Expectation maximization of a linear dynamical system with a separate offset for each data set and an emissions matrix with columns that sum to 1

The goal of this derivation is to find the EM update for the C and $d^{(i)}$ parameters of an LDS. Specifically, we want to fit a separate $d^{(i)}$ for each data set. Finally, we also want to restrict C such that all the columns sum to 1.

LDS equations where data sets indexed with i

$$\begin{aligned} & \boldsymbol{x}_{t}^{(i)} = A \boldsymbol{x}_{t-1}^{(i)} + B \boldsymbol{u}_{t}^{(i)} + \boldsymbol{w}_{t}^{(i)} \\ & \boldsymbol{y}_{t}^{(i)} = C \boldsymbol{x}_{t}^{(i)} + D \boldsymbol{u}_{t}^{(i)} + \boldsymbol{d}^{(i)} + \boldsymbol{v}_{t}^{(i)} \\ & \boldsymbol{w}_{t}^{(i)} \sim \mathcal{N}(0, Q), \, \boldsymbol{v}_{t}^{(i)} \sim \mathcal{N}(0, R) \end{aligned}$$

Consider the term of the complete data log likelihood L_y which deals with emissions y. This is taken from equation 73 in Jonathan's Kalman Filter tutorial. T is the number of time points and W is the number of worms (data sets). All vectors are assumed to be column vectors

$$L_{y} = \mathbb{E}\left[\sum_{t=1}^{T^{(i)}} \log \mathcal{N}(\boldsymbol{y}_{t}^{(i)}; C\boldsymbol{x}_{t}^{(i)} + D\boldsymbol{u}_{t}^{(i)} + \boldsymbol{d}^{(i)}, R)\right] = \\ -\frac{1}{2} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E}\left[(\boldsymbol{y}_{t}^{(i)} - C\boldsymbol{x}_{t}^{(i)} - D\boldsymbol{u}_{t}^{(i)} - \boldsymbol{d}^{(i)})^{\mathsf{T}} R^{-1} (\boldsymbol{y}_{t}^{(i)} - C\boldsymbol{x}_{t}^{(i)} - D\boldsymbol{u}_{t}^{(i)} - \boldsymbol{d}^{(i)})\right] \\ -\frac{1}{2} \sum_{i=1}^{W} T^{(i)} \log |2\pi R|$$

$$(1)$$

Expand the quadratic into all of its terms

$$L_{y} = -\frac{1}{2} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \begin{bmatrix} y_{t}^{(i)\intercal} R^{-1} y_{t}^{(i)} \\ -y_{t}^{(i)\intercal} R^{-1} C x_{t}^{(i)} - x^{(i)\intercal} C^{\intercal} R^{-1} y_{t}^{(i)} \\ -y_{t}^{(i)\intercal} R^{-1} D u_{t}^{(i)} - u_{t}^{(i)\intercal} D^{\intercal} R^{-1} y_{t}^{(i)} \\ -y_{t}^{(i)\intercal} R^{-1} d^{(i)} - d^{(i)\intercal} R^{-1} y_{t}^{(i)} \\ +x_{t}^{(i)\intercal} C^{\intercal} R^{-1} C x_{t}^{(i)} \\ +x_{t}^{(i)\intercal} C^{\intercal} R^{-1} D u_{t}^{(i)} + u_{t}^{(i)\intercal} D^{\intercal} R^{-1} C x_{t}^{(i)} \\ +x_{t}^{(i)\intercal} C^{\intercal} R^{-1} d^{(i)} + d^{(i)\intercal} R^{-1} C x_{t}^{(i)} \\ +u_{t}^{(i)\intercal} D^{\intercal} R^{-1} D u_{t}^{(i)} \\ +u_{t}^{(i)\intercal} D^{\intercal} R^{-1} d^{(i)} + d^{(i)\intercal} R^{-1} D u_{t}^{(i)} \\ +d^{(i)\intercal} R^{-1} d^{(i)} \end{bmatrix}$$

$$(2)$$

Because this entire term is a scalar, the entire thing can be written as a trace. Trace distributes across addition and matrix multiplication within a trace can be circularly permuted. Permute all the terms so that R^{-1} is on the left

