



Automotive Door Control System Design

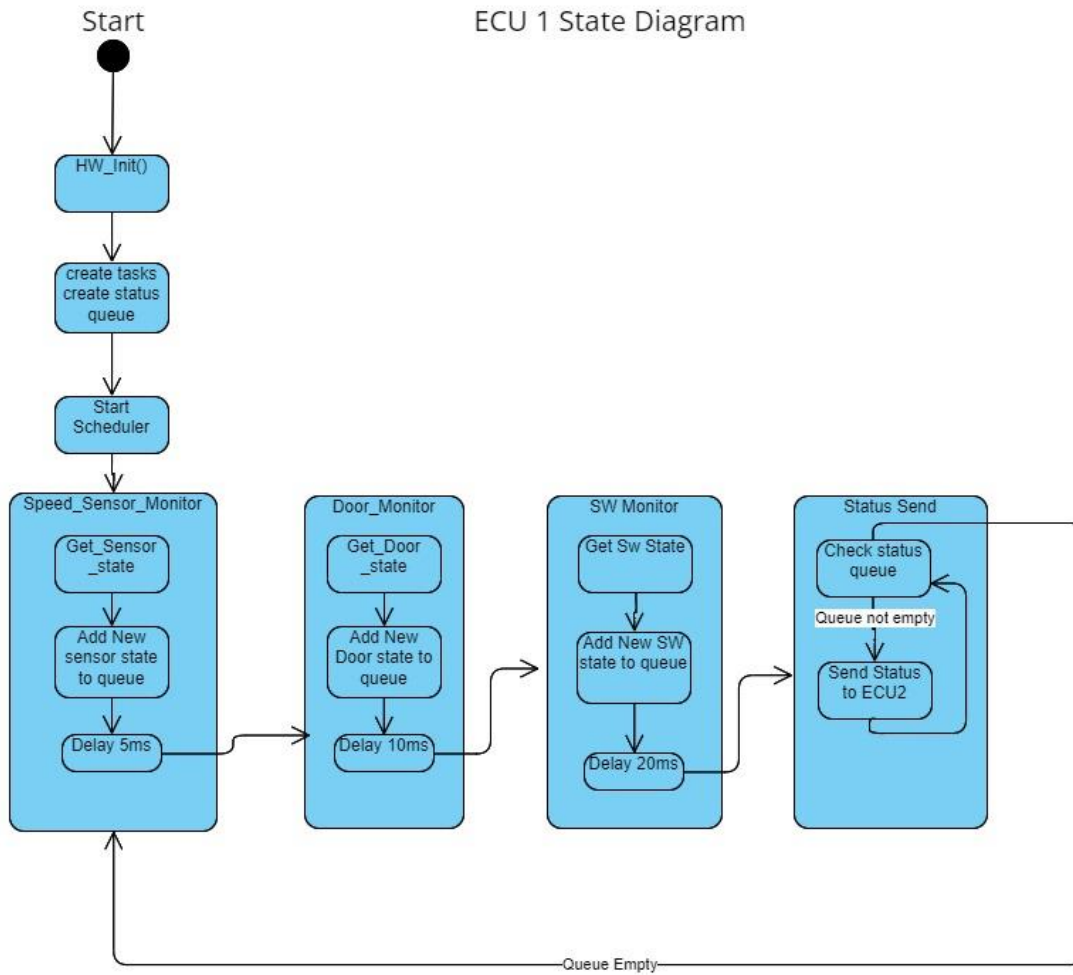
DYNAMIC DESIGN

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STATE MACHINE DIAGRAM

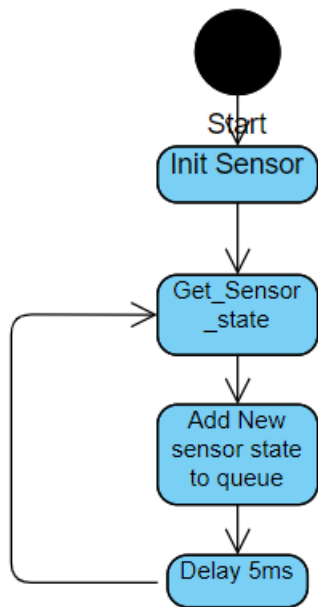
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ECU 1 State Diagram

