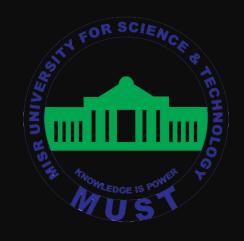
MISR UNIVERSITY FOR SCIENCE AND TECHNOLOGY COLLEGE OF ENGINEERING MECHATRONICS DEPARTMENT



MTE 506 DIGITAL CONTROL

LAB 5 - SPRING 2020

Goals of The Lab





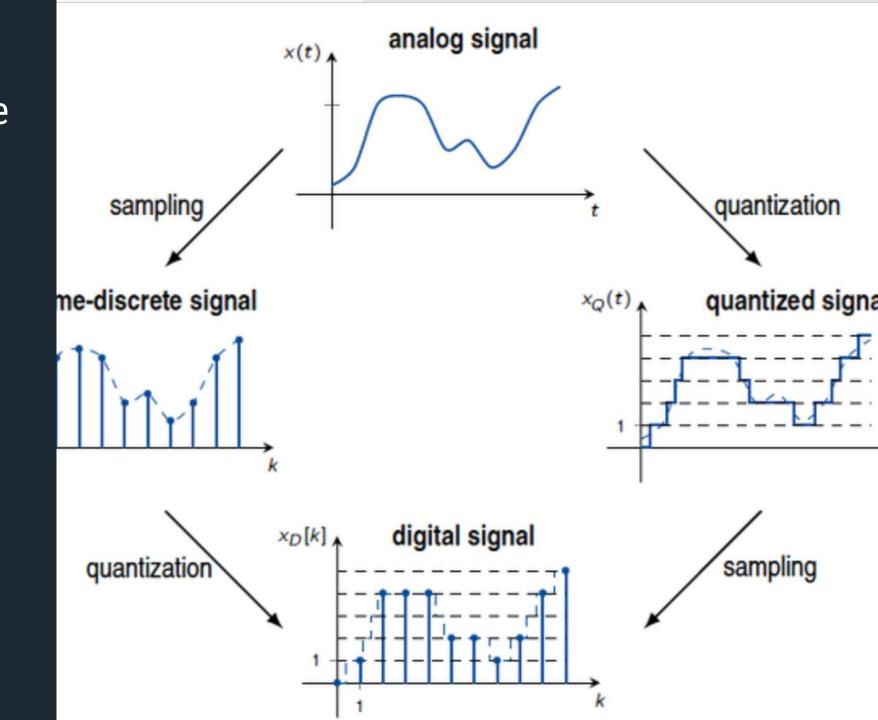
Continuous vs. discrete systems



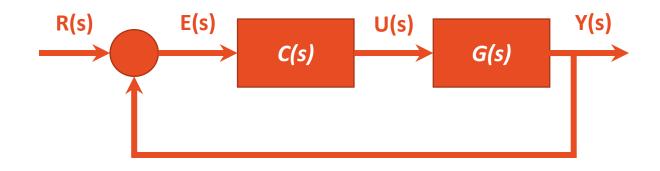
What is the Difference equation ?

Lab 5

Continuous vs. Discrete Systems



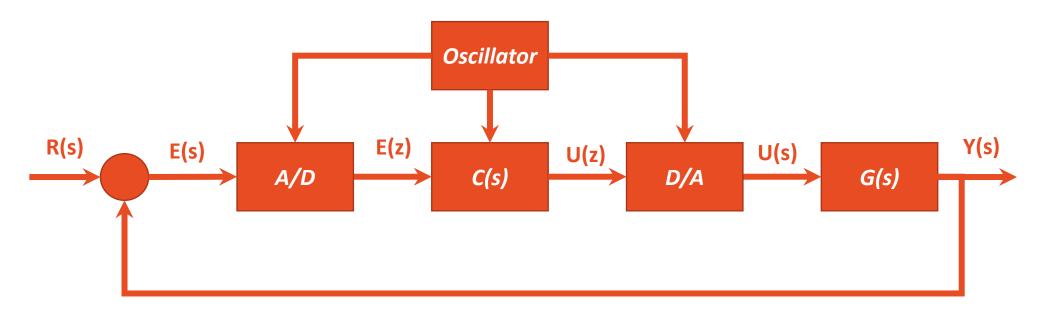
Continuous System vs. Discrete System



- R(s) ... Stimulation signal
- E(s) ... Error signal
- C(s) ... Controller
- U(s) ... Control Action
- Y(s) ... Sensor Output

