parent[v] = find_set(parent[v]);
13 }
14 void union_sets(int a, int b) {
15     a = find_set(a), b = find_set(b);
16     if (a != b) {
17         if (rank[a] < rank[b]) swap(a, b);
18         parent[b] = a;
19         if (rank[a] == rank[b]) rank[a]++;
20     }
21 }
22 int components() {
23     int cnt = 0;
24     for(int i=0; i<n; i++) {
25         if(find_set(i) == i) cnt++;
26     }
27     return cnt;
28 }
29 };

```

1.7 SQRT decomposition

```

1 struct SQ{
2     int n, b;
3     vector<int> values, blocks;
4     SQ(int _n) : n(_n), values(_n) {
5         b = (int)sqrt(n) + 1;
6         blocks = vector<int> (b);
7     }
8     // Basic update / query
9     void operation(int l, int r, int k) {
10        int bl = l/b, br = r/b;
11        // operation lies in same block
12        if(bl == br) {
13            for(int i=l; i<=r; i++) {
14                blocks[bl] -= values[i];
15                values[i] += k;
16                blocks[bl] += values[i];
17            }
18        }
19        // operation on different blocks
20        else {

```

```

21            for(int i=l; i<(bl+1)*b; i++) {
22                blocks[bl] -= values[i];
23                values[i] += k;
24                blocks[bl] += values[i];
25            }
26            for(int i=br*b; i<=r; i++) {
27                blocks[br] -= values[i];
28                values[i] += k;
29                blocks[br] += values[i];
30            }
31            for(int i=(bl+1)*b; i<br; i++) {
32                blocks[i] += k * b;
33            }
34        }
35    }
36 };

```

1.8 Trie

```

1 struct Node{
2     vector<Node*> ocu;
3     bool flag;
4     Node() : ocu(26), flag(false) {}
5 };
6 struct Trie{
7     Node *root;
8     Trie() : root(new Node()) {}
9     void insert(string word) {
10        Node *curr = root;
11        for(auto &it : word) {
12            if(!curr -> ocu[it - 'a'])
13                curr -> ocu[it - 'a'] = new Node();
14            curr = curr -> ocu[it - 'a'];
15        }
16        curr -> flag = true;
17    }
18    bool search(string word) {
19        Node *curr = root;
20        for(auto &it : word) {
21            if(!curr -> ocu[it - 'a']) return false;
22            curr = curr -> ocu[it - 'a'];
23        }
24        return curr -> flag;

```

```

25     }
26 };

```

1.9 Trie XOR

```

1 struct Node{
2     vector<Node*> ocu;
3     Node() : ocu(2) {}
4 };
5 struct Trie {
6     Node *root;
7     Trie() : root(new Node()) { insert(0); }
8
9     void insert(long long x) {
10         Node *curr = root;
11         for(int mask=63; mask>=0; mask--) {
12             bool currBit = (x >> mask) & 1;
13             if(!curr -> ocu[currBit])
14                 curr -> ocu[currBit] = new Node();
15             curr = curr -> ocu[currBit];
16         }
17     }
18     long long query(long long prefix) {
19         Node *curr = root;
20         long long res = 0;
21         for(int mask=63; mask>=0; mask--) {
22             bool currBit = (prefix >> mask) & 1;
23             if(curr -> ocu[currBit ^ 1]) {
24                 res |= (1LL << mask);
25                 curr = curr -> ocu[currBit ^ 1];
26             }
27             else curr = curr -> ocu[currBit];
28         }
29         return res;
30     }
31 };

```

1.10 Map custom hash

```

1 #include <ext/pb_ds/assoc_container.hpp>
2 using namespace __gnu_pbds;
3
4 struct custom_hash {
5     static uint64_t splitmix64(uint64_t x) {

```

```

6         x += 0x9e3779b97f4a7c15;
7         x = (x ^ (x >> 30)) * 0xbf58476d1ce4e5b9;
8         x = (x ^ (x >> 27)) * 0x94d049bb133111eb;
9         return x ^ (x >> 31);
10     }
11     size_t operator()(uint64_t x) const {
12         static const uint64_t FIXED_RANDOM = chrono::steady_clock::now()
13             .time_since_epoch().count();
14         return splitmix64(x + FIXED_RANDOM);
15     }
16 };
17 gp_hash_table<int, int, custom_hash> freq;

```

1.11 Ordered set

```

1 #include<ext/pb_ds/assoc_container.hpp>
2 #include<ext/pb_ds/tree_policy.hpp>
3 using namespace __gnu_pbds;
4 typedef tree<int,null_type,less<int>,rb_tree_tag,
5     tree_order_statistics_node_update> ordered_set;
6 // find_by_order(i) -> iterator to ith element
7 // order_of_key(k) -> position (int) of lower_bound of k

```

1.12 Merge Sort Tree

```

1 #define M ((l + r) >> 1)
2 struct ST{
3     int n;
4     vector<vector<int>>> st;
5     ST(int _n) : n(_n), st(4*_n) {}
6
7     void build(int l, int r, int i, vector<int> &values) {
8         if(l == r) {
9             st[i].pb(values[l]);
10            return;
11        }
12        build(l, M, 2*i+1, values);
13        build(M+1, r, 2*i+2, values);
14        st[i].resize(st[2*i+1].size() + st[2*i+2].size());
15        merge(st[2*i+1].begin(), st[2*i+1].end(), st[2*i+2].begin(), st
16            [2*i+2].end(), st[i].begin());
17    }
18    int query(int l, int r, int a, int b, int k, int i) {
19        if(a > r || b < l) return 0;

```

```

19     if(a <= l && r <= b) return st[i].end() - upper_bound(st[i].
        begin(), st[i].end(), k);
20     return query(l, M, a, b, k, 2*i+1) + query(M+1, r, a, b, k, 2*i
        +2);
21 }
22 };

```

1.13 Wavelet Tree

```

1 // indexed in 1
2 // from pointer to first element and to to end
3 // x and y The minimum element and y the max element
4 // If you need only one function or more erase the others
5 // If you need to construct other function you only required to
6 // understand the limit, this
7 // are the same
8 struct wavelet_tree{
9     int lo, hi;
10    wavelet_tree *l, *r;
11    vector<int> b;
12    wavelet_tree(int *from, int *to, int x, int y){
13        lo = x, hi = y;
14        if(lo == hi or from >= to) return;
15        int mid = (lo+hi)/2;
16        auto f = [mid](int x){ return x <= mid;};
17        b.reserve(to-from+1);
18        b.pb(0);
19        for(auto it = from; it != to; it++)
20            b.push_back(b.back() + f(*it));
21        auto pivot = stable_partition(from, to, f);
22        l = new wavelet_tree(from, pivot, lo, mid);
23        r = new wavelet_tree(pivot, to, mid+1, hi);
24    }
25    //kth smallest element in [l, r]
26    int kth(int l, int r, int k){
27        if(l > r) return 0;
28        if(lo == hi) return lo;
29        int inLeft = b[r] - b[l-1];
30        int lb = b[l-1];
31        int rb = b[r];
32        if(k <= inLeft) return this->l->kth(lb+1, rb, k);
33        return this->r->kth(l-lb, r-rb, k-inLeft);
34    }
35 }

```

