

Numerical methods for eigenvalue problems

D. Löchel

Supervisors: M. Hochbruck und M. Tokar

Mathematisches Institut
Heinrich-Heine-Universität Düsseldorf

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Introduction

Power Method

Inverse Power Method

- Inverse Power Method with Shift

- Rayleigh Quotient Iteration

Simultaneous Iteration

QR Algorithm

- QR Algorithm with Shift

Summary

Linear Algebra:

Definition

$A \in \mathbb{C}^{n \times n}$, **eigenvector** $\vec{x} \in \mathbb{C}^n \setminus \{0\}$, **eigenvalue** $\lambda \in \mathbb{C}$

$$A\vec{x} = \lambda\vec{x}$$

Theorem

λ *eigenvalue of* $A \iff P_A(\lambda) := \det(\lambda I - A) = 0$

- ▶ P_A **characteristic polynomial**
- ▶ $\deg(P_A) \geq 5$: no explicit formula \longrightarrow numerical algorithm required
- ▶ using $P_A(\lambda)$ numerical instable

Definition

Rayleigh quotient: $\rho_A(\vec{x}) = \frac{\vec{x}^H A \vec{x}}{\vec{x}^H \vec{x}}$

Theorem

\vec{x} eigenvector of $A \implies \rho_A(\vec{x})$ is eigenvalue of A

Definition

- ▶ numbering of eigenvalues: $|\lambda_1| \geq |\lambda_2| \geq \dots \geq |\lambda_n|$
- ▶ \vec{x}_j eigenvector for λ_j

Given: $A \in \mathbb{C}^{n \times n}$, $\vec{y}_0 \in \mathbb{C}^n \setminus \{0\}$, $\|\vec{y}_0\|_2 = 1$

Assume: $\vec{y}_0^H \vec{x}_1 \neq 0$

Idea:

$$\vec{y}_0 = \sum_{j=1}^n \beta_j \vec{x}_j$$

$$\implies A\vec{y}_0 = \sum_{j=1}^n \beta_j A\vec{x}_j = \sum_{j=1}^n \beta_j \lambda_j \vec{x}_j$$

$$\implies A^k \vec{y}_0 = \sum_{j=1}^n \beta_j \lambda_j^k \vec{x}_j = \beta_1 \lambda_1^k \vec{x}_1 + \mathcal{O}\left(\left|\frac{\lambda_2}{\lambda_1}\right|^k\right)$$

Initial guess $\|\vec{y}_0\|_2 = 1$.

for $k = 0, 1, \dots$ **do**

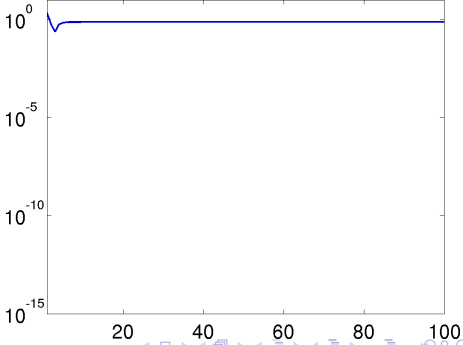
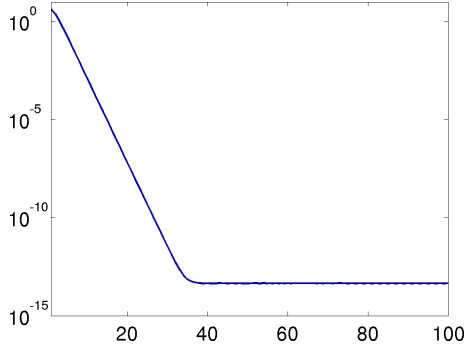
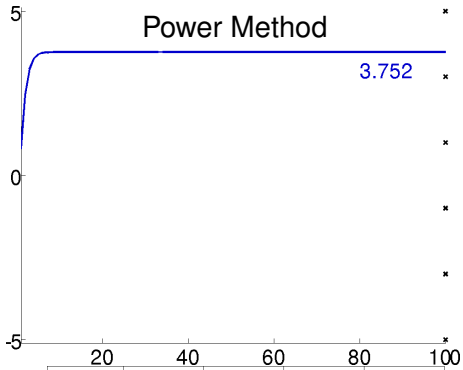
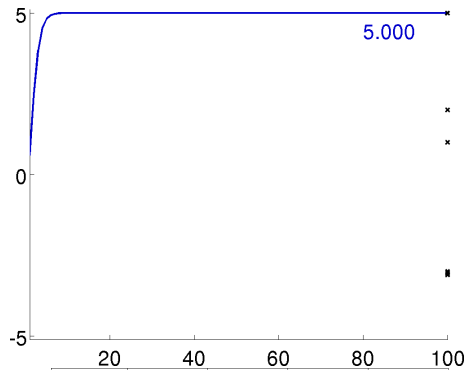
$\vec{z}_{k+1} = A\vec{y}_k$ // power