Lab 5

Continuous System vs. Discrete System

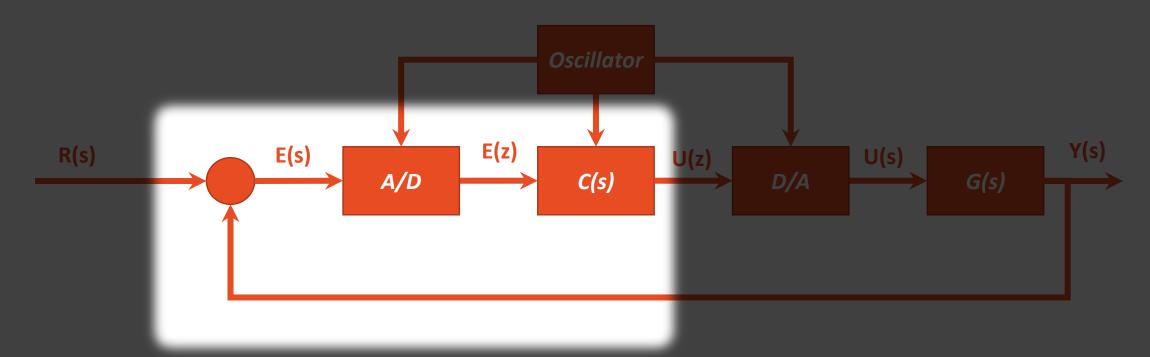


- R(s) ... Stimulation signal
- E(s) ... Error signal
- C(s) ... Controller
- U(s) ... Control Action
- Y(s) ... Sensor Output

- E(z) ... Discretized error signal
- U(z) ... Discretized Control Action

Lab 5

Continuous System vs. Discrete System



Modern Controllers

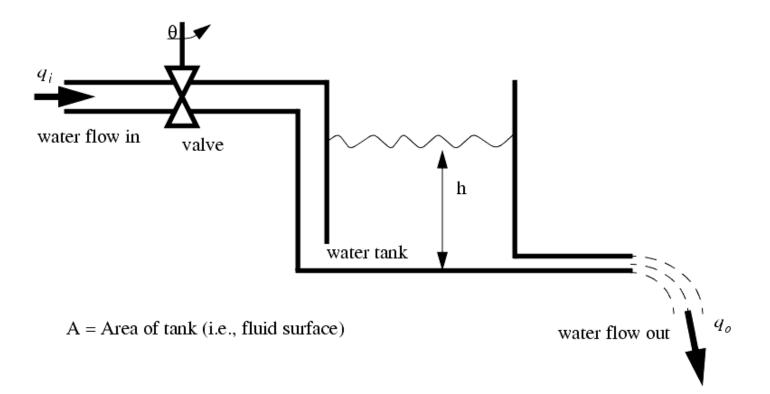
Lab 5

Simulating Water Tank

Revisited

Conversion to Discrete System

Difference Equation



Lab 5

In Lab 1

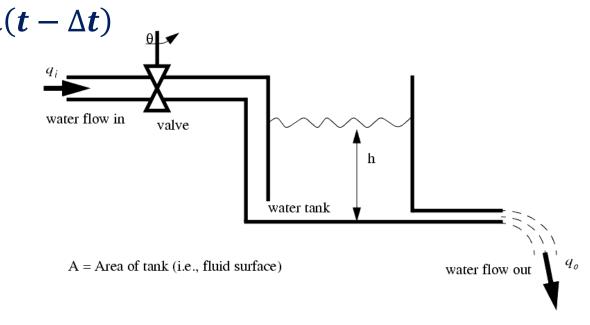
$$h(t) = \frac{\Delta t * (k * h(t - \Delta t) - q_i(t))}{A} + h(t - \Delta t)$$