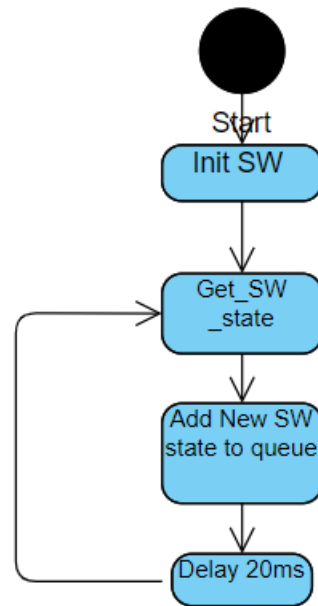


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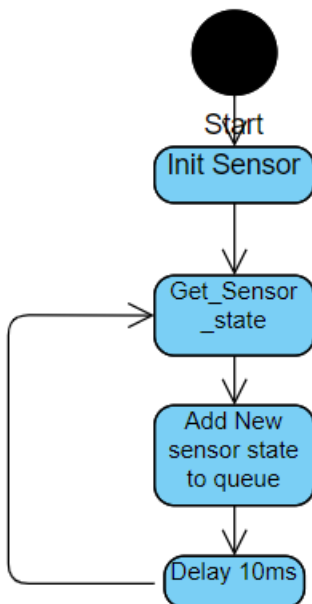
ECU₁ COMPONENTS STATE DIAGRAMS