```

34 //count of nos in [l, r] Less than or equal to k
35 int LTE(int l, int r, int k) {
36     if(l > r or k < lo) return 0;
37     if(hi <= k) return r - l + 1;
38     int lb = b[l-1], rb = b[r];
39     return this->l->LTE(lb+1, rb, k) + this->r->LTE(l-lb, r-rb, k);
40 }
41 //count of nos in [l, r] equal to k
42 int count(int l, int r, int k) {
43     if(l > r or k < lo or k > hi) return 0;
44     if(lo == hi) return r - l + 1;
45     int lb = b[l-1], rb = b[r], mid = (lo+hi)/2;
46     if(k <= mid) return this->l->count(lb+1, rb, k);
47     return this->r->count(l-lb, r-rb, k);
48 }
49 };

```

1.14 Monotonic stack

```

1 int main() {
2     ios::sync_with_stdio(0); cin.tie(0);
3     int n; cin >> n;
4     vector<int> v(n), l(n), r(n);
5     for(auto &it : v) cin >> it;
6
7     stack<pair<int, int>> st;
8     for(int i=n-1; i>=0; i--) {
9         while(!st.empty() && v[i] < st.top().first) {
10             l[st.top().second] = i;
11             st.pop();
12         }
13         st.push({v[i], i});
14     }
15
16     while(!st.empty()) l[st.top().second] = -1, st.pop();
17
18     rep(i,0,n) {
19         while(!st.empty() && v[i] <= st.top().first) {
20             r[st.top().second] = i;
21             st.pop();
22         }
23         st.push({v[i], i});
24     }
25 }

```

```

25
26 while(!st.empty()) r[st.top().second] = n, st.pop();
27
28 vector<int> res(n);
29 rep(i,0,n) {
30     int curr = r[i] - l[i] - 1;
31     res[curr-1] = max(res[curr-1], v[i]);
32 }
33 for(int i=n-2; i>=0; i--) {
34     res[i] = max(res[i], res[i+1]);
35 }
36
37 for(auto &it : res) cout << it << " ";
38 cout << endl;
39
40 return 0;
41 }

```

1.15 Matrix operations

```

1 struct Matrix {
2     ll a[N][N];
3     Matrix() {memset(a,0,sizeof(a));}
4     Matrix operator *(Matrix other) { // Product of a matrix
5         Matrix product=Matrix();
6         rep(i,0,N) rep(j,0,N) rep(k,0,N) {
7             product.a[i][k] += a[i][j] * other.a[j][k];
8             product.a[i][k] %= MOD;
9         }
10        return product;
11    }
12 };
13 Matrix expo_power(Matrix a, ll n) { // Matrix exponentiation
14     Matrix res=Matrix();
15     rep(i,0,N) res.a[i][i]=1; // Matriz identidad
16     while(n){ // binpow
17         if(n & 1) res = res * a;
18         n >>= 1;
19         a = a * a;
20     }
21     return res;
22 } // Ej. Matrix M=Matrix(); M.a[0][0]=1; M=M*M; Matrix res=
    expo_power(M,k);

```

1.16 Heavy Light Decomposition

```

1 int sz[N], in[N], out[N], timer, head[N], parent[N];
2 void dfs_sz(int u = 0, int p = -1) {
3     sz[u] = 1;
4     parent[u] = p;
5     for(auto &v : adj[u]) {
6         if(v == p) continue;
7         dfs_sz(v, u);
8         sz[u] += sz[v];
9         if(adj[u][0] == p || sz[v] > sz[adj[u][0]]) {
10             swap(v, adj[u][0]);
11         }
12     }
13 }
14 void dfs_hld(int u = 0, int p = -1) {
15     in[u] = timer++;
16     for(auto &v : adj[u]) {
17         if(v == p) continue;
18         head[v] = (adj[u][0] == v ? head[u] : v);
19         dfs_hld(v, u);
20     }
21     out[u] = timer;
22 }
23 ll query_path(int u, int v) {
24     ll res = 0;
25     while(head[u] != head[v]) {
26         if(in[u] < in[v]) swap(u, v);
27         res += query(0, timer-1, in[head[u]], in[u], 0);
28         u = parent[head[u]];
29     }
30     if(in[u] > in[v]) swap(u, v);
31     res += query(0, timer-1, in[u]+1, in[v], 0);
32     // in[u] (node) / in[u]+1 (edge)
33     return res;
34 }

```

1.17 Convex Hull Trick

```

1 typedef ll tc;
2 struct Line{tc m,h;};
3 struct CHT { // for minimum (for maximum just change the sign of lines)
4     vector<Line> c;

```

```

5  int pos=0;
6  tc in(Line a, Line b){
7      tc x=b.h-a.h,y=a.m-b.m;
8      return x/y+(x%y?!((x>0)^(y>0)):0); // ==ceil(x/y)
9  }
10 void add(tc m, tc h){ // m's should be non increasing
11     Line l=(Line){m,h};
12     if(c.size()&&m==c.back().m){
13         l.h=min(h,c.back().h);c.pop_back();if(pos)pos--;
14     }
15     while(c.size()>1&&in(c.back(),l)<=in(c[c.size()-2],c.back())){
16         c.pop_back();if(pos)pos--;
17     }
18     c.pb(l);
19 }
20 inline bool fbin(tc x, int m){return in(c[m],c[m+1])>x;}
21 tc query(tc x){
22     // O(log n) query:
23     int s=0,e=c.size();
24     while(e-s>1){int m=(s+e)/2;
25         if(fbin(x,m-1))e=m;
26         else s=m;
27     }
28     return c[s].m*x+c[s].h;
29     // O(1) query (for ordered x's):
30     while(pos>0&&fbin(x,pos-1))pos--;
31     while(pos<c.size()-1&&!fbin(x,pos))pos++;
32     return c[pos].m*x+c[pos].h;
33 }
34 }; // y=mx+b -> cht.add(m, b) | cht.query(x)

```

1.18 Dynamic Convex Hull Trick

