

# SATISIFIABILITY AND SAT & MAXSAT SOLVERS

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# TOPICS

## 1 SAT

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2 EMPIRICAL PROPERTIES

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- 3 MAXSAT

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- 4 THE DPLL ALGORITHM

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- 5 IMPROVEMENTS TO DPLL



# NEXT ISSUE

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  - A Brief History of SAT Solvers
- 2 EMPIRICAL PROPERTIES
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  - DPLL and Resolution
- 5 IMPROVEMENTS TO DPLL
  - Watched Literals
  - Further Techniques
- 6 CONCLUSION



# THE SETTING: THE LANGUAGE

- Atoms:  $\mathcal{P} = \{p_1, \dots, p_n\}$
- Literals:  $p_i$  and  $\neg p_j$
- $\bar{p} = \neg p$ ,  $\overline{\neg p} = p$
- A clause is a set of literals. Ex:  $\{p, \bar{q}, r\}$  or  $p \vee \neg q \vee r$
- A formula  $C$  is a set of clauses

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- A formula  $C$  is **satisfiable** if exists  $v$ ,  $v(C) = 1$ .
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## THE SAT PROBLEM

Given a formula  $C$ , decide if  $C$  is satisfiable.

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- SAT has small witnesses

# AN NP ALGORITHM FOR SAT

## NP-SAT( $C$ )

**INPUT:**  $C$ , a formula in clausal form

**OUTPUT:**  $v$ , if  $v(C) = 1$ ; no, otherwise.

- 1: Guess a  $v$
- 2: Show, in polynomial time, that  $v(C) = 1$
- 3: **return**  $v$
- 4: **if** no such  $v$  is guessable **then**
- 5:     **return** no
- 6: **end if**



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# A BRIEF HISTORY OF SAT SOLVERS

- [Davis & Putnam, 1960; Davis, Longemann & Loveland, 1962] The DPLL Algorithm, a complete SAT Solver















## INCOMPLETE SAT METHODS

Incomplete methods compute valuation if  $C$  is SAT; if  $C$  is unSAT, no answer.

- [Selman, Levesque & Mitchell, 1992] GSAT, a local search algorithm for SAT
- [Mitchell, Levesque & Selman, 1992] Hard and easy SAT problems
- [Kautz & Selman, 1992] SAT planning
- [Kautz & Selman, 1993] WalkSAT Algorithm
- [Gent & Walsh, 1994] SAT phase transition

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- Applications to planning, microprocessor test and verification, software design and verification, AI search, games, etc.

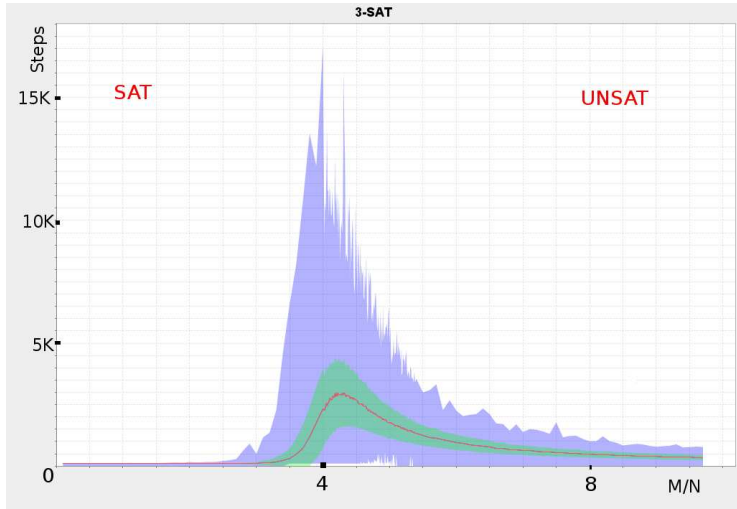
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- Very competitive SAT solvers: GRASP [1999], Chaff [2001], BerkMin [2002], zChaff [2004], MiniSAT[2003].
- Applications to planning, microprocessor test and verification, software design and verification, AI search, games, etc.
- Some non-DPLL SAT solvers incorporate all those techniques: [Dixon 2004]