$\rho_k = \vec{y}_k^H \vec{z}_{k+1}$ // Rayleigh quotient $\frac{\vec{y}_k^H A \vec{y}_k}{\vec{y}_k^H \vec{y}_k}$

$\vec{y}_{k+1} = \frac{\vec{z}_{k+1}}{\|\vec{z}_{k+1}\|_2}$ // avoid over and underflow

end for

- ▶ Convergence if $\eta := \left| \frac{\lambda_2}{\lambda_1} \right| < 1$ and $\vec{x}_1^H \vec{y}_0 \neq 0$.
- ▶ Approximation $\rho(\vec{y}_k) = \lambda_1 + \mathcal{O}(\eta^k)$, slow if $\eta \approx 1$.
- ▶ Finds λ_1 only.



Recall: $\lambda \neq 0$ eigenvalue of $A \iff \frac{1}{\lambda}$ eigenvalue of A^{-1} .

Idea: apply power method to $A^{-1} \rightarrow$ inverse power method.

Definition

LU decomposition: $A = LU$, L lower, U upper triangular matrix

$$\begin{aligned} A\vec{z} &= \vec{y} \\ \iff L(U\vec{z}) &= \vec{y} \\ \iff L\vec{t} = \vec{y}, & U\vec{z} = \vec{t} \end{aligned}$$

two triangular linear systems

Initial guess $\|\vec{y}_0\|_2 = 1$.

Calculate LU decomposition of A .

for $k = 0, 1, \dots$ **do**

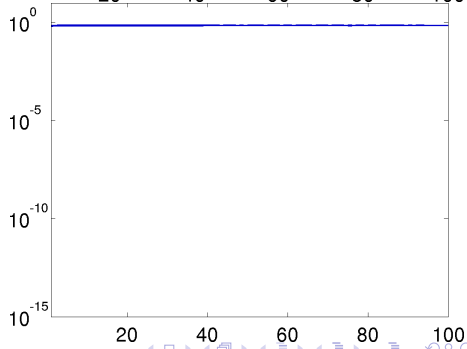
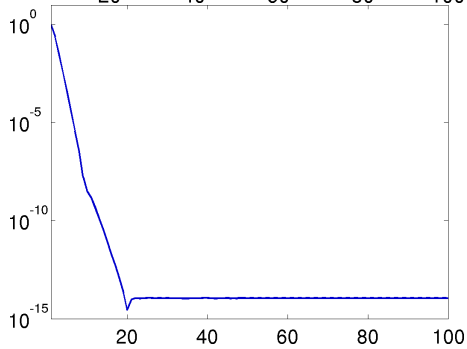
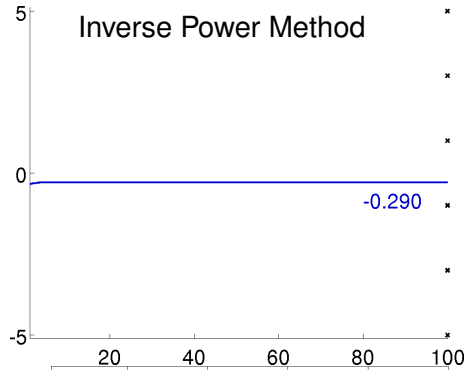
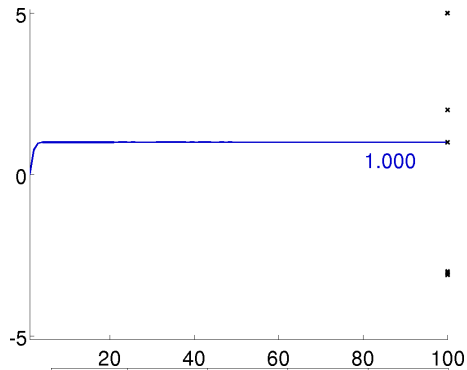
Solve $A\vec{z}_{k+1} = \vec{y}_k$ with LU decomposition. // $\vec{z}_{k+1} = A^{-1}\vec{y}_k$

$\vec{y}_{k+1} = \frac{\vec{z}_{k+1}}{\|\vec{z}_{k+1}\|_2}$ // avoid over and underflow

$\rho_k = \rho_A(\vec{y}_{k+1}) = \vec{y}_{k+1}^H A \vec{y}_{k+1}$ // Rayleigh quotient

end for

- ▶ Finds eigenvalue closest to zero.
- ▶ Convergence if $\eta := \left| \frac{\lambda_n}{\lambda_{n-1}} \right| < 1$ and $\vec{x}_n^H \vec{y}_0 \neq 0$.
- ▶ Approximation $\rho(\vec{y}_k) = \lambda_n + \mathcal{O}(\eta^k)$, slow if $\eta \approx 1$.



