1.1 Definitions and Terminology

- <u>Definition</u>: An equation containing the derivatives of one or more dependent variables, with respect to one or more independent variables, is called a **differential equation** (**DE**).
 - > Ordinary Differential Equation (ODE) contains only ordinary derivatives with respect to a single independent variable.
 - ➤ Partial Differential Equation (PDE) contains partial derivatives

The **order** of a differential equation is the order of the highest derivative in the equation.

ightharpoonup All $n^{ ext{th}}$ -order ordinary differential equations can be represented as a function

$$F\big(x,y,y',y'',\dots,y^{(n)}\big)=0$$

 \triangleright If it is possible to solve for $y^{(n)}$, we often also represent the differential equation by the normal form

$$\frac{d^n y}{dx^n} = f(x, y, y', \dots, y^{(n-1)})$$

A first-order differential equation can also be written in differential form using the conversion

$$\frac{dy}{dx} = -\frac{M(x,y)}{N(x,y)} \leftrightarrow M(x,y)dx + N(x,y)dy = 0.$$

*Note: while often thought of as "multiplying" both sides by dx, this is inaccurate. The exact process by which this works is highlighted in the section on separable differential equations.

An n^{th} -order differential equation is **linear** if it can be written as a linear combination of the derivatives,

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_o(x)y = g(x)$$

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• Example: Classify the following differential equations.

$$\frac{dy}{dx} + 5y = e^{x}$$
 -> 1st-order, linear, ODE
$$\frac{d^{4}y}{dt^{4}} + \left(\frac{dx}{dt}\right)^{5} = 2x + t$$
 -> 4th-order, non-linear, ODE
$$\frac{\partial z}{\partial x} + \frac{\partial z}{\partial y} = x^{2}y$$
 -> 1st-order, PDE
$$\frac{dy}{dx} + 3xy^{2} = x + 1$$
 -> 1st-order, non-linear, ODE
$$4\frac{d^{3}y}{dx^{3}} - \frac{dy}{dx} + x^{3}y = \sin x$$
 -> 3rd-order, linear, ODE

- <u>Definition</u>: Any function ϕ , defined on an interval I and having at least n continuous derivatives on I, which when substituted into $F(x, y, y', y'', ..., y^{(n)}) = 0$ reduces the equation to an identity, is called a **solution** of the equation on the interval I.
 - *A solution of a differential equation that is identically zero on an interval I is called a **trivial** solution.
- Example: Verify that the following are solutions on the interval $(-\infty, \infty)$

(a)
$$\frac{dy}{dt} = y^2 \sin t$$
; $y = \sec t$

$$LHS: \qquad \frac{dy}{dt} = \frac{d}{dt} (\sec t) = \sec t \tan t$$

$$RHS: \qquad y^2 \sin t = \sec^2 t \sin t = \sec t \tan t$$

Since the left-hand side and right-hand side are the same for all values of t, we have a solution on $(-\infty, \infty)$.

(b)
$$y'' + 2y' - 3y = 0$$
; $y = e^x$
LHS: $y'' + 2y' - 3y = e^x + 2e^x - 3e^x = 0$
RHS: 0

Since the left-hand side and right-hand side are the same for all values of x, we have a solution on $(-\infty, \infty)$.

- <u>Definition</u>: A solution of a differential equation that is represented in the form $y = \phi(x)$ is called an **explicit solution**.
- <u>Definition</u>: A relation G(x, y) = 0 is called an **implicit solution** of an ordinary differential equation on an interval I, if there exists at least one function $y = \phi(x)$ that satisfies the relation as well as the differential equation on I.

For this course, if we "arrive" at a solution of G(x, y) = 0, we will assume that there exists at least one function that satisfies the relation and the equation.

• Example: Show that on the interval (-2, 2), $x^2 + y^2 = 4$ is an implicit solution of the differential equation

$$\frac{dy}{dx} = -\frac{x}{y}$$

By implicit differentiation, we get

$$\frac{d}{dx}x^2 + \frac{d}{dx}y^2 = \frac{d}{dx}4 \quad \Rightarrow \quad 2x + 2y\frac{dy}{dx} = 0 \quad \Rightarrow \quad \frac{dy}{dx} = -\frac{2x}{2y} = -\frac{x}{y}$$

Families of Solutions:

We experienced problems like the following in Calculus, and solved them using integration.

$$y' = \cos x \rightarrow y = \sin x + c$$
$$y'' = 6x \rightarrow y' = 3x^2 + c_1 \rightarrow y = x^3 + c_1 x + c_2$$

In both cases, we ended up with arbitrary constants of integration. Both also represent (very) basic differential equations, so we would expect similar things to happen when solving a DE.

When solving a first-order differential equation F(x, y, y') = 0, we (*usually*) obtain a solution containing an arbitrary constant c, giving a **one-parameter family of solutions** G(x, y, c) = 0.

When solving an n^{th} -order differential equation, we seek an n-parameter family of solutions $G(x,y,c_1,c_2,...,c_n)=0$.

If every solution of an n^{th} -order ODE on an interval I can be obtained from $G(x, y, c_1, c_2, ..., c_n) = 0$, we say that the family is the **general solution** of the DE.

A solution that is free of arbitrary parameters is called a particular solution.

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Our overall goal for a differential equation is to answer the following questions:

- 1. Does a solution exist?
- 2. If a solution exists, is it unique?
- 3. If a solution exists, how do we find it?

The next two sections give us some tools to start answering those questions.

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