```

1  using ll = long long;
2  struct Line {
3      mutable ll m, b, p;
4      bool operator<(const Line& o) const { return m < o.m; }
5      bool operator<(ll x) const { return p < x; }
6  };
7  struct LineContainer : multiset<Line, less<>> {
8      // (for doubles, use inf = 1/.0, div(a,b) = a/b)
9      static const ll inf = LLONG_MAX;
10     ll div(ll a, ll b) { // floored division

```

```

11     return a / b - ((a ^ b) < 0 && a % b); }
12 bool isect(iterator x, iterator y) {
13     if (y == end()) return x->p = inf, 0;
14     if (x->m == y->m) x->p = x->b > y->b ? inf : -inf;
15     else x->p = div(y->b - x->b, x->m - y->m);
16     return x->p >= y->p;
17 }
18 void add(ll m, ll b) {
19     auto z = insert({m, b, 0}), y = z++, x = y;
20     while (isect(y, z)) z = erase(z);
21     if (x != begin() && isect(--x, y)) isect(x, y = erase(y));
22     while ((y = x) != begin() && (--x)->p >= y->p)
23         isect(x, erase(y));
24 }
25 ll query(ll x) {
26     assert(!empty());
27     auto l = *lower_bound(x);
28     return l.m * x + l.b;
29 }
30 }; // y=mx+b -> cht.add(m, b) | cht.query(x)

```

2 Graphs

2.1 Euler tour

```

1  vector<int> in(n+1), out(n+1), euler(n+1);
2  int timer = 0;
3  auto dfs = [&](auto self, int u, int p = -1) -> void {
4      in[u] = ++timer;
5      euler[timer] = u;
6      for(auto &v : adj[u]) {
7          if(v == p) continue;
8          self(self, v, u);
9      }
10     out[u] = timer;
11 };
12 dfs(dfs, 0);
13 queries[i] = {in[u], out[u], k, i};
14 int x = values[euler[idx]];

```

2.2 Find bridges

```

1  int in[N], low[N], timer;

```



```

2  /* Articulation bridges */
3  void dfs(int u, int p = -1) {
4      in[u] = low[u] = ++timer;
5      for(auto &v : adj[u]) {
6          if(v == p) continue;
7          if(!in[v]) {
8              dfs(v, u);
9              low[u] = min(low[u], low[v]);
10             if(low[v] > in[u]) IS_BRIDGE(U, V);
11         }
12         else low[u] = min(low[u], in[v]);
13     }
14 }
15
16 /* Bridge tree */
17 // Use dfs to find bridges, but change
18 if(low[v] <= in[u]) dsu.union_sets(u, v);
19
20 // Iterate over the edges
21 for(auto [u, v] : edges) {
22     u = dsu.find_set(u);
23     v = dsu.find_set(v);
24     if(u != v) {
25         bridgeTree[u].pb(v);
26         bridgeTree[v].pb(u);
27     }
28 }
29
30 /* Articulation points */
31 // Use same code as finding bridges
32 if(low[v] >= in[u]) IS_ARTICULATION_POINT(U, V);

```

2.3 Dijkstra

```

1  void dijkstra(int start, int n) {
2      priority_queue<pair<ll, int>, vector<pair<ll,int>>, greater<pair<ll,
3          int>>> pq;
4      for(int i=0; i<n; i++) {
5          dist[i] = 1e14;
6      }
7
8      dist[start] = 0;
9      pq.push({0, start});

```

```

9
10     while(!pq.empty()) {
11         auto [d, u] = pq.top();
12         pq.pop();
13
14         if(d > dist[u]) continue;
15
16         for(auto &[v, w] : adj[u]) {
17             if(dist[u] + w < dist[v]) {
18                 dist[v] = dist[u] + w;
19                 pq.push({dist[v], v});
20             }
21         }
22     }
23 }

```

2.4 Binary Lifting LCA

```

1  int depth[N], up[N][LOG];
2  void dfs1(int u, int p) {
3      up[u][0] = p;
4      rep(i,1,LOG) {
5          if(up[u][i-1] != -1)
6              up[u][i] = up[up[u][i-1]][i-1];
7          else
8              up[u][i] = -1;
9      }
10     for(auto &v : adj[u]) {
11         if(v == p) continue;
12         depth[v] = depth[u] + 1;
13         dfs1(v, u);
14     }
15 }
16 int lift(int u, int k) {
17     for(int i=LOG-1; i>=0; i--) {
18         if(k & (1 << i)) {
19             u = up[u][i];
20             if(u == -1) return 0;
21         }
22     }
23     return u;
24 }
25 int lca(int u, int v) {

```

```

26     if(depth[u] < depth[v]) swap(u, v);
27     u = lift(u, depth[u] - depth[v]);
28     if(u == v) return u;
29
30     for(int i=LOG-1; i>=0; i--) {
31         if(up[u][i] != -1 && up[u][i] != up[v][i]) {
32             u = up[u][i];
33             v = up[v][i];
34         }
35     }
36     return up[u][0] == -1 ? 0 : up[u][0];
37 }

```

2.5 Centroid decomposition

```

1 void dfs(int u, int p) {
2     sz[u] = 1;
3     for(auto &v : adj[u]) {
4         if(v == p || centroid[v]) continue;
5         dfs(v, u);
6         sz[u] += sz[v];
7     }
8 }
9 int getCentroid(int u, int p, int n) {
10     for(auto &v : adj[u]) {
11         if(v == p || centroid[v]) continue;
12         if(2 * sz[v] > n) return getCentroid(v, u, n);
13     }
14     return u;
15 }
16 void getCount(int u, int p, int depth) {
17     if(depth > k) return;
18     res += 0ll + cnt[k - depth];
19     for(auto &v : adj[u]) {
20         if(v == p || centroid[v]) continue;
21         getCount(v, u, depth+1);
22     }
23 }
24 void getPaths(int u, int p, int depth, int x) {
25     if(depth > k) return;
26     cnt[depth] += x;
27     for(auto &v : adj[u]) {
28         if(v == p || centroid[v]) continue;

```

```

29         getPaths(v, u, depth+1, x);
30     }
31 }
32 void decompose(int u, int p) {
33     dfs(u, p);
34     int c = getCentroid(u, p, sz[u]);
35     centroid[c] = 1;
36     cnt[0] = 1;
37
38     for(auto &v : adj[c]) {
39         if(centroid[v]) continue;
40         getCount(v, c, 1);
41         getPaths(v, c, 1, 1);
42     }
43
44     getPaths(c, p, 0, -1);
45
46     for(auto &v : adj[c]) {
47         if(v == c || centroid[v]) continue;
48         decompose(v, c);
49     }
50 }

```

2.6 Edmonds karp