What about the remaining eigenvalues?

Smallest eigenvalue of $A - \mu I$ is eigenvalue from A closest to μ .

Definition

μ is called **Shift** and $A - \mu I$ shifted matrix.

Initial guess $\|\vec{y}_0\|_2 = 1$.

μ_0 initial guess for desired eigenvalue.

Calculate LU decomposition of $(A - \mu_0 I)$.

for $k = 0, 1, \dots$ **do**

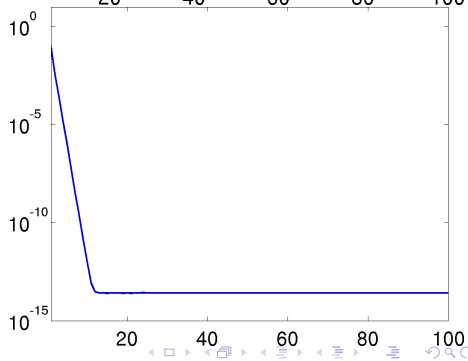
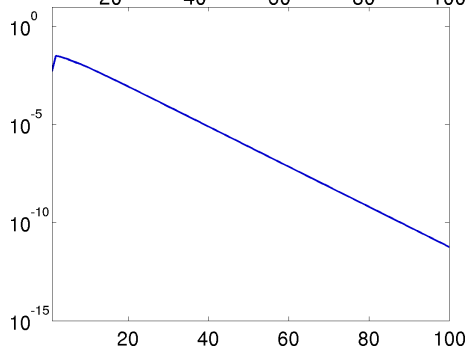
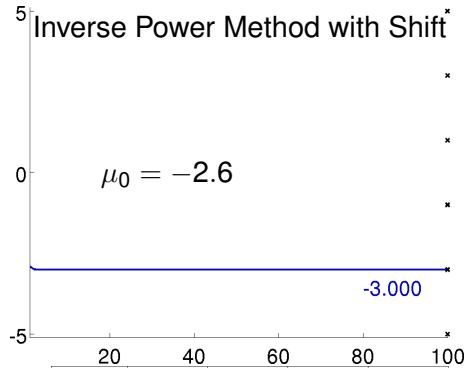
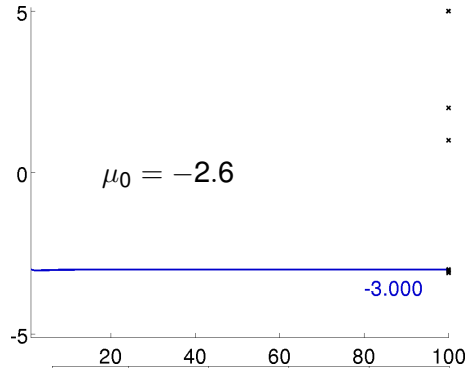
Solve $(A - \mu_0 I)\vec{z}_{k+1} = \vec{y}_k$ with LU decomposition.

$\vec{y}_{k+1} = \frac{\vec{z}_{k+1}}{\|\vec{z}_{k+1}\|_2}$ // avoid over and underflow

$\rho_k = \rho_A(\vec{y}_{k+1}) = \vec{y}_{k+1}^H A \vec{y}_{k+1}$ // Rayleigh quotient

end for

- Finds eigenvalue λ_j closest to μ_0 .
- Convergence if $\eta := \max_{m \neq j} \left| \frac{\lambda_j - \mu_0}{\lambda_m - \mu_0} \right| < 1$ and $\vec{x}_j^H \vec{y}_0 \neq 0$.
- Approximation $\rho(\vec{y}_k) = \lambda_j + \mathcal{O}(\eta^k)$, slow if $\eta \approx 1$.



Rayleigh Quotient Iteration

Initial guess $\|\vec{y}_0\|_2 = 1$.

