Initialization Heuristics for Greedy Bayesian **Network Structure Learning**

Learning BN

Walter Perez Urcia Denis Deratani Mauá

> Universidade de São Paulo Instituto de Matemática e Estadística Departamento de Ciências da Computação

> > KDMiLE 2015

Learning BN

Contents

- Introduction
- 2 Bayesian Network
- 3 Learning BN
- 4 Initializing Heuristics

- Variables X_1, \ldots, X_n takes values in $\Omega_1, \ldots, \Omega_n$
 - X_1 : Gender, $\Omega_1 = \{Male, Female\}$ • X_2 : City size, $\Omega_2 = \{Big, Small\}$
- Factored possibility space $\Omega = \Omega_1 \times \ldots \times \Omega_n$
- Event is a subset of Ω
- Probability function maps events α and β into real values such that

- $0 < \mathbb{P}(\alpha) < 1$
- $\mathbb{P}(\Omega) = 1$
- $\mathbb{P}(\alpha \cup \beta) = \mathbb{P}(\alpha) + \mathbb{P}(\beta) \mathbb{P}(\alpha \cap \beta)$

 Every assignment of value to a variable correspond to an event:

$$Gender = M \leftrightarrow \alpha = \{(M, s), (M, b)\}$$

Learning BN

• The probability distribution of a variable *X* maps assignments of the variable to the respective probabilities:

$$\mathbb{P}(X = x) = \mathbb{P}(\{\omega : \omega \text{ consistent with } x\})$$

- We denote the probability distribution of X as $\mathbb{P}(X)$ and the probability of an arbitrary event $\{X=x\}$ as $\mathbb{P}(x)$
- It follows from the properties of probability function that

$$\sum_{X} \mathbb{P}(X) = \sum_{x \in \Omega_{Y}} \mathbb{P}(X = x) = 1$$

A joint assignment to a set of variables is an event

Gender =
$$M$$
 and $City\ size = b \leftrightarrow \alpha = \{(M, b)\}$

Learning BN

• The joint probability distribution of a set of variables is a function that maps joint assignments to their event probabilities:

$$\mathbb{P}(X = x, Y = y) = \mathbb{P}(\{\omega : \omega \text{ consistent with } x, y\})$$

- We denote the probability distribution of X and Y as $\mathbb{P}(X)$ and the probability of an arbitrary joint event as $\mathbb{P}(x,y)$
- It follows from the properties of probability function that

$$\sum_{X,Y} \mathbb{P}(X,Y) = \sum_{x \in \Omega_X} \sum_{x \in \Omega_Y} \mathbb{P}(X=x,Y=y) = 1$$

Maps assignments of two variables to conditional probabilities:

$$\mathbb{P}(X = x \mid Y = y) = \frac{\mathbb{P}(X = x, Y = y)}{\mathbb{P}(Y = y)}$$

- Represented as $\mathbb{P}(X \mid Y)$
- Analogously, we can define join conditional probability distribution $\mathbb{P}(X, Y \mid Z, W)$

By definition of conditional probability:

$$\mathbb{P}(\alpha \mid \beta)\mathbb{P}(\beta) = \mathbb{P}(\alpha \cap \beta)$$

Learning BN

For events $\alpha_1, \ldots, \alpha_n$ it follows that

$$\mathbb{P}(\alpha_1 \cap \ldots \cap \alpha_n) = \mathbb{P}(\alpha_1) \prod_{i=2}^n \mathbb{P}(\alpha_i \mid \alpha_1 \cap \ldots \cap \alpha_{i-1})$$

In terms of variables:

$$\mathbb{P}(A, B, C) = \mathbb{P}(A)\mathbb{P}(B \mid A)\mathbb{P}(C \mid B, A)$$

$$\mathbb{P}(\beta \mid \alpha) = \frac{\mathbb{P}(\alpha \mid \beta)}{\mathbb{P}(\alpha)} \mathbb{P}(\beta)$$

Learning BN

• Prior probability: $\mathbb{P}(\beta)$

• Posterior probability: $\mathbb{P}(\beta \mid \alpha)$

• Data Likelihood: $\mathbb{P}(\alpha \mid \beta)$

• Evidence probability: $\mathbb{P}(\alpha)$

- Bayes' rule can be seen as a way of revising beliefs in light of new information/knowledge: start with $\mathbb{P}(\beta)$, observe α then set $\mathbb{P}(\beta)' = \mathbb{P}(\beta \mid \alpha)$
- This way of thinking is known as Bayesian Reasoning

Events α and β are independent if:

$$\mathbb{P}(\alpha \cap \beta) = \mathbb{P}(\alpha)\mathbb{P}(\beta)$$

- The following are equivalent definitions:
 - Either $\mathbb{P}(\alpha \mid \beta) = \mathbb{P}(\alpha)$ or $\mathbb{P}(\beta) = 0$
 - Either $\mathbb{P}(\beta \mid \alpha) = \mathbb{P}(\beta)$ or $\mathbb{P}(\alpha) = 0$
- Knowing β is irrelevant to determining the value of α
- Knowing α is irrelevant to determining the value of β

