

- Standard Form Problem ①

$$\min f_0(x)$$

$$\text{s.t. } f_i(x) \leq 0, i = 1, \dots, m$$

$$h_i(x) = 0, i = 1, \dots, p$$

variable $x \in \mathbb{R}^n$, domain D , optimal value p^*

\Rightarrow Lagrangian: $L: \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$

with $\text{dom } L = D \times \mathbb{R}^m \times \mathbb{R}^p$

$$L(x, \lambda, v) = f_0(x) + \underbrace{\sum_{i=1}^m \lambda_i f_i(x)}_{\text{constraint function}} + \sum_{i=1}^p v_i \underbrace{h_i(x)}_{\text{equality}}$$

λ, v are Lagrange multiplier

- Lagrange dual function ②

$$g: \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$$

$$g(\lambda, v) = \inf_{x \in D} L(x, \lambda, v)$$

$$= \inf_{x \in D} (f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p v_i h_i(x))$$

g is concave, can be $-\infty$ for some λ, v

lower bound property: if $\lambda \succeq 0$, then $g(\lambda, v) \leq p^*$

①, ② \rightarrow convex problem

\rightarrow For a convex minimization problem with inequality constraints

$$\min_x f(x)$$

$$\text{s.t. } f_i(x) \leq 0, \quad i=1, \dots, m$$

\rightarrow The Lagrangian dual problem is

$$\underset{u}{\text{maximize}} \quad \inf_x (f(x) + \sum_{i=1}^m \alpha_i f_i(x))$$

$$\text{s.t. } \alpha_i \geq 0, \quad i=1, \dots, m$$

Then, For soft SVM

\rightarrow Primal problem: Δ

$$\min_{w, b, \xi} \quad \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i$$

$$\text{s.t. } y_i (w \cdot x_i + b) \geq 1 - \xi_i, \quad i = 1, 2, \dots, N$$

$$\xi_i \geq 0, \quad i = 1, \dots, N$$

→ Lagrangian dual problem:

$$\min_{\alpha} \quad \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j k(x_i, x_j) - \sum_{i=1}^N \alpha_i$$

$$\text{s.t. } \sum_{i=1}^N \alpha_i y_i = 0$$

$$0 \leq \alpha_i \leq C.$$

Derivation

Step 1 Lagrangian for Δ :

$$L(w, b, \xi, \alpha, u) \equiv \underbrace{\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i}_{f_0(x)} - \underbrace{\sum_{i=1}^N \alpha_i (y_i (w \cdot x + b) - 1 + \xi_i)}_{-f_1(x)} - \sum_{i=1}^N u_i \underbrace{\xi_i}_{h_i(x)}$$

and $\alpha_i \geq 0, u_i \geq 0$

$$\nabla_w L = w - \sum_{i=1}^N \alpha_i y_i x_i \quad \nabla_b L = - \sum_{i=1}^N \alpha_i y_i \quad \nabla_{\xi} L = C - \sum_{i=1}^N u_i - \sum_{i=1}^N \alpha_i$$

let $\nabla_w L = \nabla_b L = \nabla_\gamma L = 0$ and get $\min L = -\frac{1}{2} \sum_i \sum_j \alpha_i \alpha_j y_i y_j k(x_i, x_j) + \sum_i \alpha_i$

there is only α in it now, do $\max_{\alpha} L$, which is $\min -L$

finally we get the dual problem:

$$\min_{\alpha} \quad \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j k(x_i, x_j) - \sum_{i=1}^N \alpha_i$$

Step 2. $s.t. \Rightarrow \sum_{i=1}^N \alpha_i y_i = 0$

$$C - \alpha_i - u_i = 0$$

$$\alpha_i \geq 0$$

$$u_i \geq 0, i=1, \dots, N$$

$$\Rightarrow s.t. \quad 0 \leq \alpha_i \leq C$$

p.s we know $w = \sum_{i=1}^n \alpha_i y_i \phi(x_i)$

$$w^T w \Rightarrow \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \underbrace{\phi(x_i) \phi(x_j)}_{k(x_i, x_j)}$$

kernels:

Linear $\rightarrow k(x, z) = x^T z$

Polynomial $\rightarrow k(x, z) = (1 + x^T z)^d$

Radial Basis Function (rbf, gaussian kernel)

$$\rightarrow k(x, z) = e^{-\frac{\|x - z\|^2}{\sigma^2}}$$

\downarrow
kernel, x_i is the sample point
 x_j is the variable.

Exp $\rightarrow e^{\frac{-\|x-z\|}{\sigma}}$, Laplacian $\rightarrow e^{\frac{-\|x-z\|}{\sigma}}$, sigmoid kernel $\rightarrow \tanh(ax^T + c)$

Explanation of KKT

$$g \equiv \mathcal{L} \Rightarrow \inf_{x \in D} (f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p v_i h_i(x))$$

gradient vector parallel:

$$\nabla f = \lambda \nabla g \quad \text{用 } \nabla f \text{ 去寻找 } g \text{ 的切点}$$

$\min f \quad \text{且 } g=0$

case 1: Unconstrained local minimum occurs in the feasible region

$g(x^*) < 0$ (< 0 in feasible region)

$\nabla f(x^*) = 0$

case 2: Unconstrained local minimum lies outside the feasible region

$$g(x^*) = 0$$

$$-\nabla f(x^*) = \lambda \nabla_x g(x^*) \Rightarrow \text{相切}$$

$$\lambda \geq 0$$

KKT



Given the optimization problem:

$$\min_{x \in \mathbb{R}^2} f(x) \text{ s.t. } \underline{g(x) \leq 0}$$

$$\lambda \geq 0$$

$$\text{Define } \mathcal{L}(x, \lambda) = f(x) + \lambda g(x) \Rightarrow \nabla f(x) = \lambda \nabla g(x) \\ \nabla \mathcal{L} = 0 \Rightarrow \text{相切}$$

Then x^* a local minimum \Leftrightarrow there exists a unique λ^* s.t

$$\textcircled{1} \nabla_x \mathcal{L}(x^*, \lambda^*) = 0 \Rightarrow \text{相切} = \nabla f_0(x) + \sum \lambda g(x) + \sum \nu h(x) = 0$$

$$\textcircled{2} \lambda^* \geq 0$$

$$\textcircled{3} \lambda^* g(x^*) = 0 \Leftrightarrow \underline{\text{complementary slackness}}$$

$$\textcircled{4} g(x^*) \leq 0$$

If a dual variable is greater or equal than zero then the corresponding primal constraint must be tight

$$(x^* \int \alpha^* = 0)$$

U

kkT: ①, ②, ③, ④

$$\text{by } kkT \rightarrow w = \sum_{i=1}^N \alpha_i y_i x_i \text{ and } y_i (w_i x_i + b) - 1 = 0$$

$$\Rightarrow b = y_i - \sum_{i=1}^N \alpha_i y_i k(x_i, x) \Rightarrow f(x) = \text{sign} \left(\sum_{i=1}^N \alpha_i y_i k(x_i, x) + b \right)$$