```

1 const int N = 1e3+5;
2 vector<int> adj[N];
3 int parent[N], cap[N][N];
4
5 void add_edge(int u, int v, int c) {
6     adj[u].pb(v);
7     adj[v].pb(u);
8     cap[u][v] += c;
9 }
10 int bfs(int s, int t) {
11     memset(parent, -1, sizeof(parent));
12     parent[s] = -2;
13     queue<pair<int, int>> q;
14     q.push({s, (int)1e9});
15
16     while(!q.empty()) {
17         auto [u, f] = q.front();
18         q.pop();

```

```

19         for(auto &v : adj[u]) {
20             if(parent[v] != -1 || !cap[u][v]) continue;
21
22             parent[v] = u;
23             int flow = min(cap[u][v], f);
24             if(v == t) return flow;
25
26             q.push({v, flow});
27         }
28     }
29     return 0;
30 }
31
32 int maxFlow(int s, int t) {
33     int mx = 0, flow;
34     while(flow = bfs(s, t)) {
35         mx += flow;
36         int curr = t;
37         while(curr != s) {
38             int prev = parent[curr];
39             cap[prev][curr] -= flow;
40             cap[curr][prev] += flow;
41             curr = prev;
42         }
43     }
44     return mx;
45 }

```

2.7 Dinics

```

1 struct Dinic {
2     int nodes, src, dst;
3     vector<int> dist, q, work;
4     struct edge{int to, rev; ll f, cap;};
5     vector<vector<edge>> g;
6     Dinic(int x) : nodes(x), g(x), dist(x), q(x), work(x){}
7     void add_edge(int s, int t, ll cap) {
8         g[s].pb((edge) {t, SZ(g[t]), 0, cap});
9         g[t].pb((edge) {s, SZ(g[s])-1, 0, 0});
10    }
11    bool dinic_bfs() {
12        fill(all(dist), -1); dist[src]=0;
13        int qt=0; q[qt++]=src;

```

```

14        for(int qh=0; qh<qt; qh++) {
15            int u=q[qh];
16            rep(i, 0, SZ(g[u])) {
17                edge &e = g[u][i]; int v=g[u][i].to;
18                if(dist[v]<0&&e.f<e.cap) dist[v]=dist[u]+1, q[qt++]=v;
19            }
20        }
21        return dist[dst]>=0;
22    }
23    ll dinic_dfs(int u, ll f) {
24        if(u==dst) return f;
25        for(int &i=work[u]; i<SZ(g[u]); i++) {
26            edge &e=g[u][i];
27            if(e.cap <= e.f) continue;
28            int v=e.to;
29            if(dist[v]==dist[u]+1) {
30                ll df=dinic_dfs(v, min(f, e.cap-e.f));
31                if(df > 0) {e.f+=df; g[v][e.rev].f-=df; return df;}
32            }
33        }
34        return 0;
35    }
36    ll max_flow(int _src, int _dst) {
37        src=_src, dst=_dst;
38        ll result=0;
39        while(dinic_bfs()) {
40            fill(all(work), 0);
41            while(ll delta=dinic_dfs(src, 1e12)) result+=delta;
42        }
43        return result;
44    }
45 };
46
47 int main() {io
48     int n,m,sl,el,s,t,u,v;
49     cin>>n>>sl>>el;
50     s=n+n, t=s+1;
51     Dinic nf(n+n+2);
52     rep(i,0,sl){
53         cin>>u; u--;
54         nf.add_edge(s,u,1);
55     }
56     rep(i,0,el){

```

```

57     cin>>u; u--;
58     nf.add_edge(u+n,t,1);
59 }
60 rep(i,0,n) nf.add_edge(i,i+n,1);
61 cin>>m;
62 rep(i,0,m){
63     int u,v;
64     cin>>u>>v;
65     u--,v--;
66     nf.add_edge(u+n,v,1);
67 }
68 cout<<nf.max_flow(s,t)<<endl;
69 return 0;
70 }

```

2.8 Bipartite check

```

1 int color[N];
2 bool f = 1;
3 // memset(color, -1, sizeof(color));
4 bool dfs(int u = 0, int c = 0) {
5     color[u] = c;
6     for(auto &v : adj[u]) {
7         if(color[v] == -1 && !dfs(v, 1-c)) return false;
8         else if(color[v] == c) return false;
9     }
10 }

```

2.9 Has cycle?

```

1 int color[N];
2 // directed graph
3 bool dfs(int u, int p = -1) {
4     color[u] = 1;
5     for(auto &v : adj[u]) {
6         if(!color[v]) if(!dfs(v, u)) return false;
7         if(color[v] == 1) return false;
8     }
9     color[u] = 2;
10    return true;
11 }
12
13 // undirected graph
14 bool dfs(int u, int p = -1) {

```

```

15     color[u] = 1;
16     parent[u] = p;
17     for(auto &v : adj[u]) {
18         if(v == p) continue;
19         if(!color[v]) {
20             if(dfs(v, u)) return true;
21         }
22         else {
23             t = u, s = v;
24             return true;
25         }
26     }
27     return false;
28 }

```

2.10 Kuhn - matching

```

1 vector<int> adj[N]; // [0,n)->[0,m)
2 int n, m, mat[M];
3 bool vis[N];
4 int match(int x){
5     if(vis[x]) return 0;
6     vis[x] = 1;
7     for(auto y : adj[x]) if(mat[y]<0 || match(mat[y])) {mat[y]=x; return 1;}
8     return 0;
9 }
10 vector<pair<int,int>> max_matching(){
11     vector<pair<int, int>> r;
12     memset(mat, -1, sizeof(mat));
13     for(int i=0; i<n; i++) memset(vis, false, sizeof(vis)), match(i);
14     for(int i=0; i<m; i++) if(mat[i] >= 0) r.pb({mat[i], i});
15     return r;
16 }

```

2.11 Hopcroft Karp - matching

```

1 vector<int> g[MAXN]; // [0,n)->[0,m)
2 int n,m;
3 int mt[MAXN],mt2[MAXN],ds[MAXN];
4 bool bfs(){
5     queue<int> q;
6     memset(ds,-1,sizeof(ds));
7     rep(i,0,n)if(mt2[i]<0)ds[i]=0,q.push(i);

```

```

8   bool r=false;
9   while(!q.empty()){
10      int x=q.front();q.pop();
11      for(int y:g[x]){
12         if(mt[y]>=0&&ds[mt[y]]<0)ds[mt[y]]=ds[x]+1,q.push(mt[y]);
13         else if(mt[y]<0)r=true;
14      }
15   }
16   return r;
17 }
18 bool dfs(int x){
19   for(int y:g[x])if(mt[y]<0||ds[mt[y]]==ds[x]+1&&dfs(mt[y])){
20     mt[y]=x;mt2[x]=y;
21     return true;
22   }
23   ds[x]=1<<30;
24   return false;
25 }
26 int mm(){
27   int r=0;
28   memset(mt,-1,sizeof(mt));memset(mt2,-1,sizeof(mt2));
29   while(bfs()){
30     rep(i,0,n)if(mt2[i]<0)r+=dfs(i);
31   }
32   return r;
33 }

```

2.12 Min cost - max flow