Speed Sensor Monitor

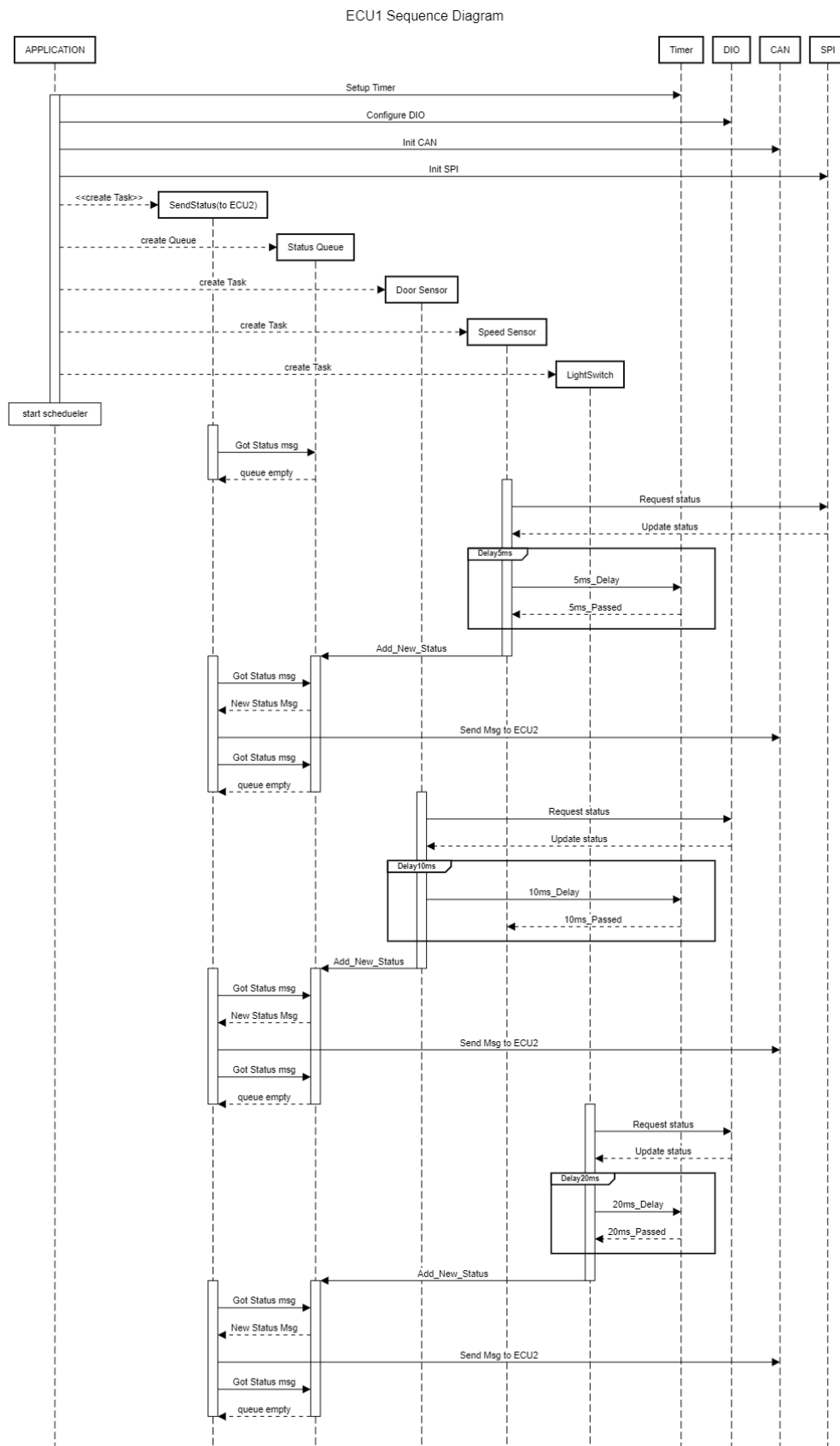


Light SW Monitor



Door Sensor Monitor

ECU1 SEQUENCE DIAGRAM



ECU₁ CPU LOAD

System has 4 tasks:

Door_Sensor_Monitor : exec time 15 us , period=10 ms