μ_0 initial guess for desired eigenvalue.

for $k = 0, 1, \dots$ **do**

Calculate LU decomposition of $(A - \mu_k I)$.

Solve $(A - \mu_k I)\vec{z}_{k+1} = \vec{y}_k$ with LU decomposition.

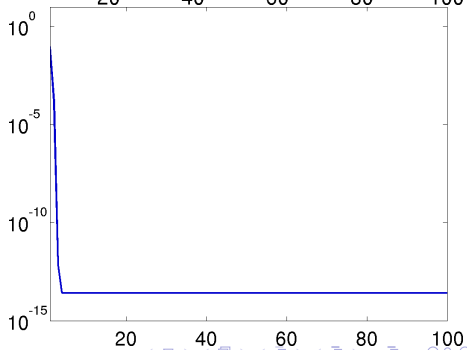
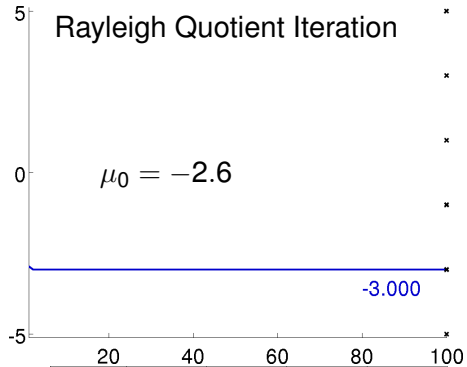
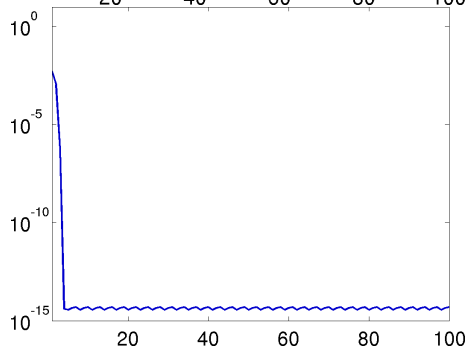
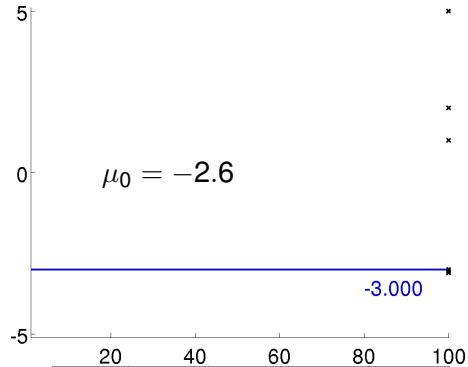
$\vec{y}_{k+1} = \frac{\vec{z}_{k+1}}{\|\vec{z}_{k+1}\|_2}$ // avoid over and underflow

$\rho_k = \rho_A(\vec{y}_{k+1}) = \vec{y}_{k+1}^H A \vec{y}_{k+1}$ // Rayleigh quotient

$\mu_k := \rho_k$

end for

- ▶ Finds eigenvalue λ_j closest to μ_0 .
- ▶ Convergence if $\eta_0 := \max_{m \neq j} \left| \frac{\lambda_j - \mu_0}{\lambda_m - \mu_0} \right| < 1$ and $\vec{x}_j^H \vec{y}_0 \neq 0$.
- ▶ $\eta_k := \max_{m \neq j} \left| \frac{\lambda_j - \mu_k}{\lambda_m - \mu_k} \right| \ll 1$, if $\eta_0 < 1$: $\lim_{k \rightarrow \infty} \eta_k = 0$.
- ▶ Approximation $\rho(\vec{y}_k) = \lambda_j + \mathcal{O}(\eta_0^{2k})$.
- ▶ LU decomposition in each step expensive
- ▶ Convergence fast