```

1  typedef ll tf;
2  typedef ll tc;
3  const tf INFFLOW=1e9;
4  const tc INFCOST=1e9;
5  struct MCF{
6     int n;
7     vector<tc> prio, pot; vector<tf> curflow; vector<int> prevedge,
8       prevnode;
9     priority_queue<pair<tc, int>, vector<pair<tc, int>>, greater<pair<tc,
10       int>>> q;
11     struct edge{int to, rev; tf f, cap; tc cost;};
12     vector<vector<edge>> g;
13     MCF(int n):n(n),prio(n),curflow(n),prevedge(n),prevnode(n),pot(n),g(n)
14       {}

```

```

12   void add_edge(int s, int t, tf cap, tc cost) {
13     g[s].pb((edge){t,SZ(g[t]),0,cap,cost});
14     g[t].pb((edge){s,SZ(g[s])-1,0,0,-cost});
15   }
16   pair<tf,tc> get_flow(int s, int t) {
17     tf flow=0; tc flowcost=0;
18     while(1){
19       q.push({0, s});
20       fill(ALL(prio),INFCOST);
21       prio[s]=0; curflow[s]=INFFLOW;
22       while(!q.empty()) {
23         auto cur=q.top();
24         tc d=cur.fst;
25         int u=cur.snd;
26         q.pop();
27         if(d!=prio[u]) continue;
28         for(int i=0; i<SZ(g[u]); ++i) {
29           edge &e=g[u][i];
30           int v=e.to;
31           if(e.cap<=e.f) continue;
32           tc nprio=prio[u]+e.cost+pot[u]-pot[v];
33           if(prio[v]>nprio) {
34             prio[v]=nprio;
35             q.push({nprio, v});
36             prevnode[v]=u; prevedge[v]=i;
37             curflow[v]=min(curflow[u], e.cap-e.f);
38           }
39         }
40       }
41       if(prio[t]==INFCOST) break;
42       rep(i,0,n) pot[i]+=prio[i];
43       tf df=min(curflow[t], INFFLOW-flow);
44       flow+=df;
45       for(int v=t; v!=s; v=prevnode[v]) {
46         edge &e=g[prevnode[v]][prevedge[v]];
47         e.f+=df; g[v][e.rev].f-=df;
48         flowcost+=df*e.cost;
49       }
50     }
51     return {flow,flowcost};
52   }
53 };

```

2.13 2sat

```

1 struct two_sat {
2     int n;
3     vector<vector<int>> g, gr;
4     vector<int> comp, topological_order, answer;
5     vector<bool> vis;
6
7     two_sat(int _n) {
8         n = _n;
9         g.assign(2 * n, vector<int>());
10        gr.assign(2 * n, vector<int>());
11        comp.resize(2 * n);
12        vis.resize(2 * n);
13        answer.resize(2 * n);
14    }
15
16    void add_edge(int u, int v) {
17        g[u].pb(v);
18        gr[v].pb(u);
19    }
20
21    void dfs(int u) {
22        vis[u] = true;
23        each(v, g[u]) if (!vis[v]) dfs(v);
24        topological_order.push_back(u);
25    }
26
27    void scc(int u, int id) {
28        vis[u] = true, comp[u] = id;
29        each(v, gr[u]) if (!vis[v]) scc(v, id);
30    }
31
32    bool satisfiable() {
33        fill(vis.begin(), vis.end(), false);
34        for (int i = 0; i < 2 * n; i++) if (!vis[i]) dfs(i);
35        fill(vis.begin(), vis.end(), false);
36        reverse(topological_order.begin(), topological_order.end());
37        int id = 0;
38        for(const auto &v : topological_order) if (!vis[v]) scc(v, id++);
39
40        for(int i=0; i<n; i++) {
            if (comp[i] == comp[i + n]) return false;

```

```

41        answer[i] = (comp[i] > comp[i + n] ? 1 : 0);
42    }
43    return true;
44 }
45
46 // Conditions
47 void add_clause(int a, int b, string op, int c) {
48     if(op=="=") {
49         if(c==0) add_nor(a, b);
50         else if(c==1) add_01_10(a, b);
51         else add_and(a, b);
52     }
53     else if(op=="!=") {
54         if(c==0) add_or(a, b);
55         else if(c==1) add_same(a, b);
56         else add_nand(a, b);
57     }
58     else if(op=="<") {
59         if(c==0) {
60             cout<<"No"<<endl;
61             exit(0);
62         }
63         else if(c==1) add_nor(a, b);
64         else add_nand(a, b);
65     }
66     else if(op==">") {
67         if(c==0) add_or(a, b);
68         else if(c==1) add_and(a, b);
69         else {
70             cout<<"No"<<endl;
71             exit(0);
72         }
73     }
74     else if(op=="<=") {
75         if(c==0) add_nor(a, b);
76         else if(c==1) add_nand(a, b);
77         else return;
78     }
79     else {
80         if(c==0) return;
81         else if(c==1) add_or(a, b);
82         else add_and(a, b);
83     }

```

```

84     }
85
86     void add_nor(int a, int b) {
87         add_edge(a, a+n);
88         add_edge(b, b+n);
89     }
90     void add_01_10(int a, int b){
91         add_or(a, b);
92         add_nand(a, b);
93     }
94     void add_and(int a, int b) {
95         add_edge(a+n, a);
96         add_edge(b+n, b);
97     }
98     void add_or(int a, int b){
99         add_edge(a+n, b);
100        add_edge(b+n, a);
101    }
102    void add_same(int a, int b) {
103        add_edge(a, b);
104        add_edge(b+n, a+n);
105        add_edge(a+n, b+n);
106        add_edge(b, a);
107    }
108    void add_nand(int a, int b) {
109        add_edge(a, b+n);
110        add_edge(b, a+n);
111    }
112 };
113
114 int main() { io
115     int n, m; cin>>n>>m;
116     two_sat ts(n);
117     rep(i,0,m) {
118         int a, b, c; string op;
119         cin>>a>>b>>op>>c;
120         ts.add_clause(a, b, op, c);
121     }
122     cout<< (ts.satisfiable() ? "Yes" : "No")<<endl;
123     return 0;
124 }

```

3 Math

3.1 Binpow