$$L_{y} = -\frac{1}{2} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \begin{bmatrix} \operatorname{Tr} \left[R^{-1} \boldsymbol{y}_{t}^{(i)} \boldsymbol{y}_{t}^{(i)\intercal} \right] \\ -\operatorname{Tr} \left[R^{-1} C \boldsymbol{x}_{t}^{(i)} \boldsymbol{y}_{t}^{(i)\intercal} \right] - \operatorname{Tr} \left[R^{-1} \boldsymbol{y}_{t}^{(i)} \boldsymbol{x}^{(i)\intercal} C^{\intercal} \right] \\ -\operatorname{Tr} \left[R^{-1} D \boldsymbol{u}_{t}^{(i)} \boldsymbol{y}_{t}^{(i)\intercal} \right] - \operatorname{Tr} \left[R^{-1} \boldsymbol{y}_{t}^{(i)} \boldsymbol{u}_{t}^{(i)\intercal} D^{\intercal} \right] \\ -\operatorname{Tr} \left[R^{-1} \boldsymbol{d}^{(i)} \boldsymbol{y}_{t}^{(i)\intercal} \right] - \operatorname{Tr} \left[R^{-1} \boldsymbol{y}_{t}^{(i)} \boldsymbol{d}^{(i)\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} C \boldsymbol{x}_{t}^{(i)} \boldsymbol{x}_{t}^{(i)\intercal} C^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} C \boldsymbol{x}_{t}^{(i)} \boldsymbol{u}_{t}^{(i)\intercal} D^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \boldsymbol{d}^{(i)} \boldsymbol{x}_{t}^{(i)\intercal} C^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} C \boldsymbol{x}_{t}^{(i)} \boldsymbol{d}^{(i)\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \boldsymbol{d}^{(i)} \boldsymbol{u}_{t}^{(i)\intercal} D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \boldsymbol{u}_{t}^{(i)} \boldsymbol{d}^{(i)\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \boldsymbol{d}^{(i)} \boldsymbol{u}_{t}^{(i)\intercal} D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \boldsymbol{u}_{t}^{(i)} \boldsymbol{d}^{(i)\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \boldsymbol{d}^{(i)} \boldsymbol{d}^{(i)\intercal} \right] \end{bmatrix}$$

Distribute the expectation and the sums

$$L_{y} = -\frac{1}{2} \begin{bmatrix} \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{y}_{t}^{(i)} \mathbf{y}_{t}^{(i)\intercal} \right] \right] \\ -\operatorname{Tr} \left[R^{-1} C \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{x}_{t}^{(i)} \mathbf{y}_{t}^{(i)\intercal} \right] \right] - \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{y}_{t}^{(i)} \mathbf{x}^{(i)\intercal} \right] \right] C^{\intercal} \right] \\ -\operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)} \mathbf{y}_{t}^{(i)\intercal} \right] \right] - \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{y}_{t}^{(i)} \mathbf{u}_{t}^{(i)\intercal} \right] \right] D^{\intercal} \right] \\ -\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \mathbf{d}^{(i)} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{y}_{t}^{(i)\intercal} \right] \right] - \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{y}_{t}^{(i)} \right] d^{(i)\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)} \mathbf{x}_{t}^{(i)\intercal} \right] C^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} C \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{x}_{t}^{(i)} \mathbf{u}_{t}^{(i)\intercal} \right] D^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} d^{(i)} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{x}_{t}^{(i)\intercal} \right] D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)\intercal} \right] D^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} d^{(i)} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)\intercal} \right] D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)\intercal} \right] d^{(i)\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)\intercal} \right] D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)\intercal} \right] d^{(i)\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)\intercal} \right] D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\mathbf{u}_{t}^{(i)\intercal} \right] d^{(i)\intercal} \right]$$

apply the expectation and calculate the following suff stats. Note that Y and \tilde{Y} get modified by imputing missing y values, though no other stats are affected. I skip that here, but adjust in the code.

$$Y = \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{y}_{t}^{(i)} \boldsymbol{y}_{t}^{(i)\mathsf{T}} \right] \qquad \tilde{Y} = \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{x}_{t}^{(i)} \boldsymbol{y}_{t}^{(i)\mathsf{T}} \right] \qquad \bar{Y}^{(i)} = \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{y}_{t}^{(i)\mathsf{T}} \right]$$

$$M_{(1,T)} = \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{x}_{t}^{(i)} \boldsymbol{x}_{t}^{(i)\mathsf{T}} \right] \qquad U_{y} = \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{u}_{t}^{(i)} \boldsymbol{y}_{t}^{(i)\mathsf{T}} \right] \qquad \bar{M}^{(i)\mathsf{T}} = \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{x}_{t}^{(i)\mathsf{T}} \right]$$

