

# Vladimir Baikalov

Machine Learning Engineer/Deep Learning Engineer

✉: [nonameuntitled159@gmail.com](mailto:nonameuntitled159@gmail.com)  
in: [linkedin.com/in/noname-untitled](https://www.linkedin.com/in/noname-untitled)  
🐙: [github.com/NonameUntitled](https://github.com/NonameUntitled)  
📌: [t.me/noname\\_untitled](https://t.me/noname_untitled)

## Work experience

### Machine Learning Engineer/[Google, YouTube](#).

January 2023 - Present

Paris, France

**Relevant areas:** Transformers, Highload, Large Language Models (LLMs)

Developed algorithm for video games detection for shorts. The final model achieved **4% recall boost without precision drop** and allowed to **conduct fine-tune more frequently**.

Currently working on **deployment of LLMs** in the production including improvement of **re-training and distillation** pipelines.

### Deep Learning Engineer/[Yandex Technology](#).

August 2021 - December 2022

Moscow, Russia

**Relevant areas:** Transformers, Highload, Recommended Systems

Transferred ML model from experimental setup (Python, Pytorch) to production framework (C++, YNMT). Supported weekly continuous finetuning process for in **Yandex.Ads**. **It was applied in production**. This model increased **GMV up to 1.5%** and a number of **clicks up to 5%**. The result is verified by AB tests and experiments.

Applied encoder-based models for improving personalized ads and search recommendations. Current solution **boosts production metric up to 6%**.

Implement multiprocessing Python package (YtReader) for fast and convenient data preprocessing. The final solution reduced the time required for models training/evaluating **up to 5 times**.

### Machine Learning Engineer/[Huawei R&D Dept](#).

March 2020 - July 2021

Saint-Petersburg, Russia

**Relevant areas:** Object Detection/Tracking, Digital Sound Processing, Optical Character Recognition.

Algorithm for vehicles trajectories prediction using radar data only. This approach now is being used in a real-world application. Proposed solution **over-performs the previous algorithm on 44%**.

Car occupation algorithm for outdoor and underground parking lots based on detection and tracking algorithms. This solution was presented to the product team for further implementation in the product.

Algorithm for the knuckle-knock sound pattern detection. Proposed architecture achieved **90% Precision** and **95% Recall**. With touch sensors usage Precision was improved up to **94%**.

### Researcher/[ITMO University, ML Lab](#)

September 2020 - July 2021

Saint-Petersburg, Russia

**Relevant areas:** Reinforcement Learning

Developed multi-agent policy-based algorithm **REM (Reinforce, Embedding, Monte-Carlo)** for baggage handling system (BHS), which over-performs previous approaches. This result was statistically proven with received **p-value less than 0.01**.

The paper, «**Multi-Agent Deep Reinforcement Learning-Based Algorithm For Fast Generalization On Routing Problems**», with the partial description of this project, was **published on the YSC 2021 conference**. This project was held in **collaboration with Aalto University, Finland**.

## Education

### Master degree/[Skoltech, DS major](#)

September 2021 - Present

Moscow, Russia

Current GPA: 5.00/5.00

Thesis project: Attention mechanism acceleration via tensor and matrix decompositions

### Bachelor degree/[ITMO University, CS major](#)

September 2017 - August 2021

Saint-Petersburg, Russia

GPA: 4.65/5.00

Thesis project: Implementing multi-agent policy-based algorithm for conveyor systems

## Skills

### Programming languages

Proficient: Python, C++

Advanced: Java, Bash, SQL

### Technologies

Proficient: Pytorch, Tensorflow

Advanced: Airflow, PySpark

### Extra

English: IELTS C1 Certified

ICPC Contest Volunteering