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# THE SAT PHASE TRANSITION



# THE PHASE TRANSITION DIAGRAM

- 3-SAT,  $N$  is fixed
- Higher  $N$ , more abrupt transition
- $M/N$ : low (SAT); high (UNSAT)
- Phase transition point:  $M/N \approx 4.3$ , 50%*SAT* [Toby & Walsh 1994]
- Invariant with  $N$
- Invariant with algorithm!

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- Invariant with  $N$
- Invariant with algorithm!
- No theoretical explanation
- There is another phase-transition for SAT based on “Impurity” [Lozinskii 2006]

# DEOLALIKAR'S $P = NP$ PROOF STRATGY

- Prove theoretically the existence of phase transition
  - Uses Statistical Physics
- Model  $P$  using Immerman-Vardi LFP-Logic
  - Show that for every  $p^k$ , some problem exists in a phase transition above  $p^k$ .





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# THE UNWEIGHTED MAXSAT-PROBLEM

- Given: set of formulas  $\Gamma = \{C_i | 1 \leq i \leq k\}$
- $\Gamma' \subseteq \Gamma$ , is **maximally satisfiable** if for every  $\Gamma''$ ,  $\Gamma' \subset \Gamma'' \subset \Gamma$ ,  $\Gamma''$  unsatisfiable.

## THE (UNWEIGHTED) MAXSAT PROBLEM

Given  $\Gamma = \{C_i | 1 \leq i \leq k\}$

Maximize  $|\Gamma'|$

Subject to  $\Gamma' \subseteq \Gamma$  is SAT.

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- Problem: MaxSAT is **not** a decision problem. Class NP only applies to decision problems

# NP VERSION OF MAXSAT

NP-MaxSAT( $\Gamma, \ell$ )

Given  $\Gamma = \{C_i | 1 \leq i \leq k\}$ ,  $\ell \leq k$

Decide if there exists satisfiable  $\Gamma' \subseteq \Gamma$  with  $|\Gamma'| \geq \ell$ .

Witness: valuation that satisfies  $\Gamma'$

# MaxSAT VIA NP-MaxSAT

Use NP-MaxSAT to solve MaxSAT: binary search on  $\ell$

# MAXSAT VIA NP-MAXSAT

Given  $\Gamma = \{C_i | 1 \leq i \leq k\}$

Fix  $M = k, m = 0$ . While  $m < M$  repeat:

- $\ell = \lceil \frac{M+m}{2} \rceil$
- If NP-MaxSAT( $\Gamma, \ell$ ),  $m = \ell + 1$
- Else  $M = \ell - 1$

Return  $M$

# PARTIAL WEIGHTED MAXSAT

$\Gamma^w = \{C_i : w_i | 1 \leq i \leq k\}$ ,  $w_i$ : weight of  $C_i$ .

$$w(\Gamma^w) = \sum_{C_i : w_i \in \Gamma^w} w_i$$

## PARTIAL WEIGHTED MAXSAT PROBLEM

Given  $\Delta = \{D_i | 1 \leq i \leq d\}$ ,  $\Gamma^w = \{C_i : w_i | 1 \leq i \leq k\}$

Maximize  $w(\Gamma')$

Subject to  $\Gamma' \subseteq \Gamma^w$  and  $\Gamma' \cup \Delta$  is SAT



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$$\begin{array}{l} p \vee q \\ p \vee \neg q \\ \neg p \vee t \vee s \\ \neg p \vee \neg t \vee s \\ \neg p \vee \neg s \\ \neg p \vee s \vee \neg a \end{array}$$

# INITIAL SIMPLIFICATIONS

Delete all clauses that contain  $\lambda$ , if  $\bar{\lambda}$  does not occur.