$$U_{(1,T)} = \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{u}_{t}^{(i)} \boldsymbol{u}_{t}^{(i)\mathsf{T}} \right] \qquad \tilde{U}_{(1,T)} \sum_{i=1}^{W} \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{u}_{t}^{(i)} \boldsymbol{x}_{t}^{(i)\mathsf{T}} \right] \qquad \bar{U}^{(i)} = \sum_{t=1}^{T} \mathbb{E} \left[\boldsymbol{u}_{t}^{(i)\mathsf{T}} \right]$$

$$(5)$$

$$L_{y} = -\frac{1}{2} \begin{bmatrix} \operatorname{Tr} \left[R^{-1} Y \right] \\ -\operatorname{Tr} \left[R^{-1} C \tilde{Y} \right] - \operatorname{Tr} \left[R^{-1} \tilde{Y}^{\intercal} C^{\intercal} \right] \\ -\operatorname{Tr} \left[R^{-1} D U_{y} \right] - \operatorname{Tr} \left[R^{-1} U_{y}^{\intercal} D^{\intercal} \right] \\ -\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \tilde{Y}^{(i)}^{\intercal} \right] - \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \tilde{Y}^{(i)} \boldsymbol{d}^{(i)}^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \tilde{Y}^{(i)}^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} C \tilde{U}_{(1,T)}^{\intercal} D^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \tilde{M}^{(i)}^{\intercal} C^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} C \sum_{i=1}^{W} \tilde{M}^{(i)} \boldsymbol{d}^{(i)}^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \tilde{U}^{(i)}^{\intercal} D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \tilde{U}^{(i)} \boldsymbol{d}^{(i)}^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \tilde{U}^{(i)}^{\intercal} D^{\intercal} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \tilde{U}^{(i)} \boldsymbol{d}^{(i)}^{\intercal} \right] \\ + \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} T^{(i)} \boldsymbol{d}^{(i)} \boldsymbol{d}^{(i)}^{\intercal} \right] \end{bmatrix}$$

Finally, add a lagrange multiplier such that the columns of C sum to the 1 vector. $-\boldsymbol{\lambda}^{\mathsf{T}}(1-C1) = -\boldsymbol{\lambda}^{\mathsf{T}}1 + \boldsymbol{\lambda}^{\mathsf{T}}C1$

$$L_{y} = -\frac{1}{2} \begin{bmatrix} \operatorname{Tr} \left[R^{-1} Y \right] \\ -\operatorname{Tr} \left[R^{-1} C \tilde{Y} \right] - \operatorname{Tr} \left[R^{-1} \tilde{Y}^{\mathsf{T}} C^{\mathsf{T}} \right] \\ -\operatorname{Tr} \left[R^{-1} D U_{y} \right] - \operatorname{Tr} \left[R^{-1} U_{y}^{\mathsf{T}} D^{\mathsf{T}} \right] \\ -\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \bar{Y}^{(i)\mathsf{T}} \right] - \operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \bar{Y}^{(i)} \boldsymbol{d}^{(i)\mathsf{T}} \right] \\ +\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \bar{Y}^{(i)\mathsf{T}} C^{\mathsf{T}} \right] + \operatorname{Tr} \left[R^{-1} C \tilde{U}_{(1,T)}^{\mathsf{T}} D^{\mathsf{T}} \right] \\ +\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \bar{M}^{(i)\mathsf{T}} C^{\mathsf{T}} \right] + \operatorname{Tr} \left[R^{-1} C \sum_{i=1}^{W} \bar{M}^{(i)} \boldsymbol{d}^{(i)\mathsf{T}} \right] \\ +\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \bar{U}^{(i)\mathsf{T}} D^{\mathsf{T}} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \bar{U}^{(i)} \boldsymbol{d}^{(i)\mathsf{T}} \right] \\ +\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} \boldsymbol{d}^{(i)} \bar{U}^{(i)\mathsf{T}} D^{\mathsf{T}} \right] + \operatorname{Tr} \left[R^{-1} D \sum_{i=1}^{W} \bar{U}^{(i)} \boldsymbol{d}^{(i)\mathsf{T}} \right] \\ +\operatorname{Tr} \left[R^{-1} \sum_{i=1}^{W} T^{(i)} \boldsymbol{d}^{(i)} \boldsymbol{d}^{(i)\mathsf{T}} \right] \end{bmatrix}$$

$$(7)$$

Take the derivative of L_y with respect to C, λ , and $d^{(i)}$ using the trace derivative equations in the appendix. Treat D as a constant. Note that all the transposed terms end up with the same derivative. Don't forget the $-\frac{1}{2}$ in front