Speed_Sensor_Monitor : exec time 15us , period=5ms

Light_SW_Monitor : exec time 15 us, period=20 ms

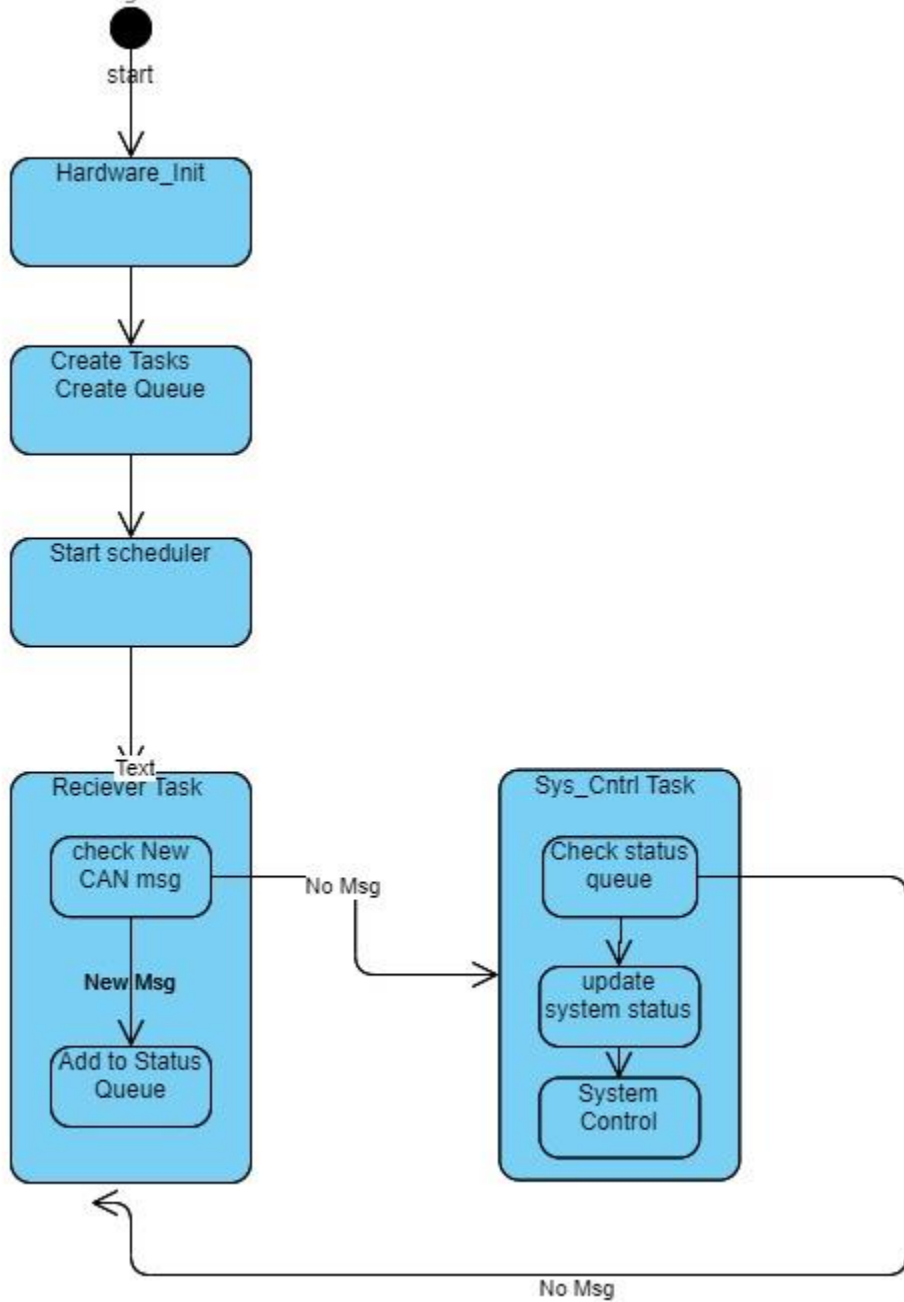
Send_Status_Task : exec time 18 us, period=5ms

