# Drowsiness Detection Using Deep Learning

NTI AI&IOT TRACK FINAL PROJECT





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## Introduction Part 01



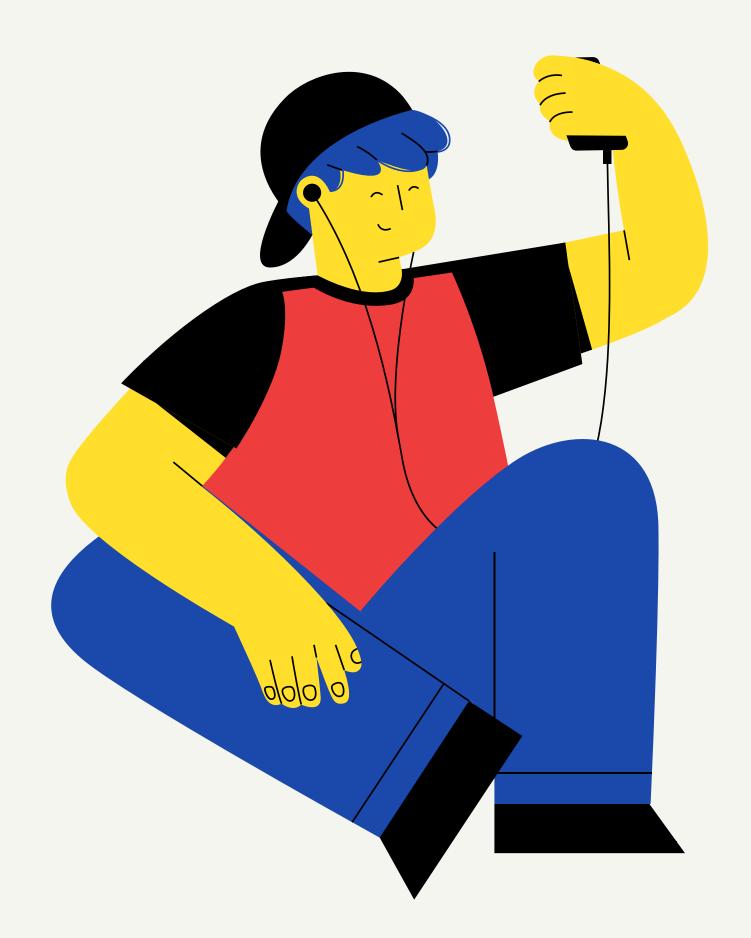


## Background

#### Overview of the project

With increase in the number of vehicles, the occurrence of traffic and accidents is also increasing gradually. Traffic collisions are a major source of deaths every year. The National Crime Record Bureau (NCRB) reports 496,762 road-related traffic collisions in all states

A computer vision system that can automatically detect driver drowsiness in a real-time video stream and then play an alarm if the driver appears to be drowsy for the driver and his manager.



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### The Problem



What we want to solve

The main goal of this work is to determine whether a driver is drowsy or awake.