```

1 ll binpow(ll a, ll b, ll m) {
2     a %= m;
3     ll res = 1;
4     while (b > 0) {
5         if (b & 1) res = res * a % m;
6         a = a * a % m;
7         b >>= 1;
8     }
9     return res;
10 }

```

3.2 Modular inverse

```

1 tuple<int, int, int> extendedGCD(int mod, int a) {
2     if (!a) return {mod, 1, 0};
3     auto[r, x, y] = extendedGCD(a, mod % a);
4     return {r, y, x - mod / a * y};
5 }
6 int modInverse(int mod, int a) {
7     auto[r, x, y] = extendedGCD(mod, a);
8     if(r != 1) {
9         return -1;
10    }
11    return ((y < 0) ? y + mod : y);
12 }

```

3.3 Linear Sieve

```

1 const int N = 1e7+5; // N: range to get primes
2 int p[N];
3 vector<int> pr;
4 void linearSieve() {
5     for(int i=2; i<N; i++) {
6         if(!p[i]) {
7             p[i] = i;
8             pr.push_back(i);
9         }
10        for(int j=0; i*pr[j] < N; j++) {
11            p[i*pr[j]] = pr[j];
12            if(pr[j] == p[i])

```

```

13         break;
14     }
15 }
16 }

```

3.4 Factorials

```

1 void pre() {
2     fact[0] = 1;
3     for(int i=1; i<N; i++) {
4         fact[i] = 1LL * fact[i-1] * i % MOD;
5     }
6
7     ifact[N-1] = binpow(fact[N-1], MOD-2, MOD);
8     for(int i=N-2; i>=0; i--) {
9         ifact[i] = 1LL * ifact[i+1] * (i+1) % MOD;
10    }
11 }

```

3.5 Prime factorization

```

1 set<int> factors;
2 for(int i=2; i*i<=n; i++) {
3     while(!(n % i)) {
4         factors.insert(i);
5         n /= i;
6     }
7 }
8 if(n > 1) factors.insert(n);

```

3.6 Divisors

```

1 vector<int> div;
2 for(int i=1; i*i<=n; i++) {
3     if(!(n % i)) {
4         div.pb(i);
5         if(d != n/d) div.pb(n / d);
6     }
7 }
8 sort(all(div));

```

3.7 Identities

$$C_n = \frac{2(2n-1)}{n+1} C_{n-1}$$

$$C_n = \frac{1}{n+1} \binom{2n}{n}$$

$$C_n \sim \frac{4^n}{n^{3/2}\sqrt{\pi}}$$

$$\sigma(n) = O(\log(\log(n))) \text{ (number of divisors of } n)$$

$$F_{2n+1} = F_n^2 + F_{n+1}^2$$

$$F_{2n} = F_{n+1}^2 - F_{n-1}^2$$

$$\sum_{i=1}^n F_i = F_{n+2} - 1$$

$$F_{n+i}F_{n+j} - F_nF_{n+i+j} = (-1)^n F_i F_j$$

(Fermat's little theorem) $a^p \bmod(p) = a \quad a^{p-1} \bmod(p) = 1 \quad a^{p-2} \bmod(p) = a^{-1}$

(Möbius Inv. Formula) Let $g(n) = \sum_{d|n} f(d)$, then $f(n) = \sum_{d|n} d \mu(d) \mu\left(\frac{n}{d}\right)$.

4 Strings

4.1 Rolling Hash

```

1 #define rep(i,a,b) for(int i=a;i<b;i++)
2 using ll = long long;
3
4 const int base = 251, MOD = 1e9+7, N = 2e5+5;
5 ll p[N], hashes[N];
6 vector<int> rolling_hash(string text, string pattern) {
7     int n = text.length(), m = pattern.length();
8     p[0] = 1;
9     rep(i,1,n+1) p[i] = p[i-1] * base % MOD;
10
11     rep(i,1,n+1) hashes[i] = (hashes[i-1] + (text[i-1]-'a'+1) * p[i-1] %
12         MOD) % MOD;
13
14     ll patternHash = 0;
15     rep(i,1,m+1) patternHash = (patternHash + (pattern[i-1]-'a'+1) * p[i
16         -1] % MOD) % MOD;
17
18     vector<int> ocu;
19     rep(i,0,n-m+1) {
20         ll curr = (hashes[i+m] - hashes[i] + MOD) % MOD;
21         if(curr == patternHash * p[i] % MOD) ocu.push_back(i);
22     }
23     return ocu;
24 }
25
26 // 0. Define 2 prime numbers: base and mod
27 // 1. Precompute powers of the base
28 // 2. Compute prefix hashes for the text
29 // 3. Compute hash of the pattern

```


28 // 4. Sliding window of pattern size over the text to find matches

4.2 LCP using hashing + bs

```

1 int getLCP(int i, int j, int len) {
2     int l = 1, r = len;
3     while(l <= r) {
4         int m = (l+r) >> 1;
5         ll left = (hashes[i+m] - hashes[i] + MOD) % MOD;
6         ll right = (hashes[j+m] - hashes[j] + MOD) % MOD;
7         left = left * p[j-i] % MOD;
8         if(left == right) l = m + 1;
9         else r = m - 1;
10    }
11    return r;
12 }
13 // Compute prefix hashes for the text
14 // LCP: getLCP(idx, idx+len, n)
15 // length of most repeated substring: LCP+len

```

5 Geometry

5.1 Convex Hull

```

1 const double eps = 1e-9;
2 bool leq(double a, double b){return b-a >= -eps;}
3 bool le(double a, double b){return b-a > eps;}
4 bool eq(double a, double b){return fabs(a-b) <= eps;}
5
6 struct point{
7     double x, y;
8     int idx = -1;
9     point(): x(0), y(0){}
10    point(double x, double y): x(x), y(y){}
11    point operator-(const point &p) const{return point(x - p.x, y - p.y)
12        ;}
13    point operator*(const int &k) const{return point(x * k, y * k);}
14    bool operator<(const point &p) const{return le(x, p.x) || (eq(x, p.x)
15        && le(y, p.y));}
16    bool operator==(const point &p) const{return eq(x, p.x) && eq(y, p.y)
17        );}
18    double cross(const point &p) const{return x * p.y - y * p.x;}
19 };

```