$$\frac{\partial L_{y}}{\partial C} = R^{-1}\tilde{Y}^{\mathsf{T}} - R^{-1}CM_{(1,T)} - R^{-1}D\tilde{U}_{(1,T)} - R^{-1}\sum_{i=1}^{W} \mathbf{d}^{(i)}\bar{M}^{(i)\mathsf{T}} + \lambda \mathbf{1}^{\mathsf{T}} \\
\frac{\partial L_{y}}{\partial C} = C\mathbf{1} - \mathbf{1} \\
R^{-1}\bar{Y}^{(i)} - R^{-1}C\bar{M}^{(i)} - R^{-1}D\bar{U}^{(i)} - T^{(i)}R^{-1}\mathbf{d}^{(i)}$$
(8)

Set all terms to 0, multiply by R and gather terms that don't include C, λ , or $d^{(i)}$

$$\tilde{Y}^{\mathsf{T}} - D\tilde{U}_{(1,T)} = CM_{(1,T)} + \sum_{i=1}^{W} \mathbf{d}^{(i)} \bar{M}^{(i)\mathsf{T}} - R \lambda 1^{\mathsf{T}}
1 = C1
\bar{Y}^{(i)} - D\bar{U}^{(i)} = C\bar{M}^{(i)} + T^{(i)} \mathbf{d}^{(i)}$$
(9)

Transpose and rewrite as a linear equation. Because R is diagonal, we could solve this equation column by column and treat R like a scalar. However, all it does it change the amplitude of λ , without affecting any other parameter. We don't use λ anywhere so we can safely remove the -R term.

$$\tilde{Y} - \tilde{U}_{(1,T)}^{\mathsf{T}} D^{\mathsf{T}} = M_{(1,T)} C^{\mathsf{T}} + \bar{M}^{(i)} \sum_{i=1}^{W} \mathbf{d}^{(i)\mathsf{T}} + 1 \boldsymbol{\lambda}^{\mathsf{T}} (-R)
1^{\mathsf{T}} = 1^{\mathsf{T}} C^{\mathsf{T}}
\bar{Y}^{(i)\mathsf{T}} - \bar{U}^{(i)\mathsf{T}} D^{\mathsf{T}} = \bar{M}^{(i)\mathsf{T}} C^{\mathsf{T}} + T^{(i)} \mathbf{d}^{(i)\mathsf{T}} \tag{10}$$

$$\begin{bmatrix} \tilde{Y} - \tilde{U}_{(1,T)}^{\mathsf{T}} D^{\mathsf{T}} \\ 1^{\mathsf{T}} \\ \bar{Y}^{(i)\mathsf{T}} - \bar{U}^{(i)\mathsf{T}} D^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} M_{(1,T)} & 1 & \bar{M}^{(1)} & \cdots & \bar{M}^{(W)} \\ 1^{\mathsf{T}} & 0 & 0 & 0 & 0 & 0 \\ \bar{M}^{(1)\mathsf{T}} & 0 & T^{(1)} & 0 & 0 \\ \vdots & 0 & 0 & \ddots & 0 \\ \bar{M}^{(W)\mathsf{T}} & 0 & 0 & 0 & T^{(W)} \end{bmatrix} \begin{bmatrix} C^{\mathsf{T}} \\ \boldsymbol{\lambda}^{\mathsf{T}} \\ \boldsymbol{d}^{(1)\mathsf{T}} \\ \vdots \\ \boldsymbol{d}^{(W)\mathsf{T}} \end{bmatrix}$$
(11)

Here is an example with two data sets

$$\begin{bmatrix} \tilde{Y} - \tilde{U}_{(1,T)}^{\mathsf{T}} D^{\mathsf{T}} \\ 1^{\mathsf{T}} \\ \bar{Y}^{(1)\mathsf{T}} - \bar{U}^{(1)\mathsf{T}} D^{\mathsf{T}} \\ \bar{Y}^{(2)\mathsf{T}} - \bar{U}^{(2)\mathsf{T}} D^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} M_{(1,T)} & 1 & \bar{M}^{(1)} & \bar{M}^{(2)} \\ 1^{\mathsf{T}} & 0 & 0 & 0 \\ \bar{M}^{(1)\mathsf{T}} & 0 & T^{(1)} & 0 \\ \bar{M}^{(2)\mathsf{T}} & 0 & 0 & T^{(2)} \end{bmatrix} \begin{bmatrix} C^{\mathsf{T}} \\ \boldsymbol{\lambda}^{\mathsf{T}} \\ \boldsymbol{d}^{(1)\mathsf{T}} \\ \boldsymbol{d}^{(2)\mathsf{T}} \end{bmatrix}$$
(12)