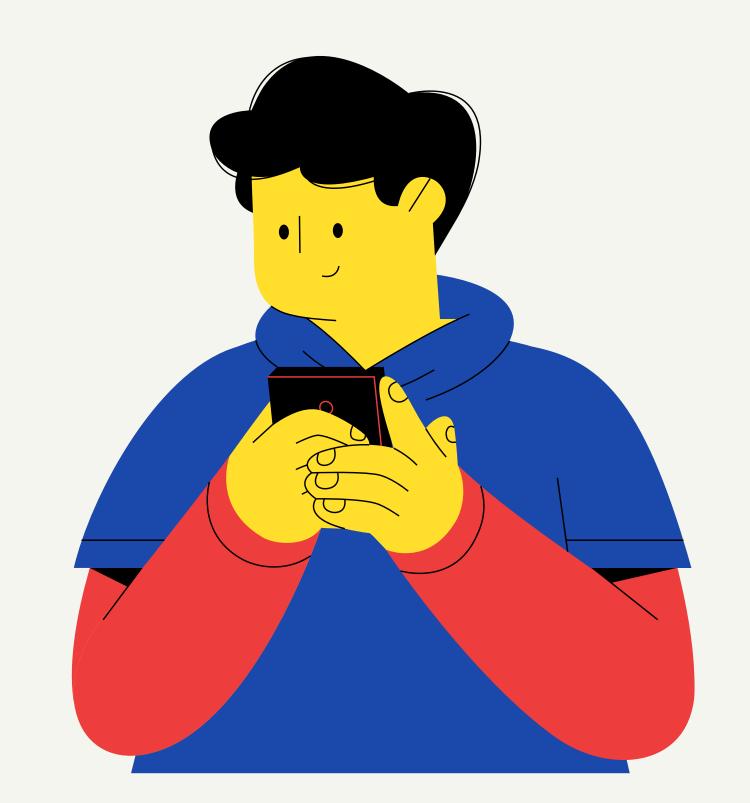
Hypothesis

Utilization of deep learning architectures will enhance the accuracy of both face detection and drowsiness detection.





## Our Data Part 02





#### **(>**

## Data Collection

## Which Datasets we used?

#### Driver Drowsiness Dataset:

Extracted and cropped faces of drivers from the videos of the Real-Life Drowsiness Dataset. The frames were extracted from videos as images using VLC software. After that, the Viola-Jones algorithm has been used to extract the region of interest from captured images.

#### yawn\_eye\_dataset:

A dataset of 2900 sample image divided into 4 categories closed\_eye, open\_eye, yawn, and non\_yawn it's used to predict drivers drowsiness throw these features.

#### Drowsiness Prediction Dataset:

A dataset of 2900 sample image has two labels: Fatigue which tends to drown and Active which is not.

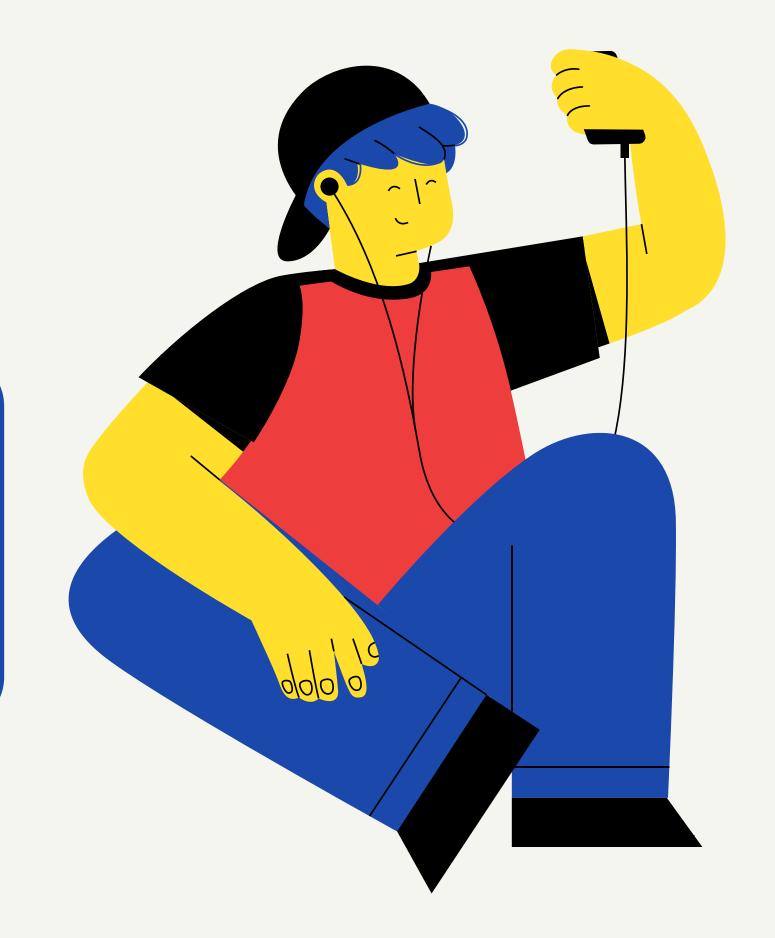
#### NITYMED

130 videos, captured in Patras, Greece, displaying drivers in real cars, moving under nighttime conditions where drowsiness detection is more important.



## Data Sequence

The avilable three data sets that have been mentioned didn't give us the required accuracy in this application so we tend to generate our custom data set.





### Data Sequence

#### yawn\_eye\_dataset

Only the two folders of yawn and nonyawn were used.

#### NITYMED dataset

frames extracted from the dataset's videos were preprocessed and used as a supplementary data for better learning

#### MTCNN Face Extraction

MTCNN (Multi -Task Cascaded Convolutional Neural Networks) for cropping faces from images to be easy for the model to learn.