$$p \vee q$$

$$p \vee \neg q$$

$$\neg p \vee t \vee s$$

$$\neg p \vee \neg t \vee s$$

$$\neg p \vee \neg s$$

$$\cancel{t} \cancel{p} \cancel{\vee} \cancel{s} \cancel{\vee} \cancel{t} \cancel{\vee} \cancel{s}$$

# CONSTRUCTION OF A PARTIAL VALUATION

Choose a literal:  $s$ .  $V = \{s\}$

Propagate choice: Delete clauses containing  $s$ . Delete  $\bar{s}$  from other clauses.

$$p \vee q$$

$$p \vee \neg q$$

$$\cancel{p} \vee \cancel{q} \vee \cancel{r} \vee s$$

$$\cancel{p} \vee \cancel{q} \vee \cancel{r} \vee \cancel{t} \vee s$$

$$\neg p \vee \cancel{q} \vee \cancel{r}$$

## UNIT PROPAGATION

Enlarge the partial valuation with unit clauses.

$$V = \{\mathbf{s}, \bar{p}\}$$

Propagate unit clauses as before.

$$\cancel{p} \vee q$$

~~$p \vee \neg q$~~

~~typ~~

Another propagation step leads to  $V = \{\mathbf{s}, \bar{p}, q, \bar{q}\}$

# BACKTRACKING

Unit propagation may lead to contradictory valuation:

$$V = \{\mathbf{s}, \bar{p}, \mathbf{q}, \bar{q}\}$$

Backtrack to the previous choice, and propagate:  $V = \{\bar{s}\}$

$$p \vee q$$

$$p \vee \neg q$$

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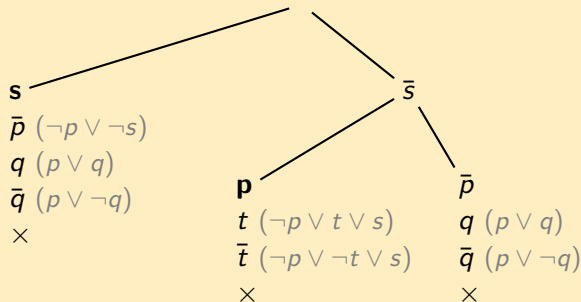
$$\neg p \vee t \not\models$$



# THE FORMULA IS UNSAT

There is nowhere to backtrack to now!

**The formula is unsatisfiable**, with a proof sketched below.





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# THE RESOLUTION INFERENCE FOR CLAUSES

## USUAL RESOLUTION

$$\frac{C \vee \lambda \quad \bar{\lambda} \vee D}{C \vee D}$$

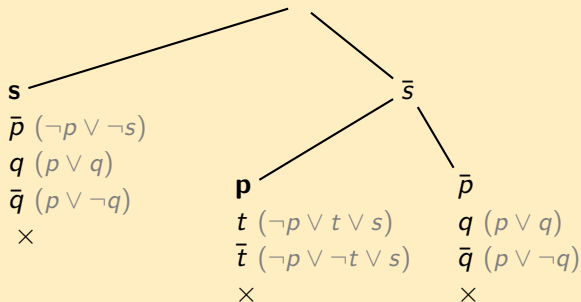
## CLAUSES AS SETS

$$\frac{\Gamma \cup \{\lambda\} \quad \{\bar{\lambda}\} \cup \Delta}{\Gamma \cup \Delta}$$

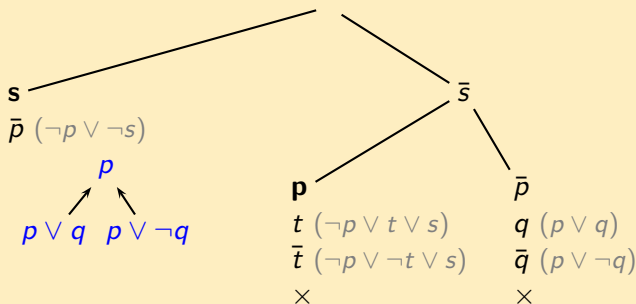
Note that, as clauses are sets

$$\frac{\Gamma \cup \{\mu, \lambda\} \quad \{\bar{\lambda}, \mu\} \cup \Delta}{\Gamma \cup \Delta \cup \{\mu\}}$$