```

17
18 istream &operator>>(istream &is, point &p){return is >> p.x >> p.y;}
19 ostream &operator<<(ostream &os, const point &p){return os << "(" << p.x
20     << ", " << p.y << ")";}
21
22 vector<point> convexHull(vector<point> P) {
23     sort(P.begin(), P.end());
24     vector<point> L, U;
25     for (int i = 0; i < P.size(); i++) {
26         while (L.size() >= 2 && le((L[L.size() - 2] - P[i]).cross(L[L.
27             size() - 1] - P[i]), 0)) {
28             L.pop_back();
29         }
30         L.push_back(P[i]);
31     }
32     for (int i = P.size() - 1; i >= 0; i--) {
33         while (U.size() >= 2 && le((U[U.size() - 2] - P[i]).cross(U[U.
34             size() - 1] - P[i]), 0)) {
35             U.pop_back();
36         }
37         U.push_back(P[i]);
38     }
39     L.pop_back();
40     U.pop_back();
41     L.insert(L.end(), U.begin(), U.end());
42     return L;
43 }
44
45 bool pointInConvexHull(const vector<point> &poly, point p) {
46     int n = poly.size();
47     if(n < 3) return false;
48     rep(i,0,n) {
49         point a = poly[i], b = poly[(i+1) % n];
50         double cp = (b - a).cross(p - a);
51         if(!le(0, cp)) return false;
52     }
53     return true;
54 }
55
56 int main() {
57     ios::sync_with_stdio(0); cin.tie(0);
58     int n;
59     double h;

```

```

57 cin >> n >> h;
58
59 vector<point> islands(n);
60 vector<double> time(n), heights(n);
61 rep(i,0,n) {
62     cin >> islands[i] >> heights[i];
63     islands[i].idx = i;
64     time[i] = max(0.0, h - heights[i]);
65 }
66
67 double l = 0.0, r = *max_element(all(time));
68 point c;
69 cin >> c;
70 auto valid = [&](double t) {
71     vector<point> aux;
72     rep(i,0,n) {
73         if(t >= time[i]) aux.pb(islands[i]);
74     }
75     if(aux.size() < 3) return false;
76     aux = convexHull(aux);
77     return pointInConvexHull(aux, c);
78 };
79
80 if(!valid(r)) {
81     cout << -1 << endl;
82     return 0;
83 }
84
85 for(int it=0; it<100; it++) {
86     double m = (l + r) / 2.0;
87     if(valid(m)) {
88         r = m;
89     }
90     else {
91         l = m;
92     }
93 }
94 cout << fixed << setprecision(12) << r << endl;
95
96 return 0;
97 }

```

6 Techniques

6.1 MO's algorithm

```

1  const int N = 3e5+5, B = 550;
2  int values[N], freq[N], res[N], ans, has[B];
3  void add(int idx) {
4      has[values[idx]/B]++;
5      freq[values[idx]]++;
6  }
7  void remove(int idx) {
8      has[values[idx]/B]--;
9      freq[values[idx]]--;
10 }
11 int getAns(int k) {
12     rep(i,0,B) if(has[i] > k) rep(j,i*B,(i+1)*B)
13         if(freq[j] > k) return j;
14     return -1;
15 }
16 void mos(vector<array<int, 4>> &queries) {
17     sort(all(queries), [](array<int, 4> &a, array<int, 4> &b) {
18         if(a[0]/B != b[0]/B) return a[0] < b[0];
19         return (a[0]/B & 1 ? a[1] < b[1] : a[1] > b[1]);
20     });
21
22     int l = 0, r = -1;
23     for(auto &[ql, qr, k, idx] : queries) {
24         while(l > ql) add(--l);
25         while(r < qr) add(++r);
26         while(l < ql) remove(l++);
27         while(r > qr) remove(r--);
28         res[idx] = getAns(k);
29     }
30 }

```

6.2 Parallel binary search

```

1  void parallel_bs() {
2      vector<array<int, 2>> queries(n+1);
3      rep(i,1,n+1) queries[i] = {1, q};
4
5      bool f = 1;
6      while(f) {

```

```

7     f = 0;
8     vector<vector<int>> mids(m+2);
9     for(auto &it : queries) {
10         if(it.l <= it.r) {
11             int mid = (it.l + it.r) >> 1;
12             mids[mid].pb(it.idx);
13             f = 1;
14         }
15     }
16
17     obj.reset();
18
19     rep(mid,1,q+1) {
20         auto &[l, r, k] = values[mid];
21         obj.update(l, r, k);
22
23         for(auto &idx : mids[mid]) {
24             Queries &q = queries[idx];
25             if(ok) q.r = mid - 1;
26             else q.l = mid + 1;
27         }
28     }
29 }
30 }

```

6.3 Split objects into light and heavy

```

1 vector<pair<int, int>> adj[N];
2 bitset<N> heavy;
3 const int B = 2050;
4 vector<pair<int, int>> heavyVertices[N];
5 int values[N], deg[N];
6
7 void solve() {
8     ll res = 0;
9     auto dfs = [&](auto self, int u, int p = -1) -> void {
10         for(auto &[v, x] : adj[u]) {
11             if(v == p) continue;
12             if(values[u] != values[v]) res += 1ll * x;
13             deg[u]++, deg[v]++;
14             self(self, v, u);
15         }
16     };

```

```

17     dfs(dfs, 0);
18
19     rep(i,0,n) if(deg[i] >= B) heavy[i] = 1;
20
21     rep(u,0,n) {
22         if(heavy[u]) {
23             for(auto &[v, x] : adj[u]) {
24                 colors[u][values[v]] += 1ll * x;
25                 if(heavy[v])
26                     heavyVertices[u].pb({v, x});
27                 heavyVertices[v].pb({u, x});
28             }
29         }
30     }
31
32     while(q--) {
33         int u, c;
34         cin >> u >> c;
35         u--;
36
37         if(heavy[u]) {
38             res += 1ll * colors[u][values[u]];
39             res -= 1ll * colors[u][c];
40             for(auto &[v, x] : heavyVertices[u]) {
41                 colors[v][values[u]] -= 1ll * x;
42                 colors[v][c] += 1ll * x;
43             }
44             values[u] = c;
45         }
46         else {
47             for(auto &[v, x] : adj[u]) {
48                 if(values[u] != values[v]) {
49                     if(c == values[v]) res -= 1ll * x;
50                 }
51                 else {
52                     if(c != values[v]) {
53                         res += 1ll * x;
54                     }
55                 }
56             }
57             if(heavy[v]) {
58                 colors[v][values[u]] -= 1ll * x;
59                 colors[v][c] += 1ll * x;
60             }
61         }
62     }

```

```

60     }
61     values[u] = c;
62 }
63
64 cout << res << endl;
65 }
66 }

```

6.4 Meet in the middle