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### Data Preprocessing



Turning Video Inputs into images frames

Face Recognition and extraction

Resizing the images

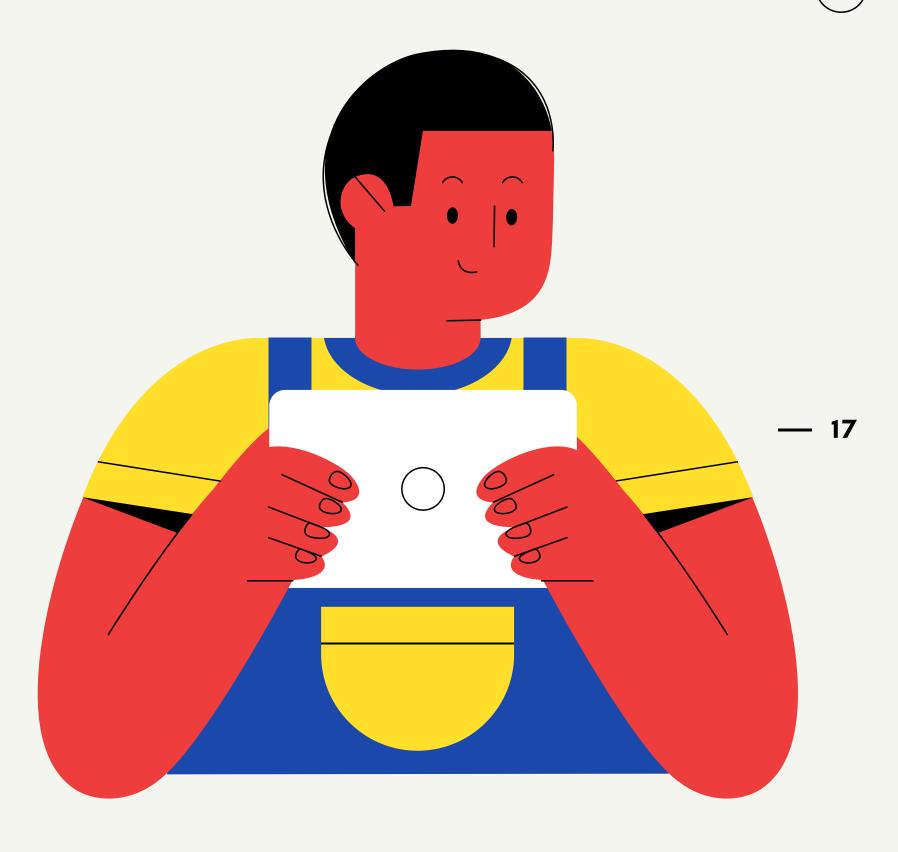
Data Augmentation





## Data Augmentation

- Based on our experience, it is not the good choice for this data set.
- Our data is augmented and used for the model training but it results with a bad test accuracy in the real time.
- So, in our work we relyed on the original data set without augmenation.





### Final Data Set

The generated data set contains three

classes:

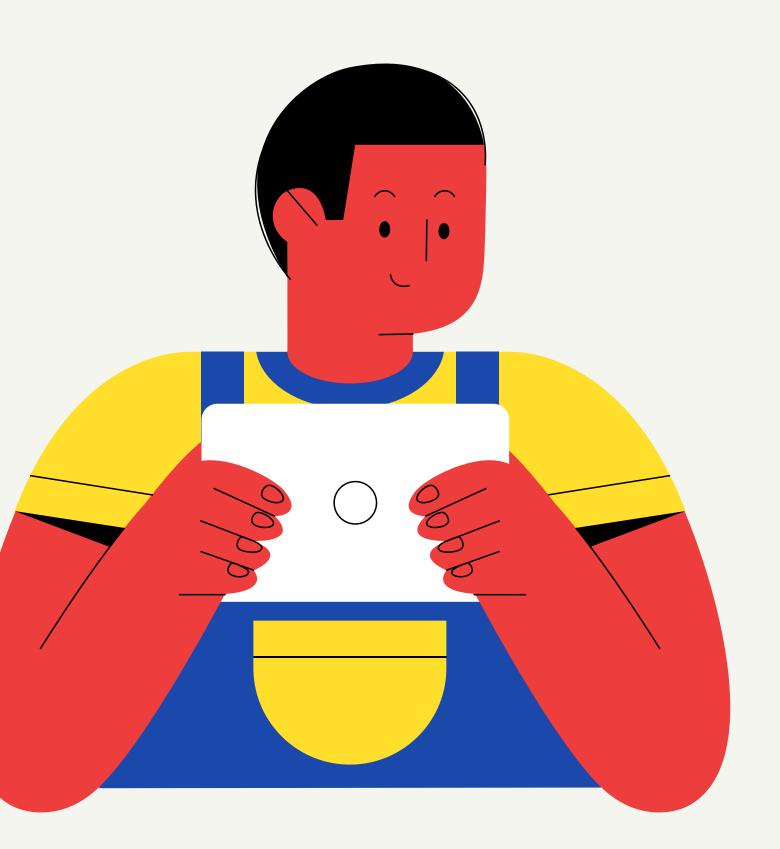
Active: 1580 Images

• Sleep:1230 Images

• Yawn: 1013 Images

**Data Link** 









### Transfer learining using different models for best model selection



#### Resnet50

20 EPOCHS

TRAIN:.75 VALID:0.74 TEST:0.73

#### Resnet152.

20 EPOCHES

TRAIN: 0.942 VALID: 0.934 TEST: 0.541



#### **INCEPTIIONV3**

20 EPOCHES

TRAIN:0.8239 VALID:0.8062 TEST:0.727





### Transfer learining using different models for best model selection

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#### DenseNet121

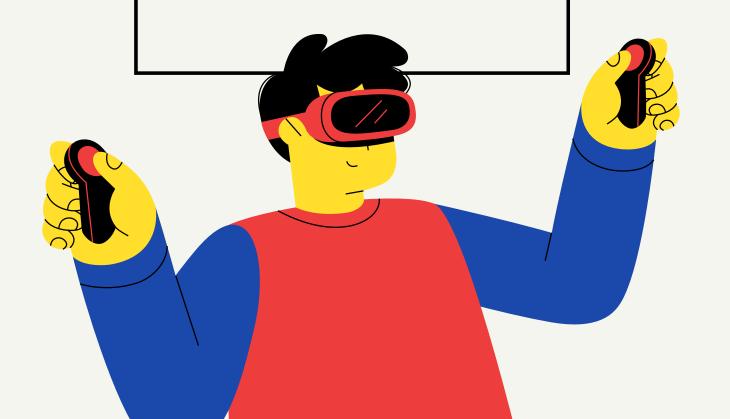
TRAIN:0.82 VALID:0.81 TEST:0.73

#### **Xception**

TRAIN:0.88 VALID:0.85 TEST:0.79

#### VGG16

TRAIN:0.9483 VALID:0.9207 TEST:0.899





### Final Data Set

The generated data set contains three

classes:

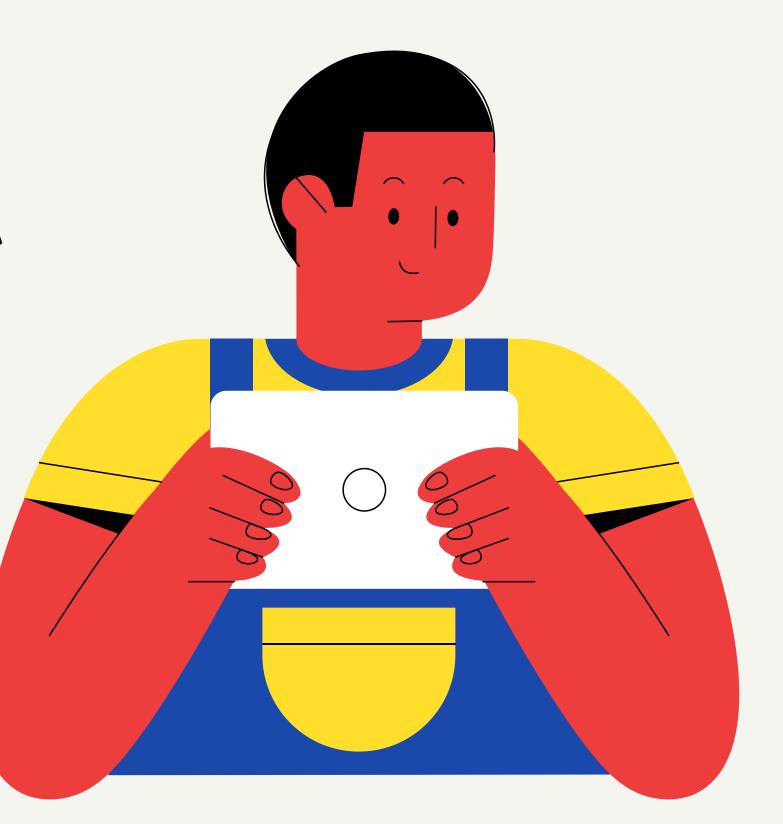
Active: 1580 Images

• Sleep:1230 Images

• Yawn: 1013 Images

**Data Link** 





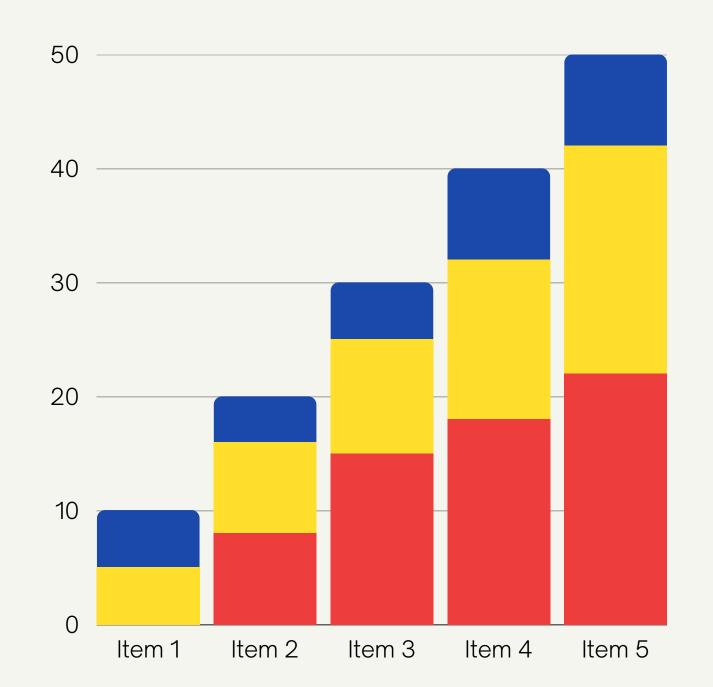






#### Best Model

- After we use all this models we find that VGG16 is the most suitable model for our problem with the highest accuracy.
- Based on transfer learning, the model is followed by two dense layers, one drop out layer and out output layer of three softmax activated nodes.





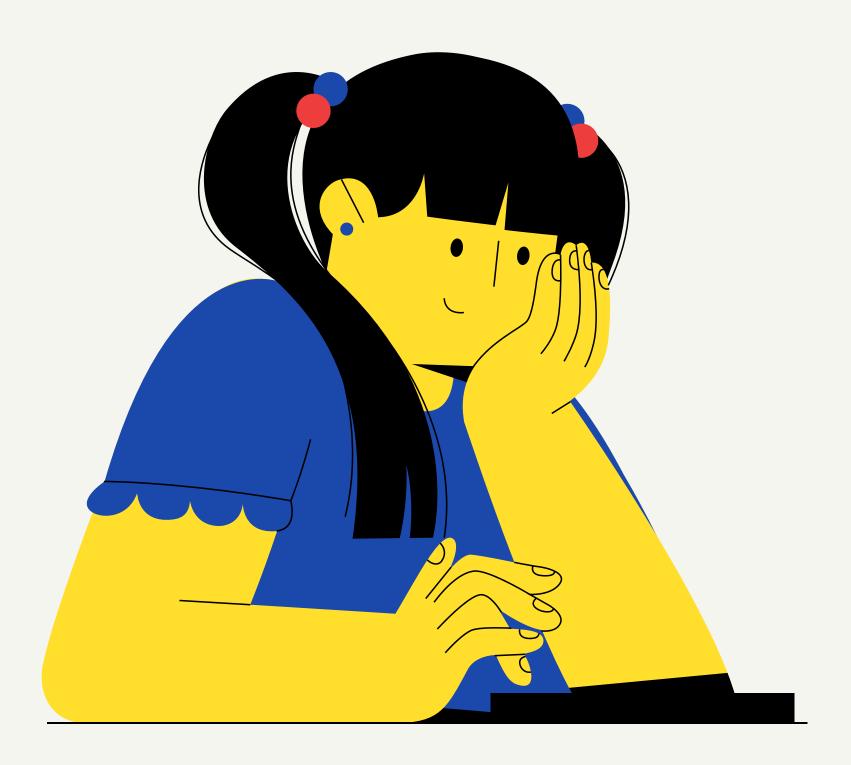


## Accuracy & Training Environment

- Training has been done on the generated data set for 30
   Epochs using Google Colab free T4 GPU resources.
- Training has ended with the following accuracy:
  - Training: 99.51%
  - Validation: 94.95%
  - Testing: 96.22%