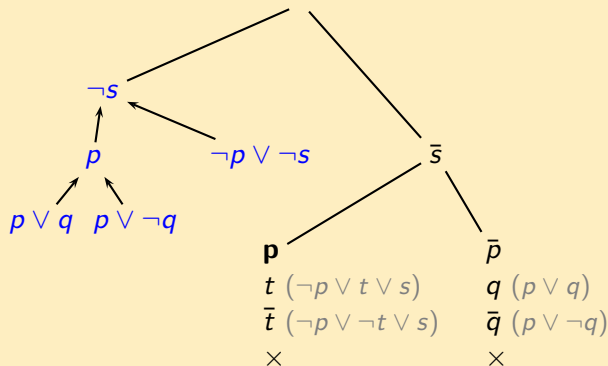
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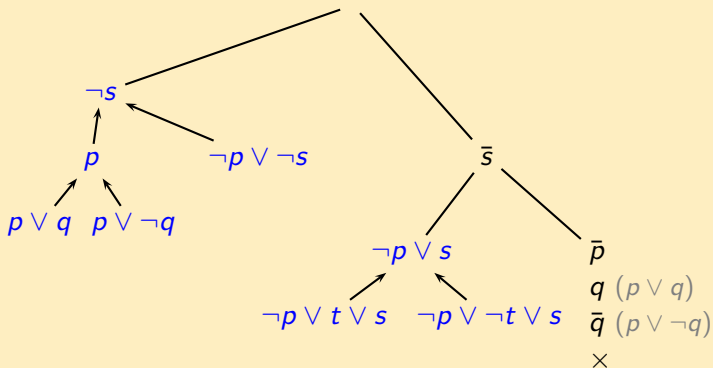
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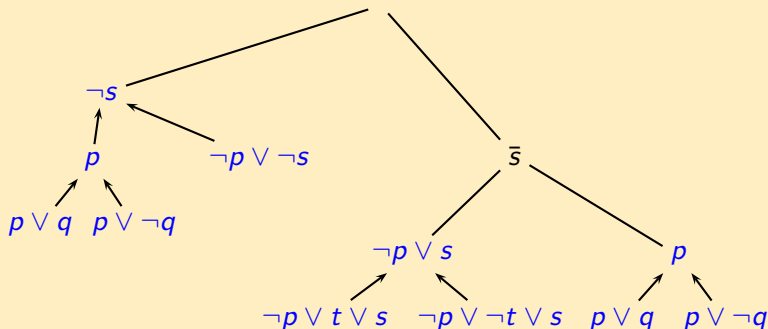
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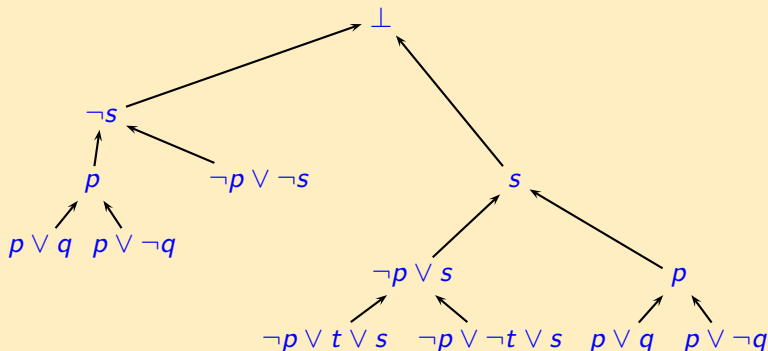
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- DPLL is **isomorphic** to (a restricted form of) resolution
- DPLL inherits all properties of this (restricted form of) resolution
- In particular, DPLL inherits the exponential lower bounds