Solving for R

Derivative rules are in the appendix

$$\frac{\partial L_{y}}{\partial R^{-1}} = -\frac{1}{2} \begin{bmatrix}
Y \\
-C\tilde{Y} - \tilde{Y}^{\mathsf{T}}C^{\mathsf{T}} \\
-DU_{y} - U_{y}^{\mathsf{T}}D^{\mathsf{T}} \\
-\sum_{i=1}^{W} \boldsymbol{d}^{(i)}\bar{Y}^{(i)\mathsf{T}} - \sum_{i=1}^{W} \bar{Y}^{(i)}\boldsymbol{d}^{(i)\mathsf{T}} \\
+CM_{(1,T)}C^{\mathsf{T}} \\
+D\tilde{U}_{(1,T)}C^{\mathsf{T}} + C\tilde{U}_{(1,T)}^{\mathsf{T}}D^{\mathsf{T}} \\
+\sum_{i=1}^{W} \boldsymbol{d}^{(i)}\bar{M}^{(i)\mathsf{T}}C^{\mathsf{T}} + C\sum_{i=1}^{W} \bar{M}^{(i)}\boldsymbol{d}^{(i)\mathsf{T}} \\
+DU_{(1,T)}D^{\mathsf{T}} \\
+\sum_{i=1}^{W} \boldsymbol{d}^{(i)}\bar{U}^{(i)\mathsf{T}}D^{\mathsf{T}} + D\sum_{i=1}^{W} \bar{U}^{(i)}\boldsymbol{d}^{(i)\mathsf{T}} \\
+\sum_{i=1}^{W} T^{(i)}\boldsymbol{d}^{(i)}\boldsymbol{d}^{(i)\mathsf{T}}
\end{bmatrix} + \frac{1}{2}\sum_{i=1}^{W} T^{(i)}R \tag{13}$$

Set the derivative to 0 and solve for R

$$R = \frac{1}{\sum_{i=1}^{W} T^{(i)}} \begin{bmatrix} Y \\ -C\tilde{Y} - \tilde{Y}^{\mathsf{T}}C^{\mathsf{T}} \\ -DU_{y} - U_{y}^{\mathsf{T}}D^{\mathsf{T}} \\ -\sum_{i=1}^{W} \mathbf{d}^{(i)}\bar{Y}^{(i)\mathsf{T}} - \sum_{i=1}^{W} \bar{Y}^{(i)}\mathbf{d}^{(i)\mathsf{T}} \\ +CM_{(1,T)}C^{\mathsf{T}} \\ +D\tilde{U}_{(1,T)}C^{\mathsf{T}} + C\tilde{U}_{(1,T)}^{\mathsf{T}}D^{\mathsf{T}} \\ +\sum_{i=1}^{W} \mathbf{d}^{(i)}\bar{M}^{(i)\mathsf{T}}C^{\mathsf{T}} + C\sum_{i=1}^{W} \bar{M}^{(i)}\mathbf{d}^{(i)\mathsf{T}} \\ +DU_{(1,T)}D^{\mathsf{T}} \\ +\sum_{i=1}^{W} \mathbf{d}^{(i)}\bar{U}^{(i)\mathsf{T}}D^{\mathsf{T}} + D\sum_{i=1}^{W} \bar{U}^{(i)}\mathbf{d}^{(i)\mathsf{T}} \\ +\sum_{i=1}^{W} T^{(i)}\mathbf{d}^{(i)}\mathbf{d}^{(i)\mathsf{T}} \end{bmatrix}$$

$$(14)$$

Appendix

Trace and determinant derivatives

$$\frac{\partial}{\partial X} \operatorname{Tr} \left[AXB \right] = A^{\mathsf{T}} B^{\mathsf{T}} \tag{15}$$

$$\frac{\partial}{\partial X} \text{Tr} \left[A X^{\mathsf{T}} B \right] = B A \tag{16}$$

If C is the identity and A and B are symmetric

$$\frac{\partial}{\partial X} \operatorname{Tr} \left[A_{\operatorname{sym}} X B_{\operatorname{sym}} X^{\mathsf{T}} \right] = 2AXB \tag{17}$$

$$\frac{\partial}{\partial X^{-1}}\log|X| = -X\tag{18}$$