Until now: calculating only one eigenvalue

Next step: calculating many or all eigenvalues

$m \leq n$, $U_0 \in \mathbb{C}^{n,m}$ unitary, $U_0^H U_0 = I_m$, $A_0 := A$

for $k = 0, 1, \dots$ **do**

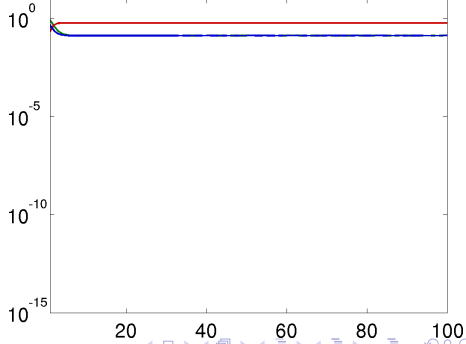
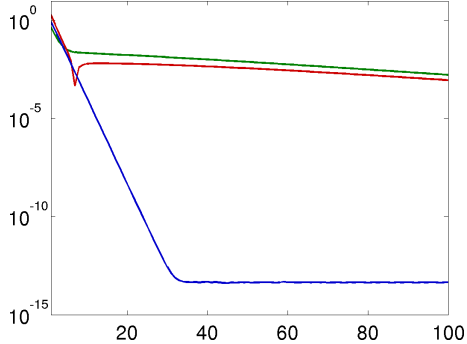
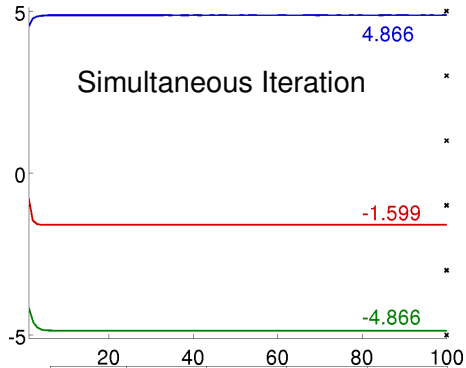
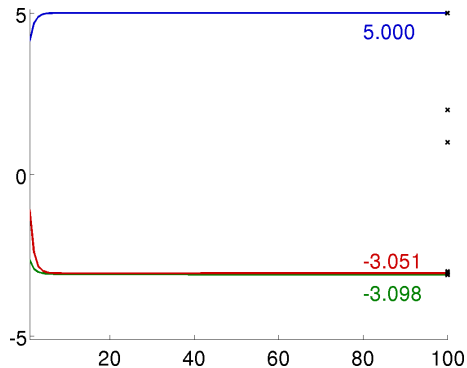
$Y_{k+1} := A_k U_k$ // power of each column of U_k

Calculate QR decomposition $Y_{k+1} = U_{k+1} R_{k+1}$.

$A_{k+1} = U_{k+1}^H A U_{k+1}$ // similarity transformation

end for

- Orthogonalisation is necessary to avoid that all columns converge against x_1 .



$m = n$: QR algorithm (equivalent to simultaneous iteration)

$$A_0 := A$$

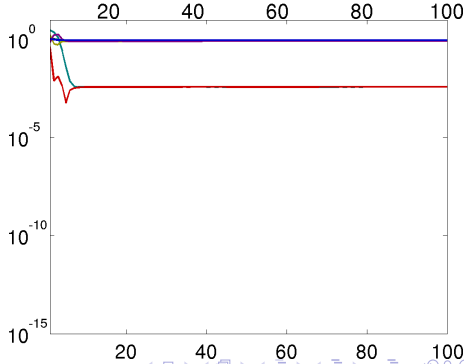
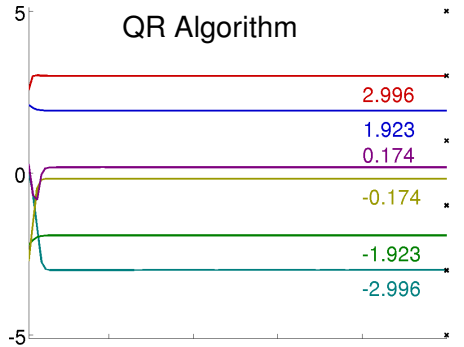
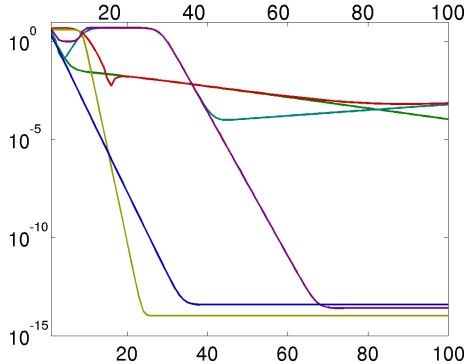
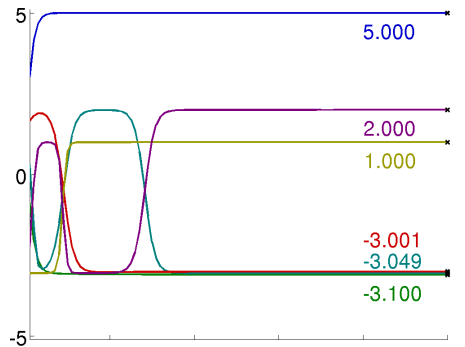
for $k = 0, 1, \dots$ **do**

 Calculate QR Decomposition $A_k = Q_k R_k$.

$$A_{k+1} := R_k Q_k$$

end for

- ▶ $A_{k+1} = R_k Q_k = Q_k^H A_k Q_k = (Q_{k-1} Q_k)^H A_{k-1} (Q_{k-1} Q_k) = \hat{Q}_k^H A_0 \hat{Q}_k$, unitary similarity transformation.
- ▶ $A_k \longrightarrow$ upper triangular matrix, eigenvalues on diagonal (proof: schur decomposition).
- ▶ This way QR algorithm can be very slow.