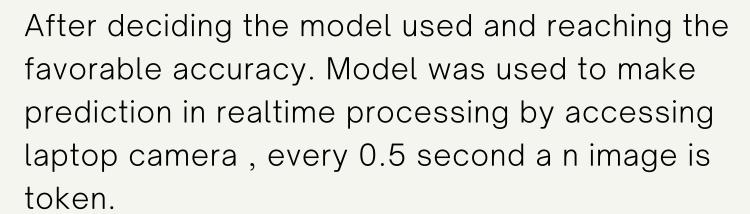


## Deployment Part 03



## Realtime Processing & Prediction

#### Camera Usage



#### Your video

You can use your driving viedo for testing, five frames are token of your viedo each 3 seconds a frame is token

#### Decision making

5 frames are taken from the camera then the model run on them to predict the result whether the subject is asleep or awake or a drown.

#### Output

Based on the prediction a message output is generated.

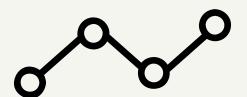












#### Decision Making

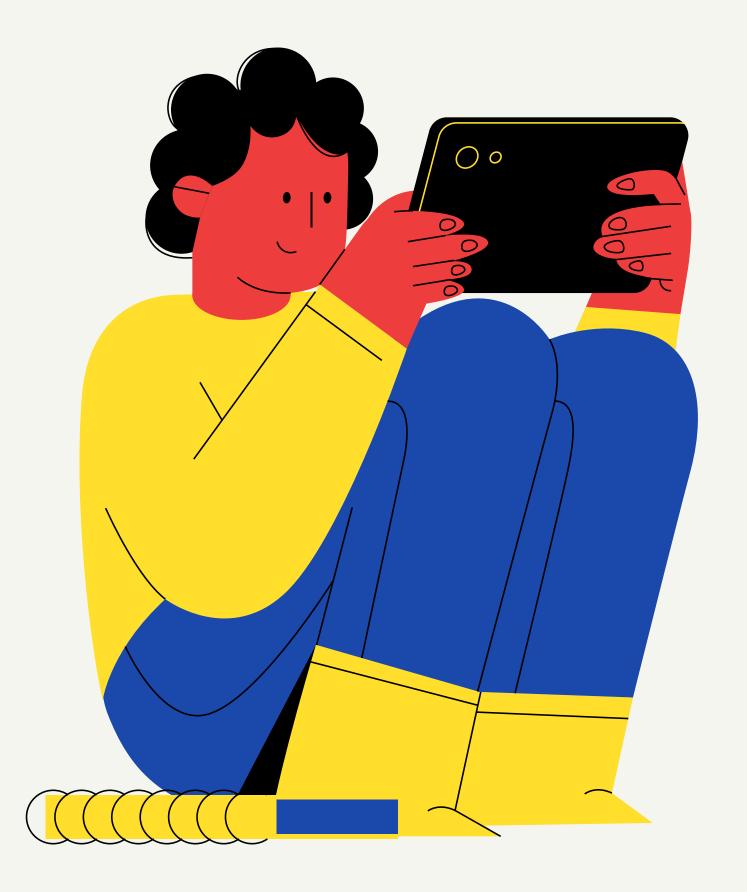
Drowsy driver:

sleep in two followed frames or yawning in one frame and sleep in the following frame

Driver is going to sleep: yawning in two following frames

Awake driver:

No sleep No yawning in two following frames





## loT integration

#### Server Connection

The message output is uploaded on a server to a specific topic.

#### Received Message

Any IoT device can be connected to the server and receive the message from it

#### Action

Based on the message sent from the model, the driver status is mointerd by his manager and an action is taken in the driver car (Alaram is going on ) if he is going to sleep



## Node Red Applecation