 $\Delta t \dots Sampling time \quad q_i(t) \dots Excitation signal$

Let Δt be T (textbook term)

Samples:

$$T$$
, $2T$, $3T$ kT , $k > 0$



$$h(kT) = \frac{T * (k * h(kT - 1) - q_i(kT))}{A} + h(kT - 1) [Difference Equation]$$

Difference Equation

$$h(kT) = \frac{T * (k * h(kT - 1) - q_i(kT))}{A} + h(kT - 1)$$

iF T = 1 second (most problems assuming this for simplicity)

$$h(k) = \frac{(k * h(k-1) - q_i(t))}{A} + h(k-1)$$

$$A[h(k) - h(k-1)] - k * h(k-1) = -q_i(t)$$

$$[A + k] * h(k-1) - A * h(k) = q_i(t)$$

$$[Difference Equation]$$

$$q_i(t)$$

$$A * h(k) - A * h(k-1) - k * h(k-1) = -q_i(t)$$

$$A * h(k) - [A + k] * h(k - 1) = -q_i(t)$$

Difference Equation

$$[A + k] * h(k - 1) - A * h(k) = q_i(t)$$

System Output

System Input

if
$$k = 0 \rightarrow h(k-1) = h(0)$$

Difference Equation

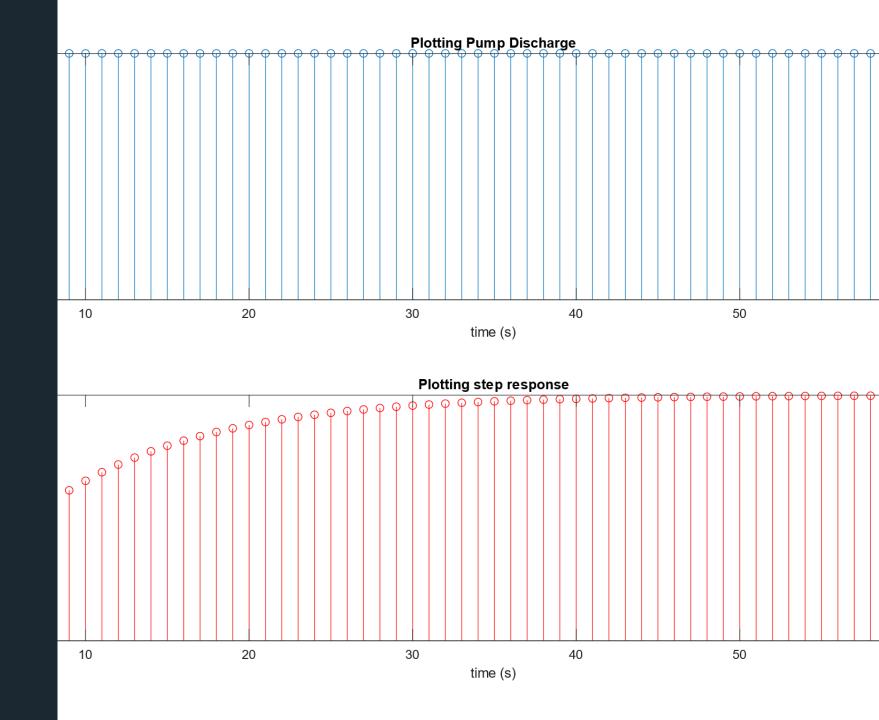
Remember

$$\frac{dh}{dT} = h(t) - h(t - \Delta t) = h(kT) - h(kT - 1)$$

Lab 5

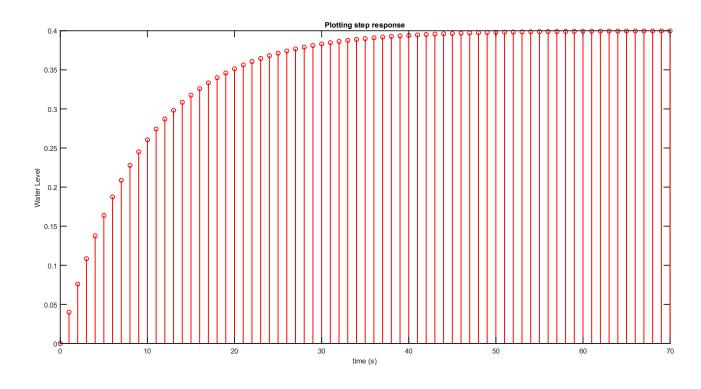
Exercise 1

Representation of discrete response using MATLAB



MATLAB command

stem (t, y) ... plots discretized (SAMPLED)data



Solved Example

Difference Equation

ne system shown in Figure 12.7. $k = 0, 1, 2, \ldots$, then the system. This text studies only the class s can be described by linear different on the class of the c

$$+ 2y(k + 1) - y(k) = 2u(k + 1)$$

$$(-1) - y(k - 2) = 2u(k - 1)$$

$$3y(k+2) + 2y(k+1) - y(k) = 2u(k+1) - 3u(k)$$

Find y value after 3 seconds assuming 1 s sampling interval

Solution

Rearranging equation terms by changing future term to past:

$$y(k+2) \rightarrow y(k)$$
 (present) \rightarrow replace k with k -2

$$\therefore 3y(k) + 2y(k-1) - y(k-2) = 2u(k-1) - 3u(k-2)$$

$$\therefore 3y(k) = 2u(k-1) - 3u(k-2) - 2y(k-1) + y(k-2)$$

$$\therefore y(k) = \frac{1}{3} [2u(k-1) - 3u(k-2) - 2y(k-1) + y(k-2)]$$

Initial conditions needed

$$y(-2) = 1$$
, $y(-1) = -2$ and $u(k) = 1$ [unit step]

We need to compute $y(0) \rightarrow y(1) \rightarrow y(2) \rightarrow y(3)$

$$y(-2) = 1, y(-1) = -2 \text{ and } u(k) = 1 \text{ [unit step]}$$

$$y(0) = \frac{1}{3} [2u(-1) - 3u(-2) - 2y(-1) + y(-2)]$$

$$= \frac{1}{3} [2 * (0) - 3 * (0) - 2 * (-2) + (1)] = \frac{5}{3}$$

$$y(1) = \frac{1}{3} [2u(0) - 3u(-1) - 2y(0) + y(-1)]$$

$$= \frac{1}{3} \left[2 * (1) - 3 * (0) - 2 * (\frac{5}{3}) + (-2) \right] = -\frac{10}{9}$$

$$y(-2) = 1, y(-1) = -2 \text{ and } u(k) = 1 \text{ [unit step]}$$

$$y(2) = \frac{1}{3} [2u(1) - 3u(0) - 2y(1) + y(0)]$$

$$= \frac{1}{3} \left[2 * (1) - 3 * (1) - 2 * (-\frac{10}{9}) + (\frac{5}{3}) \right] = \frac{26}{27}$$

$$y(3) = \frac{1}{3} [2u(2) - 3u(1) - 2y(2) + y(1)]$$

$$= \frac{1}{3} \left[2 * (1) - 3 * (1) - 2 * (\frac{26}{27}) + (-\frac{10}{9}) \right] = -\frac{109}{27}$$

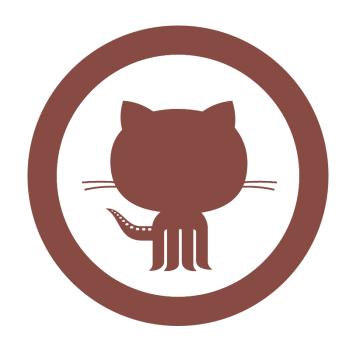
Assignment 2

$$3y(k+2) + 2y(k+1) - y(k) = 2u(k+1) - 3u(k)$$

Write a MATLAB script to calculate y(k) given k, y(-1), y(-2) assuming unit step input

Due date (Before Saturday 28 - 03 - 2020)

Your Private Github: MTE506/Assignment2



Don't forget to pull the lab update from.

http://github.com/wbadry/mte506

END OF Lab 5