$A_0 := A$

for $k = 0, 1, \dots$ **do**

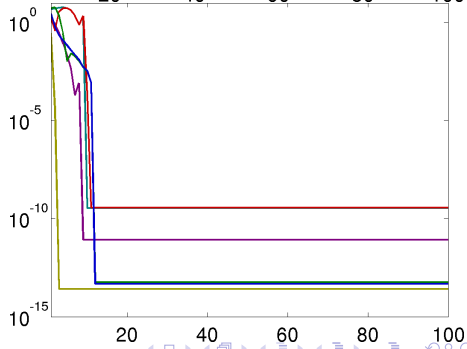
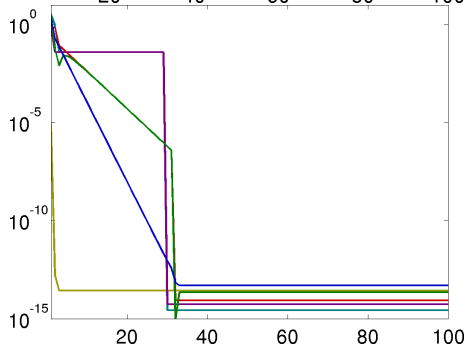
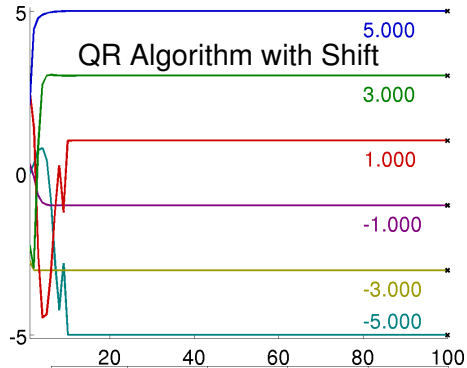
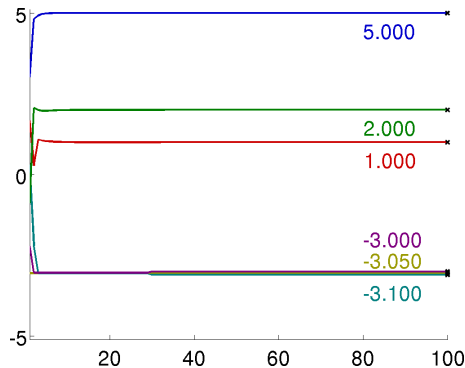
 Choose a shift μ_k .

 Calculate QR decomposition $A_k - \mu_k I = Q_k R_k$.

$A_{k+1} := R_k Q_k + \mu_k I$

end for

- this way convergence is fast in general



- ▶ complexity of one QR decomposition: $\frac{2}{3}n^3$ operations
- ▶ complexity to calculate all eigenvalues: at least $\mathcal{O}(n^4)$
- ▶ reduce complexity for QR decomposition by
 $A \leftarrow H := U^H A U$ with H upper Hessenberg.

$$U^H A U = H = \begin{bmatrix} h_{1,1} & \dots & h_{1,n-1} & h_{1,n} \\ h_{2,1} & \ddots & \vdots & \vdots \\ & \ddots & h_{n-1,n-1} & h_{n-1,n} \\ 0 & & h_{n,n-1} & h_{n,n} \end{bmatrix}$$

U product of Givens-Rotations

$$G = \begin{bmatrix} \cos(\alpha) & \sin(\alpha) \\ -\sin(\alpha) & \cos(\alpha) \end{bmatrix}$$

- ▶ power method for biggest eigenvalue
- ▶ inverse power method for eigenvalue closest to zero.
- ▶ inverse power method with shift for desired eigenvalue
- ▶ Rayleigh quotient iteration, fast
- ▶ simultaneous iteration for many eigenvalues
- ▶ QR algorithm (with shift) for all eigenvalues (fast)

Thank you for your attention!