# ENHANCING DPLL

For the reasons discussed, DPLL needs to be improved to achieve better efficiency. Several techniques have been applied:

- Learning
- Unlearning
- Backjumping
- Watched literals
- Heuristics for choosing literals

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For the reasons discussed, DPLL needs to be improved to achieve better efficiency. Several techniques have been applied:

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# Watched Literals



# THE COST OF UNIT PROPAGATION

- Empirical measures show that **80% of time** DPLL is doing Unit Propagation
- Propagation is the main target for optimization
- CHAFF introduced the technique of **Watched Literals**
  - Unit Propagation speed up
  - No need to delete literals or clauses
  - No need to watch all literals in a clause
  - Constant time backtracking (very fast)

# DPLL AND 3-VALUED LOGIC

- DPLL underlying logic is 3-valued
- Given a partial valuation

$$V = \{\lambda_1, \dots, \lambda_k\}$$

- Let  $\lambda$  be any literal.

$$V(\lambda) = \begin{cases} 1(\text{true}) & \text{if } \lambda \in V \\ 0(\text{false}) & \text{if } \bar{\lambda} \in V \\ *(\text{undefined}) & \text{otherwise} \end{cases}$$

# THE WATCHED LITERAL DATA STRUCTURE

- Every clause  $c$  has two selected literals:  $\lambda_{c1}, \lambda_{c2}$
- For each  $c$ ,  $\lambda_{c1}, \lambda_{c2}$  are dynamically chosen and varies with time
- $\lambda_{c1}, \lambda_{c2}$  are **properly watched** under partial valuation  $V$  if:
  - they are both undefined; or
  - at least one of them is true

# DYNAMICS OF WATCHED LITERALS

- Initially,  $V = \emptyset$
- A pair of watched literals is chosen for each clause. It is proper.
- Literal choice and unit propagation expand  $V$
- One or both watched literals may be falsified
- If  $\lambda_{c1}, \lambda_{c2}$  become improper then
  - The falsified watched literal is changed
- if no proper pair of watched literals can be found, two things may occur to alter  $V$ 
  - Unit propagation ( $V$  is expanded)
  - Backtracking ( $V$  is reduced)

# EXAMPLE

<i>clause</i>	$\lambda_{c1}$	$\lambda_{c2}$
$p \vee q \vee r$	$p = *$	$q = *$
$p \vee \neg q \vee s$	$p = *$	$\bar{q} = *$
$p \vee r \vee \neg s$	$p = *$	$r = *$

Initially  $V = \emptyset$

A pair of literals was elected for each clause

All are undefined, all pairs are proper

$\bar{p}$  IS CHOSEN

$$V = \{\bar{p}\}$$

All watched literals become  $(0, *)$ , improper

New literals are chosen to be watched

<i>clause</i>	$\lambda_{c1}$	$\lambda_{c2}$
$p \vee q \vee r$	$r = *$	$q = *$
$p \vee \neg q \vee s$	$s = *$	$\bar{q} = *$
$p \vee \neg r \vee \neg s$	$\bar{s} = *$	$r = *$

$\bar{r}$  IS CHOSEN

$$V = \{\bar{p}, \bar{r}\}$$

WL in clauses 1,3 become improper

No other \*- or 1-literal to be chosen

Unit propagation:  $q, \bar{s}$  become true

<i>clause</i>	$\lambda_{c1}$	$\lambda_{c2}$
$p \vee q \vee r$	$r = 0$	$q = \cancel{*} 1$
$p \vee \neg q \vee s$	$s = *$	$\bar{q} = *$
$p \vee \neg r \vee \neg s$	$\bar{s} = \cancel{*} 1$	$r = 0$

