## Daohan "Fred" Lu

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Seeking Internship in Computer Vision

**Education** 

Carnegie Mellon University

School of Computer Science

Pittsburgh, PA
12/2022

• Master of Science in Computer Vision

New York University
College of Arts and Science

• Bachelor of Arts in Economics and Computer Science

• GPA: 3.86/4.00

Work and Research Experience

NYU CILVR Lab (wp.nyu.edu/cilvr/) Advisor Prof. Rob Fergus

New York, NY

Research Assistant

05/2021 - Present

- Researched Machine Common Sense (MCS) [1, 2]: designed predictive models (VGG+LSTM) that detect and localize implausible physics events by comparing observations with predictions learned from plausible physics events. (Github)
- The predictive models generated interpretable "baselines" that estimated where and how strongly physics
  inconsistencies occur, which helped the MCS psychology team understand how predictive models detect
  inconsistencies.
- Achieved 84% True Positive and 73% True Negative rates on the Gravity physics test set.

NYU MMVC Lab (<u>mmvc.engineering.nyu.edu/</u>) Advisor Prof. Yi Fang

New York, NY

10/2019 - 08/2020

- Innovated lightweight MLPs dynamic initialized by a PointNet for 2x faster training and fine-tuning on 3D shape correspondence tasks while retaining the same level of accuracy compared to state of the art. (Paper [3])
- Designed MobileNet-SSD based models that provide real-time (>10/s) audio feedback to help the blind maintain social distance (Paper [2]) and help the blind with collaborative hand gestures (Paper [1], Talk).
- Created *Weakly Supervised Point-to-tell* (GitHub), which trained a weakly-supervised (categorical labels only) Resnet model to localize objects being pointed to by a blind person on a synthetic dataset.

## Avigilon, Motorola Solutions (avigilon.com/)

Research Engineer Intern

Somerville, MA 06/2019 - 08/2019

New York, NY

05/2021

- Trained and tested a specialized LeNet model that classified human false-positive detections from the camera's security cameras. Wrote C++ code to deploy the model on camera with temporal false-positive suppression logic, reducing human false-positive detections by ~40% on proprietary test datasets.
- Modeled enhanced versions of the Kalman Filter (UKF, EKF) with C++ and Python to evaluate their potential to improve object tracking and detection when integrated into the security cameras.

## **Research Papers**

- [1] Lu, Daohan, and Yi Fang. *Audi-Exchange: AI-Guided Hand-Based Actions to Assist Human-Human Interactions for the Blind and the Visually Impaired*. Ninth International Workshop on Assistive Computer Vision and Robotics (ACVR). 2021. View Paper, Talk@ICCV Workshop
- [2] Shrestha, Samridha, and Daohan Lu, et al. "Active Crowd Analysis for Pandemic Risk Mitigation for Blind or Visually Impaired Persons." Eighth International Workshop on Assistive Computer Vision and Robotics (ACVR). 2020. View Paper
- [3] Lu, Daohan, and Yi Fang. "Meta Deformation Network: Meta Functionals for Shape Correspondence." arXiv preprint arXiv:2006.14758 (2020). <u>View Paper</u>