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#### Module: UVM-1

Section: Ready to start coding? Task: Project 1

### Project 1 - EDA Link

Task

### > List down uvm component classes and object classes.

| Object Classes   | Component Classes  |
|--|--|
| <ol> <li>Transaction</li> <li>Base sequence</li> <li>Reset sequence</li> <li>Priority sequence</li> <li>Wrap sequence</li> </ol> | <ol> <li>Test top</li> <li>Sequencer</li> <li>Scoreboard</li> <li>Monitor</li> <li>Environment</li> <li>Driver</li> <li>Agent</li> </ol> |

# > What is build phase. Why it is top to bottom. In build phase what does this line do?

super.build\_phase (phase)

The build phase constructs and configures all UVM components top-down. It ensures that child components are created before any subsequent phases start. Calling "super.build\_phase(phase)" runs the parent's build phase first, ensuring the hierarchy is built correctly.

## What is run\_phase. Is it task or function? And in which components do we use it?

The "**run\_phase**" is a task that runs concurrently in components to execute test behavior and stimulus generation. It's commonly used in driver, monitor, and scoreboard components to drive transactions, monitor activity, and perform checks.

- ➤ What is phase.raise\_objection and phase.drop\_objection. Tell about their function in one line each.
  - a. **phase.raise\_objection**: This function is called to indicate that a particular phase requires additional time to complete, preventing the simulation from moving to the next phase until all objections are dropped.

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b. **phase.drop\_objection**: This function is used to remove a previously raised objection, signaling that the phase can proceed to the next one if no other objections remain.

### > How handshaking between driver and sequencer works?

Handshaking between a driver and a sequencer in UVM involves the sequencer calling **get\_next\_item()** to request a transaction, which blocks until the driver is ready. The driver then processes the transaction and calls **item\_done()** to acknowledge completion. This ensures synchronized communication and prevents overwhelming the driver.

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