00000000000

Variables A and B are independent if:

$$\mathbb{P}(A = a, B = b) = \mathbb{P}(A = a)\mathbb{P}(B = b)$$

Learning BN

for all values of a and b. Another way to write this is:

$$\mathbb{P}(A,B) = \mathbb{P}(A)\mathbb{P}(B)$$

Events α and β are independent conditional on event γ if:

$$\mathbb{P}(\alpha \cap \beta \mid \gamma) = \mathbb{P}(\alpha \mid \gamma)\mathbb{P}(\beta \mid \gamma)$$

Learning BN

The following are equivalent definitions:

- Either $\mathbb{P}(\alpha \mid \beta, \gamma) = \mathbb{P}(\alpha \mid \gamma)$ or $\mathbb{P}(\beta \mid \gamma) = 0$
- Either $\mathbb{P}(\beta \mid \alpha, \gamma) = \mathbb{P}(\beta \mid \gamma)$ or $\mathbb{P}(\alpha \mid \gamma) = 0$

Analogously, variables A and B are conditionally independent given C if

$$\mathbb{P}(A, B \mid C) = \mathbb{P}(A \mid C)\mathbb{P}(B \mid C)$$

for every assignment to A, B and C

The presence of independences reduces the number of probability values to specify:

- No independences: $\mathbb{P}(A, B, C)$, k^3 values
- A, B and C are dependent, and A and B are conditionally independent given $C: \mathbb{P}(A, B \mid C) = \mathbb{P}(A \mid C)\mathbb{P}(B \mid C)$, $k + 2k^2$ values
- A, B and C are independent: $\mathbb{P}(A, B, C) = \mathbb{P}(A)\mathbb{P}(B)\mathbb{P}(C)$, 3k values

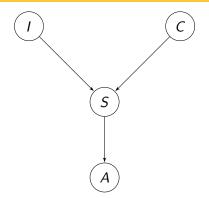
Markov property

Given its parents, every variable is conditionally independent from its non-descendants non-parents

Learning BN

Factorization property

$$\mathbb{P}(X_1,\ldots,X_n)=\prod_{i=1}^n\mathbb{P}(X_i\mid Pa(X_i))$$



The directed acyclic graph (DAG) above has joint probability distribution:

$$\mathbb{P}(I, C, S, A) = \mathbb{P}(I)\mathbb{P}(C \mid I)\mathbb{P}(S \mid C, I)\mathbb{P}(A \mid S, C, I)$$
$$= \mathbb{P}(I)\mathbb{P}(C)\mathbb{P}(S \mid C, I)\mathbb{P}(A \mid S)$$

A Bayesian Network consists of

- A DAG G over a set of variables X_1, \ldots, X_n
- Probability constraints: $\mathbb{P}(X_i = k \mid Pa(X_i) = j) = \theta_{iik}$

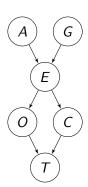
Learning BN

Joint Probability Distribution

There is a unique probability function consistent with a BN:

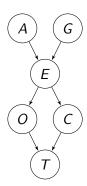
$$\mathbb{P}(X_1,\ldots,X_n)=\prod_{i=1}^n\mathbb{P}(X_i\mid Pa(X_i))=\prod_{i=1}^n\theta_{ijk}$$

- Age (A): young, adult, old
- Gender (G): male, female
- Education (E): primary, high school, university
- Occupation (O): employee, self-employed
- City size (C): big, small
- Transport (T): private (car), public (bus, train, etc)



 Education rates have been increasing over years; young people are more likely to have university degrees than old people

- Women are more likely to invest in their education than men; women outnumber men in the vast majority of university-level courses
- High education levels is key to getting prestigious professions; jobs requiring university degrees are more easily available in big cities
- Preferred means of transport depends on occupation and city size



$$\mathbb{P}(A = young) = 0.3$$

$$\mathbb{P}(A = adult) = 0.5$$

$$\mathbb{P}(A = old) = 0.2$$

$$\mathbb{P}(E = high \mid A = young, G = F) = 0.7$$

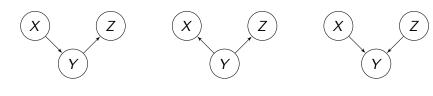
$$\vdots$$

$$\mathbb{P}(C = small \mid E = high) = 0.25$$

common effect

causal chain

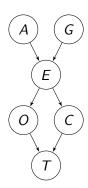
An arc $X \to Y$ can be interpreted as "X causes Y"



common cause

Learning BN

Defining and verifying causality is difficult and controversial: We can loosely define X causes Y if X temporarily precedes and direct influences Y



We can query a Bayesian Network about unspecified probabilities

Learning BN

 Are women more likely to prefer public transport over men:

$$\mathbb{P}(T = public \mid G = F) > \mathbb{P}(T = public \mid G)$$
?

• What is the distribution of ages for people who use private means of transport:

$$\mathbb{P}(A \mid T = private)$$
?