```

1  int main() {
2      ios::sync_with_stdio(0); cout.tie(0); cin.tie(0);
3      int n; cin >> n;
4      vector<long long> a(n), b(n);
5      for(auto &it : a) cin >> it;
6      for(auto &it : b) cin >> it;
7
8      auto subsets = [](vector<long long> &a, vector<long long> &b, bool f
9          ){
10         int n = a.size();
11         vector<long long> aux;
12         for(int mask=0; mask<(1<<n); mask++) {
13             long long sum = 0;
14             for(int j=0; j<n; j++) {
15                 if((1 << j) & mask) sum += a[j];
16                 else sum -= b[j];
17             }
18             if(f) sum = abs(sum);
19             aux.push_back(sum);
20         }
21         return aux;
22     };
23
24     if(n <= 20) {
25         vector<long long> res = subsets(a, b, 1);
26         sort(res.begin(), res.end());
27         for(auto &it : res) cout << it << "␣";
28         cout<< endl;
29         return 0;
30     }
31
32     vector<long long> leftA(a.begin(), a.begin()+n/2),
33         leftB(b.begin(), b.begin()+n/2),

```

```

33         rightA(a.begin()+n/2, a.end()),
34         rightB(b.begin()+n/2, b.end());
35
36     vector<long long> left = subsets(leftA, leftB, 0),
37         right = subsets(rightA, rightB, 0);
38     sort(right.begin(), right.end());
39
40     priority_queue<tuple<long long, int, int, int>, vector<tuple<long
41         long, int, int, int>>, greater<tuple<long long, int, int, int>>>
42         > pq;
43     for(int i=0; i<left.size(); i++) {
44         int idx = lower_bound(right.begin(), right.end(), -left[i]) -
45             right.begin();
46         long long best = LONG_LONG_MAX, curr;
47         int idxBest;
48         for(int j=-1; j<=1; j++) {
49             if(idx + j >= 0 && idx + j < right.size()) {
50                 curr = abs(left[i] + right[idx+j]);
51                 if(curr < best) {
52                     best = curr;
53                     idxBest = idx+j;
54                 }
55             }
56         }
57         pq.push({best, idxBest, i, 0});
58     }
59
60     int req = 1 << 20, cnt = 0;
61     while(!pq.empty() && cnt < req) {
62         auto [sum, idx, i, event] = pq.top();
63         pq.pop();
64         cout << sum << "␣";
65         cnt++;
66         if(event <= 0 && idx-1 >= 0) {
67             long long lsum = abs(left[i] + right[idx-1]);
68             pq.push({lsum, idx-1, i, -1});
69         }
70         if(event >= 0 && idx+1 < right.size()) {
71             long long rsum = abs(left[i] + right[idx+1]);
72             pq.push({rsum, idx+1, i, 1});
73         }
74     }
75     cout << endl;

```

```

73
74     return 0;
75 }

```

6.5 Dijkstra on ST

```

1 vector<pair<int, int>> adj[2*4*N];
2 ll dist[2*4*N];
3 int mp[N], vis[2*4*N];
4 void build(int l, int r, int i) {
5     if (l == r) {
6         mp[l] = i;
7         adj[i].pb({i+4*N, 0});
8         adj[i+4*N].pb({i, 0});
9         return;
10    }
11    int m = (l+r)>>1;
12    build(l, m, 2*i+1);
13    build(m+1, r, 2*i+2);
14    adj[i].pb({2*i+1, 0});
15    adj[i].pb({2*i+2, 0});
16    adj[2*i+1+4*N].pb({i+4*N, 0});
17    adj[2*i+2+4*N].pb({i+4*N, 0});
18 }
19 void add(int l, int r, int u, int a, int b, int w, int op, int i) {
20     if (a > r || b < l) return;
21     if (a <= l && r <= b) {
22         if(op == 2) adj[mp[u]].pb({i, w});
23         else adj[i+4*N].pb({mp[u]+4*N, w});
24         return;
25     }
26     int m = l+r>>1;
27     add(l, m, u, a, b, w, op, 2*i+1);
28     add(m+1, r, u, a, b, w, op, 2*i+2);
29 }

```

6.6 Venice set

```

1 struct VeniceSet {
2     multiset<int> st;
3     int global = 0;
4
5     void add(int x) {
6         st.insert(x + global);

```

```

7     }
8     void remove(int x) {
9         st.erase(st.find(x + global));
10    }
11    void updateAll(int x) {
12        global += x;
13    }
14    int min(int x) {
15        return *st.begin() - global;
16    }
17 };

```

7 Basic techniques

7.1 Difference array

```

1 // If we only need to get the final result, we can increase l and r+1
2 // to simulate range update and use a prefix sum to get the answer.
3 diff[l] += k;
4 diff[r+1] -= k;
5
6 // If we have initial values, we need to subtract the previous values:
7 diff[i] -= values[i - 1];

```

7.2 Prefix Sum 2D

```

1 // Compute prefix sum 2D
2 rep(i,1,n+1) rep(j,1,m+1)
3     prefix[i][j] = prefix[i-1][j] + prefix[i][j-1]
4                     - prefix[i-1][j-1]
5                     + matrix[i-1][j-1]
6
7 // Query prefix sum 2D
8 query = prefix[i][j] - prefix[i-1][j] - prefix[i][j-1] + prefix[i-1][j-1]
9
10 // Specific parts
11 query = prefix[r2][c2] - prefix[r1-1][c2] - prefix[r2][c1-1] + prefix[r1-1][c1-1];

```

7.3 Random number generator

```

1 // Secure random seed
2 mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());

```

```
3
4 // Generate values using distribution
5 uniform_int_distribution<int> dist(0, N); // [0, N]
6 randval = dist(rng);
```

7.4 Coordinate compression

```
1 // Push to an array all possible values
2 coord.pb(x);
3 sort(all(coord));
4 coord.resize(unique(all(coord)) - coord.begin());
5
6 auto get = [&](int x) = {
7     return lower_bound(all(coord), x) - coord.begin();
8 };
```

7.5 Digit DP

```
1 int dp[11][2][2];
2 auto calc = [&](auto self, int idx, bool f1, bool f2) -> int {
3     if(idx >= n) return 0;
4
5     int &x = dp[idx][f1][f2];
6     if(x != -1) return x;
7
8     int num1 = a[idx] - '0', num2 = b[idx] - '0';
9     int l = (f1 ? 0 : num1);
10    int r = (f2 ? 9 : num2);
11    int mn = 1e9+5;
12
13    rep(i,l,r+1) {
14        mn = min(mn, self(self, idx+1, f1 | (i > num1), f2 | (i < num2))
15                + (num1==i) + (num2==i));
16    }
17    return x = mn;
18 };
19 memset(dp, -1, sizeof(dp));
20 cout << calc(calc, 0, 0, 0) << endl;
```

7.6 Intersection [L1, R1] and [L2, R2]

```
1 We need to check whether there is any number common to both ranges:
2 max(L1, L2) <= min(R1, R2)
```