# UNIT PROPAGATION LEADS TO BACKTRACKING

$$V = \{\bar{p}, \bar{r}, q, \bar{s}\}$$

WL in clause 2 becomes improper

No other \*- or 1-literal to be chosen

No unit propagation is possible: clause 2 is false

<i>clause</i>	$\lambda_{c1}$	$\lambda_{c2}$
$p \vee q \vee r$	$r = 0$	$q = 1$
$p \vee \neg q \vee s$	$s = 0$	$\bar{q} = 0$
$p \vee r \vee \neg s$	$\bar{s} = 1$	$r = 0$



# FAST BACKTRACKING

$V$  is contracted to last choice point

$$V = \{\cancel{\bar{p}}, \cancel{\bar{r}}, \cancel{q}, \cancel{\bar{s}}\} \quad \{\bar{p}, r\}$$

<i>clause</i>	$\lambda_{c1}$	$\lambda_{c2}$
$p \vee q \vee r$	$r = 1$	$q = *$
$p \vee \neg q \vee s$	$s = *$	$\bar{q} = *$
$p \vee r \vee \neg s$	$\bar{s} = *$	$r = 1$

Only affected WLs had to be recomputed

No need to reestablish previous context from a stack of contexts

Very quick backtracking

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# IMPROVEMENTS TECHNIQUES FROM CHAFF

- Learning new clauses
- VSDIS Heuristics
- Random restarts
- Backjumping

# Learning

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  - We learn that the clauses involved have enough information to avoid the mistake
- We can added learned information to the problem
- **Learning means adding new clauses**, without adding new variables

# LEARNING 1: BAD CHOICES

Suppose we had choices

$$V = \{\bar{p}, \bar{r}\}$$

which after propagation led to

$$V = \{\bar{p}, \bar{r}, q, \bar{s}, s\}$$

That is, in that context we learned that we cannot have both  $\bar{p}$  and  $\bar{r}$ .

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That is, in that context we learned that we cannot have both  $\bar{p}$  and  $\bar{r}$ .

Add the new clause:

$$p \vee r$$

# LEARNING 1: PROPERTIES

- From a closed branch with choices  $\lambda_1, \dots, \lambda_k$ , learn

$$\bar{\lambda}_1 \vee \dots \vee \bar{\lambda}_k$$

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  - it will only be used if  $k - 1$  literals occur in another branch



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- Theorem: proofs with DPLL + Learning2 can polynomially simulate full resolution proofs

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  - SATO Heuristics** is a variation of MOM. Let  $f(p)$  be 1 plus the number of clauses of smallest size which contain  $p$ . Choose  $p$  that maximizes  $f(p) * f(\neg p)$ . Choose  $p$  if  $f(p) > f(\neg p)$ ;  $\neg p$  otherwise.



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- Low overheads: counters updated only during learning

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- This problem is avoided if learned formulas are kept

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- Empirically checked: this brings efficiency gains

# Backjumping

# BACKJUMPING VIA EXAMPLES

- Suppose we have the partial valuation  
 $\{(\bar{p}, \top), (\bar{r}, \top), (a, \top), (q, p \vee q \vee r), (\bar{s}, p \vee r \vee \neg s), (s, p \vee \neg q \vee s)\}$

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# NEXT ISSUE

- 1 SAT
  - A Brief History of SAT Solvers
- 2 EMPIRICAL PROPERTIES
- 3 MAXSAT
- 4 THE DPLL ALGORITHM
  - DPLL and Resolution
- 5 IMPROVEMENTS TO DPLL
  - Watched Literals
  - Further Techniques
- 6 CONCLUSION

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- But the techniques learned from DPLL are incorporated in new techniques



# SAT IS NOT A PANACEA

- Reduction to SAT may be ok for some NPc problems, but ...
  - ... some NPc problems with **no known** polynomial SAT-reduction.

E.g. Answer Set Programming
  - ... some NPc problems with **no efficient** polynomial SAT-reduction.

E.g. Probabilistic SAT