HyperPeriod =20 ms.

CPU Load = $((0.015 \times 2 + 0.015 \times 4 + 0.015 + 0.018 \times 4) / 20) \times 100 = 0.885 \%$

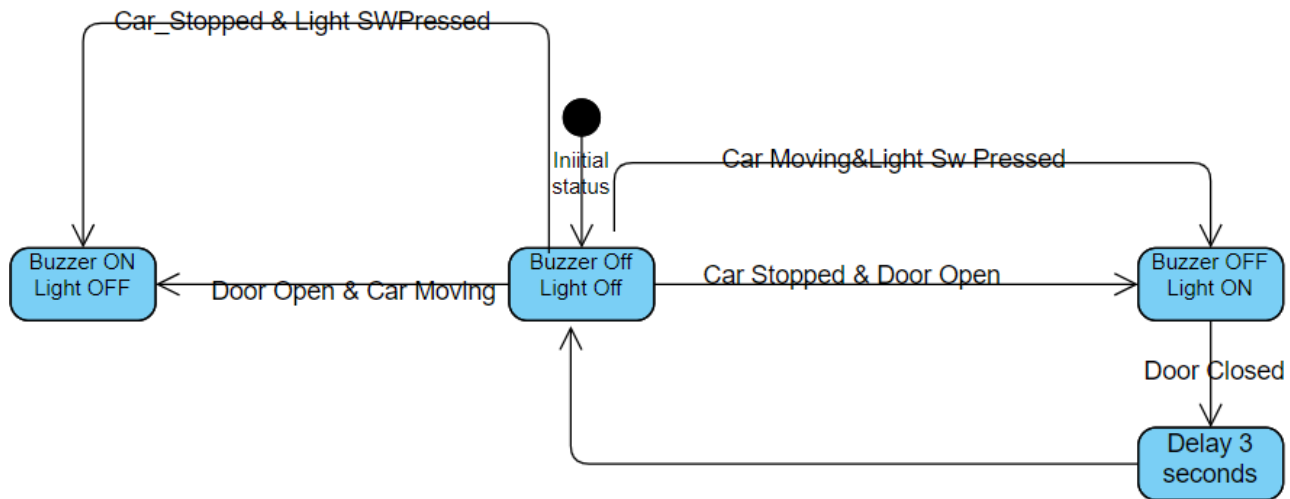
ECU₂ STATE DIAGRAM

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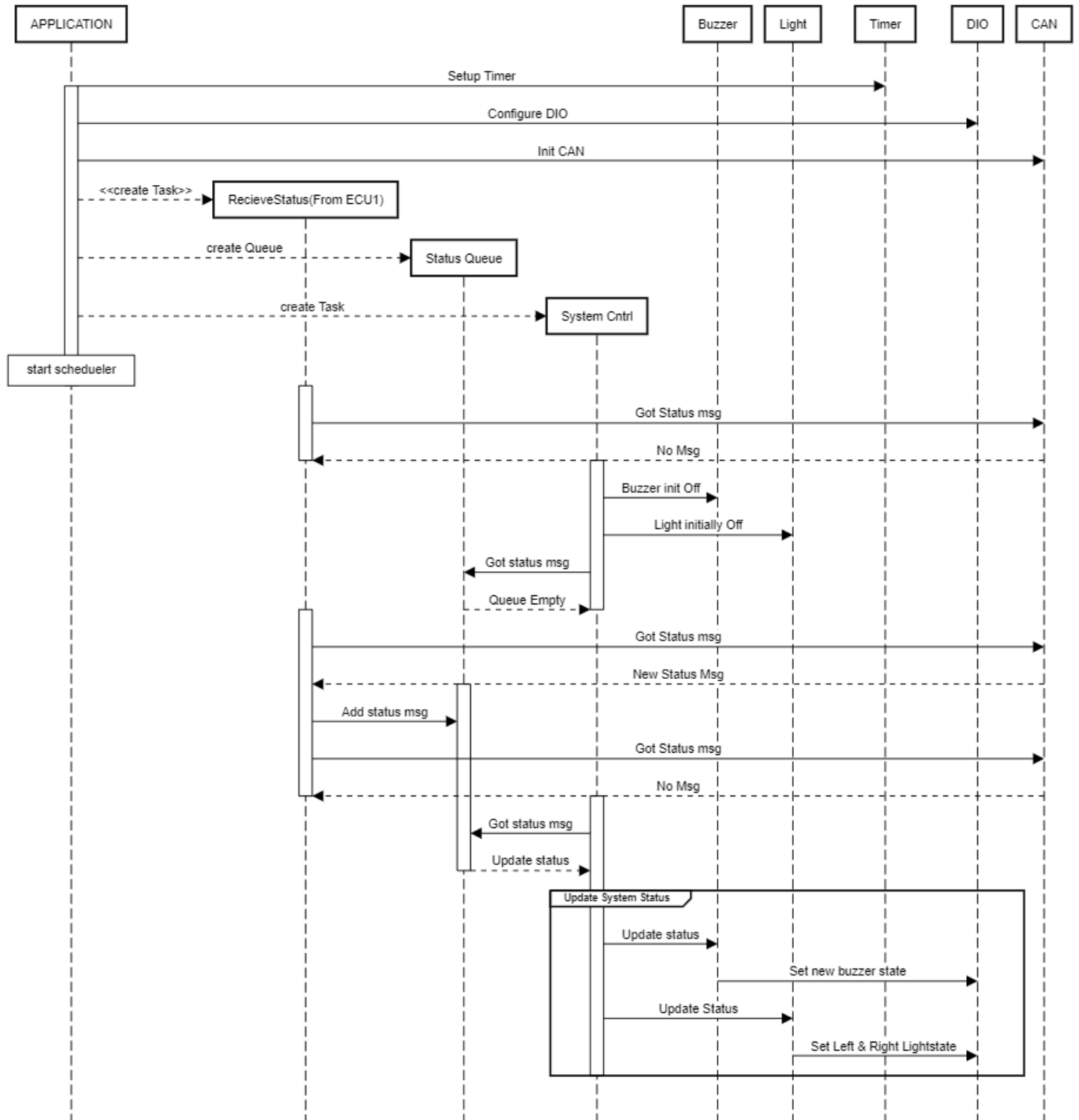
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System Control



ECU₂ SEQUENCE DIAGRAM

ECU₂ Sequence Diagram



ECU₂ CPU LOAD

System has two tasks :

RecvStatus_task : exe time= 18 us , period =5ms

SystemCntrl: exe time =15 us, period =5ms

Hyper period =5ms

CPU Load = $((0.015+0.018)/5) \times 100 = 0.66 \%$

NOTE: task exe time was assumed according to real exec time for similar tasks from RTOS project.

SYSTEM BUS LOAD

Speed Sensor Status (5ms)=200 message/second

Door Sensor Status(10ms)=100 message/second

Light Sw Status(20ms) = 50 message /second

Total messages on bus = 350 message/second.

Assuming simple can protocol with 125 bit frame length at speed 500kbit/s:

Bus Load= $((350 \times 250)/(1000 \times 1000)) \times 100 = 8.75\%$